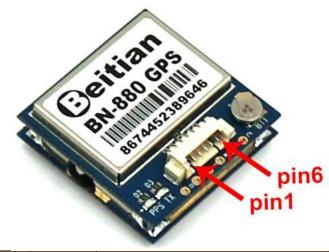


Any question about product, bulk order, free sample or cooperation, please email sales@diymalls.com

Features =

litem	Description					
	Chipset	M8030-KT				
Electrical	Frequency	GPS L1, GLONASS L1, BDS B1, GALILEO E1,				
Characteristics	1 3	SBAS L1, QZSS L1				
	Receiving Format	GPS, GLONASS, BDS, GALILEO, SBAS, QZSS. Default GPS, GLONASS, SBAS, QZSS.				
	Channels	72 Searching Channel				
	Tracking	-167dBm				
Sensitivity	Reacquisition	-160dBm				
	Cold Start	-148dBm				
	Hot Start	-156dBm				
Accuracy	Position Horizontal	2.0 m CEP 2D RMS SBAS Enable (Typical Open Sky)				
	Velocity	0.1m/sec 95% (SA off)				
	Timing	1us synchronized to GPS time				
A Time	Cold Start	26s				
Acquisition Time	Warm Start	25s				
	Hot Start	1s				
	Support Rate	4800bps to 921600bps, Default 9600bps				
Data Output	Data Level	TTL Level				
Data Output	Data Protocol	NMEA-0183				
	NMEA Message	RMC, VTG, GGA, GSA, GSV, GLL				
	Update Rate	1Hz-10Hz, Default 1Hz				
	FLASH	4M FLASH, Store the configuration permanently				
On anotic mal I invite	Altitude	<50,000m				
Operational Limits	Velocity	<515m/s				
	Acceleration	<4g				
Power Consumption	VCC	DC Voltage 3.6V-5.5V, Typical: 5.0V				
	Current	Capture 50mA/5.0V				
Mechanical	Dimension	28mm*28mm*10mm				
Specifications	Weight	12.0g				
	Connector	1.25mm 6pins connector				
Environment	Operating Temp	-40 °C ~ +85°C				
	Storage Temp	-40°C ~ +105°C				
LED	Built-in LED	TX LED: blue. The data output, TX LED flashing				
	Duit iii DDD	PPS LED: red. PPS LED not bright when GPS not fixed, flashing when fixed				
Compass	Compass	Built-in compass, With electronic compass IC HMC5883L				

Pin Description =



PIN	PIN Name	I/O	Description
1	SDA	О	Compass SDA
2	GND	G	Ground
3	TX	О	Serial Data Output.
4	RX	I	Serial Data input.
5	VCC	I	DC 3.6V~ 5.5V supply input, Typical: 5.0V
6	SCL	I	Compass SCL

LED =

- 1.TX LED:blue.The data output, TX LED flashing
- 2.PPS LED:red.PPS LED not bright when GPS not fixed, flashing when fixed.

Bottom view =

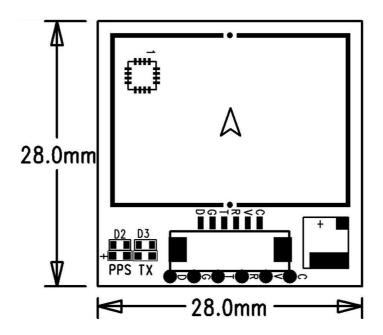


Compass Direction and Dimension:





28.0mm*28.0mm*10.0mm



NMEA message output sample =

\$GNRMC,073114.00,A,2237.56240,N,11401.59614,E,1.329,21.11,020916,,,A,V*37

\$GNVTG,21.11,T,,M,1.329,N,2.462,K,A*1B

\$GNGGA,073114.00,2237.56240,N,11401.59614,E,1,12,0.78,112.9,M,-2.5,M,,*54

\$GNGSA,A,3,19,05,02,06,17,12,09,13,,,,1.48,0.78,1.26,1*01

\$GNGSA,A,3,69,83,84,70,68,82,,,,,,1.48,0.78,1.26,2*0E

\$GPGSV,4,1,13,02,46,340,36,05,52,254,37,06,42,041,41,09,22,053,40,0*6E

\$GPGSV,4,2,13,12,32,282,35,13,13,185,33,17,36,131,37,19,57,119,44,0*66

\$GPGSV,4,3,13,20,03,237,,23,00,038,,25,09,311,19,42,51,128,32,0*60

\$GPGSV,4,4,13,50,46,123,33,0*50

\$GLGSV,2,1,08,68,25,027,39,69,78,011,36,70,40,213,43,74,00,259,,0*78

\$GLGSV,2,2,08,82,06,124,36,83,46,085,44,84,44,358,41,85,05,324,14,0*74

\$GNGLL,2237.56240,N,11401.59614,E,073114.00,A,A*7C

NMEA Message Talker IDs:

Configured GNS	Talker ID
GPS, SBAS, QZSS	GP
GLONASS	GL
GALILEO	GA
BEIDOU	GB
Any combination of GNSS	GN

NMEA Message Structure:

\$xxGGA,time,lat,NS,long,EW,quality,numSV,HDOP,alt,M,sep,M,diffAge,diffStation*cs<CR><LF>Example:

\$GPGGA,092725.00,4717.11399,N,00833.91590,E,1,08,1.01,499.6,M,48.0,M,,*5B

Field No	Name	Unit	Format	Example	Description
0	100CA		-1.2	\$GPGGA	GGA Message ID (xx = current Talker
0	xxGGA	-	string	T T T T T T T T T T T T T T T T T T T	ID)
1	time	-	hhmmss.ss	092725.00	UTC time
2	lat	-	ddmm.mmmmm	4717.11399	Latitude (degrees & minutes)
3	NS	-	character	N	North/South indicator
4	long	-	dddmm.mmmmm	00833.91590	Longitude (degrees & minutes)
5	EW	-	character	Е	East/West indicator
		uality -	digit	1	0:No Fix / Invalid
6	au ality				1:Standard GPS (2D/3D)
0	quality				2:Differential GPS
					6:Estimated (DR) Fix
7	numSV	-	numeric	08	Number of satellites used
8	HDOP	-	numeric	1.01	Horizontal Dilution of Precision
9	alt	m	numeric	499.6	Altitude above mean sea level
10	uAlt	-	character	М	Altitude units: meters (fixed field)
11	sep	m	numeric	48.0	Geoid separation: difference between

					geoid and mean sea level
12	uSep	-	character	M	Separation units: meters (fixed field)
40 4:44		numorio		Age of differential corrections (blank	
13	13 diffAge s	S	numeric	-	when DGPS is not used)
					ID of station providing differential
14	diffStation	-	numeric	-	corrections (blank when DGPS is not
					used)
15	CS	-	hexadecimal	*5B	Checksum
16	<cr><lf></lf></cr>	-	character	-	Carriage return and line feed

Message Structure:

\$xxGLL,lat,NS,long,EW,time,status,posMode*cs<CR><LF>

Example:

\$GPGLL.4717.11364.N.00833.91565.E.092321.00.A.A*6

Field No	Name	Unit	Format	Example	Description
0	xxGLL	-	string	\$GPGLL	GLL Message ID (xx = current Talker ID)
1	lat	-	ddmm.mmmmm	4717.11364	Latitude (degrees & minutes)
2	NS	-	character	N	North/South indicator
3	long	-	dddmm.mmmmm	00833.91565	Longitude (degrees & minutes)
4	EW	-	character	E	East/West indicator
5	time	-	hhmmss.ss	092321.00	UTC time
6	status	_	character	٨	V = Data invalid or receiver warning, A =
O	Status	-	Character	Α	Data valid
7	posMode	-	character	Α	Positioning mode
8	cs	-	hexadecimal	*60	Checksum
9	<cr><lf></lf></cr>	-	character	-	Carriage return and line feed

Message Structure:

 $$xxGSA,opMode,navMode\{,sv\},PDOP,HDOP,VDOP,systemId*cs<CR><LF>$

Example:

\$GPGSA,A,3,23,29,07,08,09,18,26,28,,,,,1.94,1.18,1.54,1*0D

Field No	Name	Unit	Format	Example	Description		
0	xxGSA	-	string	\$GPGSA	GSA Message ID (xx = current Talker ID)		
					Operation mode		
					M:Manually set to operate in 2D or 3D		
1	opMode	-	character	Α	mode		
					A:Automatically switching between 2D		
					or 3D mode		
			digit	3	Navigation mode		
2	navMode				1:Fix not available		
2	Havivioue	-			2:2D Fix		
					3:3D Fix		
Start of re	Start of repeated block (12 times)						
3 +	21/		numeric	20	Catallita number		
1*N	SV	-		29	Satellite number		

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End of re	End of repeated block						
15	PDOP	-	numeric	1.94	Position dilution of precision		
16	HDOP	-	numeric	1.18	Horizontal dilution of precision		
17	VDOP	-	numeric	1.54	Vertical dilution of precision		
18	systemId	4		4	NMEA defined GNSS System ID		
10	systemia	-	numeric	I	NMEA v4.1 and above only		
19	cs	-	hexadecimal	*0D	Checksum		
20	<cr><lf></lf></cr>	-	character	-	Carriage return and line feed		

Message Structure:

\$xxGSV,numMsg,msgNum,numSV,{,sv,elv,az,cno},signalId*cs<CR><LF>

Example:

\$GPGSV,3,1,10,23,38,230,44,29,71,156,47,07,29,116,41,08,09,081,36,0*7F

\$GPGSV,3,2,10,10,07,189,,05,05,220,,09,34,274,42,18,25,309,44,0*72

\$GPGSV,3,3,10,26,82,187,47,28,43,056,46,0*7

Field No	Name	Unit	Format	Example	Description
0	xxGSV	-	string	\$GPGSV	GSV Message ID (xx = GSV Talker ID)
1	numMsg		digit	3	Number of messages, total number of
1	Hullivisg	-	digit	3	GSV messages being output
2	msgNum	-	digit	1	Number of this message
3	numSV	-	numeric	10	Number of satellites in view
Start of re	epeated block	(14 tim	nes)		
4 +	SV		numeric	23	Satellite ID
4*N	SV	-	numenc	23	Satellite ID
5 +	elv	doa	numeric	38	Elevation (range 0-90)
4*N	elv deg	ueg	numeric 3	30	Lievation (range 0-90)
6 +	az	deg	numeric	230	Azimuth, (range 0-359)
4*N	az	ueg	Hameno	230	Azimutii, (range 0-359)
7 +	cno	dBH	numeric	44	Signal strength (C/N0, range 0-99),
4*N	GIIO	ubii	Hameno	77	blank when not tracking
End of rep	peated block				
5	signalld		numeric	0	NMEA defined GNSS Signal ID (0 = All
16	Signaliu	-	Humenc	U	signals) NMEA v4.1 and above only
6	00		hexadecimal	*7F	Checksum
16	CS	-	пехачесниа	<i>1</i> F	CHECKSUIII
7	<cr><lf></lf></cr>	_	character		Carriage return and line feed
16	\UN/\LI'/	_	Gialactei	-	Carriage return and line leed

Message Structure:

\$xxRMC,time,status,lat,NS,long,EW,spd,cog,date,mv,mvEW,posMode,navStatus*cs<CR><LF>Example:

\$GPRMC,083559.00,A,4717.11437,N,00833.91522,E,0.004,77.52,091202,,,A,V*57

Field No	Name	Unit	Format	Example	Description
0 xxRMC	1C ota	string	¢CDDMC	RMC Message ID (xx = current Talker	
U	XXINIU	_	Sumg	\$GPRMC	ID)

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BN-880 GNSS Module + Compass Datasneet						
1	time	_	hhmmss.ss	083559.00	UTC time, see note on UTC	
'	unic		1111111133.33	000000.00	representation	
					Status	
2	status	_	character	Α	V:Navigation receiver warning	
2	Status	-	Character	^	A :Data valid, see position fix flags	
					description	
3	lat	_	ddmm.mmmmm	4717.11437	Latitude (degrees & minutes), see	
3	lat	-	dullilli.llillillillillilli	47 17.11437	format description	
4	NS	-	character	N	North/South indicator	
5	long		dddmm.mmmmm	00833.91522	Longitude (degrees & minutes), see	
5	long	-	addillii.iiiiiiiiiiiiiiiiiiiiiiiiiiiiiii	00033.91322	format description	
6	EW	-	character	E	East/West indicator	
7	spd	Kno s	numeric	0.004	Speed over ground	
8	cog	degr	numeric	77.52	Course over ground	
0	dete			004202	Date in day, month, year format, see	
9	date	-	ddmmyy	091202	note on UTC representation	
10	m.,	degr	numeric	-	Magnetic variation value (blank - not	
10	mv	ees			supported)	
11	mvEW		character		Magnetic variation E/W indicator (blank -	
11	IIIVEVV	-	Character	-	not supported)	
12	posMode	-	character	-	Mode Indicator, see position fix flags	
					Navigational status indicator (V =	
13	navStatus	-	character	V	Equipment is not providing navigational	
					status information)	
14	cs	-	hexadecimal	*57	Checksum	
15	<cr><lf></lf></cr>	-	character	-	Carriage return and line feed	

Message Structure:

xxVTG, cogt, T, cogm, M, knots, N, kph, K, posMode*cs < CR > < LF >

Example:

\$GPVTG,77.52,T,,M,0.004,N,0.008,K,A*06

Field No	Name	Unit	Format	Example	Description
0	xxVTG	-	string	\$GPVTG	VTG Message ID (xx = current Talker ID)
1	cogt	degrees	numeric	77.52	Course over ground (true)
2	Т	-	character	Т	Fixed field: true
3	cogm	degrees	numeric	-	Course over ground (magnetic), not output
4	М	-	character	M	Fixed field: magnetic
5	knots	knots	numeric	0.004	Speed over ground
6	N	-	character	N	Fixed field: knots
7	kph	km/	numeric	0.008	Speed over ground
8	K	-	character	K	Fixed field: kilometers per hour
9	posMode		character	Λ	Mode Indicator, see position fix flags
9	posivioue	-	Cilaracter	Α	description
10	cs	-	hexadecimal	*06	Checksum

8

					1
11	<cr><lf></lf></cr>	_	character	_	Carriage return and line feed
