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# **Backward Stochastic Differential Equation**

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#### Motivation

## Example of a Stock Graph



# American Option

#### Objective

- Let  $t \in [0, T]$
- Payoff at time T:

$$V_T = (S_T - K)^+$$

- We can exercise at any stopping time between [0, T]
- Hence, we would like, with  $g: x \to (x K)^+$ , to maximize  $\mathbb{E}[g(S_t)]$  from today to maturity.

$$V_0 = \sup_{t \in au} \mathbb{E}[g(S_t)]$$

with au the set of stopping times



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# Forward Diffusion

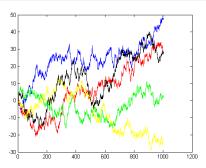
#### Model

$$dX_t = \mu(t, X_t)dt + \sigma(t, X_t)dB_t$$

# Forward Diffusion

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### **Backward**

#### Model

$$dX_{t} = \mu(t, X_{t})dt + \sigma(t, X_{t})dB_{t}$$
$$-dY_{t} = f(t, X_{t}, Y_{t}, Z_{t})dt - Z_{t}dB_{t}$$
$$Y_{T} = \xi(X_{T})$$

#### **Backward**

#### Model

$$dX_t = \mu(t, X_t)dt + \sigma(t, X_t)dB_t$$
$$-dY_t = f(t, X_t, Y_t, Z_t)dt - Z_tdB_t$$
$$Y_T = \xi(X_T)$$

#### Where:

- f is called the driver
- $Z_t$  is a stochastic process related to  $u(t, X_t) = Y_t$  by :

$$Z_t = \sigma(t, X_t) Du_{\mathsf{x}}(t, X_t)$$

•  $\xi$  is a measurable function



### **Backward**

#### Example: European Option

The driver for a European Option with a Geometric Brownian motion model for  $X_t$  and using risk neutral measure :

$$f(t, X_t, Y_t, Z_t) = -rY_t \tag{1}$$

#### Proof

$$dY_{t} = \underbrace{\phi_{t}}_{\text{amount invested in stock}} \frac{dX_{t}}{X_{t}} + (Y_{t} - \phi_{t})rdt$$

$$dY_{t} = r\phi dt + \sigma dB_{t} + (Y_{t} - \phi_{t})rdt$$

$$dY_{t} = rY_{t}dt + \sigma \phi dB_{t}$$

$$-dY_{t} = -rY_{t}dt - Z_{t}dB_{t}$$
(2)

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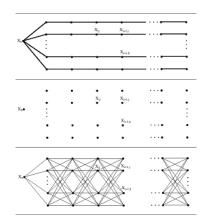
### Discretization

$$egin{aligned} Z_{t_i} &= rac{1}{\Delta t_i} \mathbb{E}[Y_{t_{i+1}} \Delta B_{t_i} | \mathcal{F}_{t_i}] \ Y_{t_i} &= \mathbb{E}[Y_{t_{i+1}} | \mathcal{F}_{t_i}] + f(t_i, S_{t_i}, Y_{t_{i+1}}, Z_{t_i}) \Delta t_i \end{aligned}$$

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## Mesh Method: Glasserman



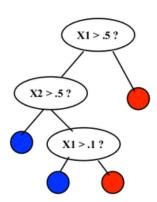
### Mesh Method: Glasserman

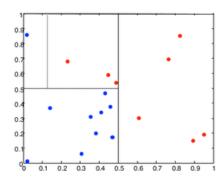
#### Propositon

$$\mathbb{E}[Y_{t_{i+1}}^j|(X_{t_{i+1}})] = \sum_{j=1}^N W_{i,k}^j Y_{t_{i+1}}^j$$

the weights being given by the properties of the diffusion

# Tree Regression: Random Forest



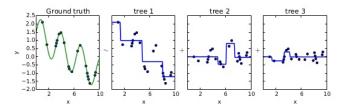


# Tree Regression : Gradient Boosting

#### Statistical view on boosting

•  $\Rightarrow$  Generalization of boosting to arbitrary loss functions

#### Residual fitting



# Using BSDE properties

 $Z_{t_i} = \frac{1}{\Delta t_i} \mathbb{E}[Y_{t_{i+1}} \Delta B_{t_i} | \mathcal{F}_{t_i}]$  includes a very noisy process to approximate.

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 where  $u(t, X_t) = Y_t$ 

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We make use of :  $Z_t = \sigma(t, X_t) Du_x(t, X_t)$  where  $u(t, X_t) = Y_t$ 

- 1 :  $Z_{t_i} = \frac{1}{\Delta t_i} \mathbb{E}[Y_{t_{i+1}} \Delta B_{t_i} | \mathcal{F}_{t_i}]$  with one of previous methods
- 2:  $Y_{t_i} = \mathbb{E}[Y_{t_{i+1}}|\mathcal{F}_{t_i}] + f(t_i, S_{t_i}, Y_{t_{i+1}}, Z_{t_i})\Delta t_i$

We use then a Picard Iteration (considering this as a Markovian case):

- 3 : We approximate  $Y_{t_i} = \hat{h}(t_i, X_{t_i})$
- 4:  $Z_{t_i} = \sigma(t_i, X_{t_i}) \nabla \hat{h}(t_i, X_{t_i})$

This gives a more stable  $Z_t$  process at time t.



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# Bid-ask Spread Option

#### driver in this case

$$\begin{cases} f(t, Y_t, Z_t) = -Z_t \theta - rY + (R - r)(Y - \frac{Z_t}{\sigma})^- \\ \theta = \frac{\mu - r}{\sigma} \\ \xi(X_T) = (X_T - K_1) - 2(X_T - K_2) \end{cases}$$

#### European combination with different interest rates

We again consider a one dimensional Black-Scholes model with parameters

μ	$\sigma$	r	R	T	$S_0$	$K_1$	$K_2$
0.05	0.2	0.01	0.06	0.25	100	95	105



# Gobet use of Hypercubes regression

#### Ex.1: bid-ask spread for interest rates

- Black-Scholes model and  $\Phi(\mathbf{S}) = (S_T K_1)_+ 2(S_T K_2)_+$ .
- $f(t, x, y, z) = -\{yr + z\theta (y \frac{z}{\sigma})^{-}(R r)\}, \ \theta = \frac{\mu r}{\sigma}.$

Acknowledgements

• Parameters

	$\mu$	$\sigma$	r	R	T	$S_0$	$K_1$	$K_2$
•	0.05	0.2	0.01	0.06	0.25	100	95	105

	$N=5, \delta=5$	$N=20,\delta=1$	$N = 50,  \delta = 0.5$
M	D = [60, 140]	D = [60, 200]	D = [40, 200]
128	3.05(0.27)	3.71( <b>0.95</b> )	3.69(4.15)
512	2.93(0.11)	3.14(0.16)	3.48(0.54)
2048	2.92(0.05)	3.00(0.03)	3.08(0.12)
8192	2.91(0.03)	2.96(0.02)	2.99(0.02)
32768	2.90(0.01)	<b>2.95</b> (0.01)	2.96(0.01)

### Our Results

	stat parameter	values	
LSM	mean	2.9381	
LSM	std	0.0154	
LSM	95% confidence interval	[2.9366, 2.9396]	
LSM	min	2.9159	
LSM	max	2.9787	
Mesh	mean	2.841	
Mesh	std	0.0711	
Mesh	95% confidence interval	[2.834, 2.848] N=1000 might be too small	
Mesh	min	2.6986	
Mesh	max	2.9682	
Derivative	mean	2.9403	
Derivative	std	0.1441	
Derivative	95% confidence interval	[2.9121, 2.9685]	
Derivative	min	2.7534	
Derivative	max	3.2832	
RandomForest	mean	2.8007	
RandomForest	std	0.0508	
RandomForest	95% confidence interval	[2.7957, 2.8057] Parameters of the method	
RandomForest	min	2.7281	
RandomForest	max	2.8888	

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$$-dY_t = f(t, X_t, Y_t, Z_t)dt - Z_tdB_t + dL_t$$
$$Y_T = \xi(X_T)$$
$$\int_0^T (Y_t - \xi(X_t))dL_t = 0$$

 $L_t$  controls Y to stay above the barrier  $\xi$ 



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- Clean the code, comment and put on Github for open source.

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