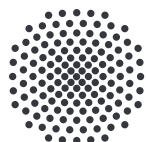


SIAM CSE25 - Fort Worth, TX, USA - March 5, 2025

Black-box coupling of simulation codes using preCICE

Gerasimos Chourdakis

Institute for Parallel and Distributed Systems
University of Stuttgart
gerasimos.chourdakis@ipvs.uni-stuttgart.de

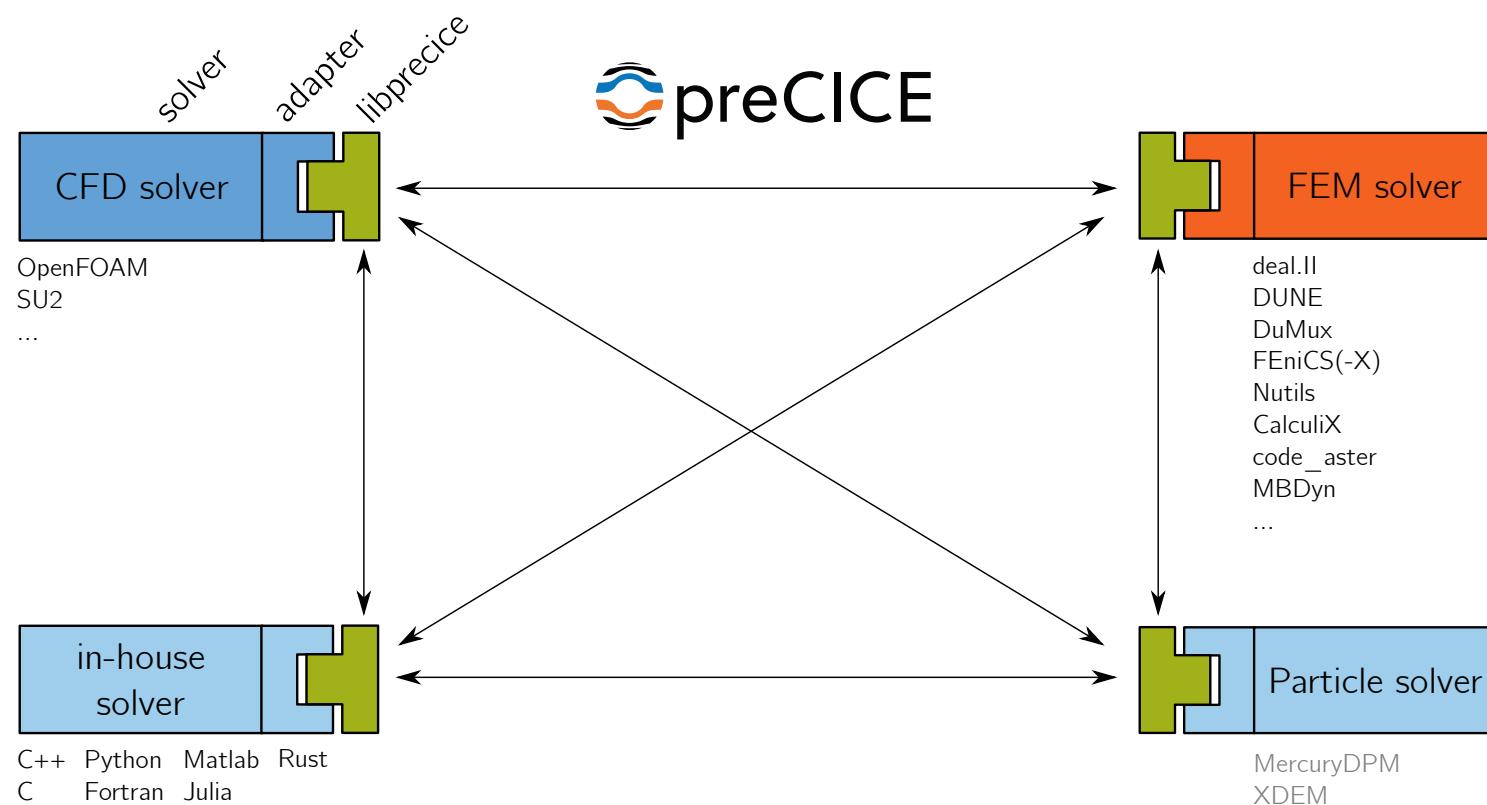


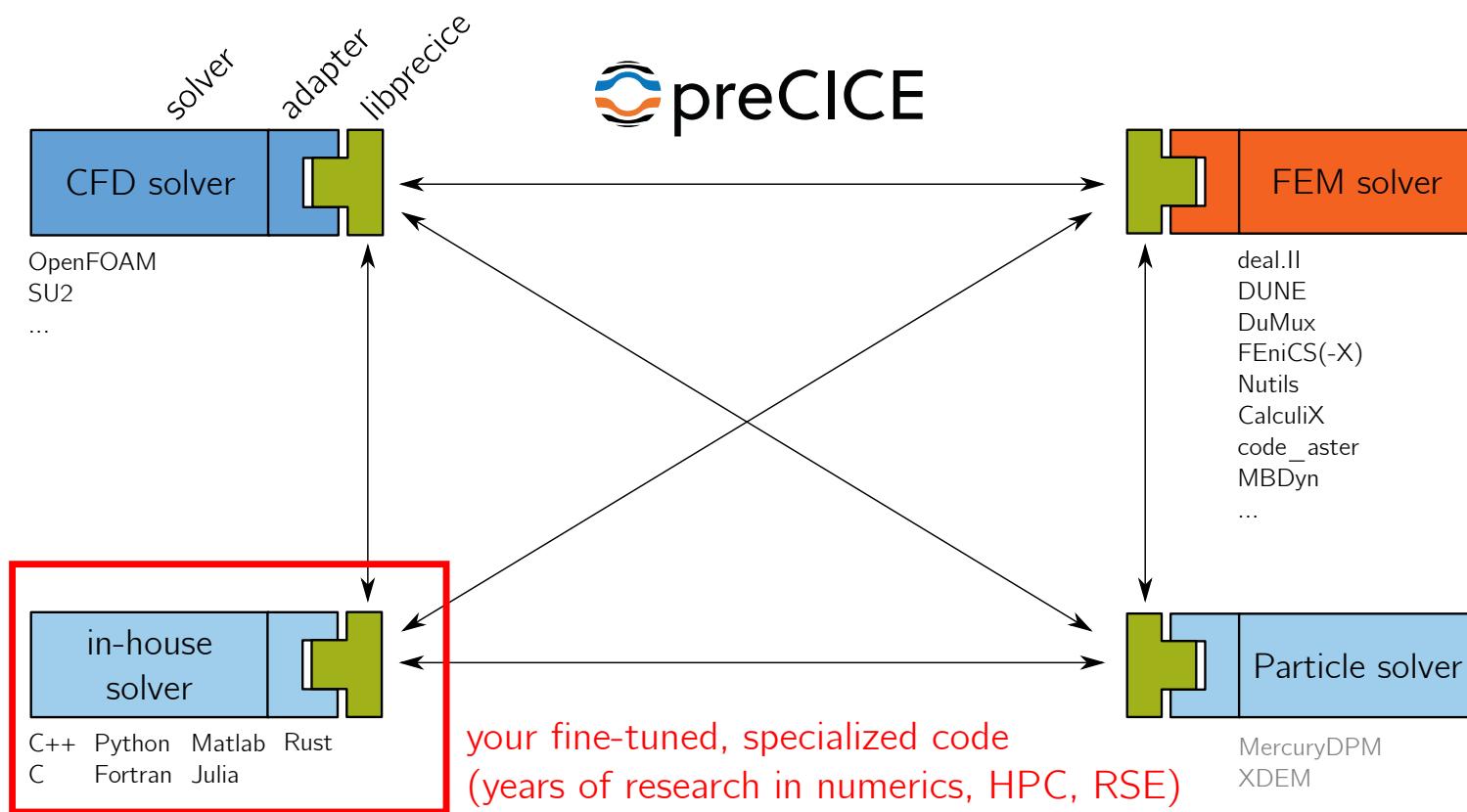
University of Stuttgart
Germany



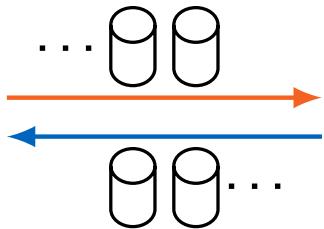


preCICE





Where preCICE helps



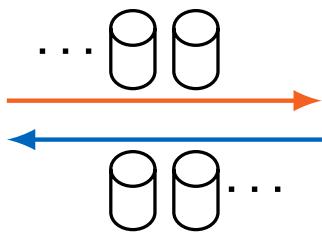
Communication

Options:

- MPI ports (fast)
- TCP sockets (robust)

Fully-parallel, peer-to-peer

Where preCICE helps

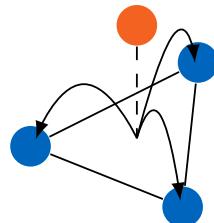


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Options:

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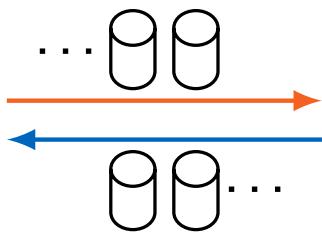
Data mapping

Options:

- radial-basis functions
- projection-based
- conservative/consistent
- direct mesh access

Compute on any side

Where preCICE helps

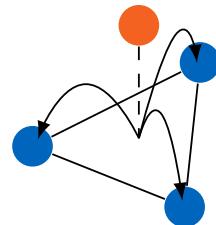


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- MPI ports (fast)
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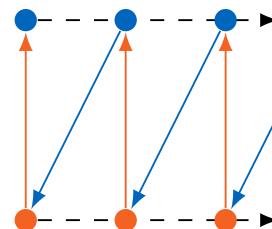


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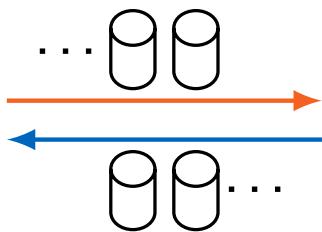
Coupling schemes

Options:

- serial / parallel
- explicit / implicit
- compositional, multi
- IQN, Aitken, ...

Same high-level API
Configurable at runtime

Where preCICE helps

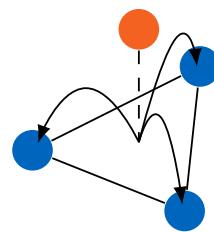


Communication

Options:

- MPI ports (fast)
- TCP sockets (robust)

Fully-parallel, peer-to-peer

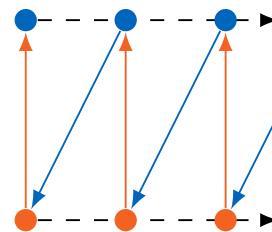


Data mapping

Options:

- radial-basis functions
- projection-based
- conservative/consistent
- direct mesh access

Compute on any side

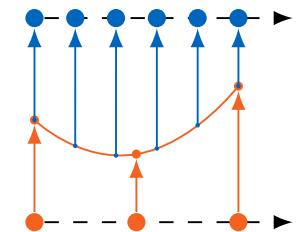


Coupling schemes

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Same high-level API
Configurable at runtime

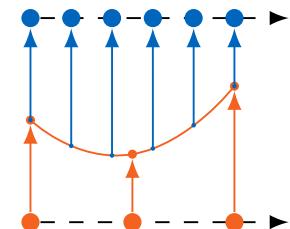
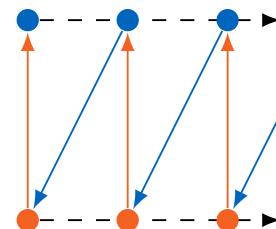
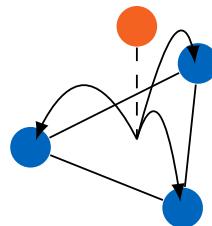
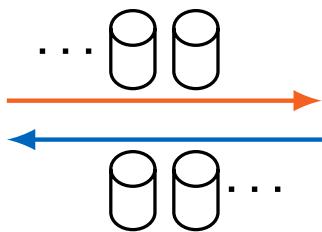


Time interpolation

Options:

- waveform iteration

Where preCICE helps



Communication

Options:

- MPI ports (fast)
- TCP sockets (robust)

Fully-parallel, peer-to-peer

Data mapping

Options:

- radial-basis functions
- projection-based
- conservative/consistent
- direct mesh access

Compute on any side

Coupling schemes

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Same high-level API
Configurable at runtime

Time interpolation

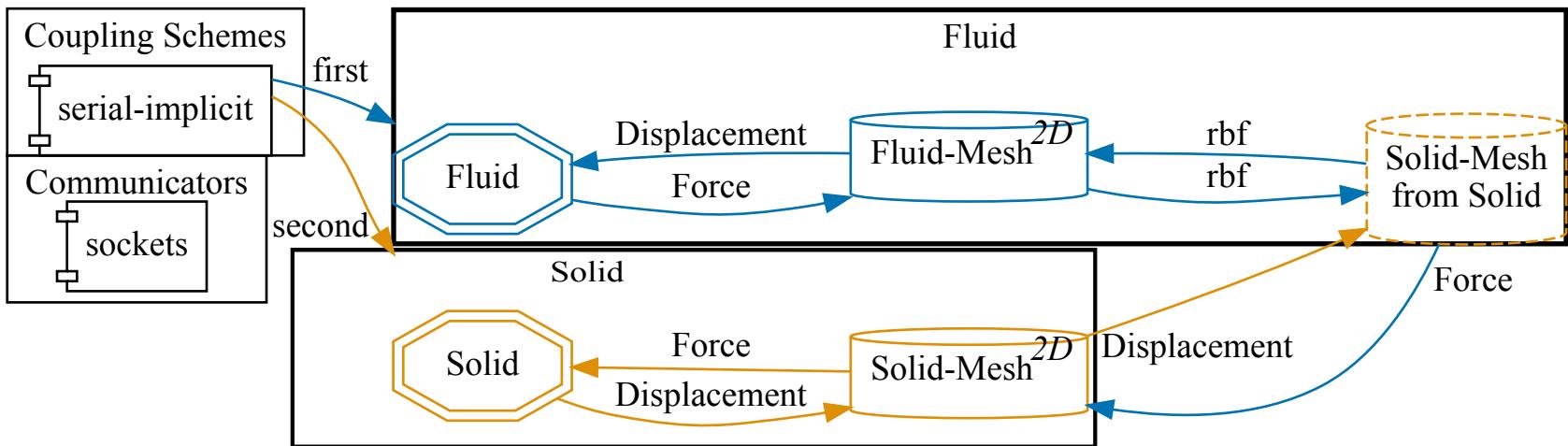
Options:

- waveform iteration

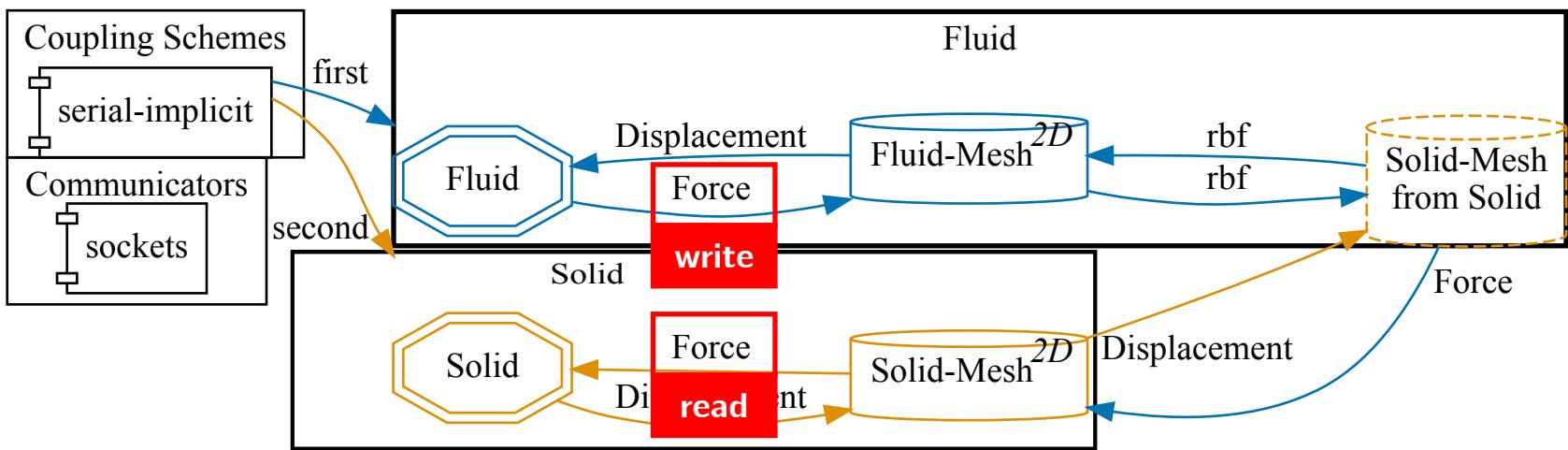
<http://doi.org/>

10/m9d8

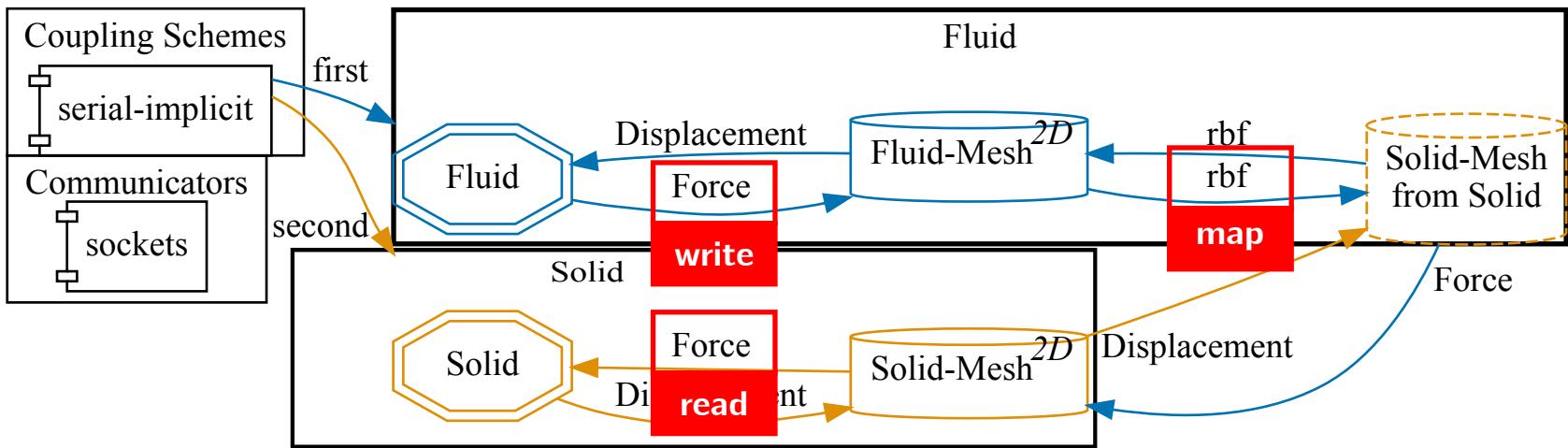
An FS example setup



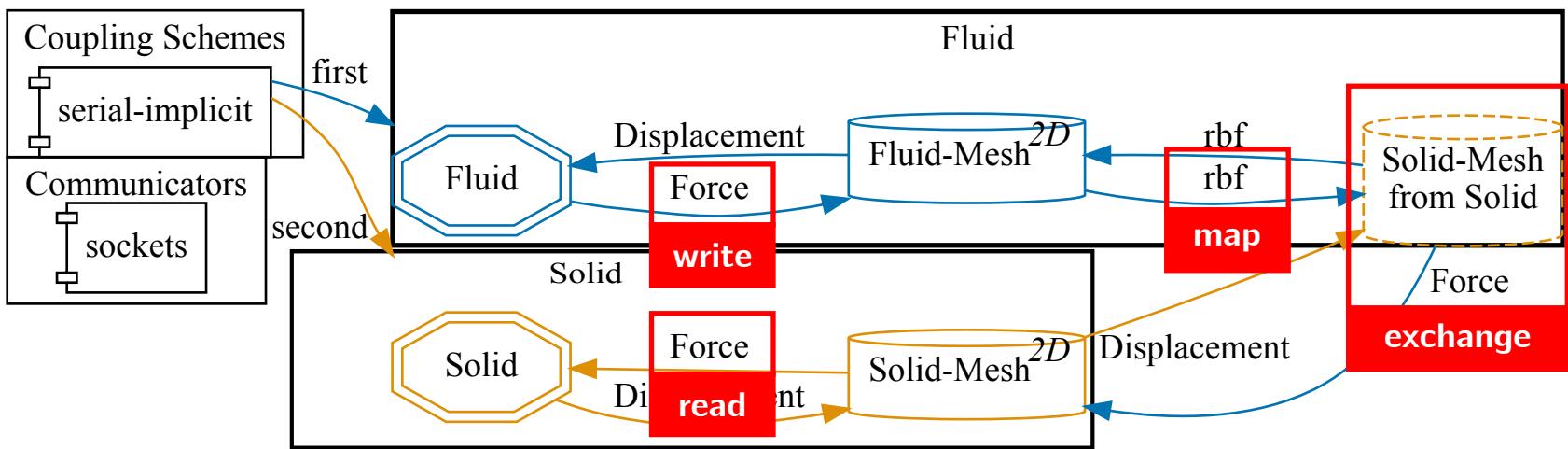
An FS example setup



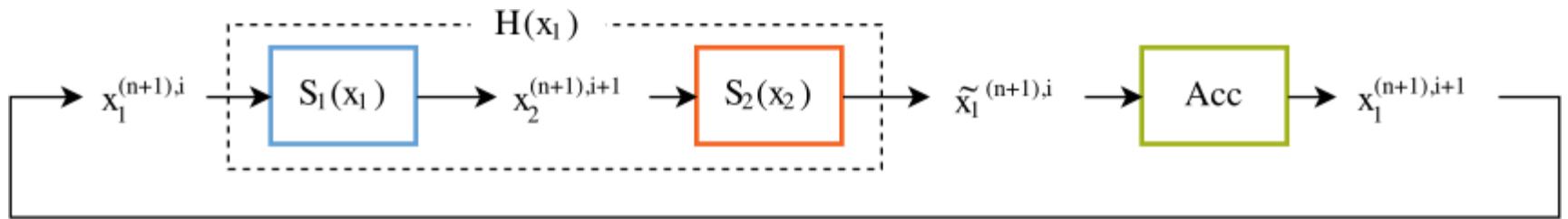
An FS example setup



An FS example setup



Implicit coupling algorithm (serial)



$$i \leftarrow i + 1, \quad S_1 \leftarrow S_1^{(n)}, \quad S_2 \leftarrow S_2^{(n)}$$

Acc: constant / Aitken under-relaxation, Anderson acceleration (IQN).

Also explicit, parallel-implicit, and multi-coupling schemes.

What people do with preCICE

From fluid-structure interaction to new directions

What people do with preCICE (1)

[Home](#) > [Software for Exascale Computing - SPPEXA 2016-2019](#) > [Conference paper](#)

ExaFSA: Parallel Fluid-Structure-Acoustic Simulation

[Florian Lindner](#), [Amin Totounferoush](#), [Miriam Mehl](#)✉, [Benjamin Uekermann](#), [Neda Ebrahimi Pour](#), [Verena Krupp](#), [Sabine Roller](#), [Thorsten Reimann](#), [Dörte C. Sternel](#), [Ryuji Egawa](#), [Hiroyuki Takizawa](#) & [Frédéric Simonis](#)

Conference paper | [Open Access](#) | [First Online: 31 July 2020](#)



Kolb, Elena (2022):

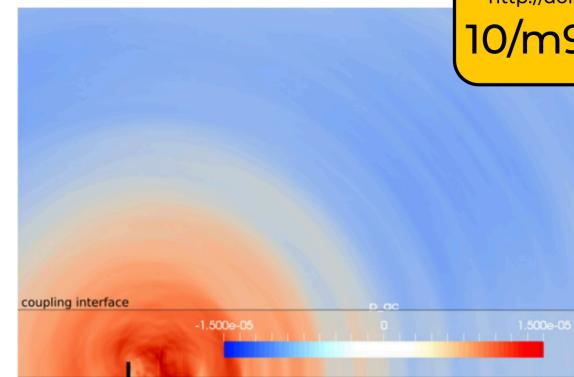
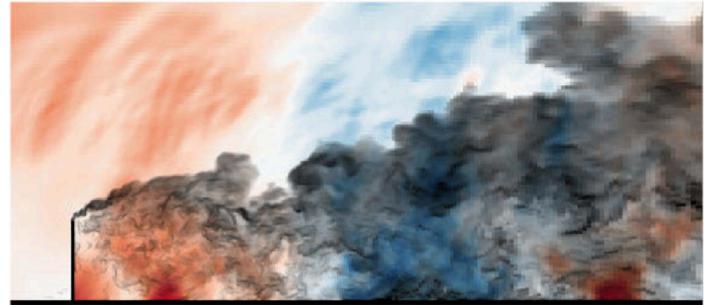
Aeroacoustic Simulation of Turbulent Fluid-Structure Interactions at Low Mach Numbers.

In: Ingenieurwissenschaften, Berlin, Verlag Dr. Hut, TU Darmstadt, ISBN 978-3-8439-5061-9, [Dissertation]

Mariño Salguero, Jessica Marcela (2021):

Numerical simulation of free surface flows interacting with flexible structures. (Verlagsversion)

Darmstadt, Technische Universität, → DOI: 10.26083/tuprints-00019193, → Offizielle URL, [Dissertation]



[http://doi.org/
10/m9d9](http://doi.org/10/m9d9)

ExaFSA SPPEXA program, TU Darmstadt (Germany)

What people do with preCICE (2)

Massively Multiscale Modeling using NASA Multiscale Analysis Tool through Partitioned Task-Parallel Approach

Ibrahim Kaleel, Trenton M. Ricks, Peter A. Gustafson, Evan J. Pineda, Brett A. Bednarcyk and Steven M. Arnold

AIAA 2023-2027
Session: Multiscale Modeling II

Published Online: 19 Jan 2023 • <https://doi.org/10.2514/6.2023-2027>

Read Now

Tools Share

Abstract:

View Video Presentation: <https://doi.org/10.2514/6.2023-2027.vid>

NASA Multiscale Analysis Tool (NASMAT) is a "plug and play" software package that allows users to conduct massively multiscale modeling of hierarchical and nonlinear materials. This work extends the scalability and improves the High Performance Computing friendliness of NASMAT by adopting a partitioned task-parallel approach. The interoperability of NAS-MAT with external software is enhanced through integration with preCICE, an open source library for multiphysics coupling in a partitioned manner. Enhancement through preCICE allows for easy integration of NASMAT to other macro solvers and dissociates the parallelization strategy adopted within NASMAT from the macro solver. A task-parallel framework based on the master-worker approach is implemented as the parallelization scheme. The scheme accounts for the hierarchy of multiple scales (task-dependence) and the heterogeneous nature (dynamic load balancing) of computations. The applicability and scalability of the framework are evaluated by analyzing multiscale problems with varying degrees of complexity and computational loads.

Figures References Related Details

SCITECH FORUM

AIAA SCITECH 2023 Forum
23-27 January 2023
National Harbor, MD & Online
<https://doi.org/10.2514/6.2023-2027>

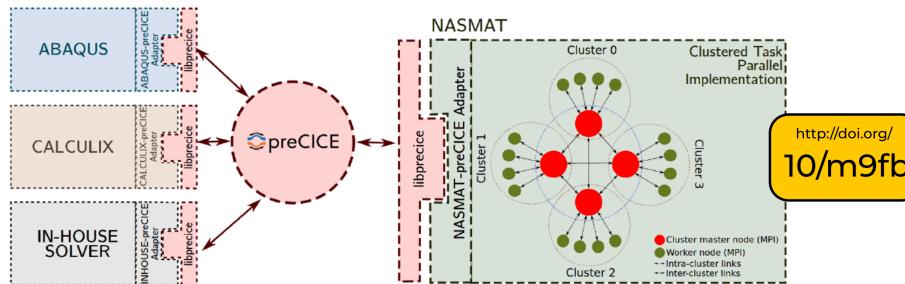
Crossmark

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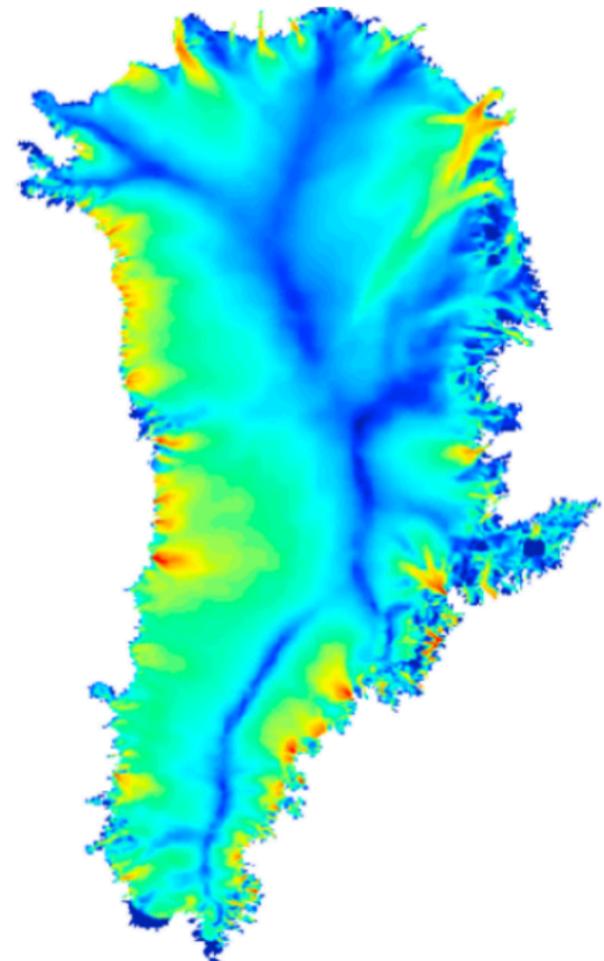
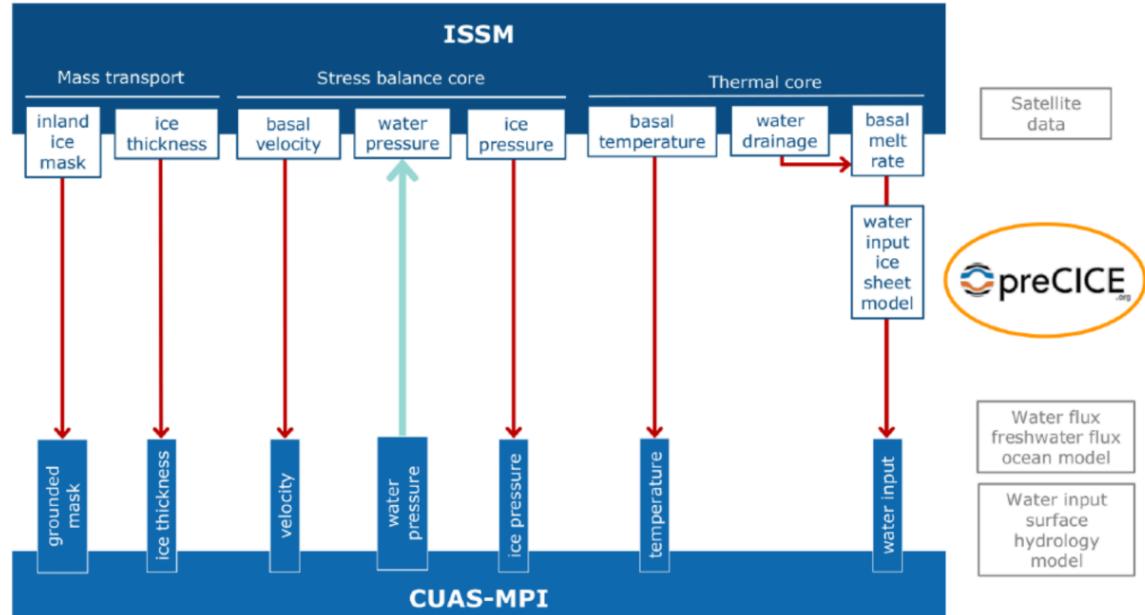
Hierarchical materials, NASA Glenn Research Center (USA)

What people do with preCICE (3)

A preCICE-Interface for the Ice-sheet and Sea-level System Model (ISSM)

Yannic Fischler
yannic.fischler@tu-darmstadt.de
preCICE Workshop 2023

[http://doi.org/
10/m9fc](http://doi.org/10/m9fc)



Ice-sheets and subglacial hydrology, AWI (Germany)

What people do with preCICE (4)



Contents lists available at ScienceDirect

SoftwareX

journal homepage: www.elsevier.com/locate/softx



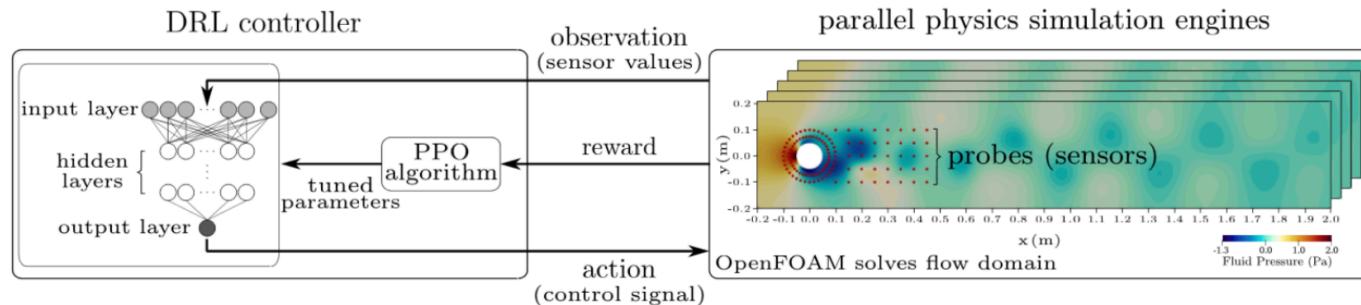
Original software publication

Gym-preCICE: Reinforcement learning environments for active flow control

Mosayeb Shams*, Ahmed H. Elsheikh

Heriot-Watt University, Edinburgh, United Kingdom

[http://doi.org/
10/n3rd](http://doi.org/10/n3rd)

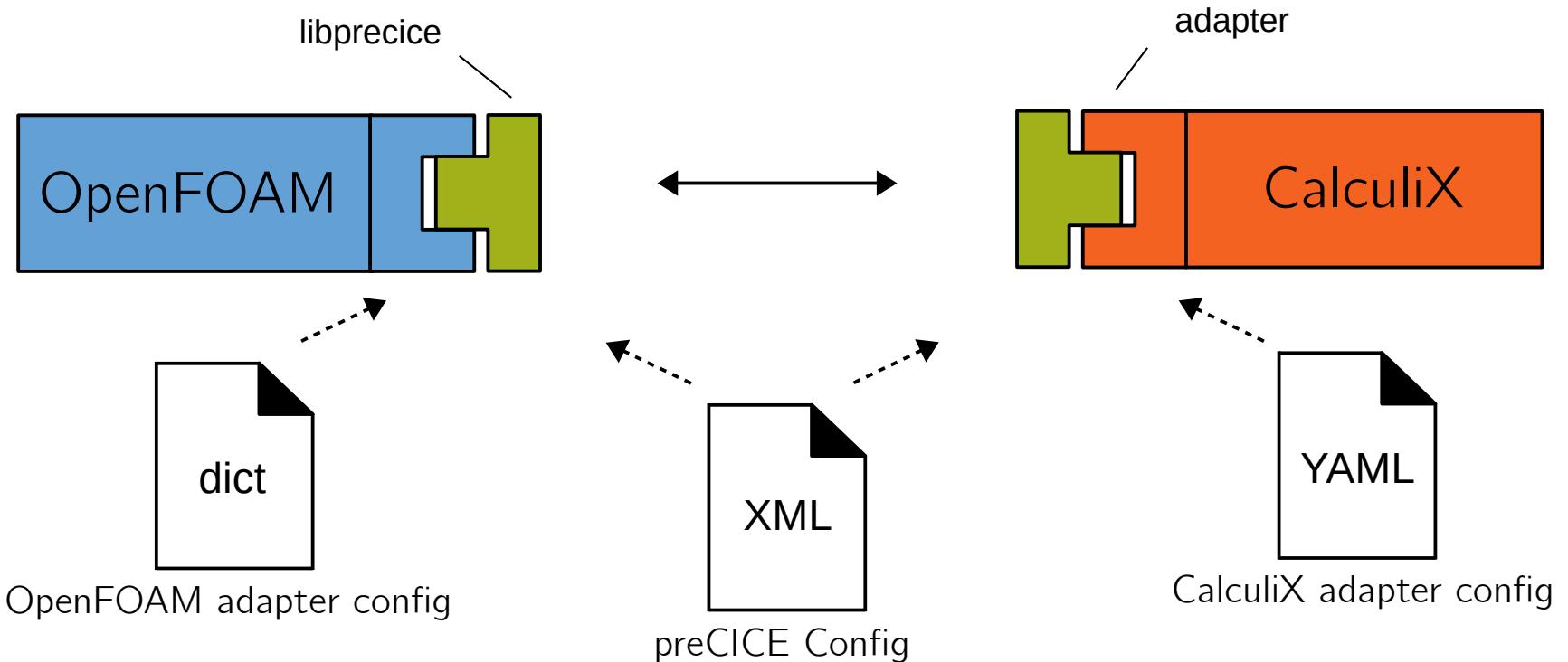


Active flow control with ML, Heriot-Watt University (UK)

Current research



Defining community standards



Overview of an FSI setup: How easy is it to replace CalculiX by FEniCS?



xSDK Version 1.1.0: November 2024

<https://xsdk.info>

<https://xsdk.info>

Each xSDK member package uses or can be used with one or more xSDK packages, and the connecting interface is regularly tested for regressions.

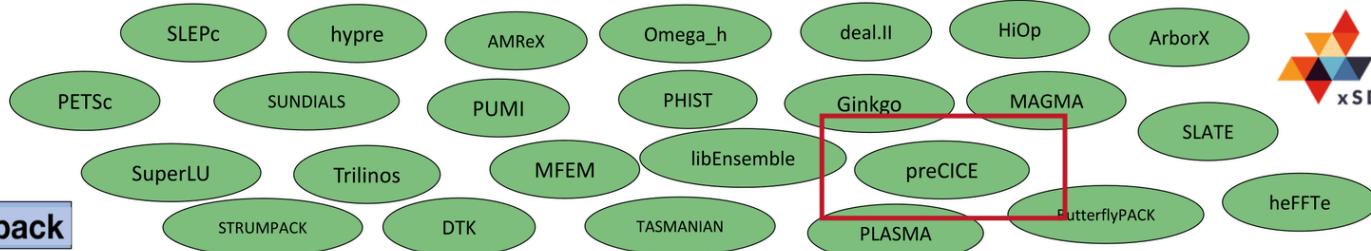
Multiphysics Application C

Application A

Application B

xSDK functionality, Nov 2024

Tested on Linux work-stations



November 2024

- 25 math libraries
- 17 mandatory xSDK community policies
- Spack xSDK installer

Domain components

- Reacting flow, etc.
- Reusable.

Libraries

- Solvers, etc.
- Interoperable.

Frameworks & tools

- Doc generators.
- Test, build framework.

SW engineering

- Productivity tools.
- Models, processes.

Extreme-Scale Scientific Software Development Kit (xSDK)

Impact: Improved code quality, usability, access, sustainability

Foundation for work on performance portability, deeper levels of package interoperability

We can learn from the Extreme-Scale Development Toolkit: xsdk.info/packages/

Save the date: preCICE Workshop 2025, Hamburg, Sep 8-12

Community

Overview & news

preCICE workshops ▾

preCICE minisymposia ▾

Support preCICE

Training

Stories

Contributors

Contribute ▲

Contribute to preCICE

- Adapter guidelines
- Application case guidelines

Community channels

Guidelines for adapters

Summary: Quality guidelines and standards for preCICE adapters and related tools

Table of Contents

- [Metadata](#)
- [Best practices](#)
 - [Required](#)
 - [Additional](#)
- [An adapter example](#)

v0.2, published on December 9, 2024

Are you developing a preCICE adapter or related tool? Follow these guidelines to make your adapter easier to publish, easier to integrate with the rest of the preCICE ecosystem, and more useful for the community.

We differentiate between adapters and application cases: For example, we consider the “[Nutils adapter](#)” to be a collection of application cases instead of an adapter. An [adapter](#) can be a stand-alone software project, but can also be a class, a patch, or something else with significant scholarly effort compared to the uncoupled solver. Other tools that interact with the preCICE API or configuration files can also be considered here, on a case-by-case basis.

For the guidelines, we distinguish between **metadata** and **best practices**. The best practices are split between required and optional. Adapters fulfilling all the required best practices are listed on the preCICE website as adapters conforming to the preCICE standards. Additional criteria bring further benefits and are visible individually for each adapter. Adapters not fulfilling all the required criteria can still be listed here as legacy adapters. By submitting your adapter for review, you can expect a thorough check from the preCICE team on whether these guidelines are met.

•  Edit me ↗

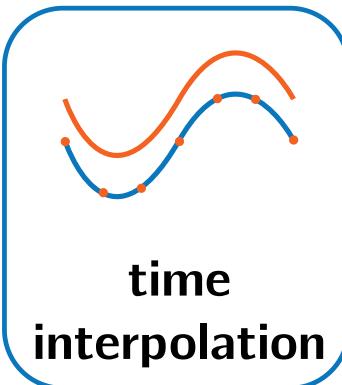
Updated 23 Jan 25

precice.org/community-guidelines-adapters.html

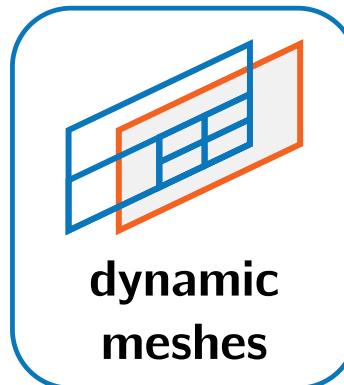
Current research



ecosystem



**time
interpolation**



**dynamic
meshes**



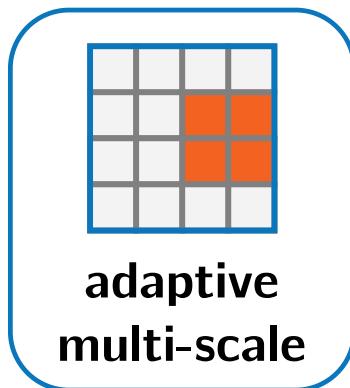
**data mapping
efficiency**

Gerasimos Chourdakis

Benjamin Rodenberg

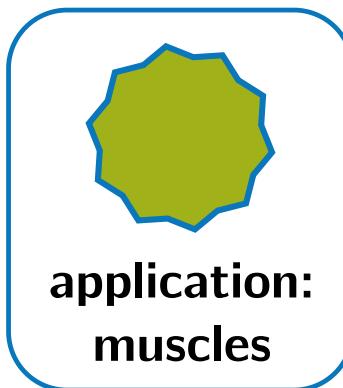
Frédéric Simonis

David Schneider



**adaptive
multi-scale**

Ishaan Desai



**application:
muscles**

Carme Homs Pons



**application:
porous media**

Jun Chen



Time interpolation: See related talk by Niklas Kotarsky in MS205

Further research and development

- Coupling with Functional Mock-Up units
- Non-mesh-related global data exchange
- Volume coupling (overlapping domains)
- Coupling with particle codes
- Automatic acceleration configuration



Workshop #6

preCICE 2025

HSU Hamburg

Germany

September

8 - 12

~50 participants - Training - Talks - Posters - User support sessions - World Café
Abstract submission till May 31 - Registration till July 15 - See precice.org

Resources

Start here: preCICE.org



Quickstart Docs Tutorials Community Blog ↗ About

Search ...

Search by algolia



Save the date: preCICE Workshop 2025, Hamburg, Sep 8-12

Welcome to preCICE

The coupling library for partitioned multi-physics simulations.

[Star on Github](#) ★ 777

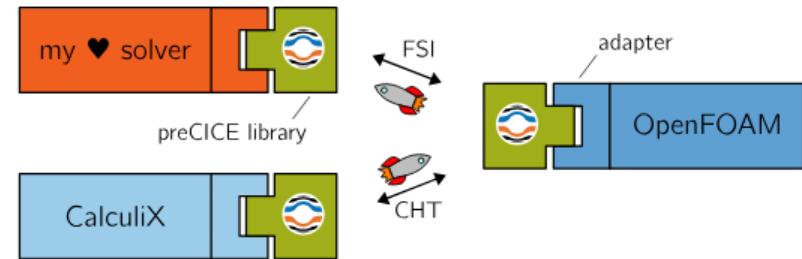
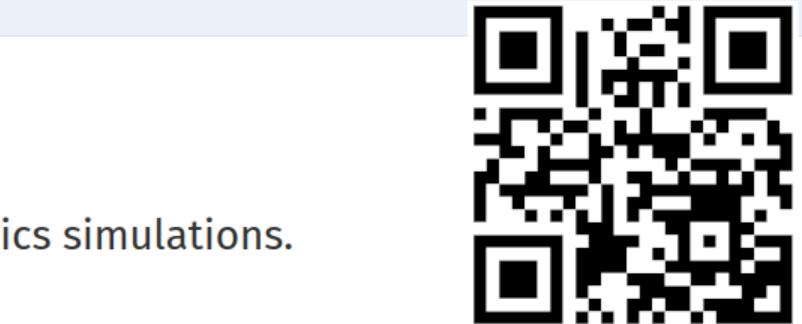
Latest v3.1.2 (Jun 6, 2024)

[Get started >](#)

preCICE is an **open-source coupling library** for partitioned multi-physics simulations, including, but not restricted to fluid-structure interaction and conjugate heat transfer simulations.

Partitioned means that **preCICE couples existing programs/solvers** capable of simulating a subpart of the complete physics involved in a simulation. This allows for the high flexibility that is needed to keep a decent time-to-solution for complex multi-physics scenarios.

The software offers convenient methods for transient equation coupling, communication, and data mapping.



Everything is open and user-centered

- Developed in the open: github.com/precice
- Extensive documentation
- (Diamond) open-access publications
- Public recordings of talks

Extra effort to maintain and update

Further channels



precice.discourse.group



preCICECoupling



groups/9073912/



project/preCICE



fosstodon.org/@precicerecice



@precice.org

preCICE is free because of



Research Software
Sustainability



EXC 2075
SimTech



Bundesministerium
für Wirtschaft
und Energie



This project has received funding from the European Union's Horizon 2020 research and innovation programme under the Marie Skłodowska-Curie grant agreement No 754462

and the code/issues/testing/documentation contributions of people like you (thank you!).

Summary

1. preCICE offers efficient algorithms for black-box coupling
2. New directions beyond FSI: looking for collaborations
3. Standardizing a community-driven bazaar of components

Gerasimos Chourdakis (US/TUM) + many more (see precice.org/about)



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Extra slide: Example of using the API

```
1 import precice, nutils
2
3 def main(young=4e6, density=3e3, poisson=0.3, nelems=2, solver_dt=0.01):
4     # Setup Nutils simulation... (mesh, equations, boundary condition)
5
6     # preCICE setup
7     solver_process_index = 0
8     solver_process_size = 1
9     participant =
10    precice.Participant("Solid", ".../precice-config.xml",
11                          solver_process_index, solver_process_size)
12    vertex_ids =
13    participant.set_mesh_vertices(mesh_name, wall.eval(ns.X))
14
15    participant.initialize()
16
17    while participant.is_coupling_ongoing():
```

Extra slide: Example of using the API

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12    vertex_ids =
13    participant.set_mesh_vertices(mesh_name, wall.eval(ns.X))
14
15    participant.initialize()
16
17    while participant.is_coupling_ongoing():
18        if participant.requires_writing_checkpoint():
19            checkpoint = timestep, arguments
20
21            precice_dt = participant.get_max_time_step_size()
22            dt = min(precice_dt, solver_dt)
```

Extra slide: Example of using the API

```
9     participant =  
10    precice.Participant("Solid", "../precice-config.xml",  
11                          solver_process_index, solver_process_size)  
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19            checkpoint = timestep, arguments  
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21        precice_dt = participant.get_max_time_step_size()  
22        dt = min(precice_dt, solver_dt)  
23  
24        # read forces from participant at the end of the timestep  
25        force = participant.read_data("Solid-Mesh", "Force", verti
```

Extra slide: Example of using the API

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19         checkpoint = timestep, arguments
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22         dt = min(precice_dt, solver_dt)
23
24         # read forces from participant at the end of the timestep
25         force = participant.read_data("Solid-Mesh", "Force", verti
26
27         timestep += 1
28
29         arguments = dict(dt=dt, u0=arguments['u'], v0=arguments[
30             arguments = solver.solve_linear('u:testu,v:testv', res, a
31
32         # write displacements to participant
33         write_data = wall.eval(ns.u, **arguments)
34         participant.write_data("Solid-Mesh", "Displacement", verti
35
```

Extra slide: Example of using the API

```
20
21
22
23
24
25
26
27     timestep += 1
28
29     arguments = dict(dt=dt, u0=arguments['u'], v0=arguments['
30     arguments = solver.solve_linear('u:testu,v:testv', res, a
31
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33     write_data = wall.eval(ns.u, **arguments)
34     participant.write_data("Solid-Mesh", "Displacement", vert
35
36     # do the coupling
37     participant.advance(dt)
38
39     # read checkpoint if required
40     if participant.requires_reading_checkpoint():
41         timestep, arguments = checkpoint
42
43     participant.finalize()
```

Extra slide: Example of using the API

```
27         timestep += 1
28
29     arguments = dict(dt=dt, u0=arguments['u'], v0=arguments['v'])
30     arguments = solver.solve_linear('u:testu,v:testv', res, arguments)
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32     # write displacements to participant
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