

Support Vector Machines

Classification with SVM, kernel trick

Machine Learning and Data Mining, 2025

Majid Sohrabi

National Research University Higher School of Economics



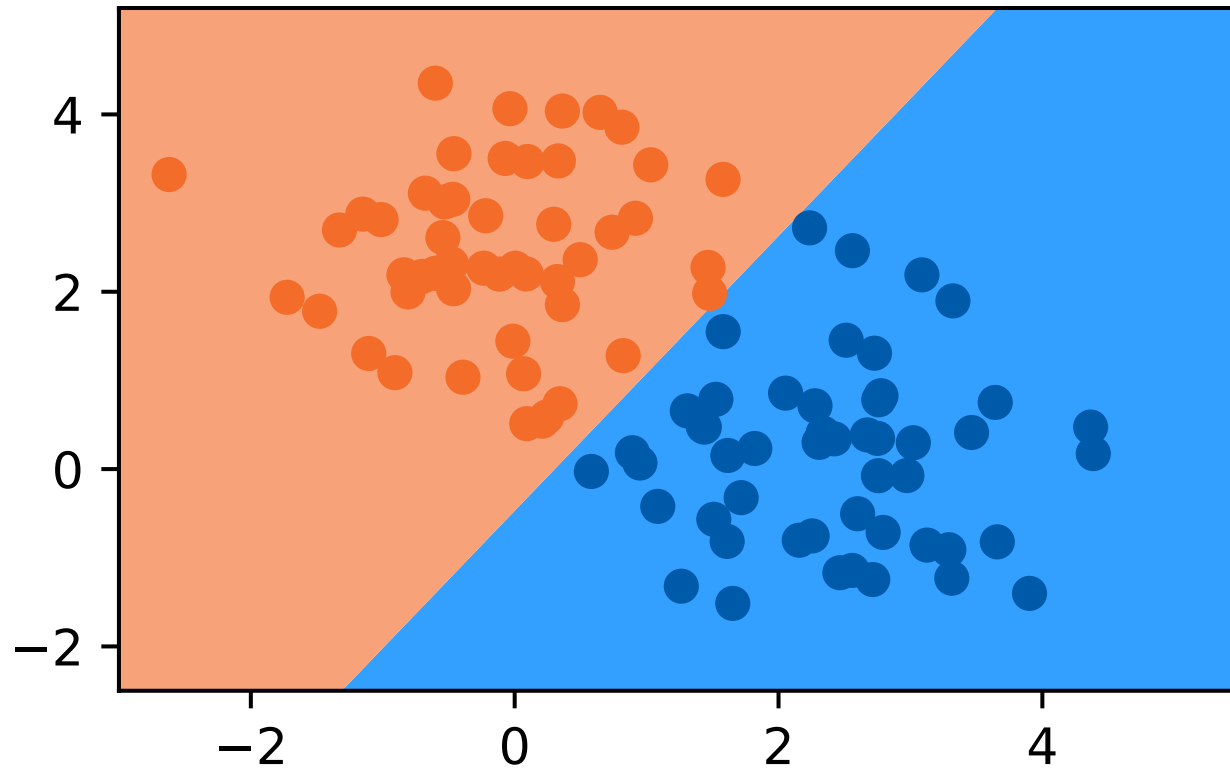
MMCP

October 01, 2025

General Idea (linearly separable case)



Classification with linear models



$$\hat{f}(x) = \text{sign}[w^T x + w_0]$$

$$y \in \{-1, 1\}$$

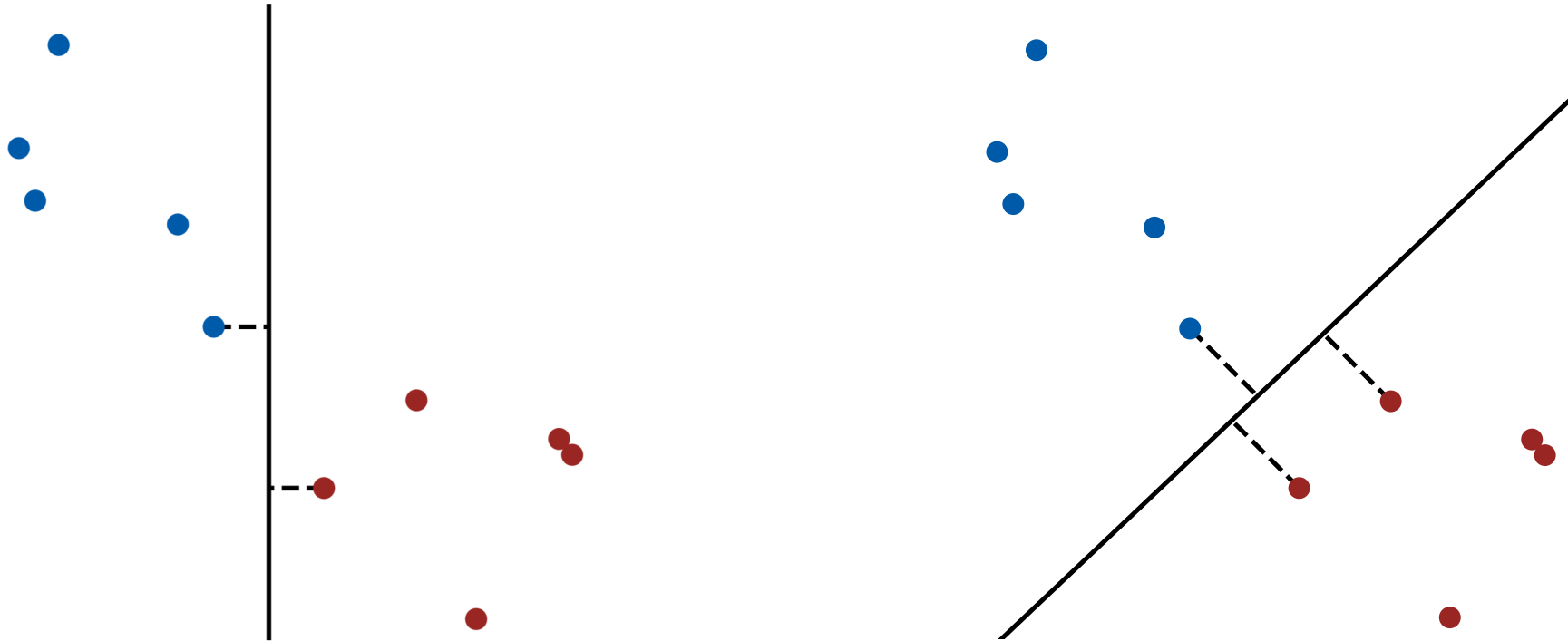
Separating hyperplane:

$$w^T x + w_0 = 0$$

Optimal hyperplane

Assume a separating hyperplane exists (task is linearly separable)

Idea: find the best hyperplane by maximizing the distance to the closest data points



Mathematical formulation

Correct classification if:

$$\begin{cases} w^T x + w_0 > 0, & y = +1 \\ w^T x + w_0 < 0, & y = -1 \end{cases}$$

or equivalently:

$$y(w^T x + w_0) > 0$$

Mathematical formulation

Correct classification if:

$$\begin{cases} w^T x + w_0 > 0, & y = +1 \\ w^T x + w_0 < 0, & y = -1 \end{cases}$$

or equivalently:

$$y(w^T x + w_0) > 0$$

defined up to a multiplicative constant
We can choose this constant s.t. for the
closest point: $y_{\text{closest}}(w^T x_{\text{closest}} + w_0) = 1$

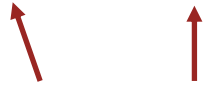
Mathematical formulation

Correct classification if:

$$\begin{cases} w^T x + w_0 > 0, & y = +1 \\ w^T x + w_0 < 0, & y = -1 \end{cases}$$

or equivalently:

$$y(w^T x + w_0) > 0$$



defined up to a multiplicative constant
We can choose this constant s.t. for the
closest point: $y_{\text{closest}}(w^T x_{\text{closest}} + w_0) = 1$

So for all points:

$$y(w^T x + w_0) \geq 1$$

Mathematical formulation

Correct classification if:

$$\begin{cases} w^T x + w_0 > 0, & y = +1 \\ w^T x + w_0 < 0, & y = -1 \end{cases}$$

or equivalently:

$$y(w^T x + w_0) > 0$$

defined up to a multiplicative constant
We can choose this constant s.t. for the
closest point: $y_{\text{closest}}(w^T x_{\text{closest}} + w_0) = 1$

So for all points:

$$y(w^T x + w_0) \geq 1$$

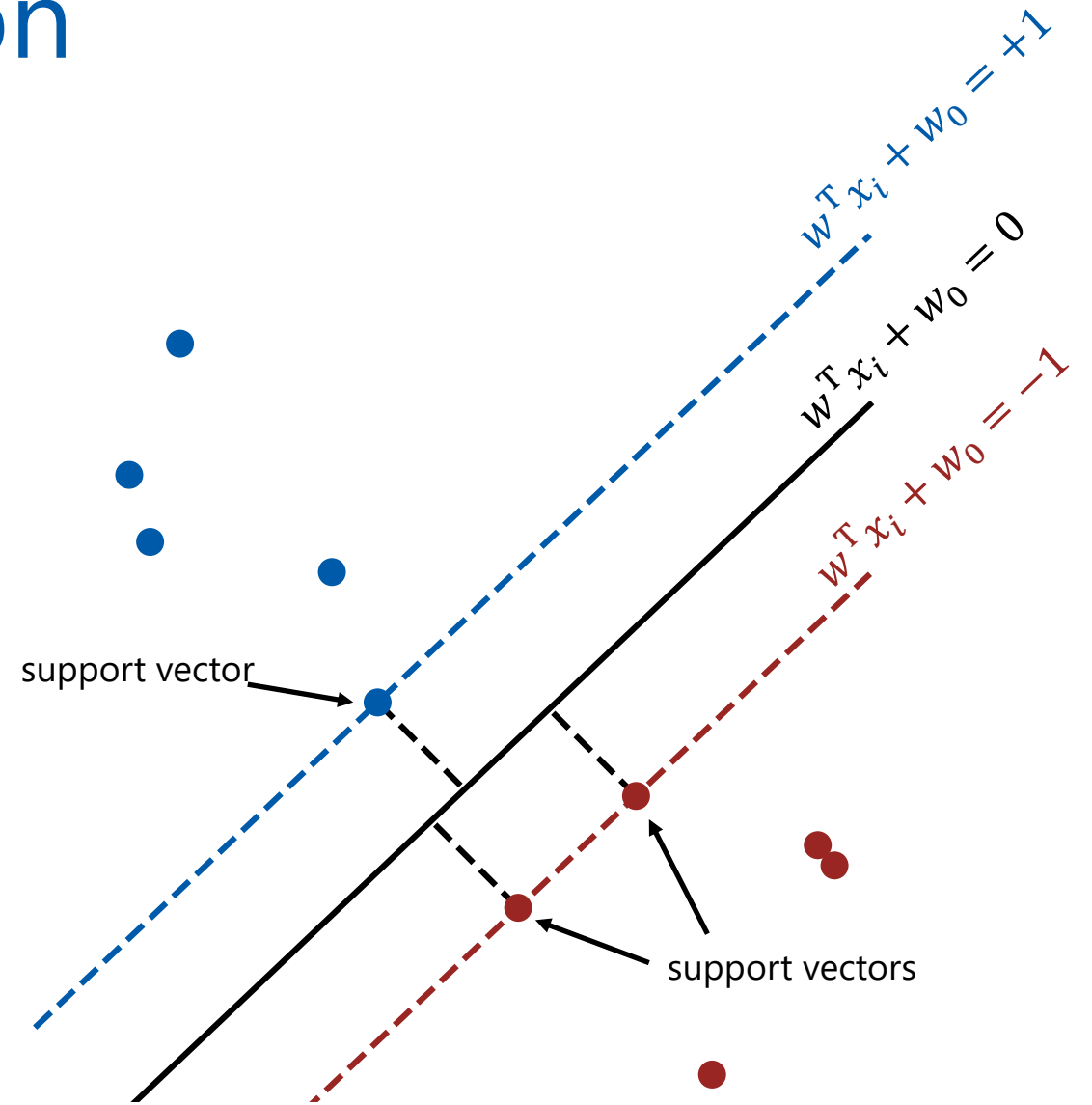
Distance to the closest point is:

$$h = y_{\text{closest}} \frac{(w^T x_{\text{closest}} + w_0)}{\|w\|} = \frac{1}{\|w\|}$$

Mathematical formulation

So the problem can be defined as:

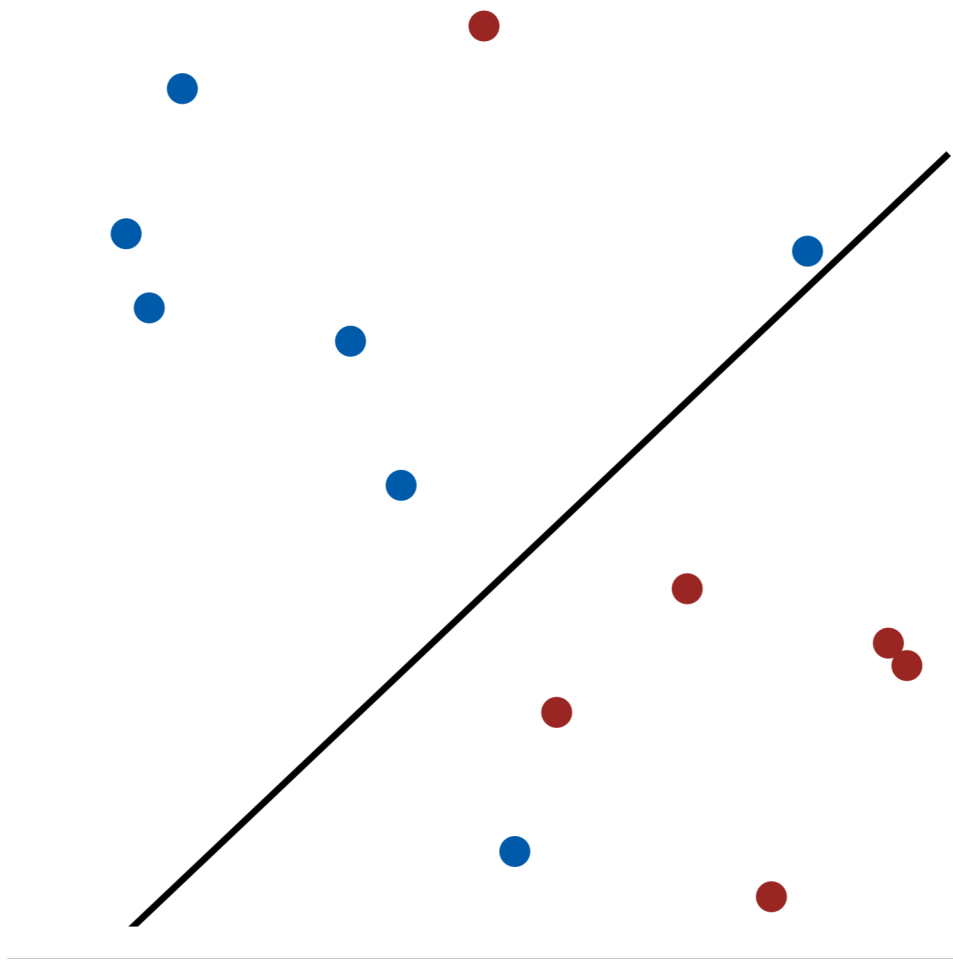
$$\begin{cases} \frac{1}{2} \|w\|^2 \rightarrow \min_{w, w_0} \\ y_i(w^T x_i + w_0) \geq 1, & i = 1, \dots, N \end{cases}$$



Nonseparable case



Slack variables

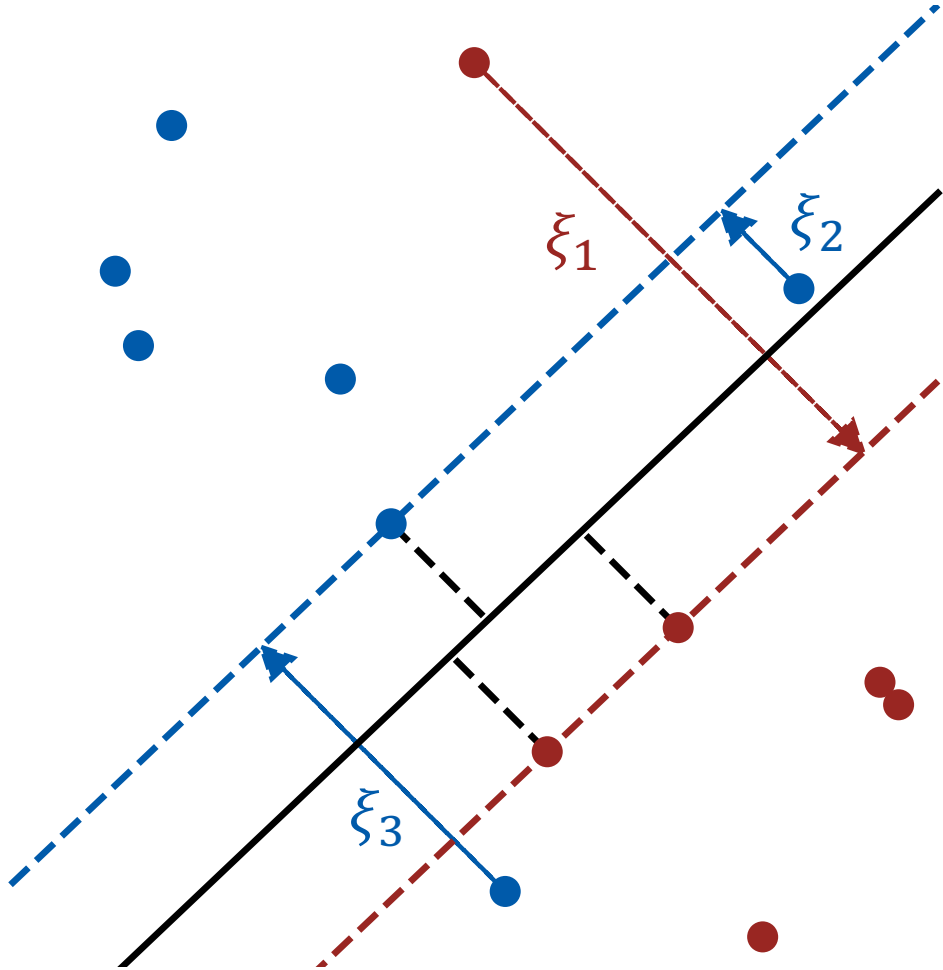


For nonseparable case, these conditions:

$$y_i(w^T x_i + w_0) \geq 1, \quad i = 1, \dots, N$$

cannot be satisfied simultaneously.

Slack variables



For nonseparable case, these conditions:

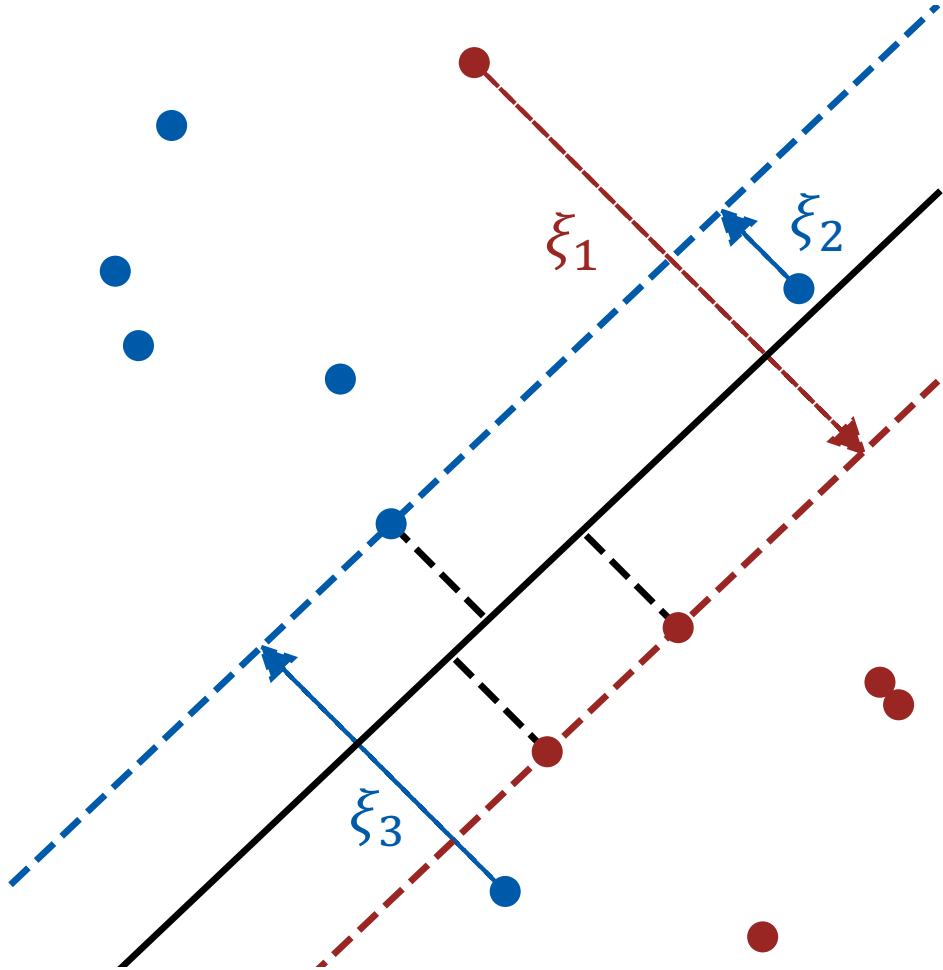
$$y_i(w^T x_i + w_0) \geq 1, \quad i = 1, \dots, N$$

cannot be satisfied simultaneously.

Need to introduce slack variables ξ_i :

$$\begin{aligned} y_i(w^T x_i + w_0) &\geq 1 - \xi_i, \\ \xi_i &\geq 0, \quad i = 1, \dots, N \end{aligned}$$

Slack variables



For nonseparable case, these conditions:

$$y_i(w^T x_i + w_0) \geq 1, \quad i = 1, \dots, N$$

cannot be satisfied simultaneously.

Need to introduce slack variables ξ_i :

$$\begin{aligned} y_i(w^T x_i + w_0) &\geq 1 - \xi_i, \\ \xi_i &\geq 0, \quad i = 1, \dots, N \end{aligned}$$

And the objective function becomes:

$$\frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i \rightarrow \min_{w, w_0, \xi}$$

Solution

To solve:

$$\frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i \rightarrow \min_{w, w_0, \xi}$$

subject to:

$$y_i(w^T x_i + w_0) \geq 1 - \xi_i,$$
$$\xi_i \geq 0, \quad i = 1, \dots, N$$

Solution

To solve:

$$\frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i \rightarrow \min_{w, w_0, \xi}$$

subject to:

$$y_i(w^T x_i + w_0) \geq 1 - \xi_i, \\ \xi_i \geq 0, \quad i = 1, \dots, N$$

define the Lagrangian:

$$L(w, w_0, \xi, \alpha, r) = \frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \alpha_i (y_i(w^T x_i + w_0) - 1 + \xi_i) - \sum_{i=1}^N r_i \xi_i$$

Solution

To solve:

$$\frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i \rightarrow \min_{w, w_0, \xi}$$

subject to:

$$y_i(w^T x_i + w_0) \geq 1 - \xi_i, \\ \xi_i \geq 0, \quad i = 1, \dots, N$$

define the Lagrangian:

$$L(w, w_0, \xi, \alpha, r) = \frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \alpha_i (y_i(w^T x_i + w_0) - 1 + \xi_i) - \sum_{i=1}^N r_i \xi_i$$

Solution determined by the Karush–Kuhn–Tucker conditions:

$$\frac{\partial L}{\partial (w, w_0, \xi_i)} = 0 \quad L \rightarrow \max_{\alpha, r}$$

$$\alpha_i \geq 0, \quad r_i \geq 0$$

$$y_i(w^T x_i + w_0) \geq 1 - \xi_i$$

$$\xi_i \geq 0,$$

$$\alpha_i (y_i(w^T x_i + w_0) - 1 + \xi_i) = 0$$

$$r_i \xi_i = 0 \quad i = 1, \dots, N$$

Solution

$$L(w, w_0, \xi, \alpha, r) = \frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \alpha_i (y_i (w^T x_i + w_0) - 1 + \xi_i) - \sum_{i=1}^N r_i \xi_i$$
$$\frac{\partial L}{\partial w} = 0 \quad \Rightarrow \quad w = \sum_{i=1}^N \alpha_i y_i x_i$$

i.e. the solution is a **linear combination** of the training objects.

Solution

$$L(w, w_0, \xi, \alpha, r) = \frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \alpha_i (y_i (w^T x_i + w_0) - 1 + \xi_i) - \sum_{i=1}^N r_i \xi_i$$
$$\frac{\partial L}{\partial w} = 0 \quad \Rightarrow \quad w = \sum_{i=1}^N \alpha_i y_i x_i$$

i.e. the solution is a **linear combination** of the training objects.

$$\frac{\partial L}{\partial w_0} = 0 \quad \Rightarrow \quad \sum_{i=1}^N \alpha_i y_i = 0$$

i.e. the combination coefficients need to be **balanced** between classes.

Solution

$$L(w, w_0, \xi, \alpha, r) = \frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \alpha_i (y_i (w^T x_i + w_0) - 1 + \xi_i) - \sum_{i=1}^N r_i \xi_i$$
$$\frac{\partial L}{\partial w} = 0 \quad \Rightarrow \quad w = \sum_{i=1}^N \alpha_i y_i x_i$$

i.e. the solution is a **linear combination** of the training objects.

$$\frac{\partial L}{\partial w_0} = 0 \quad \Rightarrow \quad \sum_{i=1}^N \alpha_i y_i = 0$$

i.e. the combination coefficients need to be **balanced** between classes.

$$\frac{\partial L}{\partial \xi_i} = 0 \quad \Rightarrow \quad C - \alpha_i - r_i = 0$$

Dual problem

Substituting these into the Lagrangian:

$$w = \sum_{i=1}^N \alpha_i y_i x_i, \quad \sum_{i=1}^N \alpha_i y_i = 0, \quad C - \alpha_i - r_i = 0$$

we obtain the **dual problem**:

$$\sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j x_i^T x_j \rightarrow \max_{\alpha}$$

subject to:

$$\sum_{i=1}^N \alpha_i y_i = 0, \quad 0 \leq \alpha_i \leq C$$

Support vectors

Due to these KKT conditions:

$$\alpha_i(y_i(w^T x_i + w_0) - 1 + \xi_i) = 0, \quad r_i \xi_i = 0$$

there are the following options for the training objects:

Support vectors

Due to these KKT conditions:

$$\alpha_i(y_i(w^T x_i + w_0) - 1 + \xi_i) = 0, \quad r_i \xi_i = 0$$

there are the following options for the training objects:

$$y_i(w^T x_i + w_0) > 1 \Rightarrow \alpha_i = 0 \quad \textbf{(non-informative vector)}$$

Support vectors

Due to these KKT conditions:

$$\alpha_i(y_i(w^T x_i + w_0) - 1 + \xi_i) = 0, \quad r_i \xi_i = 0$$

there are the following options for the training objects:

$$y_i(w^T x_i + w_0) > 1 \Rightarrow \alpha_i = 0 \quad \textbf{(non-informative vector)}$$

$$y_i(w^T x_i + w_0) < 1 \Rightarrow \xi_i > 0, r_i = 0, \alpha_i = C \quad \textbf{(non-boundary support vector)}$$

Support vectors

Due to these KKT conditions:

$$\alpha_i(y_i(w^T x_i + w_0) - 1 + \xi_i) = 0, \quad r_i \xi_i = 0$$

there are the following options for the training objects:

$$y_i(w^T x_i + w_0) > 1 \Rightarrow \alpha_i = 0 \quad \textbf{(non-informative vector)}$$

$$y_i(w^T x_i + w_0) < 1 \Rightarrow \xi_i > 0, r_i = 0, \alpha_i = C \quad \textbf{(non-boundary support vector)}$$

$$y_i(w^T x_i + w_0) = 1 \Rightarrow \xi_i = 0, \alpha_i \in [0, C] \quad \textbf{(boundary support vector)}$$

Whole pipeline:


Solve the dual problem to find the optimal α^*

$$\sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j x_i^T x_j \rightarrow \max_{\alpha}$$
$$\sum_{i=1}^N \alpha_i y_i = 0, \quad 0 \leq \alpha_i \leq C$$

Make predictions for new data:

$$\hat{y} = \text{sign} \left(\sum_{i \in \text{SV}} \alpha_i^* y_i x_i^T x + w_0 \right)$$

Can be obtained from e.g. boundary support vectors from: $y_i(w^T x_i + w_0) = 1$



Kernel trick



Whole pipeline:

Note that the dual problem and prediction depend on the data only through **scalar products**:

$$\sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j \mathbf{x}_i^T \mathbf{x}_j \rightarrow \max_{\alpha}$$

$$\sum_{i=1}^N \alpha_i y_i = 0, \quad 0 \leq \alpha_i \leq C$$

$$\hat{y} = \text{sign} \left(\sum_{i \in SV} \alpha_i^* y_i \mathbf{x}_i^T \mathbf{x} + w_0 \right)$$

Feature expansion

Suppose we want to expand our features:

$$x_i \rightarrow \phi(x_i)$$

Then, our solution would only depend on the scalar products: $\phi^T(x_i)\phi(x_j)$.

Feature expansion

Suppose we want to expand our features:

$$x_i \rightarrow \phi(x_i)$$

Then, our solution would only depend on the scalar products: $\phi^T(x_i)\phi(x_j)$.

E.g. for the following polynomial expansion: $(x_1, x_2)_i \rightarrow \left(\frac{1}{2}, x_1, x_2, x_1^2, \sqrt{2}x_1x_2, x_2^2\right)_i$, the scalar product equals to:

$$\begin{aligned} \frac{1}{4} + x_{1i}x_{1j} + x_{2i}x_{2j} + (x_{1i}x_{1j})^2 + 2(x_{1i}x_{1j})(x_{2i}x_{2j}) + (x_{2i}x_{2j})^2 = \\ = \frac{1}{4} + x_i^T x_j + (x_i^T x_j)^2 = \left(x_i^T x_j + \frac{1}{2}\right)^2 \end{aligned}$$

Feature expansion

Suppose we want to expand our features:

$$x_i \rightarrow \phi(x_i)$$

Then, our solution would only depend on the scalar products: $\phi^T(x_i)\phi(x_j)$.

E.g. for the following polynomial expansion: $(x_1, x_2)_i \rightarrow \left(\frac{1}{2}, x_1, x_2, x_1^2, \sqrt{2}x_1x_2, x_2^2\right)_i$, the scalar product equals to:

$$\begin{aligned} \frac{1}{4} + x_{1i}x_{1j} + x_{2i}x_{2j} + (x_{1i}x_{1j})^2 + 2(x_{1i}x_{1j})(x_{2i}x_{2j}) + (x_{2i}x_{2j})^2 &= \\ = \frac{1}{4} + x_i^T x_j + (x_i^T x_j)^2 &= \left(x_i^T x_j + \frac{1}{2}\right)^2 \end{aligned}$$

So instead of doing the expansion we can replace all scalar products with:

$$x_i^T x_j \rightarrow K(x_i, x_j) = \left(x_i^T x_j + \frac{1}{2}\right)^2$$

RBF kernel

This trick allows for expansions that would normally be infeasible to compute, e.g. expansions to infinite dimension spaces.

Example: **Radial Basis Function** (RBF) kernel:

$$K(x_i, x_j) = e^{-\gamma \|x_i - x_j\|^2}$$

This kernel has maximum of 1 for $x_i = x_j$, and decays to 0 as the vectors become further apart. Hence, the solution averages the labels for nearby support vectors:

$$\hat{y} = \text{sign} \left(\sum_{i \in SV} \alpha_i^* y_i K(x_i, x) + w_0 \right)$$

Can any function be a kernel?

Note that the quadratic form of the dual problem is defined by the symmetric, positive semi-definite matrix XX^T :

$$\sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j \mathbf{x}_i^T \mathbf{x}_j \rightarrow \max_{\alpha}$$

In fact, kernel functions should also have these properties (Mercer theorem):

Symmetry:

$$K(x_i, x_j) = K(x_j, x_i)$$

For every set x_1, \dots, x_M the Gram matrix is positive semi-definite:

$$K(x_i, x_j) \equiv K_{ij} \quad - \text{p.s.d.}$$

Summary

SVM is a linear classification model. In the linearly separable case it maximizes the distance from the closest training points to the decision boundary

Summary

SVM is a linear classification model. In the linearly separable case it maximizes the distance from the closest training points to the decision boundary

For the inseparable case, it balances between:

- minimizing $\|w\|^2$, i.e. pushing the $w^T x_i + w_0 = \pm 1$ lines further away from the decision boundary
- maximizing the sum of margins for objects with $y_i(w^T x_i + w_0) < 1$ (through slack variables)

The balance is controlled by the constant C

Summary

SVM is a linear classification model. In the linearly separable case it maximizes the distance from the closest training points to the decision boundary

For the inseparable case, it balances between:

- minimizing $\|w\|^2$, i.e. pushing the $w^T x_i + w_0 = \pm 1$ lines further away from the decision boundary
- maximizing the sum of margins for objects with $y_i(w^T x_i + w_0) < 1$ (through slack variables)

The balance is controlled by the constant C

Solution only depends on the support vectors

- Not robust to outliers as they always become support vectors

Summary

SVM is a linear classification model. In the linearly separable case it maximizes the distance from the closest training points to the decision boundary

For the inseparable case, it balances between:

- minimizing $\|w\|^2$, i.e. pushing the $w^T x_i + w_0 = \pm 1$ lines further away from the decision boundary
- maximizing the sum of margins for objects with $y_i(w^T x_i + w_0) < 1$ (through slack variables)

The balance is controlled by the constant C

Solution only depends on the support vectors

- Not robust to outliers as they always become support vectors

Kernel trick allows to expand features by just redefining the scalar product in the original feature space (i.e. almost no computational overhead)

- This allows for infinite dimension representations
- Can define kernels (similarity measures) for complex objects like strings, sets, graphs, etc.

Thank you!

Majid Sohrabi



msohrabi@hse.ru