CFS: System Verification and Validation Plan [good to see the library name in the title —SS]

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1 Revision History

Date	Version	Notes
Oct 16, 2018	1.0	First draft by Malavika
Oct 23, 2018	2.0	Second draft by Malavika

2 Symbols, Abbreviations and Acronyms

symbol	description
Т	Test

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[if you don't have any figures, you can comment out this heading —SS]

This document explains the verification and validation plan to improve the quality of CFS. It is organized into different sections which gives a detailed description of the CFS in terms of its goals, objectives, essential qualities and test cases for the functional and non functional requirements as mentioned in the CA document.

3 General Information

This section explains the summary of what is being tested in this document, the objectives of this document and references for this document.

3.1 Summary

This document will summarize the plan for verification and validation of CFS in compliance with the requirements specified in the CA document found at https://github.com/Malavika-Srinivasan/CAS741/tree/master/docs/SRS/CA.pdf [good to have a link to your repo. —SS] The goal statement as found in the CA document is presented below.

"Given the set of data points, the choice of software from CFS and the variabilities of the software the CFS should:

1. Compute the parameters of the curve which is the best possible fit through the set of data points. "

3.2 Objectives

The goal of verification and validation is to improve the quality of the CFS [I recently modified the blank project template to put the (equivalent of) the famname command in a common file, which can be shared between all your files. You might want to do the same. —SS]and obtain confidence in the software implementation. There are several standards which define software quality. According to the quality model of ISO 9126, software quality is described as a structured set of characteristics namely - Functional suitability, Performance, efficiency, Compatibility, Usability, Reliability, Security, Maintainability and Portability (ISO). The qualities which are important concerning CFS are correctness(functional suitability), maintainability, reusability and portability. The definitions of the above mentioned qualities are explained below.

[You still don't have lines of text that are 80 characters long (separated by hard returns) in the tex file. —SS]

3.2.1 Functional Suitability

This characteristic represents the degree to which a product or system provides functions that meet stated and implied needs when used under specified conditions. It can be further characterized into completeness, correctness and appropriateness. In this project, we focus only on correctness which is defined as shown below.

Correctness [do you mean for this to be a subsection (not a paragraph), like the other subsections? —SS] The degree to which a product or system provides the correct results with the needed degree of precision.

3.2.2 Maintainability

This characteristic represents the degree of effectiveness and efficiency with which a product or system can be modified to improve it, correct it or adapt it to changes in the environment, and in requirements.

3.2.3 Portability

The degree of effectiveness and efficiency with which a system, product or component can be transferred from one hardware, software or other operational or usage environment to another.

3.3 References

Throughout this document, we refer to the terminologies that have been already explained in the CA document for Program CFS. [Reference your SRS.—SS]

4 Plan

4.1 Verification and Validation Team

1. Malavika srinivasan

4.2 SRS Verification Plan

The CA document for CFS will be reviewed by Dr. Spencer Smith [IATEX has a rule that it inserts two spaces at the end of a sentence. It detects a sentence as a period followed by a capital letter. This comes up, for instance, with Dr. Smith. Since the period after Dr. isn't actually the end of a sentence, you need to tell IATEX to insert one space. You do this either by Dr. Smith (if you don't mind a line-break between Dr. and Smith), or Dr. Spencer Smith (to force IATEX to not insert a line break). —SS] and my classmate Mr. Robert White.

4.3 Design Verification Plan

My design will be verified with the help of my supervisor Dr. Spencer Smith and my classmates Ms. Jennifer Garner and Mr. Brooks MacLachlan. [Good to list the specific people. You should also split this up between the MG and the MIS.—SS]

4.4 Implementation Verification Plan

My implementation will be verified by the tests listed in this document and the unitVnVplan document. My classmate Ms. Vajiheh Motamer will help me verify the document.

4.5 Software Validation Plan

Not Applicable [why not? —SS]

5 System Test Description

System testing is a process in which we test the overall working of the system. The instance models in CA document will be tested here. This does not test the individual units or modules of the system. It is a black box testing approach.

5.1 Tests for Functional Requirements

[It would be nice to have a blurb here to explain why the subsections below cover the requirements. References to the SRS would be good. —SS]

5.1.1 Input Testing

[It would be nice to have a blurb here to explain why the subsections below cover the requirements. References to the SRS would be good. —SS]

1. T1: Test case for inputs with less than 2 points

Control: Automatic

Initial State: NA

Input: t=[1], y=[2] (length 1)

Output: Error message ("Please enter at least [proof read —SS][Corrected

—Malavika] 2 points")

How test will be performed: Pytest

2. T2: Test case for data type mismatch

Control: Automatic

Initial State: NA

Input: t=[1,2,3,4,t], y=[2,2,3,4,5]

Output: Error message ("Please enter only numbers") or TypeError

exception

How test will be performed: Pytest

3. T3: Test case for unordered inputs

Control: Automatic

Initial State: NA

Input: t=[1,2,5,4] , y=[2,0,3,4]

Output: Error message ("Wrong input: t_{i+1} must be greater than t_i ")

How test will be performed: Pytest

5.1.2 Interpolation Testing

[It would be nice to have a blurb here to explain why the subsections below cover the requirements. References to the SRS would be good. —SS]

4. T4: I^{st} test case for monomial interpolation

Control: Automatic

Initial State: NA

Input: Data points t = [0,1,2], y = [0,1,2]

Output: [0, 1] (Coefficients of t, starting from t^0 .)

How test will be performed: Pyunit

[How did you come up with the output? How does the reader verify this? A similar comment applies elsewhere in your documentation. —SS]

5. T5: II^{nd} test case for Monomial interpolation

Control: Automatic

Initial State: NA

Input: Data points t = [-2,0,1], y = [-27,-1,0]

Output: [-1,5,-4] (Coefficients of t, starting from t^0 .)

How test will be performed: Pytest

Test case reference: Page 314, example 7.1 of Heath (2002)

6. T6: I^{st} test case for Lagrange's interpolation

[You list first and second test cases, but why were they selected? Why does the second test case cover something different from the first? —SS]

Control: Automatic

Initial State: NA

Input: Data points t = [0,1,2], y = [0,1,2]

Output: [0, 1] (Coefficients of t, starting from t^0 .)

How test will be performed: Pyunit [You repeat this same test case several times, but for different algorithms. This is a good idea, but you should record this in a more efficient way. You can list the test case once and then reference it in the subsequent cases and simply say that it will be repeated, but for a different algorithm. You could summarize a much higher number of test cases if you used tables. —SS]

7. T7: II^{nd} test case for Lagrange's interpolation

Control: Automatic

Initial State: NA

Input: Data points t = [-2,0,1], y = [-27,-1,0]

Output: [-1,5,-4] (Coefficients of t, starting from t^0 .)

How test will be performed: Pytest

Test case reference: Page 314, example 7.1 of Heath (2002)

8. T8: I^{st} test case1 for Newton's interpolation

Control: Automatic

Initial State: NA

Input: Data points t = [0,1,2], y = [0,1,2]

Output: [0, 1] (Coefficients of t, starting from t^0 .)

How test will be performed: Pyunit

9. T9: II^{nd} test case for Newton's interpolation

Control: Automatic

Initial State: NA

Input: Data points t = [-2,0,1], y = [-27,-1,0]

Output: [-1,5,-4] (Coefficients of t, starting from t^0 .)

How test will be performed: Pytest

Test case reference: Page 314, example 7.1 of Heath (2002)

10. T10: I^{st} test case for hermite cubic interpolation

Control: Automatic

Initial State: NA

Input: t = [1,3], y = [2,1]

Output: [1,-5.75, 9.5, 2] (Coefficients of t, starting from t^0 .)

How test will be performed: Pytest

Test case reference: HermiteCubic (a)

11. T11: II^{nd} test case for hermite [Hermite —SS] cubic interpolation

Control: Automatic

Initial State: NA

Input: t = [1, 2, 4, 5], y = [2, 1, 4, 3]

Output:

[1.0,1.0, 1.38888889, 2.0] in [1,2), (Coefficients of t, starting from t^0 .)

[4.0, 4.0, 1.0, 1.0] in [2,4), (Coefficients of t, starting from t^0 .)

[3.0, 3.61111111, 4.0, 4.0] in [4,5), (Coefficients of t, starting from t^0 .)

How test will be performed: Pytest

Test case reference: HermiteCubic (b)

12. T12: I^{st} test case for BSpline interpolation

Control: Automatic

Initial State: NA

Input: t = [0.0, 1.2, 1.9, 3.2, 4.0, 6.5], y = [0.0, 2.3, 3.0, 4.3, 2.9, 3.1],

s=0, k=4

Output:

[-5.62048630e-18, 2.98780300e+00, -5.74472095e-01, 1.46700914e+01, -1.03253068e+01, 3.10000000e+00, 0.00000000e+00, 0.00000000e+00, 0.00000000e+00, 0.00000000e+00], (Coefficients of t, starting from t^0 .)

How test will be performed: Pytest

Test case reference: BSpline

13. T13: Test case 1 for evalMonomial

Type: Automatic

Initial State: NA

Input: [0,1], 2

Output: 2

Test Case Derivation: Please see inputs of T4 in section 5.1.1 in System

verification and validation plan.

How test will be performed: Pytest

14. T14: Test case 2 for evalMonomial

Type: Automatic

Initial State: NA

Input: [-1, 5, 4], -2

Output: -27

Test Case Derivation: Page 314, example 7.1 of Heath (2002).

How test will be performed: Pytest

15. T15: Test case 1 for evalLagrange

Type: Automatic Initial State: NA Input: [0,1,2], 1

Output: 1

Test Case Derivation: Please see inputs of T4 in section 5.1.1 in System

verification and validation plan.

How test will be performed: Pytest

16. T16: Test case 2 for evalLagrange

Type: Automatic

Initial State: NA

Input: [-27,-1,0], -2

Output: -27

Test Case Derivation: Page 314, example 7.1 of Heath (2002).

How test will be performed: Pytest

17. T17: Test case 1 for evalNewton

Type: Automatic

Initial State: NA

Input: [0,1], 2

Output: 2

Test Case Derivation: Please see inputs of T4 in section 5.1.1 in System

verification and validation plan.

How test will be performed: Pytest

18. T18: Test case 2 for evalNewton

Type: Automatic

Initial State: NA

Input: [-1, 5, 4], -2

Output: -27

Test Case Derivation: Page 314, example 7.1 of Heath (2002).

How test will be performed: Pytest

19. T19: Test case 1 for evalHermiteCubic

Type: Automatic Initial State: NA

Input:

[1, -5.75, 9.5, 2], [1,3][Interval to be read as 1 to 3 —Malavika], [1,3][Input x values —Malavika]

Output: [2,1][Output for each x value —Malavika]

Test Case Derivation: HermiteCubic (b)

How test will be performed: Pytest

20. T20: Test case 2 for evalHermiteCubic

Type: Automatic

Initial State: NA

Input:

[[1.0, 1.0, 1.38888889, 2.0]

[4.0, 4.0, 1.0, 1.0]

[3.0, 3.61111111, 4.0, 4.0]], [1,2,4,5][Interval to be read as 1 to 2, 2 to 4 and 4 to 5 —Malavika], [1,2,4,5] [Input x values —Malavika]

Output: [2, 1, 4, 3][Output for each x value —Malavika]

Test Case Derivation: HermiteCubic (b)

How test will be performed: Pytest

21. **T21:** Test case for evalBSpline

Type: Automatic

Initial State: NA

 $0.000000000e+00,\, 0.000000000e+00,\, 0.000000000e+00]],\, t=[\,0.0,\, 1.2,\, 1.9,\, 0.0000000000e+00]$

3.2, 4.0, 6.5

Output: [0.0, 2.3, 3.0, 4.3, 2.9, 3.1]

Test Case Derivation: BSpline

How test will be performed: Pytest

5.1.3 Regression Testing

22. **T22**: I^{st} test case for regression using normal equations

Control: Automatic

Initial State: NA

Input: t = [0,1,2,3,4,5,6,7,8,9,10], y = [0,1,2,3,4,5,6,7,8,9,10], deg = 1

Output: 0,1 (Coefficients of t, starting from t^0 .)

How test will be performed: Pytest

23. T23: II^{nd} test case for regression using normal equations

Control: Automatic

Initial State: NA

Input: Data points t = [1,2,3], y = [1,3,7], deg = 1

How test will be performed: Pytest

 $Test\ case\ reference : \ Normal Equations$

24. T24: III^{rd} test case for regression using normal equations

Control: Automatic

Initial State: NA

Input: t = [0.200, 400, 600, 800], y = [0.0010, 0.0015, 0.0021, 0.0051,

0.0094], degree = 2

Output: 0.00116857142857, -0.00000408571429, 0.00000001785714 (Co-

efficients of t, starting from t^0 .)

How test will be performed: Pytest

Test case reference: NormalEquations

25. T25: I^{st} test case for regression using augmented systems

Control: Automatic

Initial State: NA

Input: Data points t = [0,1,2,3,4,5,6,7,8,9,10], y = [0,1,2,3,4,5,6,7,8,9,10],

degree = 1

Output: 0,1 (Coefficients of t, starting from t^0 .)

How test will be performed: Pytest

26. T26: IInd test case for regression using augmented systems

Control: Automatic

Initial State: NA

Input: Data points t = [1,-1,-2], y = [3,-5,12]

Output: -8, 4, 7 (Coefficients of t, starting from t^0 .)

How test will be performed: Pytest

 $Test\ case\ reference:\ Augmented Equations$

27. T27: I^{st} test case for regression using orthogonal transformations

Control: Automatic

Initial State: NA

Input: Data points t = [0,1,2,3,4,5,6,7,8,9,10], y = [0,1,2,3,4,5,6,7,8,9,10]

Output: 0,1 (Coefficients of t, starting from t^0 .)

How test will be performed: Pytest

28. T28: II^{nd} test case for regression using orthogonal transformations

Control: Automatic

Initial State: NA

Input: Data points t = [1,2,3,4], y = [5,3,2,1], degree = 1

Output: 6,-1.3 (Coefficients of t, starting from t^0 .)

How test will be performed: Pytest

Test case reference: Page 4 and 5 of OrthogonalTransformations

29. T29: Test case for evalReg

Control: Automatic

Initial State: NA

Input: [-8, 4, 7],-2

Output: 12

How test will be performed: Pytest

Test case reference: AugmentedEquations

5.2 Tests for Nonfunctional Requirements

30. T20: Test case for correctness

Type: Nonfunctional, Manual, Parallel testing

Initial State: NA

Input/Condition: Results from Matlab for T4, T6, T9, T10, T12, T14, T16 and T19 will be manually compared using relative error by the formula below.

$$err = \frac{val_{CFS} - val_{Matlab}}{val_{CFS}}$$

 $err < Admissible_error$

[good test case —SS]

ADMISS_ERR is available in appendix section. [This isn't a good symbol. A constant like this should be in all caps and it won't space out properly. Use something like ADMISS_ERR. —SS]

Output/Result: Pass/Fail [The output should be the expected result. Since you are summarizing multiple test cases at once, you could think of your output as a table of all of the relative errors, or you could report the maximum relative error (infinity norm.) —SS

How test will be performed: Manual

31. **T21:** Test case for maintainability

Type: Nonfunctional, Manual

Initial State: NA

Input: Module guide, Module Interface specification

Steps:

- (a) Choose participants
- (b) Assign a task such as changing the secret of a module
- (c) Give the participants MG and MIS
- (d) Ask them to find, which module undergoes change.

This will help in accessing the maintainability of the software by measuring the ability to undergo change.

Output: Pass/Fail

How test will be performed: Manual [I like this test case experiment.—SS]

32. **T22**: Test case for Portability

Type: Nonfunctional, Manual

Initial State: NA

Input/Condition: Try and run CFS in Mac, Windows and Linux using

virtual machines.

Output/Result: Pass/Fail

How test will be performed: Manual

5.3 Traceability Between Test Cases and Requirements

The following table shows the traceability mapping for test cases, instance models and the requirements.

Table 1: Requirements Traceability Matrix

Test Number	Instance Models	CA Requirements
T1		R1, R3
T2		R1, R2
Т3		R1, R3
T4	IM1,IM3	R4, R5, R6, R9, R10
T5	IM1,IM3	R4, R5, R6, R9, R10
Т6	IM1, IM4	R4, R5, R6, R9, R10
T7	IM1, IM4	R4, R5, R6, R9, R10
Т8	IM1,IM5	R4, R5, R6, R9, R10
Т9	IM1, IM5	R4, R5, R6, R9, R10
T10	IM2, IM6	R4, R5, R7, R9, R10
T11	IM2, IM6	R4, R5, R7, R9, R10
T12	IM2, IM7	R4, R5, R7, R9, R10
T13	IM8	R4, R8, R9, R10
T14	IM8	R4, R8, R9, R10
T15	IM8	R4, R8, R9, R10
T16	IM9	R4, R8, R9, R10
T17	IM9	R4, R8, R9, r10
T18	IM10	R4, R8, R9, R10
T19	IM10	R4, R8, R9, R10
T20		R12
T21		R13
T22		R11

6 Static Verification Techniques

Code walkthrough and inspection will be used to verify the implementation.

7 Appendix

7.1 Symbolic Parameters

The definition of the test cases will call for SYMBOLIC_CONSTANTS. Their values are defined in this section for easy maintenance.

• $ADMISS_ERR = 1 \times 10^{-1}$

[You should write numbers properly 1×10^{-1} —SS][Changed —Malavika]

References

An overview of the iso 9126-1 software quality model definition, with an explanation of the major characteristics. URL https://en.wikipedia.org/wiki/ISO/IEC_9126#cite_note-2.

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