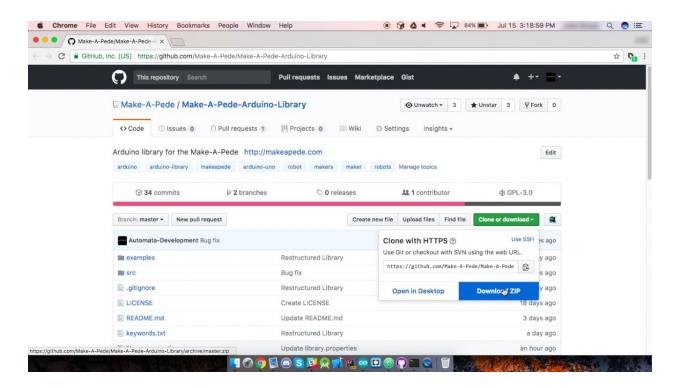
Installing Make-A-Pede Library and Loading the Remote Control Program

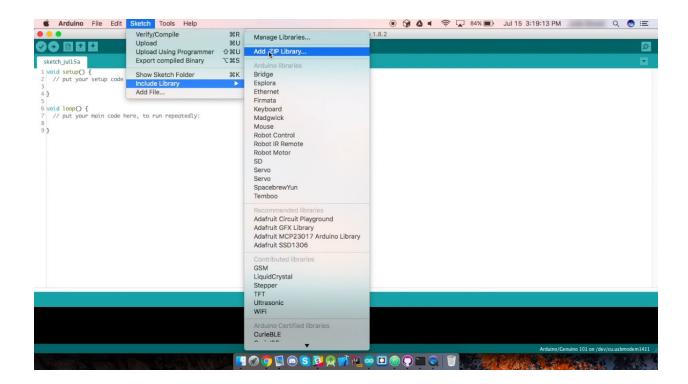
Step 1: Download the library from the Github repository (https://github.com/Make-A-Pede/Make-A-Pede-Arduino-Library) by clicking Clone or Download → Download ZIP.



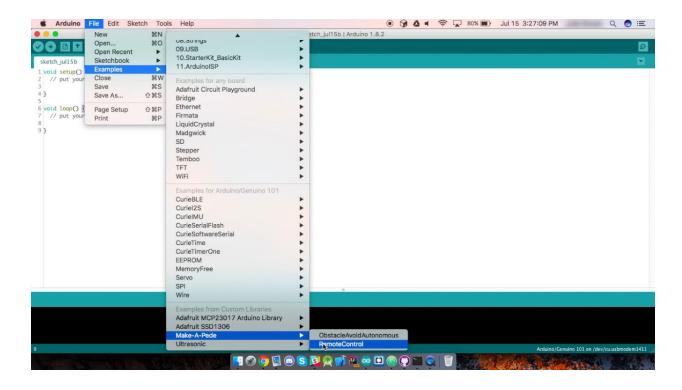
Step 2: Install and open the Arduino IDE. Add the library by clicking Sketch \rightarrow Include Library \rightarrow Add .ZIP library and selecting the .ZIP file downloaded in step 1.

Arduino IDE Installation Instructions:

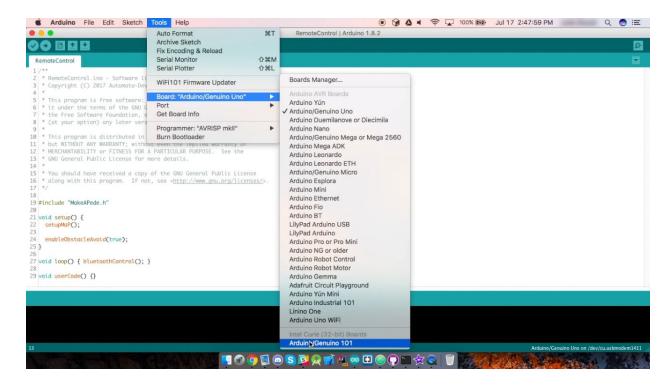
https://www.arduino.cc/en/Guide/Windowshttps://www.arduino.cc/en/Guide/MacOSX



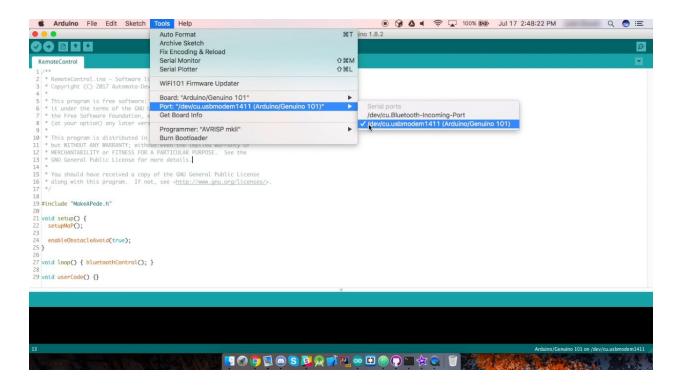
Step 3: Open the RemoteControl example program by clicking File \rightarrow Examples \rightarrow Make-A-Pede \rightarrow RemoteControl.



Step 4: Select "Arduino/Genuino Uno" from the Tools \rightarrow Board menu.



Step 5: Connect the robot to your computer using the download cable provided and select the port the robot is connected to in the Tools \rightarrow Port menu.



Step 6: Upload the program to your robot.

