



<pre> +-----+ Data Acquisition/Generation +-----+ Data Preparation +-----+ Feature Extraction and Visual Mapping +-----+ Rendering Analysis +-----+ Image and Animation +-----+ </pre>	<ul style="list-style-type: none"> Parametric coordinate of P: $\alpha = a / (a+b)$ Linearly interpolated value of P: $V_p = (1-\alpha) * V_1 + \alpha * V_2$ 	<h3>Lerp in Triangle</h3> <ul style="list-style-type: none"> Parametric coordinates of P: (α, β, γ) $\alpha = \delta A / (\delta A + \delta B + \delta C)$ $\beta = \delta B / (\delta A + \delta B + \delta C)$ $\gamma = \delta C / (\delta A + \delta B + \delta C)$ Linearly interpolated value of P: $V_p = V_A * \alpha + V_B * \beta + V_C * \gamma$ 	<h3>Lerp in Rectangle</h3> <ul style="list-style-type: none"> Parametric coordinates of P: (α, β) $\alpha = a / \text{width}$; $\beta = b / \text{height}$ Bi-linear interpolation: $V_p = \text{Bi-Lerp}(V_A, V_B, V_C, V_D, \alpha, \beta)$ Linearly interpolated value of P: $\text{Lerp}(V_{L1}, V_{L2}, \beta)$
<h3>Lerp in Cube</h3> <p>Another way to perform calculate the value at P:</p> <ul style="list-style-type: none"> Parametric coordinates of P: (α, β, γ) $\alpha = a / \text{width}$; $\beta = b / \text{depth (along y)}$; $\gamma = c / \text{height}$ Value at P = $(1-\alpha)(1-\beta)(1-\gamma)V_0 + \alpha(1-\beta)(1-\gamma)V_1 + (1-\alpha)\beta(1-\gamma)V_2 + \alpha\beta(1-\gamma)V_3 + (1-\alpha)(1-\beta)\gamma V_4 + \alpha(1-\beta)\gamma V_5 + (1-\alpha)\beta\gamma V_6 + \alpha\beta\gamma V_7$ Linearly interpolated value of P: $V_p = V_A * \alpha + V_B * \beta + V_C * \gamma + V_D * \delta$ 	<h3>Lerp in Tetrahedron</h3> <ul style="list-style-type: none"> Tetrahedral coordinates of P: $(\alpha, \beta, \gamma, \delta)$ $\alpha = V_{BDCP} / V_{ABCD}$ $\beta = V_{ACDP} / V_{ABCD}$ $\gamma = V_{ADBP} / V_{ABCD}$ $\delta = V_{ABCP} / V_{ABCD}$ Linearly interpolated value of P: $V_p = V_A * \alpha + V_B * \beta + V_C * \gamma + V_D * \delta$ 	<h3>Volume of Tetrahedron</h3> $V = \frac{1}{6} \det \begin{bmatrix} 1 & 1 & 1 & 1 \\ x_1 & x_2 & x_3 & x_4 \\ y_1 & y_2 & y_3 & y_4 \\ z_1 & z_2 & z_3 & z_4 \end{bmatrix} = \frac{1}{6} \det(J) = \frac{1}{6} J.$ <p>V will be positive if when you look at the triangle 123 from vertex 4, vertex 1 2 3 are in a counter clockwise order</p>	<ul style="list-style-type: none"> The intersection point $f(p) = c$ on the edge can be computed by linear interpolation $\frac{d_1/d_2}{d_1+d_2} = \frac{(v_1-C)/(C-v_2)}{(v_1-C)/(v_1-v_2)} \Rightarrow \frac{(p-p_1)/(p_2-p_1)}{(p_2-p_1)/(v_1-v_2)} = \frac{(v_1-C)/(v_1-v_2)}{(v_1-C)/(v_1-v_2)}$ $p = (v_1-C)/(v_1-v_2) * (p_2-p_1) + p_1$
$I(D) = I_0 * e^{-\int_0^D \tau(t)dt} + \int_0^D g(s)e^{-\int_s^D \tau(t)dt} ds$ <p>I_0 : background light</p> <p>$\tau(t)$: extinction coefficient at t , related to the rate that light is occluded</p> <p>D : total distance light will travel</p> <p>$e^{-\int_0^D \tau(t)dt}$: transparency of medium between 0 and D</p> <p>$1 - e^{-\int_0^D \tau(t)dt} = \alpha$: opacity of medium between 0 and D</p> <p>$g(s)$: source term at point s, typically derived from the data value</p>	<h3>Back-to-Front Compositing</h3> <p>The initial pixel color = Black</p> <p>Back-to-Front compositing: use 'under' operator</p> <p>C = C1 'under' background C = C2 'under' C C = C3 'under' C ...</p> <p>$C_{out} = C_{in} * (1-\alpha(x)) + C(x)*\alpha(x)$ (this is the alpha blending formula)</p>	<h3>Front-to-Back Compositing</h3> <p>Front-to-Back compositing: use 'over' operator</p> <p>C = background 'over' C1 C = C 'over' C2 C = C 'over' C3 ...</p> <p>$C_{out} = C_{in} + C(x) \alpha(x) * (1-\alpha_{in})$ $\alpha_{in} = \alpha_{in} + \alpha(x) * (1-\alpha_{in})$</p>	<p>切線方向 丟一粒子流動軌跡</p> <p>丟n次一粒子，連起來</p> <p>丟一次N粒子，連起來</p>
<h3>Multi-Dimensional Transfer Functions</h3> <ul style="list-style-type: none"> 1D histogram can capture homogeneous region only <ul style="list-style-type: none"> A : air B : tissue C : bone 2D histogram can capture <ul style="list-style-type: none"> D : air and tissue boundary E : tissue and bone boundary F : air and bone boundary 	<h3>Type of flow lines:</h3> <ul style="list-style-type: none"> Streamline: a field line tangent to the velocity field at an instant in time Pathline: the trajectory of a massless particle released from a seed point over a period of time Streakline: a line joining the positions, at an instant in time, of particles released from a seed point Timeline: a line connecting a row of particle that are released simultaneously 		
$p_{k+1} = p_k + v(p_k) \times \Delta t$	$p^* = p_k + v(p_k) \Delta t$ $p_{k+1} = p_k + (v(p_k) + v(p^*)) \times \Delta t / 2$		
$a = 2\Delta t v(p_k),$ $b = 2\Delta t v(p_k+a/2),$ $c = 2\Delta t v(p_k+b/2),$ $d = 2\Delta t v(p_k+c/2),$			
$p_{k+1} = p_k + (a+2b+2c+d)/6$			