

Installing VirtualBox, Ubuntu and ROS

What is ROS

ROS means **Robot Operating System**.

ROS is not an operating system but a meta operating system meaning, that it assumes there is an underlying operating system that will assist it in carrying out its tasks. But what is an operating system? There is no clear definition for operating systems. Usually, an operating system consists of all the things provided by the operating system provider¹.

How to install ROS on Ubuntu

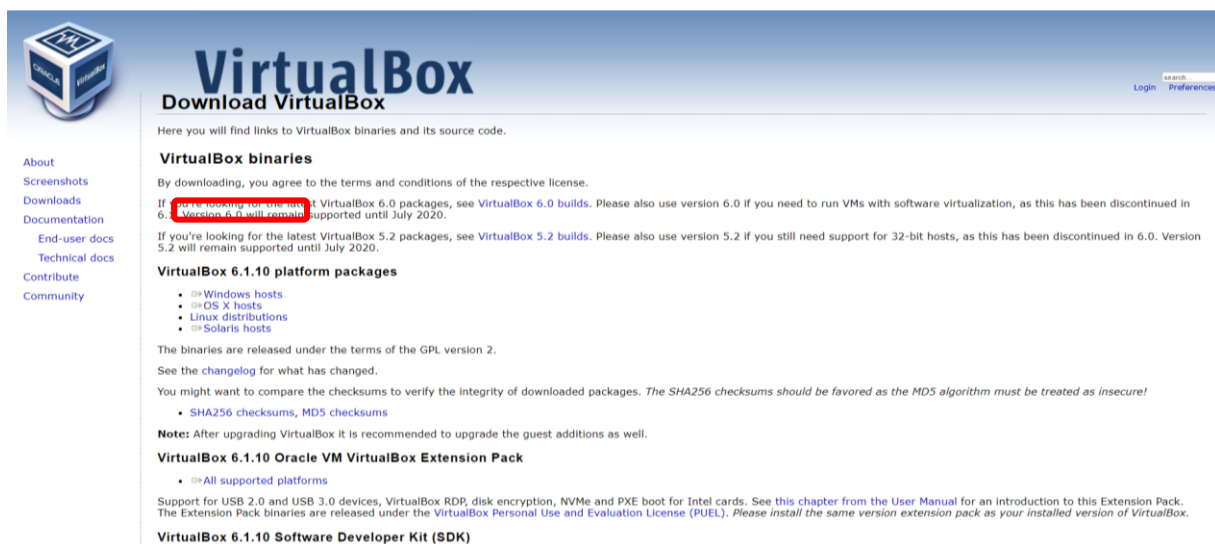
Installation of ROS goes through stages

Operating system (windows10) → Virtual machine (VirtualBox) → Linux (Ubuntu) → ROS

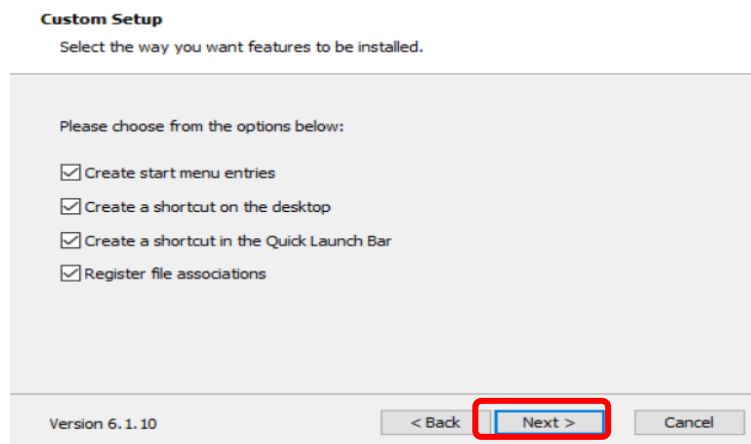
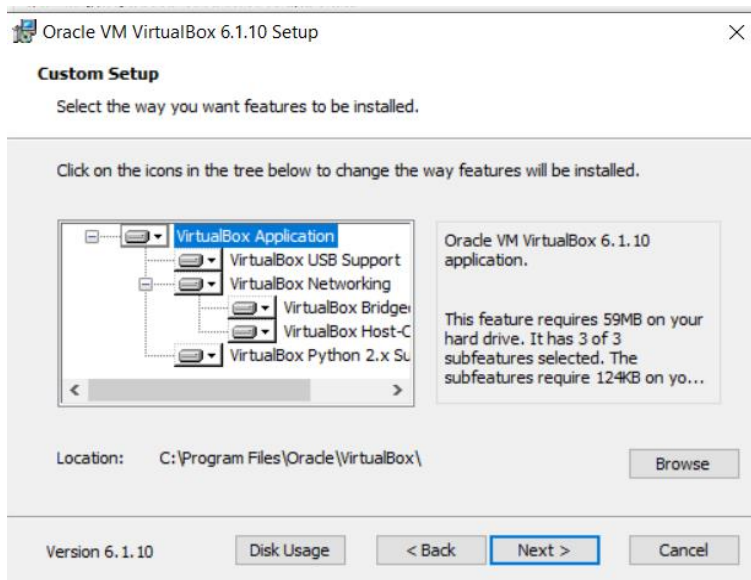
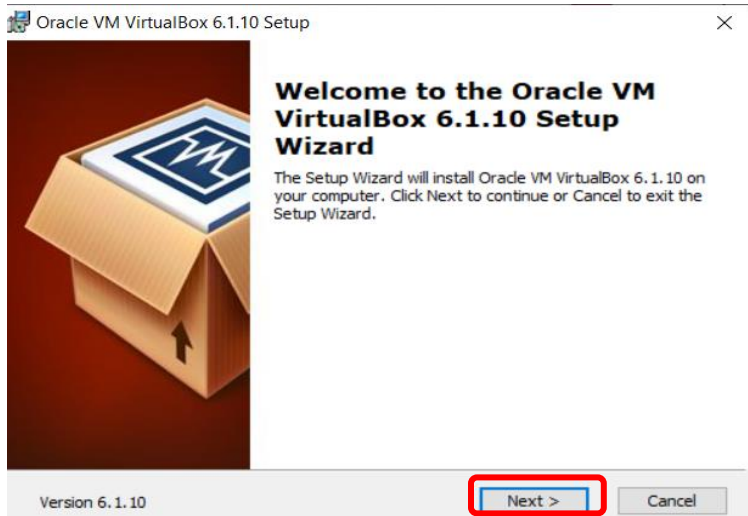
Step 1: Virtual Machine

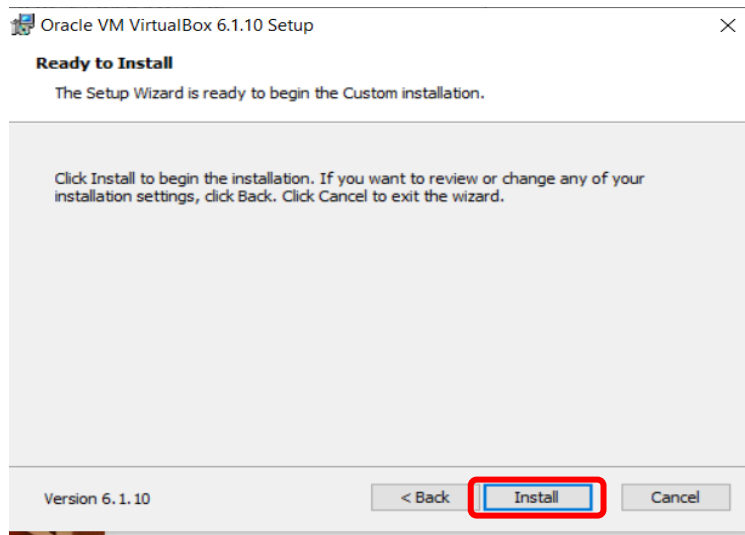
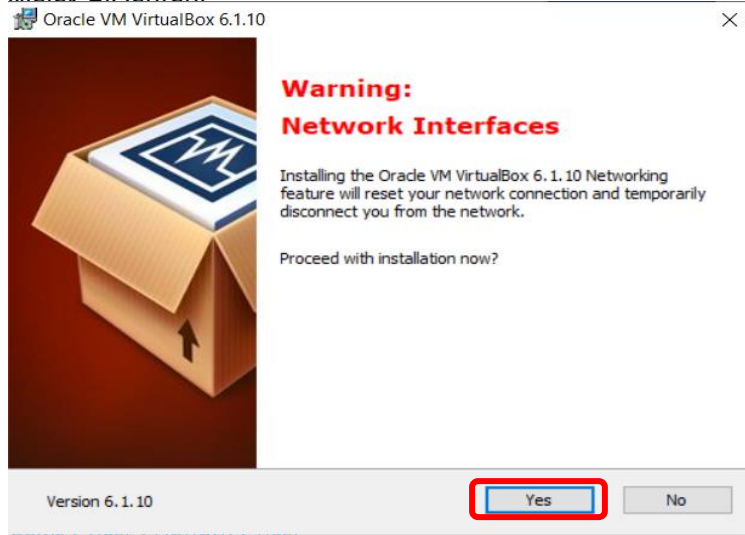
Step 1.1: download the VirtualBox

<https://www.virtualbox.org/wiki/Downloads>



¹ <https://towardsdatascience.com/what-why-and-how-of-ros-b2f5ea8be0f3>

Step 1.2: Install the VirtualBox

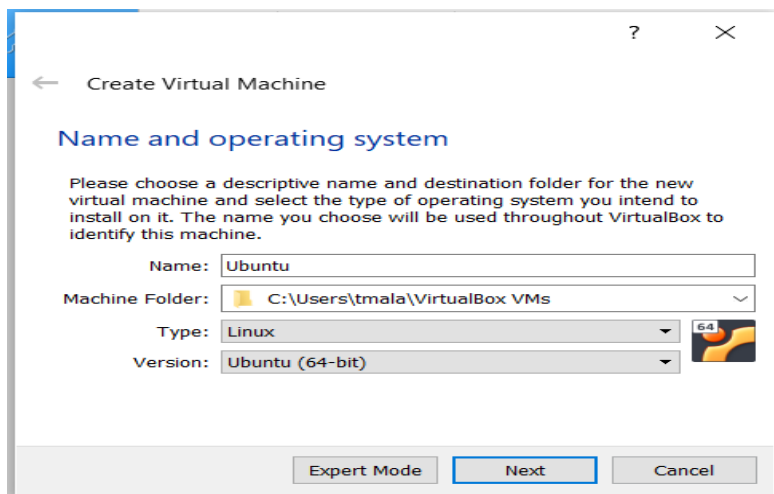
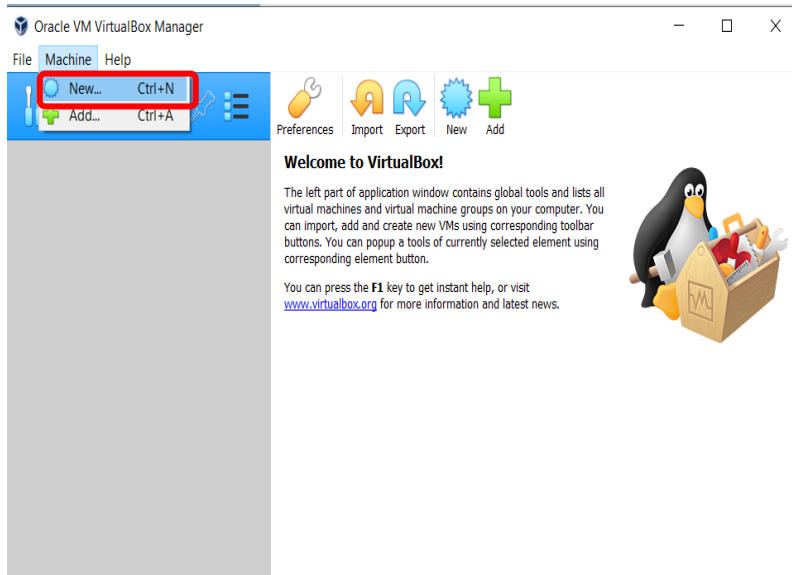


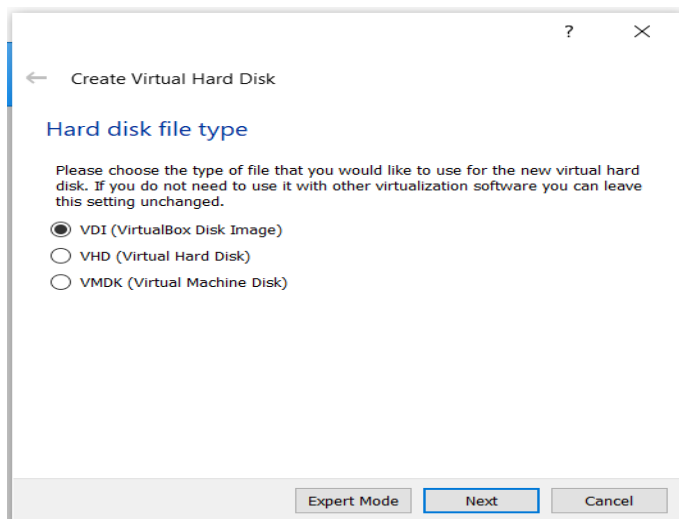
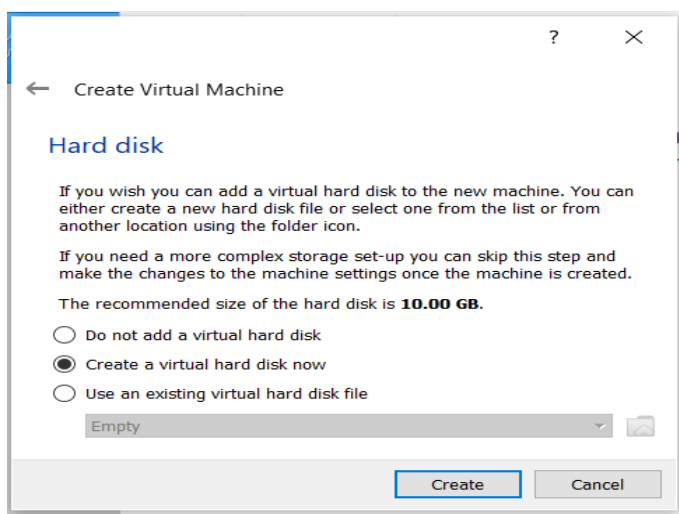
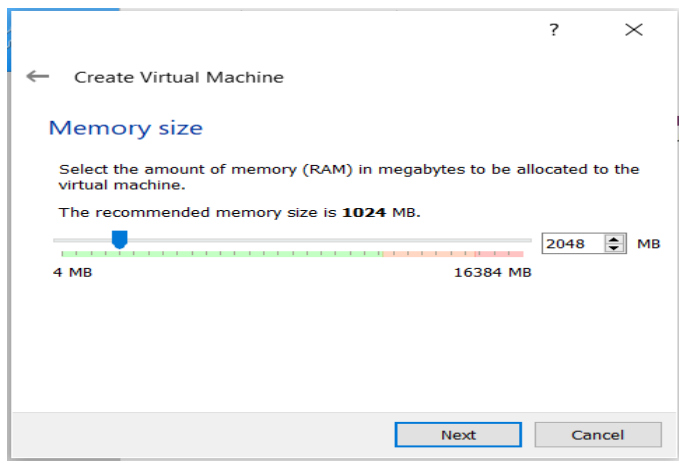
Step 2: Create Virtual Machine

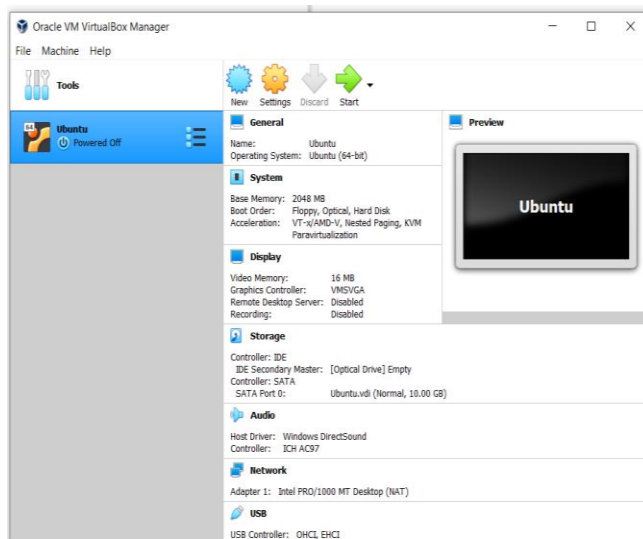
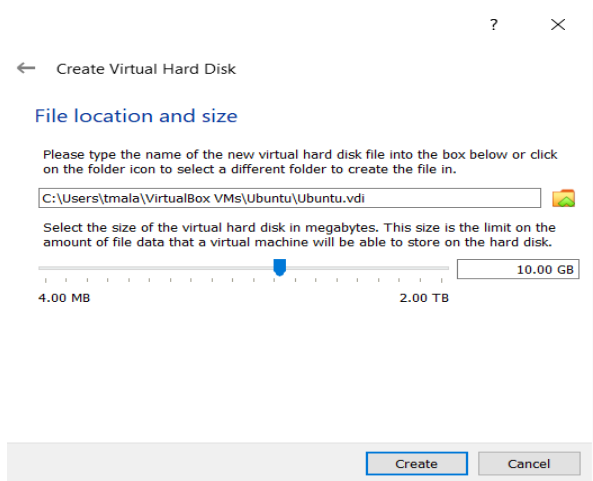
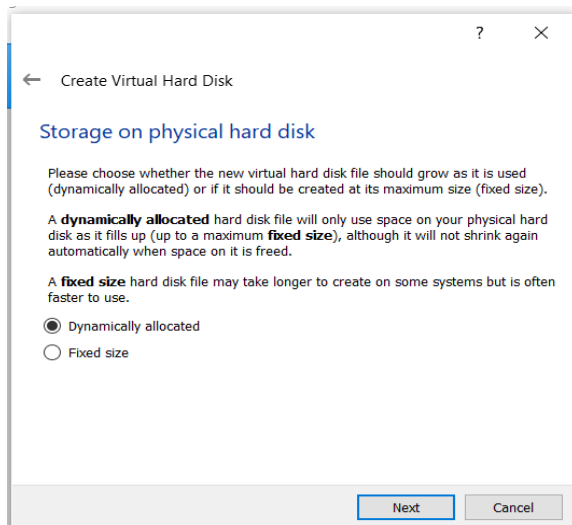
Step 2.1: download the Ubuntu

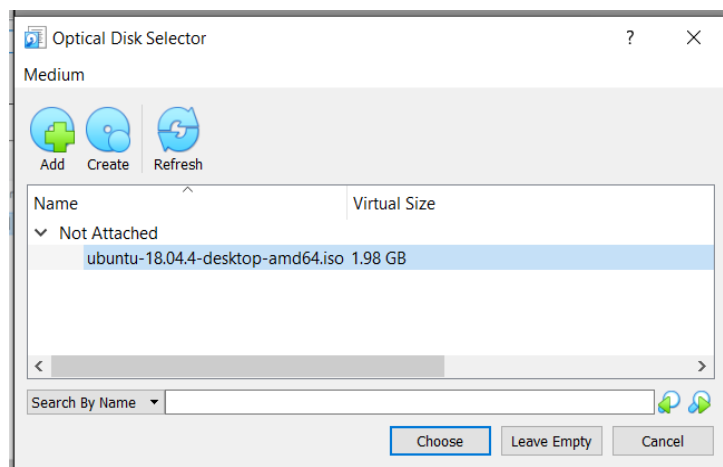
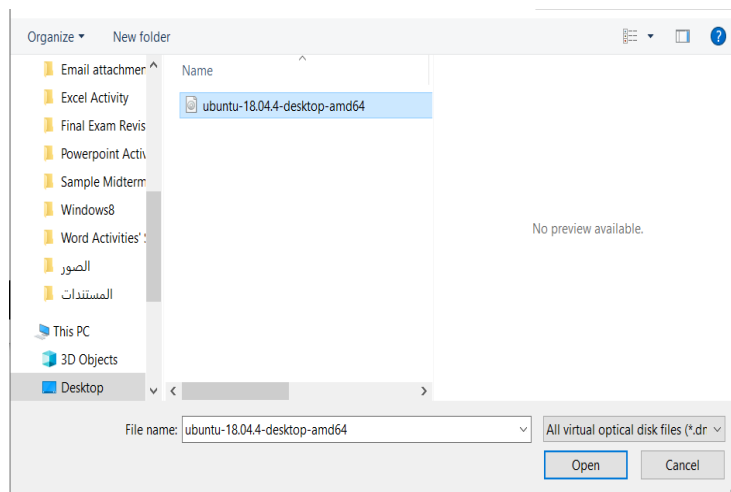
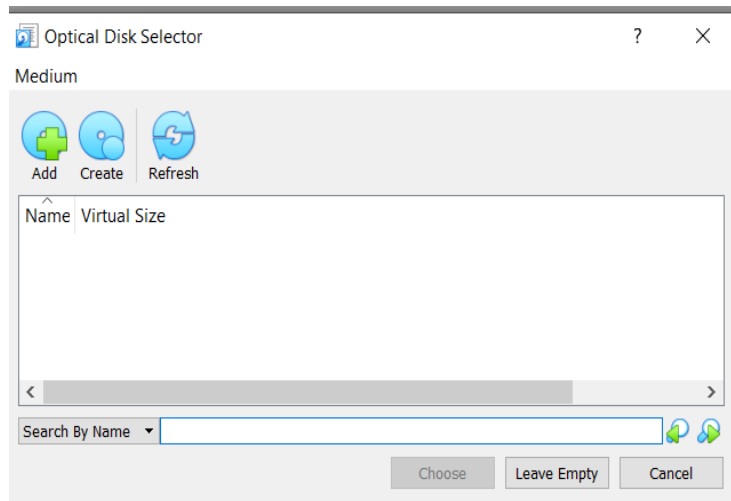
<https://releases.ubuntu.com/18.04//ubuntu-18.04.4-desktop-amd64.iso>

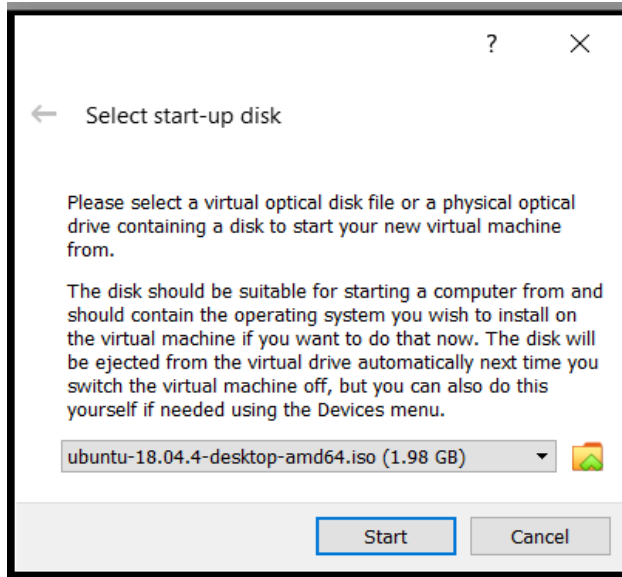
Step 2.2: install the Ubuntu on VirtualBox







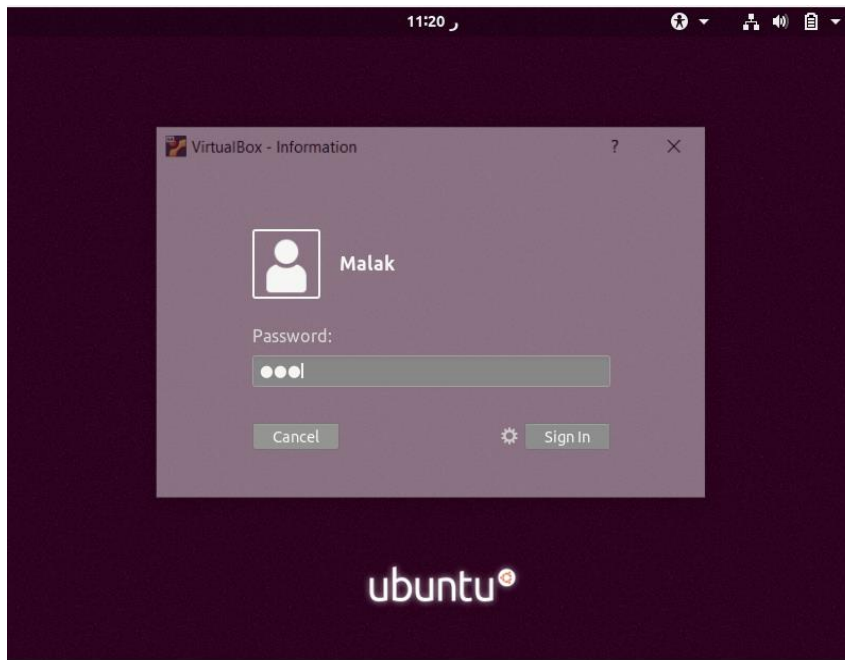




Then select install ubuntu, language and zone

After that, define username and password

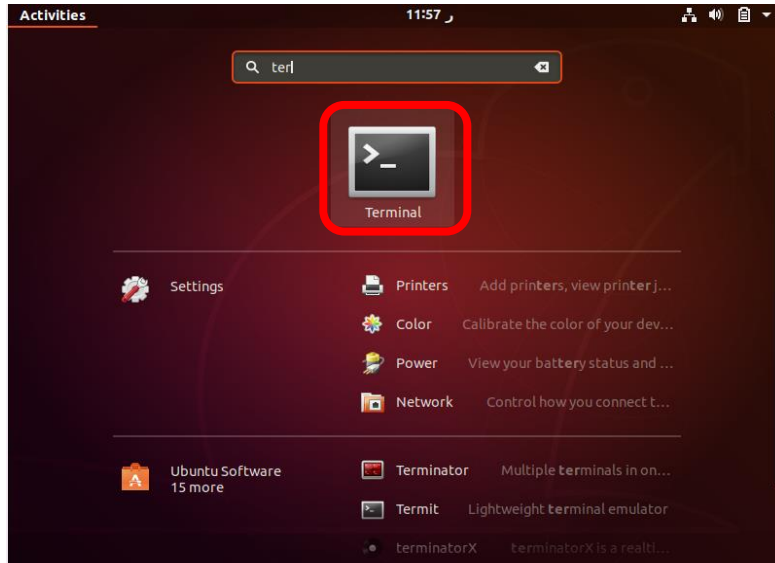
finally, restart the ubuntu



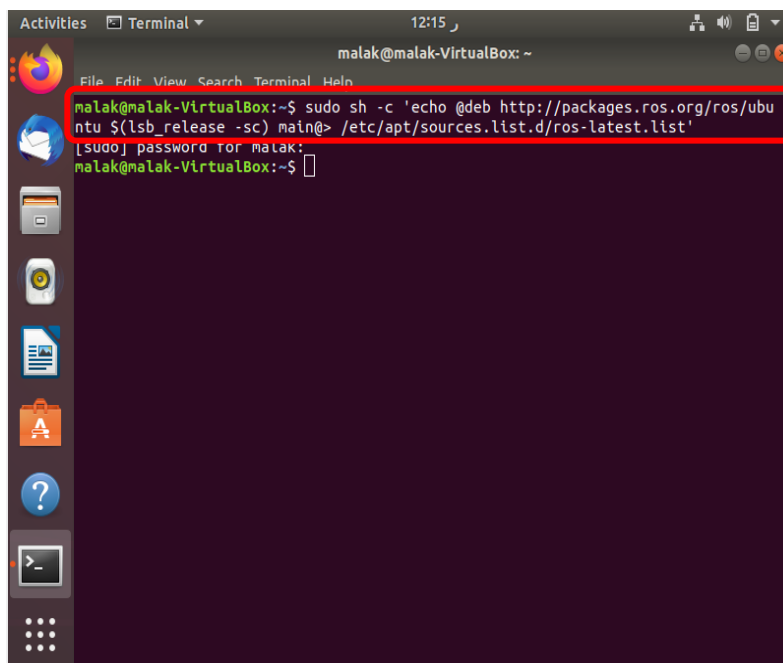
Step 3: Install ROS on Ubuntu

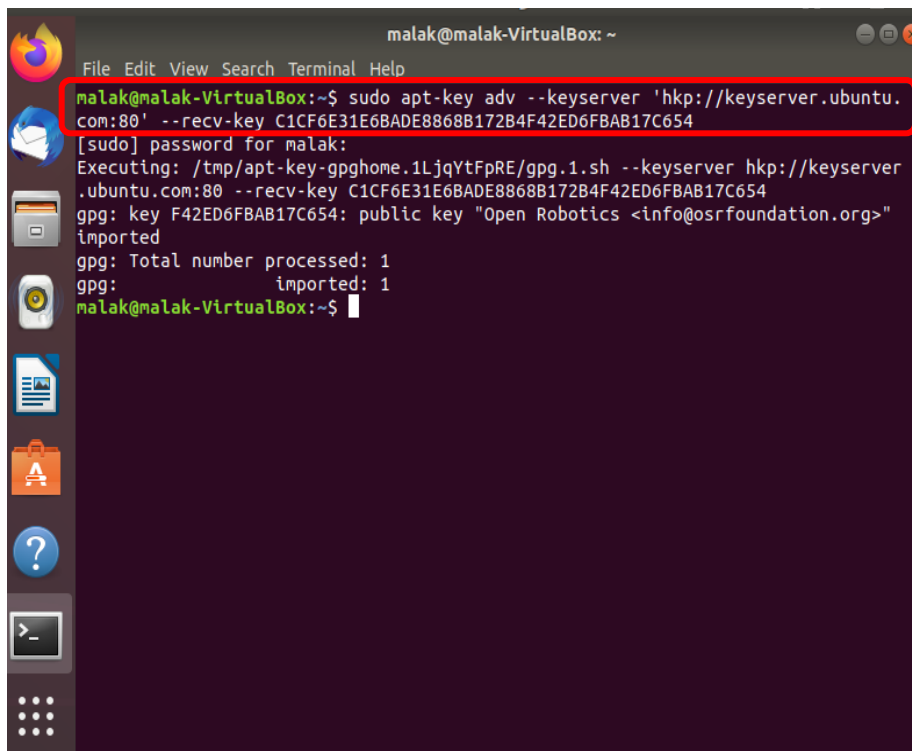
<http://wiki.ros.org/noetic/Installation/Ubuntu>

Step 3.1: open the terminal in Ubuntu



Step 3.2: Setup your sources.list



Step 3.3: Set up your keysA terminal window titled 'malak@malak-VirtualBox: ~' with a menu bar (File, Edit, View, Search, Terminal, Help). The terminal shows the command 'sudo apt-key adv --keyserver 'hkp://keyserver.ubuntu.com:80' --recv-key C1CF6E31E6BADE8868B172B4F42ED6FBAB17C654' highlighted with a red box. The output shows the key being imported successfully.

```
malak@malak-VirtualBox:~$ sudo apt-key adv --keyserver 'hkp://keyserver.ubuntu.com:80' --recv-key C1CF6E31E6BADE8868B172B4F42ED6FBAB17C654
[sudo] password for malak:
Executing: /tmp/apt-key-gpghome.1LjqYtFpRE/gpg.1.sh --keyserver hkp://keyserver.ubuntu.com:80 --recv-key C1CF6E31E6BADE8868B172B4F42ED6FBAB17C654
gpg: key F42ED6FBAB17C654: public key "Open Robotics <info@osrfoundation.org>" imported
gpg: Total number processed: 1
gpg:      imported: 1
malak@malak-VirtualBox:~$
```

Step 3.4: Installation of ROS

```
malak@malak-VirtualBox:~$ curl -sSL 'http://keyserver.ubuntu.com/pks/lookup?op=get&search=0xC1CF6E31E6BADE8868B172B4F42ED6FBAB17C654' | sudo apt-key add -
OK
malak@malak-VirtualBox:~$
```

```
malak@malak-VirtualBox:~$ sudo apt update
Hit:1 http://sa.archive.ubuntu.com/ubuntu bionic InRelease
Get:2 http://sa.archive.ubuntu.com/ubuntu bionic-updates InRelease [88.7 kB]
Get:3 http://packages.ros.org/ros/ubuntu focal InRelease [4650 B]
Get:4 http://sa.archive.ubuntu.com/ubuntu bionic-backports InRelease [74.6 kB]
Get:5 http://packages.ros.org/ros/ubuntu focal/main i386 Packages [15.4 kB]
Get:6 http://sa.archive.ubuntu.com/ubuntu bionic-updates/main amd64 Packages [1008 kB]
Get:7 http://packages.ros.org/ros/ubuntu focal/main amd64 Packages [236 kB]
Get:8 http://security.ubuntu.com/ubuntu bionic-security InRelease [88.7 kB]
Get:9 http://security.ubuntu.com/ubuntu bionic-security/main amd64 Packages [781 kB]
Get:10 http://sa.archive.ubuntu.com/ubuntu bionic-updates/main i386 Packages [781 kB]
```

```
malak@malak-VirtualBox:~$ sudo apt-get install aptitude
Reading package lists... Done
Building dependency tree
Reading state information... Done
The following additional packages will be installed:
  aptitude-common libcwwidget3v5 libsigc++-2.0-0v5
Suggested packages:
  aptitude-doc-en | aptitude-doc apt-xapian-index debtags
  tasksel libcwwidget-dev
The following NEW packages will be installed:
  aptitude aptitude-common libcwwidget3v5
  libsigc++-2.0-0v5
0 upgraded, 4 newly installed, 0 to remove and 244 not upgraded.
Need to get 2580 kB of archives.
After this operation, 10.9 MB of additional disk space will be used.
Do you want to continue? [Y/n]
```

```
malak@malak-VirtualBox:~$ sudo aptitude install ros-noetic-desktop-full
The following NEW packages will be installed:
  autoconf{a} automake{a} autopoint{a} autotools-dev{a} binfmt-support{a}
  blt{a} build-essential{a} bzip2-doc{a} cmake{a} cmake-data{a} cython{a}
  debhelper{a} default-libmysqlclient-dev{a} dh-autoreconf{a} dh-python{a}
  dh-strip-nondeterminism{a} docutils-common{a} dpkg-dev{a} fakeroot{a}
  fltk1.3-doc{a} fluid{a} fonts-lato{a} fonts-lyx{a} freeglut3{a}
  freeglut3-dev{a} g++{a} g++-7{a} gazebo11{ab} gazebo11-common{a}
  gazebo11-plugin-base{ab} gcc{a} gcc-4.8-base{a} gcc-7{a} gdal-data{a}
  gir1.2-gtk-2.0{a} gir1.2-harfbuzz-0.0{a} google-mock{a} googletest{a}
  graphviz{a} hddtemp{a} hdf5-helpers{a} i965-va-driver{a}
  ibverbs-providers{a} icu-devtools{a} ignition-tools{a}
  javascript-common{a} libaacs0{a} libaacs-dev{a} libaacs0{a}
```