

Implementing an HTML5 mobile simulation utilizing web workers

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Abstract—HTML5 introduced web workers as a way to utilize concurrent computation in the domain of web-based JavaScript applications. This paper follows the implementation of a computer physics simulation and compares the architectural decisions that can be applied to it. Different architectures with and without web workers are analysed and compared in terms of their performance metrics such as FPS, memory usage and message transfer time.

I. INTRODUCTION

The internet has progressed from a distributed document sharing system to a platform that can host computationally demanding applications. This evolution makes performance a crucial web-client requirement. The modern browser provides a possibility to develop intricate web applications utilizing only HTML, CSS and JavaScript. The developers of a web-based game, for example, need to optimize their code taking the processing capability of different browsers into account. Current hardware mostly focuses on concurrent execution while many web applications still only use the main browser thread. HTML5 introduced web workers as a first step towards concurrent execution in web applications. [1]

Web workers offload processing tasks from the main browser thread to background worker threads, requiring the platform to have basic support for concurrency. The communication between the threads is facilitated with message sending. Web workers can not use DOM operations or access window objects and parent objects. Also, direct data sharing between the main thread and the worker threads is not possible. The process of main thread web worker communication is illustrated in Figure 1. [1], [2]

This paper follows and compares the architecturally different implementations of a computer physics simulation. These architectures apply different ways to implement a web-based application with and without

web workers. The comparison is done with respect to performance metrics such as FPS, memory usage and message transfer time. After this introduction, section II of this paper covers the literature and studies related to web workers. Section III describes all the physics simulation implementations made for the purposes of this research paper. Section IV evaluates and compares the performance of these implementations and Section V concludes this paper.

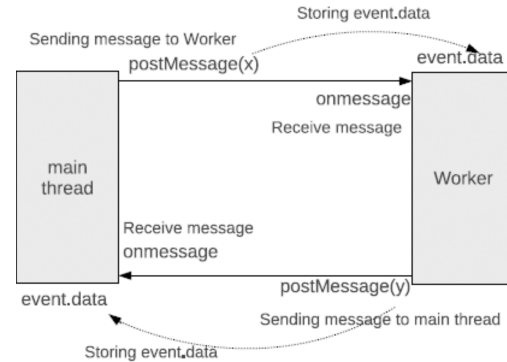


Fig. 1. Communication between the main thread and worker threads [2].

II. RELATED WORK

For web-based games, Erbad et al. [1] propose a concurrent processing solution called DOHA, which consists of game event-loops running in worker threads and MultiProc, which is the module for scheduling, state management and other concurrent execution related tasks. Their game implementation had three main components: simulation, graphics rendering and AI. The main thread handles rendering and offloads game event processing to web workers. This communication also requires the sending of state information. In general, DOHA offered better scalability and responsiveness across different platforms. However, thread communication required replicating state across workers, which increased jitter.

Zhang et al. [3] introduce WWOFF, which is a framework for seamlessly offloading web workers to the cloud. On average, the framework achieved energy savings of 85% on devices such as mobile phones, desktop computers and pads. The performance of the devices improved by a factor of 2-4.

Verdú et al. [4] examine how utilizing web workers scales the performance of a JavaScript application. They found that the optimal number of workers depends on various factors such as the CPU architecture and the browser. Using a large number of web workers did not prove to be beneficial compared to using only a few.

III. IMPLEMENTATION

This section covers the different architectures of the physics simulation application implemented in this paper. The main idea of the simulation is to generate a given amount of spherical objects and simulate their interactions via a graphical interface. These objects have attributes such as position, radius, velocity and acceleration. The physics of the application includes simulating explosions and collisions between the objects.

A. Default simulation

The first implementation of the physics simulation only utilized the main thread in computation. This default architecture of the application implemented classes for the spherical objects, their interactions and the physics stage. A class utilizing the PIXI JavaScript library was implemented for managing the game loop, rendering and physics simulation objects.

B. Spatial partitioning

The first architectural decision only optimized the simulation by partitioning the physics space and it did not yet include web workers.

C. One worker solution

After the spatial partitioning solution, an implementation with a single web worker communicating with the main thread was made. This version initialized the objects used in physics simulation only in the worker thread. The worker thread executed the simulation and communicated the state information to the main thread via the messaging interface. The only responsibility of the main thread was then to read the received information and render the graphics accordingly.

IV. EVALUATION

Here we present our evaluation of the implementation.

V. CONCLUSIONS

We conclude our research paper here.

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