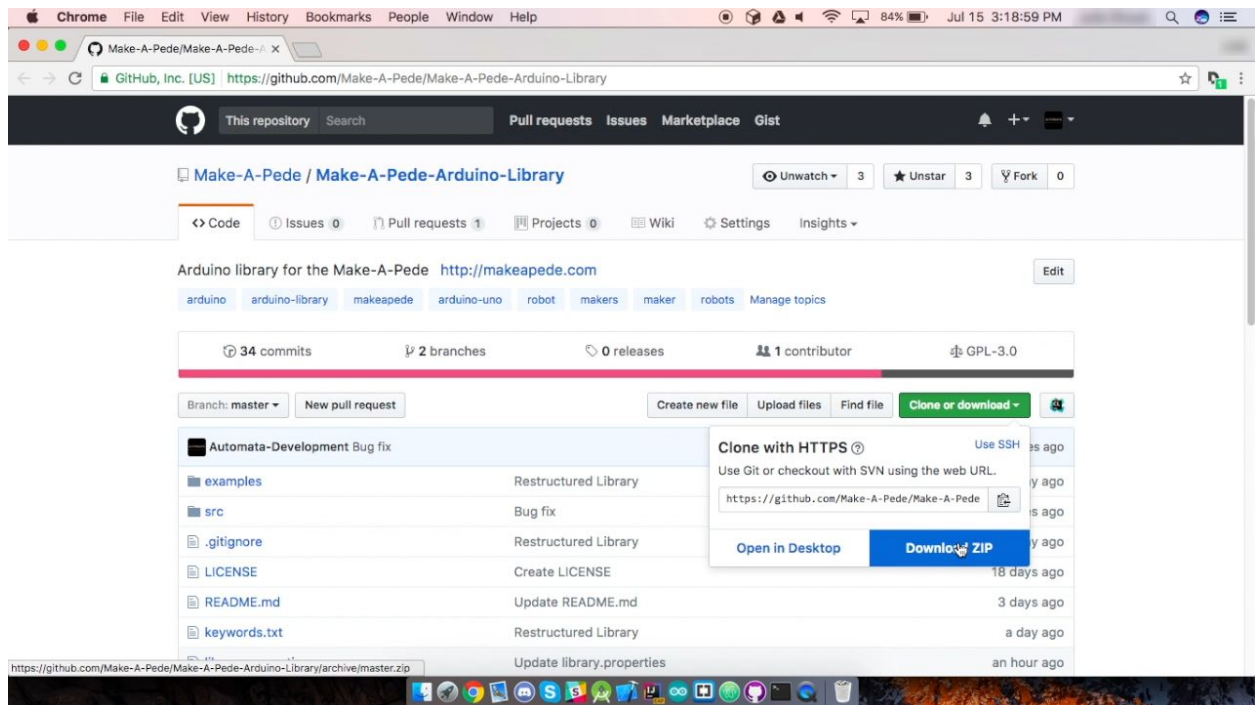


# Installing Make-A-Pede Library and Loading the Remote Control Program

**Step 1:** Download the library from the Github repository

(<https://github.com/Make-A-Pede/Make-A-Pede-Arduino-Library>) by clicking Clone or Download → Download ZIP.

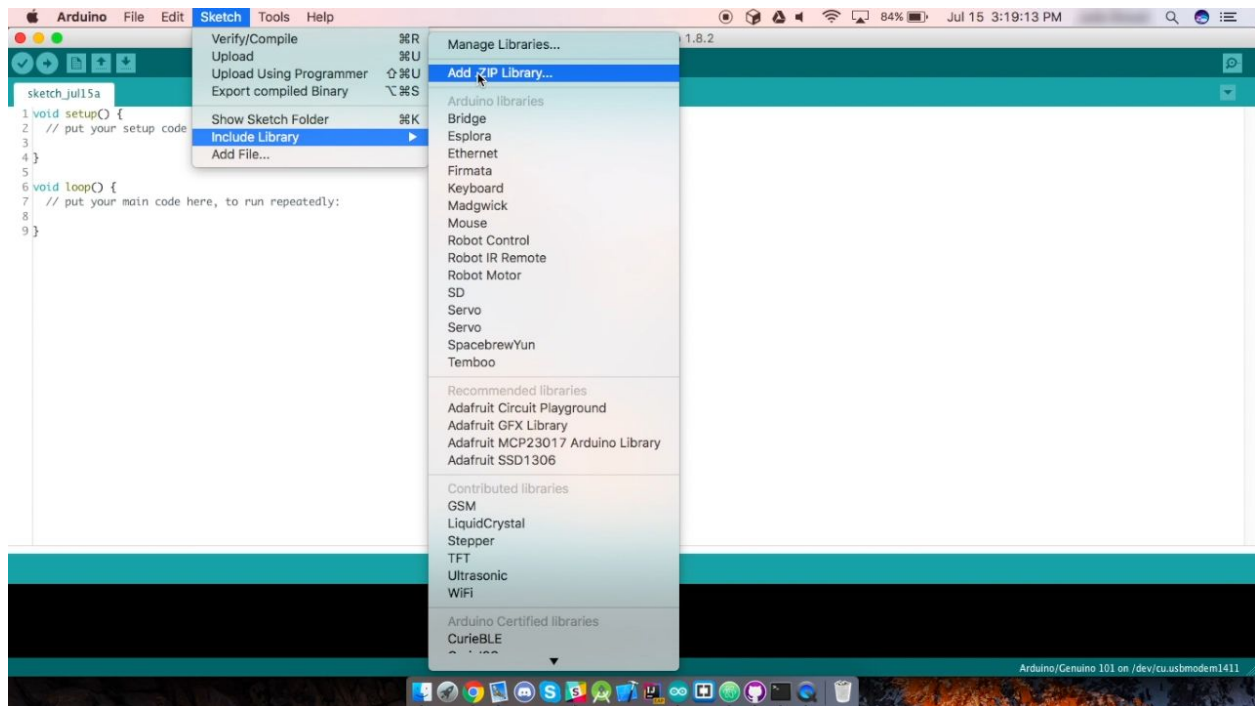


**Step 2:** Install and open the Arduino IDE. Add the library by clicking Sketch → Include Library → Add .ZIP library and selecting the .ZIP file downloaded in step 1.

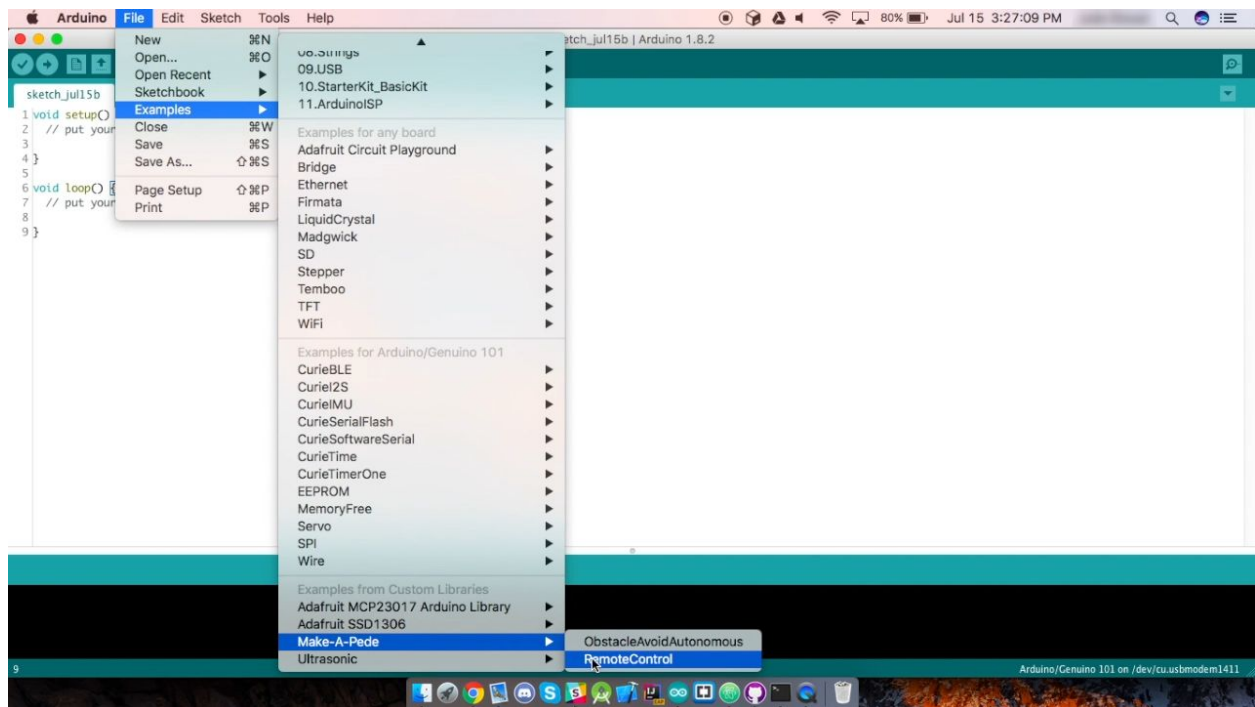
Arduino IDE Installation Instructions:

<https://www.arduino.cc/en/Guide/Windows>

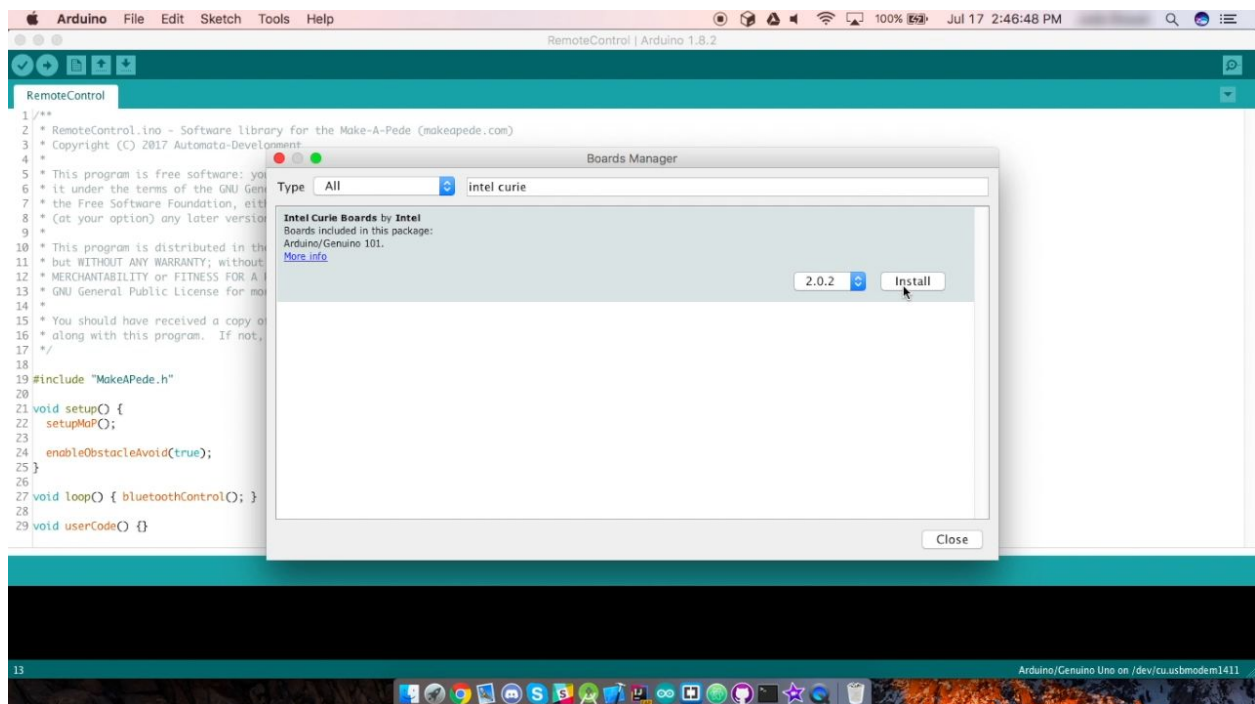
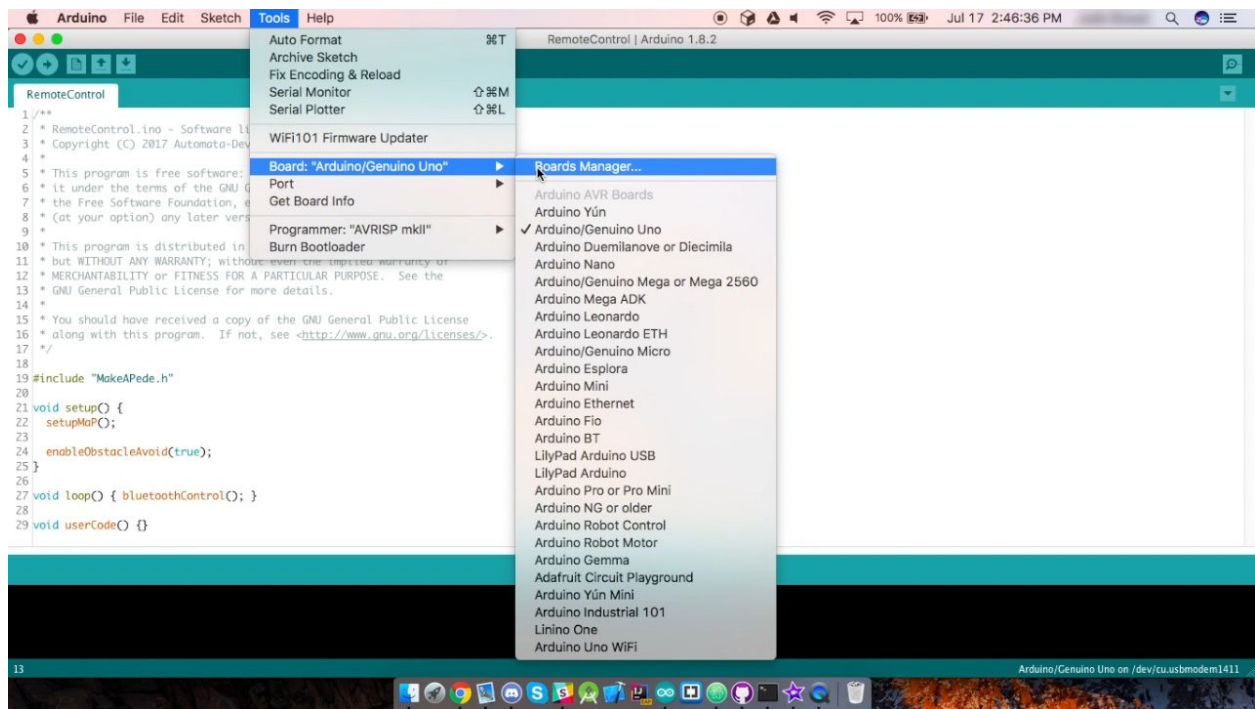
<https://www.arduino.cc/en/Guide/MacOSX>



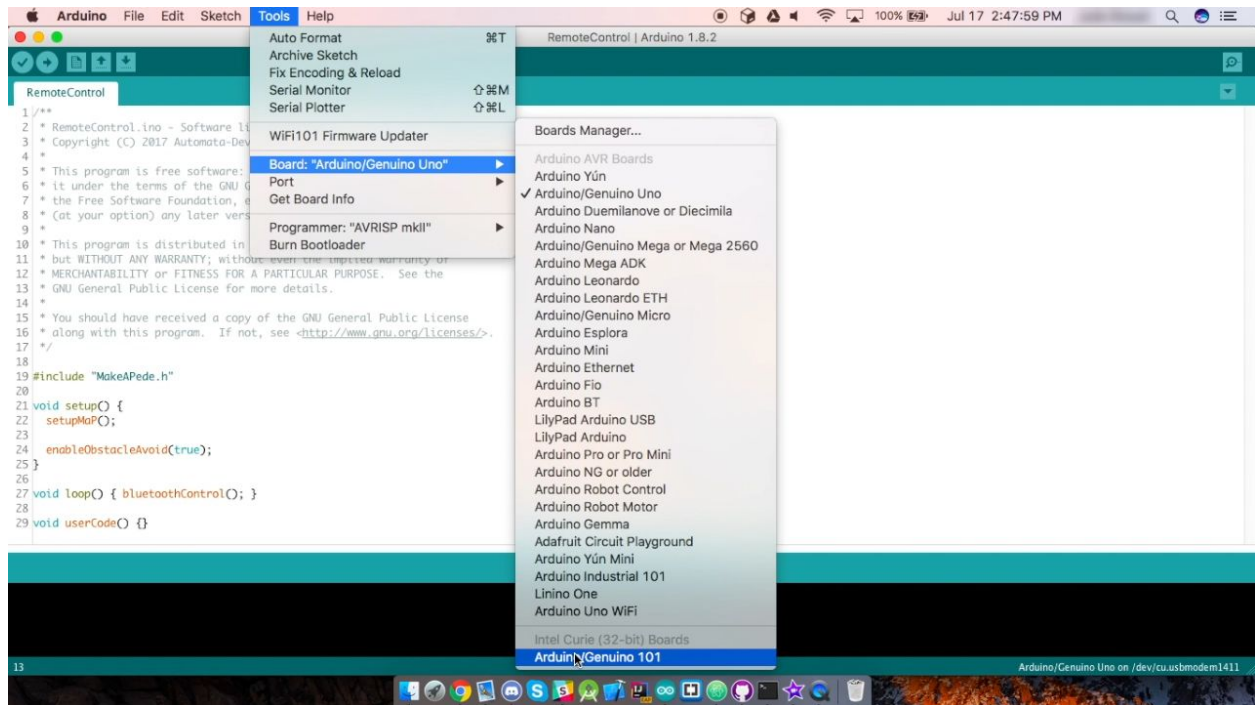
**Step 3:** Open the RemoteControl example program by clicking File → Examples → Make-A-Pede → RemoteControl.



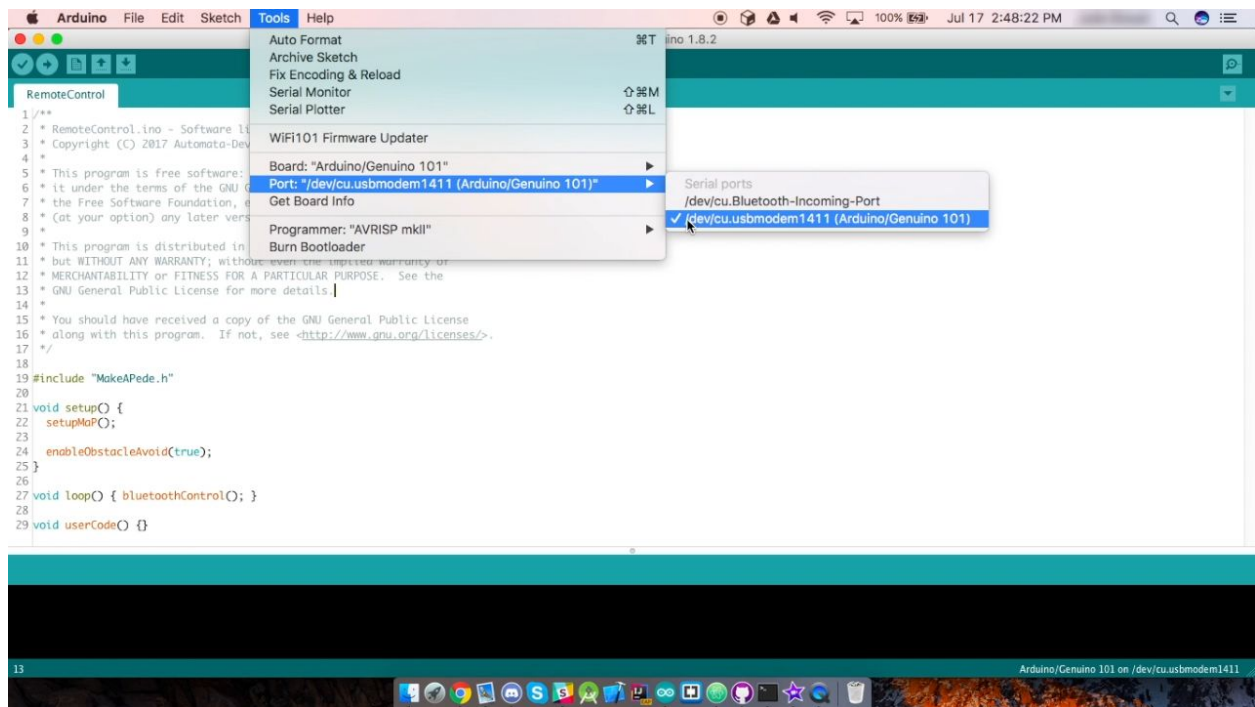
**Step 4:** Before downloading the program to the Arduino 101, the Intel Curie boards package must be installed. To install this, click Tools → Board → Boards Manager and search for “Intel Curie”. Select the package and install it.



**Step 5:** Select “Arduino/Genuino 101” from the Tools → Board menu.



**Step 6:** Connect the robot to your computer using the download cable provided and select the port the robot is connected to in the Tools → Port menu.



## Step 7: Upload the program to your robot.

