

## Supplementary Material for EMORF-II

This document contains the supplementary material for the manuscript titled "**EMORF-II: ADAPTIVE EM-BASED OUTLIER-ROBUST FILTERING WITH CORRELATED MEASUREMENT NOISE**" submitted to the "*International Workshop on Machine Learning and Signal Processing 2025*". It provides notations used in the paper, details of derivations of  $\hat{\mathcal{I}}_k^i$  and  $\hat{b}_k$  in the paper and discussion of some more numerical evaluations.

### Notation

As a general notation in this work,  $\mathbf{r}^\top$  is the transpose of the vector  $\mathbf{r}$ ,  $r^i$  denotes the  $i$ -th element of a vector  $\mathbf{r}$ ;  $\mathbf{r}^{-i}$  is the vector  $\mathbf{r}$  with its  $i$ -th element removed; the subscript  $k$  is used for the time index;  $\mathbf{r}_k$  is the vector  $\mathbf{r}$  at time instant  $k$ ;  $\mathbf{r}_k$  is the sequence of vectors  $\mathbf{r}$  over all time steps except  $k$ ;  $R^{i,j}$  is the element of the matrix  $\mathbf{R}$  in the  $i$ -th row and  $j$ -th column;  $\mathbf{R}^{-1}$  is the inverse of  $\mathbf{R}$ ;  $|\mathbf{R}|$  is the determinant of  $\mathbf{R}$ ;  $\delta(\cdot)$  represents the delta function;  $\langle \cdot \rangle_{q(\psi_k)}$  denotes expectation with respect to the distribution  $q(\psi_k)$ ;  $\text{tr}(\cdot)$  is the trace operator;  $a \bmod b$  denotes the remainder of  $a/b$ ; the superscripts  $-$  and  $+$  mark predicted and updated filtering parameters, respectively. Furthermore, for any matrix  $\mathbf{R}$  we obtain the sub-matrix  $\mathbf{R}^{-i,-i}$  by removing its  $i$ -th column and row.  $\mathbf{R}_k(\mathcal{I}_k^i, \hat{\mathcal{I}}_k^{i-})$  denotes  $\mathbf{R}_k(\mathcal{I}_k)$  evaluated at  $\mathcal{I}_k$  with its  $i$ -th element as  $\mathcal{I}_k^i$  and remaining entries  $\hat{\mathcal{I}}_k^{i-}$ .

### Details of estimating $\hat{\mathcal{I}}_k^i$

Invoking the EM algorithm, the estimates  $\hat{\mathcal{I}}_k^i$  can be obtained with the following maximization

$$\hat{\mathcal{I}}_k^i = \underset{\mathcal{I}_k^i}{\operatorname{argmax}} \langle \ln(p(\mathbf{x}_k, \mathcal{I}_k^i, \hat{\mathcal{I}}_k^{i-}, \hat{b}_k | \mathbf{y}_{1:k})) \rangle_{q(\mathbf{x}_k)}$$

This leads to Equation (21) in the manuscript given as

$$\hat{\mathcal{I}}_k^i = \underset{\mathcal{I}_k^i}{\operatorname{argmax}} \left\{ \underbrace{-\frac{1}{2} \operatorname{tr}(\mathbf{W}_k \mathbf{R}_k^{-1}(\mathcal{I}_k^i, \hat{\mathcal{I}}_k^{i-})) - \frac{1}{2} \ln |\mathbf{R}_k(\mathcal{I}_k^i, \hat{\mathcal{I}}_k^{i-})| + \ln((1 - \theta_k) f(a_k, \hat{b}_k) (\mathcal{I}_k^i)^{a_k-1} e^{-\hat{b}_k \mathcal{I}_k^i} + \theta_k \delta(\mathcal{I}_k^i - 1)) + k_1^i}_{\ln q(\mathcal{I}_k^i)} \right\} \quad (21)$$

where the term to be maximized is supposed as  $\ln q(\mathcal{I}_k^i)$ . We perform the following manipulations to obtain Equations (23)-(25) in the manuscript. Manipulating  $\ln q(\mathcal{I}_k^i)$  we can get

$$\ln q(\mathcal{I}_k^i) = -\frac{1}{2} \ln |\mathbf{R}_k(\mathcal{I}_k^i, \hat{\mathcal{I}}_k^{i-})| - \frac{1}{2} \operatorname{tr}(\mathbf{W}_k \mathbf{R}_k^{-1}(\mathcal{I}_k^i, \hat{\mathcal{I}}_k^{i-})) + \ln((1 - \theta_k^i) f(a_k, \hat{b}_k) (\mathcal{I}_k^i)^{a_k-1} e^{-\hat{b}_k \mathcal{I}_k^i} + \theta_k^i \delta(\mathcal{I}_k^i - 1)) + k_1^i$$

which leads to

$$q(\mathcal{I}_k^i) = k_2^i \exp\left(-\frac{1}{2} \ln |\mathbf{R}_k(\mathcal{I}_k^i, \hat{\mathcal{I}}_k^{i-})| - \frac{1}{2} \operatorname{tr}(\mathbf{W}_k \mathbf{R}_k^{-1}(\mathcal{I}_k^i, \hat{\mathcal{I}}_k^{i-}))\right) \times (1 - \theta_k^i) f(a_k, \hat{b}_k) (\mathcal{I}_k^i)^{a_k-1} e^{-\hat{b}_k \mathcal{I}_k^i} + k_2^i \exp\left(-\frac{1}{2} \ln |\mathbf{R}_k(\mathcal{I}_k^i = 1, \hat{\mathcal{I}}_k^{i-})| - \frac{1}{2} \operatorname{tr}(\mathbf{W}_k \mathbf{R}_k^{-1}(\mathcal{I}_k^i = 1, \hat{\mathcal{I}}_k^{i-}))\right) \theta_k^i \delta(\mathcal{I}_k^i - 1)$$

where  $k_2^i$  is another proportionality constant. Further manipulation of  $q(\mathcal{I}_k^i)$  yields

$$q(\mathcal{I}_k^i) = k_2^i (R_k^{ii}/\mathcal{I}_k^i)^{-\frac{1}{2}} |\hat{\mathbf{R}}_k^{-i,-i}|^{-\frac{1}{2}} \exp\left(-\frac{1}{2} W_k^{ii} \frac{\mathcal{I}_k^i}{R_k^{ii}} - \frac{1}{2} \operatorname{tr}(\mathbf{W}_k^{-i,-i} (\hat{\mathbf{R}}_k^{-i,-i})^{-1})\right) \times (1 - \theta_k^i) f(a_k, \hat{b}_k) (\mathcal{I}_k^i)^{a_k-1} e^{-\hat{b}_k \mathcal{I}_k^i} + k_2^i \exp\left(-\frac{1}{2} \ln |\mathbf{R}_k(\mathcal{I}_k^i = 1, \hat{\mathcal{I}}_k^{i-})| - \frac{1}{2} \operatorname{tr}(\mathbf{W}_k \mathbf{R}_k^{-1}(\mathcal{I}_k^i = 1, \hat{\mathcal{I}}_k^{i-}))\right) \theta_k^i \delta(\mathcal{I}_k^i - 1)$$

Moving the relevant terms in the exponents we get

$$q(\mathcal{I}_k^i) = k_2^i (R_k^{ii})^{-\frac{1}{2}} |\hat{\mathbf{R}}_k^{-i,-i}|^{-\frac{1}{2}} \exp\left(-\frac{1}{2} \text{tr}(\mathbf{W}_k^{-i,-i} (\hat{\mathbf{R}}_k^{-i,-i})^{-1})\right) \times (1 - \theta_k^i) f(a_k, \hat{b}_k) (\mathcal{I}_k^i)^{\overbrace{(a_k + \frac{1}{2})}^{\alpha_k} - 1} e^{-\overbrace{(\hat{b}_k + \frac{1}{2} \frac{W_k^{ii}}{R_k^{ii}})}^{\beta_k^i} \mathcal{I}_k^i} \\ + k_2^i \exp\left(-\frac{1}{2} \ln|\mathbf{R}_k(\mathcal{I}_k^i = 1, \hat{\mathcal{I}}_k^{-i})| - \frac{1}{2} \text{tr}(\mathbf{W}_k \mathbf{R}_k^{-1}(\mathcal{I}_k^i = 1, \hat{\mathcal{I}}_k^{-i}))\right) \theta_k^i \delta(\mathcal{I}_k^i - 1)$$

$\alpha_k$  and  $\beta_k^i$  can easily be identified as follows given as Equations (26)-(27) in the manuscript

$$\alpha_k = a_k + 0.5 \quad (26)$$

$$\beta_k^i = \hat{b}_k + 0.5 \frac{W_k^{ii}}{R_k^{ii}} \quad (27)$$

Through further manipulation we can write  $q(\mathcal{I}_k^i)$  as

$$q(\mathcal{I}_k^i) = k_2^i \underbrace{(R_k^{ii})^{-\frac{1}{2}} |\hat{\mathbf{R}}_k^{-i,-i}|^{-\frac{1}{2}} \exp\left(-\frac{1}{2} \text{tr}(\mathbf{W}_k^{-i,-i} (\hat{\mathbf{R}}_k^{-i,-i})^{-1})\right) (1 - \theta_k^i) \frac{\Gamma(\alpha_k) \hat{b}_k^{\alpha_k}}{\Gamma(\alpha_k) \beta_k^{\alpha_k}}}_{G_k^i} \overbrace{f(\alpha_k, \beta_k^i) (\mathcal{I}_k^i)^{\alpha_k - 1} e^{-\beta_k^i \mathcal{I}_k^i}}^{Gamma(\alpha_k, \beta_k^i)} \\ + k_2^i \underbrace{\exp\left(-\frac{1}{2} \ln|\mathbf{R}_k(\mathcal{I}_k^i = 1, \hat{\mathcal{I}}_k^{-i})| - \frac{1}{2} \text{tr}(\mathbf{W}_k \mathbf{R}_k^{-1}(\mathcal{I}_k^i = 1, \hat{\mathcal{I}}_k^{-i}))\right) \theta_k^i \delta(\mathcal{I}_k^i - 1)}_{H_k^i}$$

Since maximizing logarithm of a positive function is equivalent to maximizing the function, the resulting decision criterion (from Equation 21) depends on which part -  $G_k^i$  or  $H_k^i$  - of the multi-modal function  $q(\mathcal{I}_k^i)$  has higher weight. If  $H_k^i \geq G_k^i$  we declare  $\hat{\mathcal{I}}_k^i = 1$ . Otherwise, if  $H_k^i < G_k^i$ , we assign  $\hat{\mathcal{I}}_k^i$  as the mode of  $Gamma(\alpha_k, \beta_k^i)$ . The criterion is summarized in Equation (23) in the manuscript reproduced as

$$\mathcal{I}_k^i = \begin{cases} 1 & \text{if } H_k^i \geq G_k^i \\ (\alpha_k - 1)/\beta_k^i & \text{if } H_k^i < G_k^i \end{cases} \quad (23)$$

## Details of estimating $\hat{b}_k$

Employing the EM algorithm the estimate for  $b_k$  can be calculated through the following maximization

$$\hat{b}_k = \underset{b_k^i}{\text{argmax}} \langle \ln(p(\mathbf{x}_k, \hat{\mathcal{I}}_k, b_k | \mathbf{y}_{1:k})) \rangle_{q(\mathbf{x}_k)}$$

which leads to

$$\hat{b}_k = \underset{b_k}{\text{argmax}} \sum_{i=1}^m \ln \left[ (1 - \theta_k^i) f(a_k, b_k) (\hat{\mathcal{I}}_k^i)^{a_k - 1} e^{-b_k \hat{\mathcal{I}}_k^i} + \theta_k^i \delta(\hat{\mathcal{I}}_k^i - 1) \right] + \ln(f(A_k, B_k) b_k^{A_k - 1} e^{-B_k b_k})$$

Since  $\hat{\mathcal{I}}_k^i = 1$  do not affect the estimates  $\hat{b}_k$ , we can further write

$$\hat{b}_k = \underset{b_k}{\text{argmax}} \sum_{\{i: \hat{\mathcal{I}}_k^i \neq 1\}} \ln \left[ (1 - \theta_k^i) f(a_k, b_k) (\hat{\mathcal{I}}_k^i)^{a_k - 1} e^{-b_k \hat{\mathcal{I}}_k^i} \right] + \ln(f(A_k, B_k) b_k^{A_k - 1} e^{-B_k b_k})$$

which can be simplified as

$$\hat{b}_k = \underset{b_k}{\text{argmax}} \sum_{\{i: \hat{\mathcal{I}}_k^i \neq 1\}} (a_k \ln b_k - b_k \mathcal{I}_k^i) - B_k b_k + (A_k - 1) \ln b_k$$

Maximizing the above equation through differentiation leads to the estimate  $\hat{b}_k$  given as

$$\hat{b}_k = \frac{M_k a_k + A_k - 1}{B_k + \sum_{\{i: \hat{\mathcal{I}}_k^i \neq 1\}} \hat{\mathcal{I}}_k^i}$$

where  $M_k = \#\{i : \hat{\mathcal{I}}_k^i \neq 1\}$  i.e. the count of  $\mathcal{I}_k$  elements not equal to one. Further defining  $\bar{A}_k = M_k a_k + A_k$  and  $\bar{B}_k = B_k + \sum_{\{i: \hat{\mathcal{I}}_k^i \neq 1\}} \hat{\mathcal{I}}_k^i$  results in Equation (28) of the manuscript

$$\hat{b}_k = \frac{\bar{A}_k - 1}{\bar{B}_k} \quad (28)$$

## Other numerical experiments

We further extend our numerical experiments by introducing outliers generated from Uniform and Laplace distributions, replacing the previously considered Gaussian-based outliers. Across a range of parameter variations, the comparative performance trends remained similar to those presented in the main manuscript. Further evaluation of EMORF-II was conducted by testing alternative prior parameters  $\theta_k^i$ , including values sampled from a Uniform distribution over the range  $[0.05, 0.95]$ . The results show that EMORF-II maintains robust performance across variations in  $\theta_k^i$ . Nevertheless, setting  $\theta_k^i = 0.5$  is recommended as a default choice in the absence of specific prior knowledge regarding outlier rates.