

# Tuning Spectral Element Preconditioners for Parallel Scalability on GPUs

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Malachi Phillips<sup>1</sup> Stefan Kerkemeier<sup>2</sup> Paul Fischer<sup>1,2,3</sup>

<sup>1</sup>Department of Computer Science, University of Illinois at Urbana-Champaign

<sup>2</sup>Mathematics and Computer Science, Argonne National Laboratory, Lemont, IL 60439

<sup>3</sup>Department of Mechanical Science and Engineering, University of Illinois at Urbana-Champaign

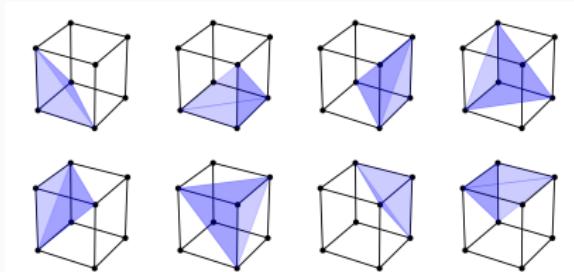
# Introduction

- Poisson solve for pressure arises in Navier-Stokes simulations.
- This solve encompasses the majority of the solution time.
- Spectral element (SE):  $E$  elements with polynomial degree  $p$ ,  $n \approx Ep^3$  unknowns and  $\mathcal{O}(Ep^6)$  nonzeros.
  - Exploit tensor-product-sum factorization,  $\mathcal{O}(Ep^4)$  cost to apply matrix-vector product [Deville et al., 2002].
  - Fast SE-based flow simulations require iterative solvers.
  - Poor conditioning of system:  $\kappa(A) \sim \mathcal{O}(h^{-p})$  requires preconditioning.

# Poisson Preconditioners

- Jacobi
- Additive Schwarz method (ASM)
- Low-order operator preconditioning (SEMFEM)
- Geometric  $p$ -Multigrid (pMG), requiring a smoother:
  - (Damped) Jacobi (again)
  - ASM (again)
  - Chebyshev polynomial smoothing

- Precondition high-order system with low-order discretizations with coinciding nodes
- [Orszag, 1979] demonstrated  $\kappa(M^{-1}A) \sim \pi^2/4$  scaling for second-order Dirichlet problems.
- [Bello-Maldonado and Fischer, 2019] proposed using one-per-vertex scheme.
  - Same approach, but solve resultant system using algebraic multigrid (AMG) implemented in CUDA in AmgX [Naumov et al., 2015] with single pass V-cycle, damped Jacobi relaxation ( $\omega = 0.9$ ).



# Multigrid

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## Algorithm 1 Multigrid V-cycle

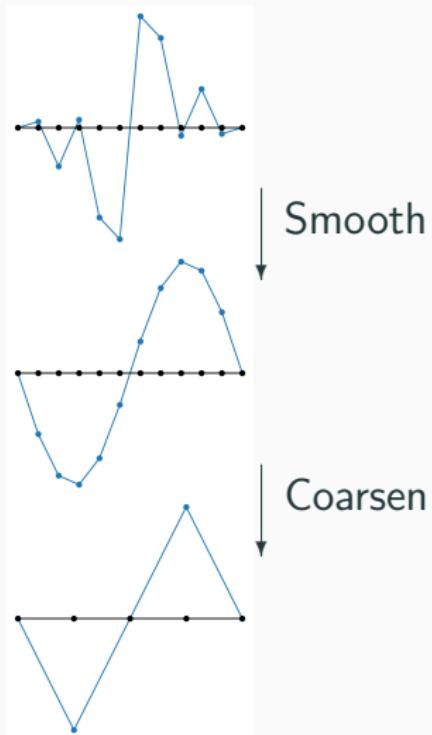
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```
x = x + M-1(b - Ax) // smooth  
r = b - Ax // re-evaluate residual  
rC = PTr // coarsen  
eC = AC-1rC // solve/re-apply V-cycle  
e = PCeC // prolongate  
x = x + e // update solution  
x = x + M-1(b - Ax) // post smoothing
```

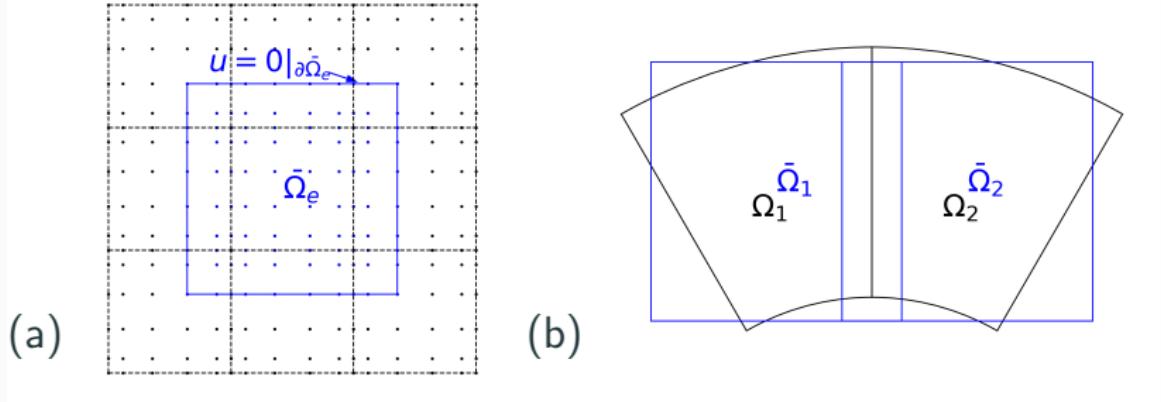
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Smoothening choices:

- Damped Jacobi
- Schwarz
- Chebyshev Jacobi smoothing
- *Chebyshev Schwarz smoothing*



# Additive Schwarz (ASM), Restrictive Additive Schwarz (RAS)



- $M^{-1} := \sum_{e=1}^E W_e R_e^T \bar{A}_e^{-1} R_e$ , subdomain (a) [Lottes and Fischer, 2005, Loisel et al., 2008].
- How to form  $\bar{A}_e^{-1}$ ?
  - Galerkin:  $\bar{A}_e = R_e A R_e^T$ , ruins  $\mathcal{O}(p^3)$  storage,  $\mathcal{O}(p^4)$  work per element.
  - Box-like approximation (b): recover  $\mathcal{O}(p^3)$  storage,  $\mathcal{O}(p^4)$  work per element using fast diagonalization method (FDM).

- 3D Poisson-in-a-box:

$$\bar{A} = B_z \otimes B_y \otimes A_x + B_z \otimes A_y \otimes B_x + A_z \otimes B_y \otimes B_x,$$

- Directly invert with FDM with  $\mathcal{O}(p^3)$  storage,  $\mathcal{O}(p^4)$  work:

$$\bar{A}^{-1} = (S_z \otimes S_y \otimes S_x) D^{-1} (S_z^T \otimes S_y^T \otimes S_x^T),$$

where

$$D = I \otimes I \otimes \Lambda_x + I \otimes \Lambda_y \otimes I + \Lambda_z \otimes I \otimes I$$

and each  $S_*$ ,  $\Lambda_*$  are from the generalized eigenvalue problem:

$$A_* s_i = \lambda_i B_* s_i$$

where  $B_*$ ,  $A_*$  are 1D mass-stiffness matrices.

# Chebyshev Smoothing

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## Algorithm 2 Chebyshev smoother

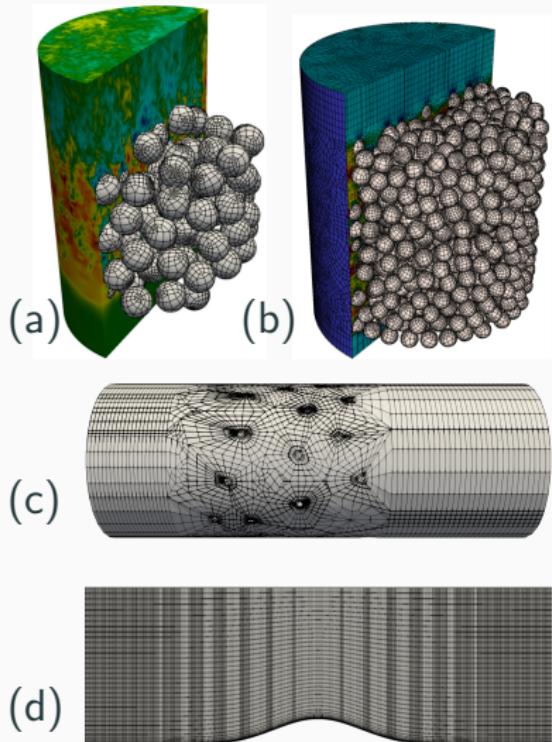
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```
 $\theta = \frac{1}{2}(\lambda_{\max} + \lambda_{\min}), \delta = \frac{1}{2}(\lambda_{\max} - \lambda_{\min}), \sigma = \frac{\theta}{\delta}, \rho_1 = \frac{1}{\sigma}$ 
 $r = S(b - Ax), d_1 = \frac{1}{\theta}r, x_1 = 0$ 
for  $k = 1, \dots, \text{chebyshevOrder}$  do
     $x_{k+1} = x_k + d_k$ 
     $r_{k+1} = r_k - SAd_k, \rho_{k+1} = \frac{1}{2\sigma - \rho_k}$ 
     $d_{k+1} = \rho_{k+1}\rho_k d_k + \frac{2\rho_{k+1}}{\delta}r_{k+1}$ 
end for
 $x_{k+1} = x_k + d_k$ 
return  $x_{k+1}$ 
```

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Max eigenvalue estimate  $\tilde{\lambda}$  obtained with 10 Arnoldi iterations,  
 $(\lambda_{\max}, \lambda_{\min}) = (1.1, 0.1)\tilde{\lambda}$ . See [Adams et al., 2003, Phillips et al.,  
] for sensitivity to coefficients. Jacobi based  $S$  from [Adams et al.,  
2003, Sundar et al., 2015, Kronbichler and Ljungkvist, 2019].

# Navier-Stokes

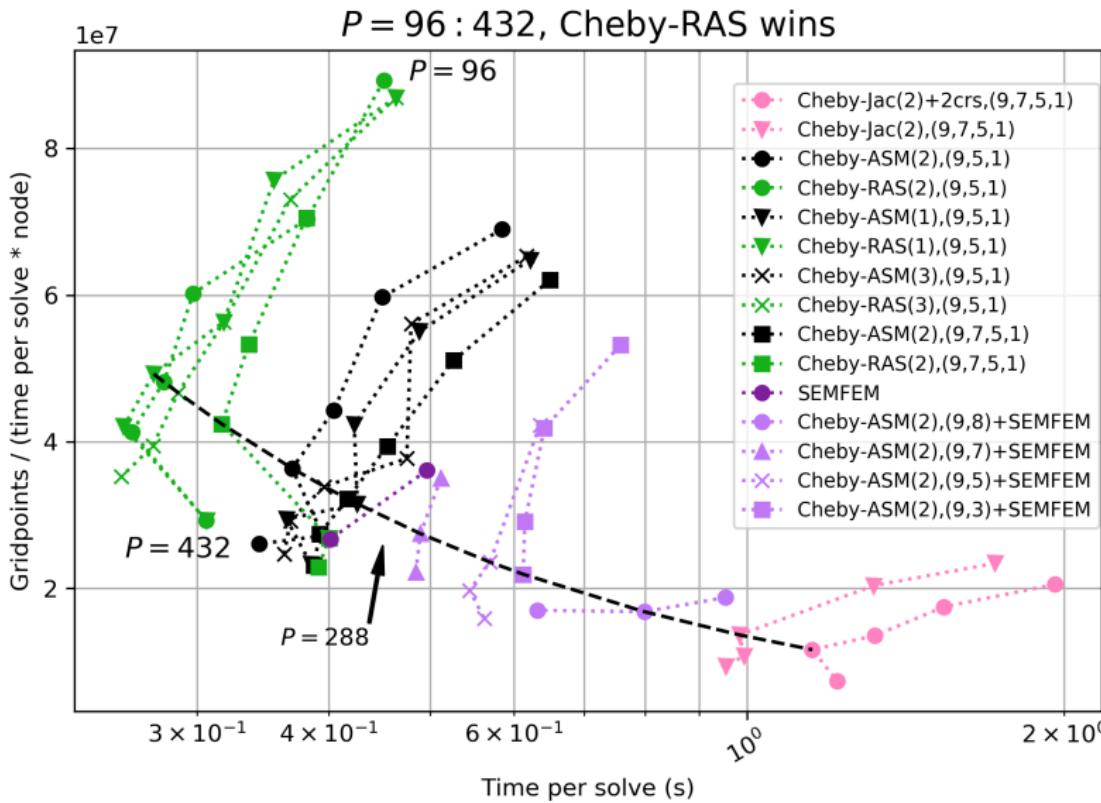


Case Name	E	p	n
146 pebble (a)	62K	7	21M
1568 pebble (b)	524K	7	180M
67 pebble (c)	122K	7	42M
Speed bump (d)	885K	9	645M
	CFL	$\Delta t$	$T_{restart}$
(a) [Lan et al., 2021]	4	$2 \times 10^{-3}$	10
(b) [Lan et al., 2021]	4	$5 \times 10^{-4}$	20
(c) [Yuan et al., 2020]	4	$5 \times 10^{-5}$	10.6
(d) [Shur et al., 2021]	0.8	$2 \times 10^{-3}$	5.6
	Re	Tol	Steps
(a)	5000	$10^{-4}$	2000
(b)	5000	$10^{-4}$	2000
(c)	1460	$10^{-4}$	2000
(d)	$10^6$	$10^{-5}$	2000

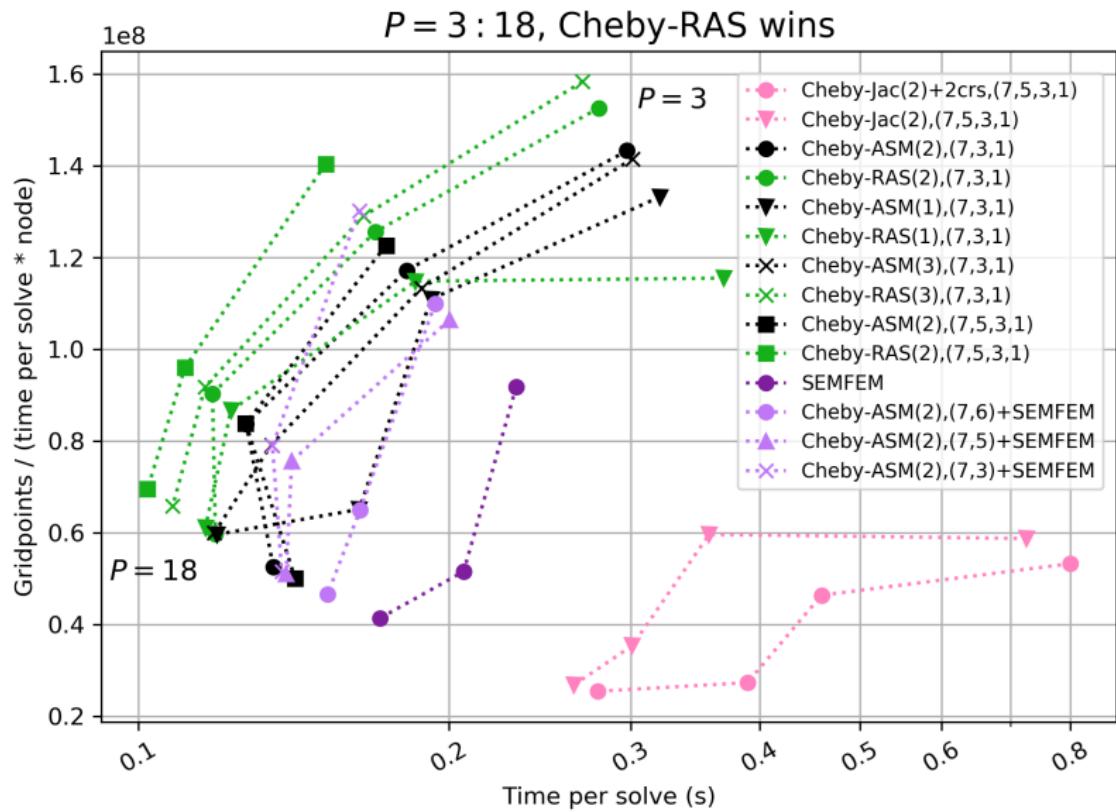
Problem discretization, timestepping parameters. Pebble cases use a two stage subcycling scheme. All cases use a 2nd-order timestepper with 10 prior solution vectors to generate the initial guess [Fischer, 1998].

## Results

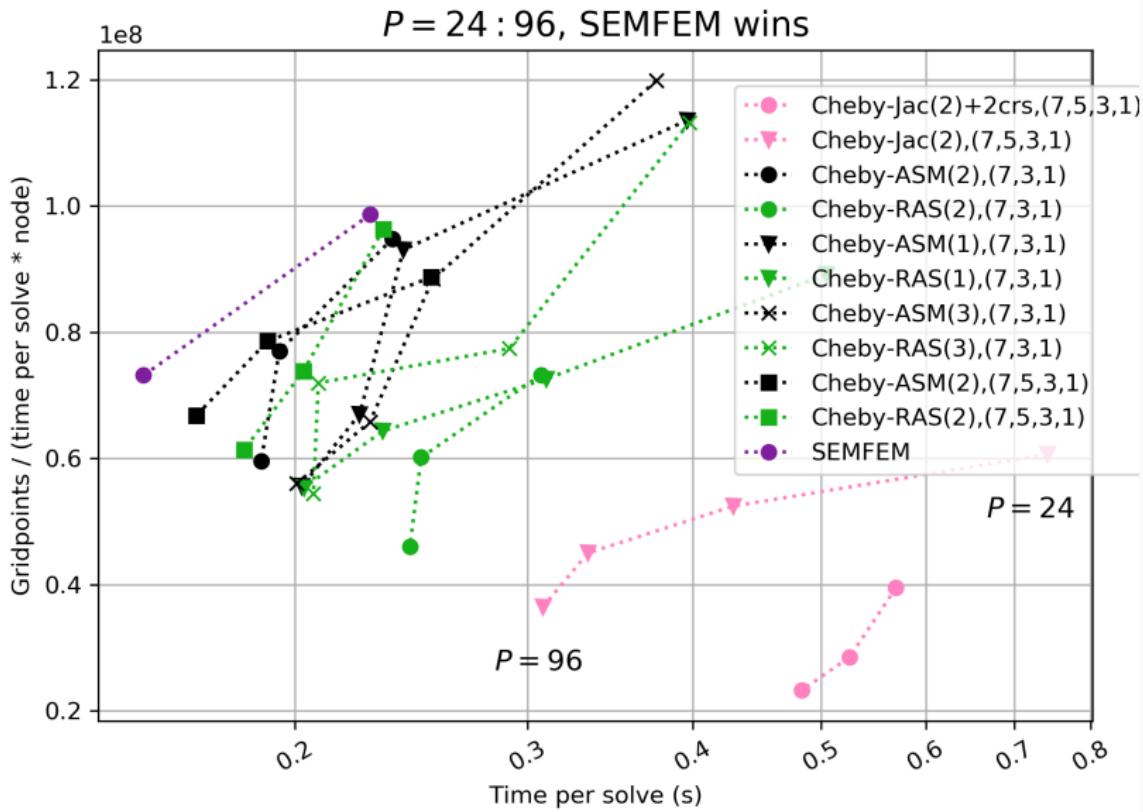
- All results on Summit (42 IBM Power9 CPUs, 6 NVIDIA V100 GPUs per node).
- Each of the  $P$  ranks are assigned one GPU, 6 GPUs per node (unless  $P < 6$ ).
- At coarsest level, solve using one or two BoomerAMG V-cycles [Henson and Yang, 2002]
- pMG preconditioner with  $\eta$ -order Chebyshev-accelerated  $\xi$  smoother with a multigrid schedule  $\Pi$  is denoted Cheby- $\xi(\eta), \Pi$ .
  - Cheby-ASM(2),(7,3,1) denotes pMG preconditioning with a 2nd-order Chebyshev-accelerated ASM smoother with  $p = 7$ ,  $p = 3$ , and  $p = 1$  as multigrid levels.



Strong scaling results on Summit for the Boeing speed bump problem.

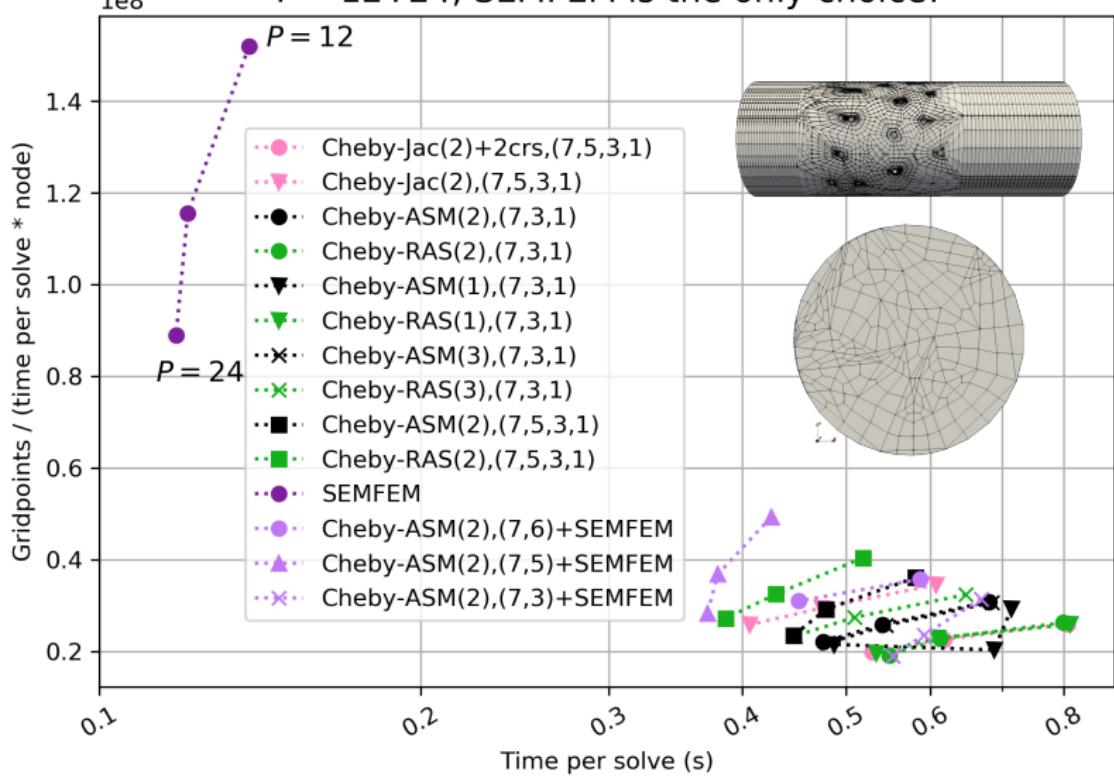


Strong scaling results on Summit for the 146 pebble case.



Strong scaling results on Summit for the 1568 pebble case.

$P = 12 : 24$ , SEMFEM is the only choice!



Strong scaling results on Summit for the 67 pebble case.

## Tuning

- There is no single optimal preconditioning strategy.
- Tuning should be done by the software, not the user.
- In large-scale fluid mechanics applications, any tuning overhead is amortized over  $10^4$ – $10^5$  Poisson solves.
- Auto-tuning of preconditioners considered by [Imakura et al., 2012, Yamada et al., 2018, Brown et al., 2021].
- A primitive exhaustive search over a few reasonable preconditioner setups recovers performance in the 67 pebble case.

# Conclusion

- Introduce Chebyshev-accelerated Schwarz smoothers.
- Chebyshev-accelerated Schwarz smoothers with  $p$ -multigrid, and SEMFEM solved with AmgX, prove to be good SE Poisson preconditioners on OLCF's Summit.
- Introduce (primitive) tuner to select preconditioner strategy.
- Need additional understanding of Chebyshev-accelerated Schwarz smoothers through Local Fourier analysis [Thompson et al., 2021].
- nekRS: <https://github.com/nek5000/nekrs>

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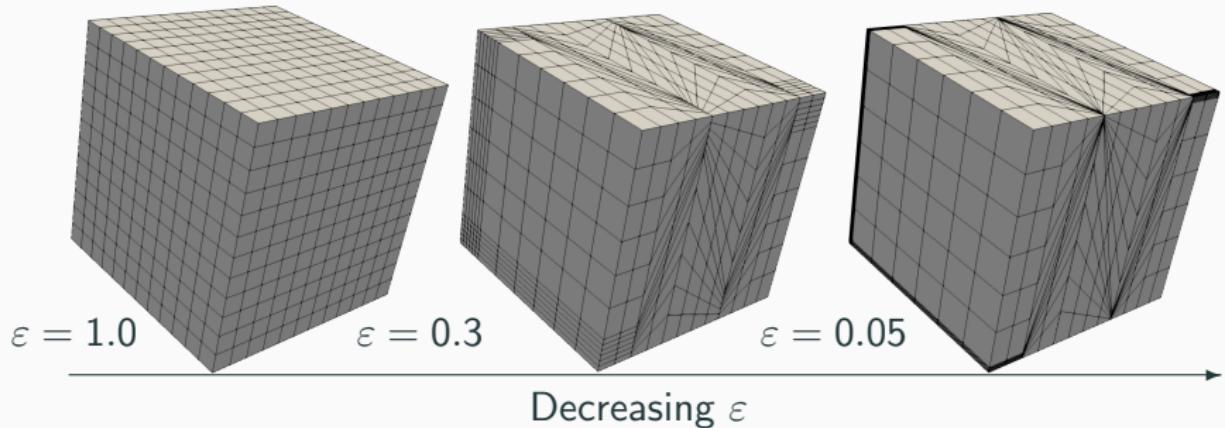
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## Supplementary Material

## Kershaw



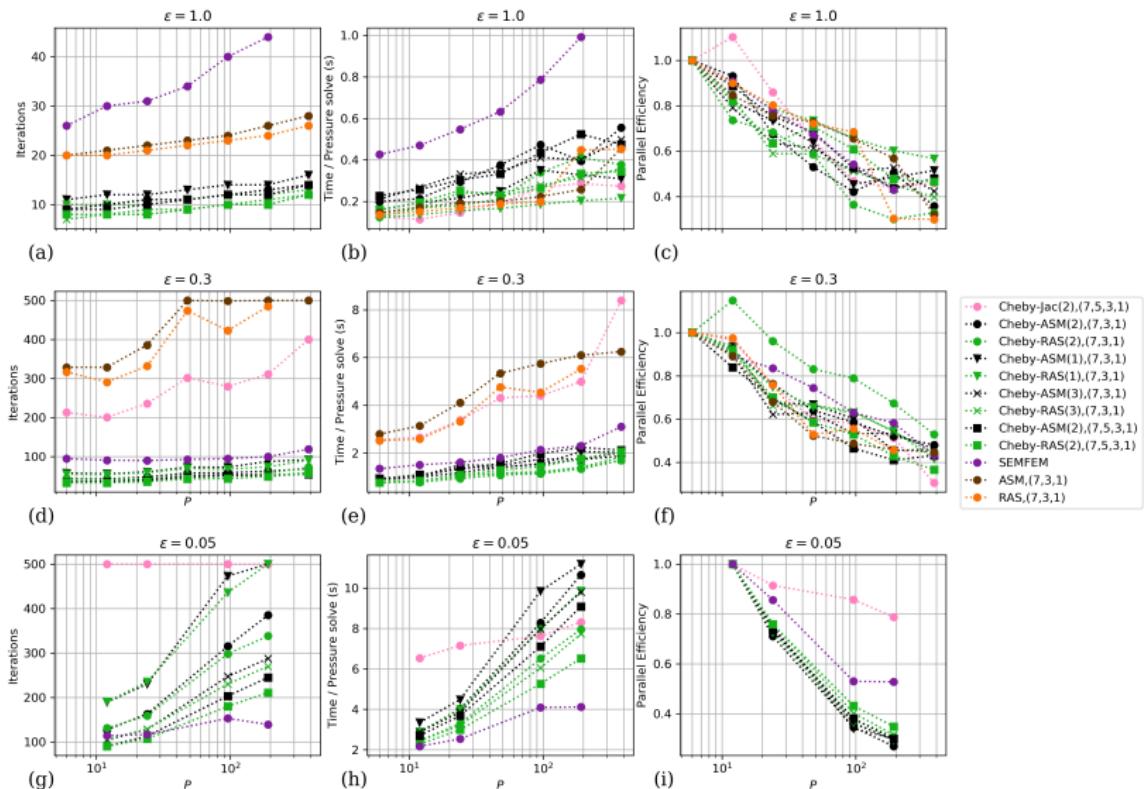
Kershaw family of meshes [Kolev et al., 2021, Kershaw, 1981] on  $\Omega := [-1/2, 1/2]^3$ , Dirichlet on  $\partial\Omega$  with right hand side:

$$f(x, y, z) = 3\pi^2 \sin(\pi x) \sin(\pi y) \sin(\pi z) + g,$$

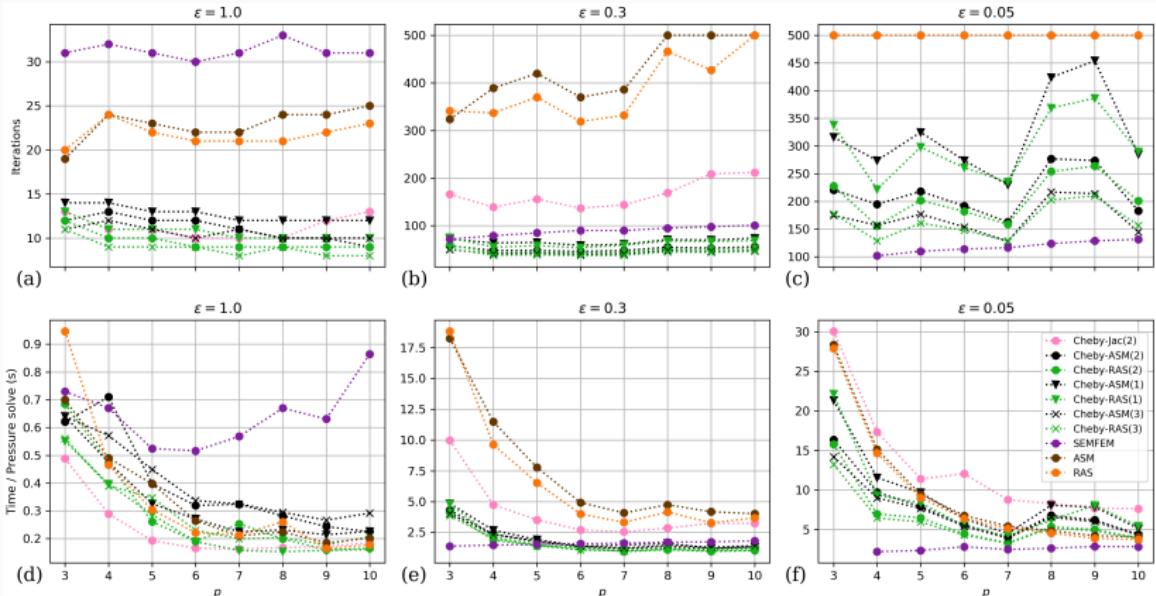
where  $g(x, y, z)$  is a random, continuous vector vanishing on  $\partial\Omega$ .

Vary  $(E, p)$  for weak scaling and order dependence studies.

Solution target:  $10^{-8}$  relative residual reduction.



Kershaw weak scaling, GMRES(20).  $n/P = 2.67M.$



Kershaw order dependence, GMRES(20).  $n/P = 2.88M$ ,  $P = 6$ .

# Spectral Element Poisson

- Poisson PDE:

$$-\nabla^2 u = f \text{ for } u, f \in \Omega \subset \mathbb{R}^3 \mapsto \mathbb{R}.$$

- Weak form: *Find  $u \in X_0^p$  such that,*

$$(\nabla v, \nabla u)_p = (v, f)_p \quad \forall v \in X_0^p.$$

- Results in linear system:

$$\mathbf{A}\mathbf{u} = \mathbf{B}\mathbf{f},$$

with  $B_{ij} := (\phi_i, \phi_j)_p$ , and  $A_{ij} := (\nabla \phi_i, \nabla \phi_j)_p$ .

- Poor conditioning:  $\kappa(A) \sim \mathcal{O}(h^{-p})$

## Chebyshev Multiplier Sensitivity

$\lambda_{min} \setminus \lambda_{max}$	0.9 $\tilde{\lambda}$	0.95 $\tilde{\lambda}$	1.0 $\tilde{\lambda}$	1.1 $\tilde{\lambda}$	1.2 $\tilde{\lambda}$	1.3 $\tilde{\lambda}$
0.0 $\tilde{\lambda}$	-	-	-	-	-	-
0.025 $\tilde{\lambda}$	-	-	-	110	64	48
0.05 $\tilde{\lambda}$	-	-	-	50	40	38
0.1 $\tilde{\lambda}$	-	-	124	40	38	38
0.2 $\tilde{\lambda}$	159	45	43	42	43	44
0.25 $\tilde{\lambda}$	47	45	44	44	45	46

Iteration counts for the  $(\lambda_{min}, \lambda_{max})$  sensitivity study. Omitted entries failed to converge in 1000 iterations.