

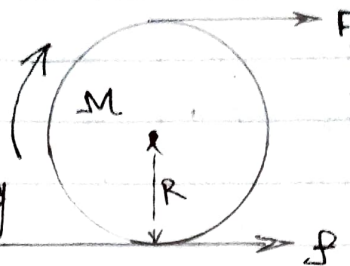
Accelerated Pure Rolling :

Linear velocity = v

Angular velocity = ω

Condition for pure rolling

$$v = R\omega$$



$$\frac{dv}{dt} = R \frac{d\omega}{dt} \quad \text{or} \quad a = R\alpha$$

Linear Acceleration = $R \times$ angular acceleration.

- If $a = R\alpha$, then frictional force $f = 0$.
- If $a < R\alpha$, f will act in forward direction
- If $a > R\alpha$, f will act in the backward direction.

From figure

$$a = \frac{F_{\text{net}}}{M} = \frac{F + f}{M}$$

$$\alpha = \frac{\tau_c}{I} = \frac{(F - f)R}{I}$$

For pure rolling $a = R\alpha$.

$$\frac{F + f}{M} = \frac{(F - f)R^2}{I}$$

$$\Rightarrow IF + If = MR^2 F - MR^2 f$$

$$\Rightarrow f(I + MR^2) = (MR^2 - I)F$$

$$\boxed{f = \left(\frac{MR^2 - I}{MR^2 + I} \right) F}$$

(i) If $I = MR^2$ then $f = 0$

(ii) If $I < MR^2$ $\therefore f$ is positive, f is in forward direction.

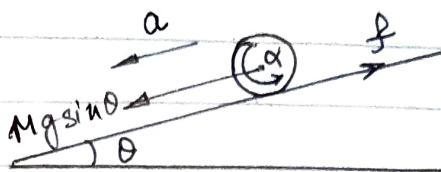
(iii) If $I > MR^2$ f is in backward direction.

Although $I > MR^2$ not possible
So the force of friction is either
in the forward direction or zero.

Rolling on rough inclined plane

$$a = \frac{Mg \sin \theta - f}{M}$$

$$\alpha = \frac{\tau}{I} = \frac{fR}{I}$$



For pure rolling

$$a = R\alpha$$

$$\frac{Mg \sin \theta - f}{M} = \frac{fR^2}{I}$$

$$\Rightarrow IMg \sin \theta - If = MfR^2$$

$$\Rightarrow f(I + MR^2) = IMg \sin \theta$$

$$f = \frac{IMg \sin \theta}{(I + MR^2)} = \frac{Mg \sin \theta}{(1 + \frac{MR^2}{I})}$$

$$a = \frac{Mg \sin \theta - f}{M} = g \sin \theta - \frac{f}{M}$$

$$a = g \sin \theta - \frac{Mg \sin \theta}{(1 + \frac{MR^2}{I})M}$$

$$= g \sin \theta \left[1 - \frac{1}{1 + \frac{MR^2}{I}} \right]$$

$$= g \sin \theta \left[1 - \frac{I}{I + MR^2} \right]$$

$$= g \sin \theta \left[\frac{MR^2}{I + MR^2} \right]$$

$$a = \frac{g \sin \theta}{\left[1 + \frac{I}{MR^2} \right]}$$

Solid sphere, hollow sphere, cylinder.

$$I_{\text{sphere}} = \frac{2}{5} MR^2$$

$$I_{\text{hollow}} = \frac{2}{3} MR^2$$

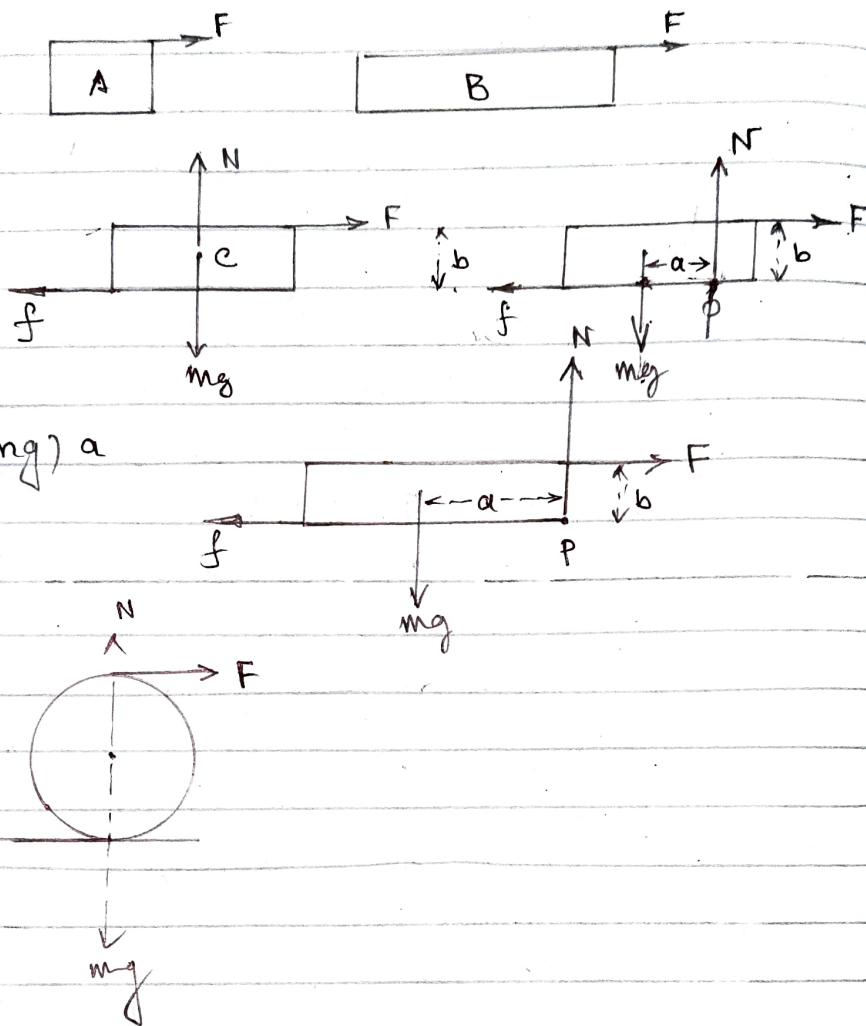
$$I_{\text{cyl}} = \frac{1}{2} MR^2$$

Angular Impulse :

$$\vec{\tau} = \frac{d\vec{L}}{dt} \quad \therefore \vec{\tau} \cdot dt = d\vec{L}$$

$$\int_{t_1}^{t_2} \vec{\tau} dt = \text{Angular impulse} = d\vec{L} = \vec{L}_2 - \vec{L}_1$$

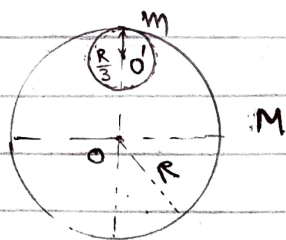
Toppling of a body



$$Fb = (mg)a$$

Numericals

- Find the M.I of the remaining disc about an axis perpendicular to the plane of the disc passing through O .



Let $\sigma \rightarrow$ Mass per unit area.

$$m = \pi \left(\frac{R}{3}\right)^2 \sigma$$

$$\frac{m}{M} = \frac{1}{9}$$

$$\therefore M = 9m$$

$$M = \pi R^2 \sigma$$

$$\begin{aligned} \text{M.I of the small disc about } O' &= \frac{1}{2} m \left(\frac{R}{3}\right)^2 \\ &= \frac{1}{2} m \frac{R^2}{9} \end{aligned}$$

$$\text{M.I of the small disc about } O = \frac{1}{2} m \frac{R^2}{9} + m \left(\frac{2R}{3}\right)^2$$

$$\therefore \frac{1}{2} \frac{M}{9} R^2 = \frac{1}{18} MR^2$$

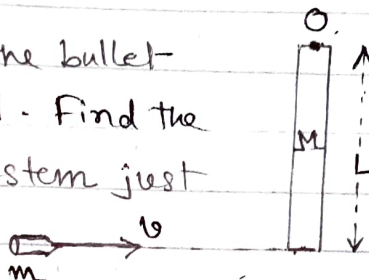
$$\begin{aligned} &= \frac{1}{9} \frac{1}{2} MR^2 + \frac{1}{9} 4MR^2 \\ &= \frac{1}{18} MR^2 + \frac{4}{9} MR^2 \\ &= \frac{1}{2} MR^2 \end{aligned}$$

\therefore M.I of the full disc about O = $\frac{1}{2}MR^2$

\therefore M.I of the remaining portion = $\left(\frac{1}{2}MR^2 - \frac{1}{18}MR^2\right)$
 $= \frac{MR^2}{2} \left[1 - \frac{1}{9}\right]$
 $= \frac{4MR^2}{9}$

Problem 2

After the strike, the bullet gets embedded in the rod. Find the angular velocity of the system just after the impact.



Before impact initial angular momentum
 $L_i = m v L$

After impact final angular momentum.

$$L_f = I \omega$$

But $I = I_{\text{bullet}} + I_{\text{rod}}$

$$= m L^2 + \frac{1}{3} M L^2$$

$$= \frac{M+3m}{3} L^2$$

\therefore By Conservation of angular momentum

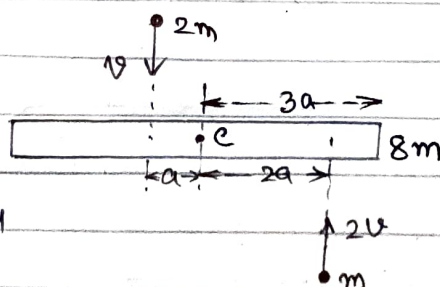
$$L_i = L_f$$

$$m v L = \left(\frac{M+3m}{3} L^2\right) \omega$$

$$\omega = \frac{3 m v L}{L^2 (M+3m)} = \frac{3 m v}{(M+3m) L}$$

Problem 3

After collision m and 2m stick to the rod.



Determine (i) velocity of COM

(ii) ω about COM

(iii) Total Kinetic energy just after the collision

By Conservation of linear momentum

$$2mv - 2mv + 8m \times 0 = (8m + m + 2m) v_c$$

$$v_c = 0$$

Initial angular momentum $L_i = 2m(v)(a) + 2m(v)(2a)$
 $= 6mva$

Final angular momentum $L_f = I_{\text{total}} \omega$

$$\begin{aligned}
 I_{\text{total}} &= 2ma^2 + m(2a)^2 + 8m \frac{(6a)^2}{12} \\
 &= 2ma^2 + 4ma^2 + 24ma^2 \\
 &= 30ma^2
 \end{aligned}$$

$$\therefore L_f = 30ma^2 \omega$$

\therefore By conservation of angular momentum
 $L_i = L_f$

$$6mva = 3ma^2 \omega$$

$$\omega = \frac{6mva}{3ma^2} = \frac{v}{5a}$$

Total Kinetic energy $E_k = \frac{1}{2} I_{\text{total}} \omega^2$

$$\begin{aligned}
 &= \frac{1}{2} (30ma^2) \omega^2 \\
 &= 15ma^2 \cdot \frac{v^2}{25a^2} \\
 E_k &= \frac{3}{5} mv^2
 \end{aligned}$$