



RUN POSITION

INTERMEDIATE POSITION

REST POSITION

NOTE :

RUN POSITION : Arm rotates counter-clockwise once user flips switch SW1

INTERMEDIATE POSITION : Arm touches and flips SW1, the motor reverses direction, and arm starts moving clockwise

REST POSITION : When the lever in the arm opens SW2, the motor stops rotating and the Useless box is in it's rest position

If things don't work as expected, swap motor terminals and / or battery terminals

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Sheet: /		
File: useless_box.kicad_sch		
Title: USELESS BOX		
Size: A4	Date: 2022-11-28	Rev: rev 1
KiCad E.D.A. kicad 6.0.8-f2edbf62ab-116-ubuntu20.04.1		Id: 1/1