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SE  $A = A^T$  (MATRICI QUADRATE) ALLORA  $A$  E' DIAGONALIZZABILE.

$A = V \Lambda V^{-1}$  PER UNA CERTA  $V$  MATRICE INVERTIBILE  $\in \mathbb{R}^{n \times n}$

DIAGONALIZZABILE DI  $A$   $\Lambda$  MATRICE DIAGONALE

MATRICI SIMMETRICHE ( $A = A^T$ )

TEOREMA SPECTRALE  $\leadsto$  LA DIAGONALIZZAZIONE E' DATA DA:

$$A = V \Lambda V^{-1} \quad V \text{ PUO' ESSERE SCELTA } \underline{\text{ORTOGONALE}}$$

SE SI SCEGLIE UNA  $V$  ORTOGONALE CHIAMAMO  $X$  QUESTA MATRICE

$$V \text{ COME } A = X \Lambda X^T$$

ESEMPIO

$$A \in \mathbb{R}^{3 \times 3}$$

$$A = \begin{pmatrix} 2 & 1 & 0 \\ 1 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix} \quad A = A^T, \text{ E' SIMMETRICA}$$

$$\det(A - \lambda I) = \det \begin{pmatrix} 2-\lambda & 1 & 0 \\ 1 & 2-\lambda & 0 \\ 0 & 0 & 2-\lambda \end{pmatrix} = \lambda \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \det \begin{pmatrix} 2-\lambda & 1 & 0 \\ 1 & 2-\lambda & 0 \\ 0 & 0 & 2-\lambda \end{pmatrix}$$

$$= (2-\lambda) \begin{vmatrix} 2-\lambda & 1 \\ 1 & 2-\lambda \end{vmatrix} = (2-\lambda) [(2-\lambda)^2 - 1] =$$

$$= (2-\lambda) \cdot [\lambda^2 - 4\lambda + 3] = (2-\lambda)(\lambda-1)(\lambda-3)$$

$$L=1 \quad \begin{pmatrix} 2 & 1 & 0 \\ 1 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix} - \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{cases} x_1 + x_2 = 0 \\ x_1 + x_2 = 0 \\ x_3 = 0 \end{cases} =$$

$$= \begin{cases} x_2 = -x_1 \\ x_3 = 0 \end{cases} = \underline{v}_1 \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$$

$$L_2=2 \quad \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \rightsquigarrow \begin{cases} x_2 = 0 \\ x_1 = 0 \\ 0 = 0 \end{cases} \sim \underline{v}_2 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$L_3=3 \quad \begin{pmatrix} -1 & 1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \rightsquigarrow \begin{cases} -x_1 + x_2 = 0 \\ x_1 - x_2 = 0 \\ -x_3 = 0 \end{cases} \sim \underline{v}_3 \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

$$\Lambda = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix} \quad \underline{V} = \begin{pmatrix} 1 & 0 & 1 \\ -1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

ESSENDO  $A$  SIMMETRICA NON  
DEVE FARE L'INVERSA

NON ABBIAMO  
CARTESE, POSSIAMO  
ORDINARE COME VOGLIAMO

ATTENZIONE PERO': D'FACILE  
L'INVERSA D'IL MESSAGGIO, CHE  
VEURAMO DORO

$$A = \underline{V} \Lambda \underline{V}^{-1} \quad \tilde{\Lambda} = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \quad \tilde{V} = \begin{pmatrix} 1 & 1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= \tilde{V} \tilde{\Lambda} \tilde{V}^{-1}$$

$A$  SIMMETRICA  $\Rightarrow \exists A = X \Delta X^T$  con  $X$  ORTOGONALE

$$X = \left( \underline{x_1} \mid \underline{x_2} \mid \underline{x_3} \right)$$

$$\underline{x_1} \perp \underline{x_2} \perp \underline{x_3} \quad \|\underline{x_1}\|_2 = \|\underline{x_2}\|_2 = \|\underline{x_3}\|_2 = 1$$

SE NON VOGLIAMO FARE L'INVERSA DOBBIAMO FARE:

$$V = \begin{pmatrix} 1 & 0 & 1 \\ -1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \quad \left. \begin{array}{l} \|\underline{v_1}\| = \sqrt{2} \\ \|\underline{v_2}\| = 1 \\ \|\underline{v_3}\| = \sqrt{2} \end{array} \right\} X = \begin{pmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & 1 & 0 \end{pmatrix}$$

$$\underline{v_1} = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} \quad \underline{v_2} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} \quad \begin{array}{l} \underline{v_1}^T \underline{v_2} = 0 \\ \underline{v_1}^T \underline{v_3} = 0 \\ \underline{v_2}^T \underline{v_3} = 0 \end{array}$$

$$\boxed{X^{-1} = X^T}$$

$$\frac{\underline{v_1}}{\|\underline{v_1}\|} = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \\ 0 \end{pmatrix} \quad \left\| \frac{\underline{v_1}}{\|\underline{v_1}\|} \right\|_2 = \left\| \frac{1}{\|\underline{v_2}\|_2} \underline{v_2} \right\|_2 = \frac{\|\underline{v_1}\|_2}{\|\underline{v_1}\|_2} = 1$$

ALTRO ESEMPIO:

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \quad A = A^T \text{ SIMMETRICA} \quad \text{HA RANGO } 1$$

$$\det(A - \lambda I) = \begin{vmatrix} 1-\lambda & 1 & 1 \\ 1 & 1-\lambda & 1 \\ 1 & 1 & 1-\lambda \end{vmatrix}$$

$$= (1-\lambda) \begin{vmatrix} 1-\lambda & 1 \\ 1 & 1-\lambda \end{vmatrix} - 1 \begin{vmatrix} 1 & 1 \\ 1 & 1-\lambda \end{vmatrix} + \begin{vmatrix} 1 & 1-\lambda \\ 1 & 1 \end{vmatrix}$$

$$= (1-\lambda) [(1-\lambda)^2 - 1] - [1-\lambda - 1] + [1 - (1-\lambda)] =$$

$$= (1-\lambda) [\lambda^2 - 2\lambda - 1] - [-\lambda] + [1 - 1 + \lambda] =$$

$$= \lambda \left[ (1-\lambda)(\lambda-2) + 2 \right] = \lambda [\lambda - 2 - \lambda^2 + 2\lambda + 2] =$$

$$= \lambda^2 (3 - 2\lambda)$$

$$\lambda = 0 \quad \text{multiple} \quad 2 \quad (\lambda^2 = 0)$$

$$\lambda = 3 \quad // \quad 1$$

$$\lambda = 3 \quad \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} - 3 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix}$$

$$= \begin{cases} -2x_1 + x_2 + x_3 = 0 \\ x_1 - 2x_2 + x_3 = 0 \\ x_1 + x_2 - 2x_3 = 0 \end{cases}$$

$$x_1 - 2x_2 + x_3 = x_1 + x_2 \cdot 1 \cdot x_3$$

$$3x_3 = 3x_2$$

$$x_3 = x_2$$

$$-2x_1 + x_2 + \overset{x_3}{\sim} x_2 = -2x_1 = -2x_1 \Rightarrow \boxed{x_1 = x_2}$$

$$V_3 = \left\{ t \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \mid t \neq 0 \right\} \quad A \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = 3 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$L=0 \quad \text{Moltiplicando di 2}$$

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} - 0 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \rightsquigarrow \begin{cases} x_1 + x_2 + x_3 = 0 \\ \dots \dots \dots = 0 \\ \dots \dots \dots = 0 \end{cases}$$

$$A \rightarrow \ker(A) = \left\{ x \in \mathbb{R}^n : A \underline{x} = \underline{0} \right\}$$

$$\boxed{A \underline{x} = \underline{0}} \quad (\underline{x} \neq \underline{0}) \quad L=0 \quad \boxed{A \underline{x} = \underline{0} \quad \underline{x} = \underline{0}}$$

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \quad V_{(L=0)} = \left\{ \underline{x} \neq \underline{0} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3 : x_1 + x_2 + x_3 = 0 \right\}$$

$$\begin{array}{ccc} x_1, x_2 & \xrightarrow{\text{VINCOLO LINEARE}} & x_3 = -x_1 - x_2 \\ \underbrace{\hspace{1cm}} & & \underbrace{\hspace{1cm}} \\ \text{PARAMETRI} & & \text{PARAMETRI} \\ \text{LIBERI} & & \text{VINCOLATI} \end{array}$$

$$\text{SCEGLI } x_1, x_2$$

$$x_1 = 1, x_2 = 0 \Rightarrow x_3 = -1$$

$$x_1 = 0, x_2 = 1 \Rightarrow x_3 = -1$$

$$\boxed{V_{(L=3)} = \left\{ t \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} : t \neq 0 \right\} \quad \underline{v}_1 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}}$$

$$\underline{v}_2 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \quad \underline{v}_3 = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$

$$\underline{V}_{(L=0)} = \left\{ t \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + s \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \mid (t, s) \neq (0, 0) \right\}$$

$$A \underline{v}_2 = \underline{0} \quad A \underline{v}_3 = \underline{0} \quad A(t \underline{v}_2 + s \underline{v}_3) = \underline{0}$$

$$\underline{v}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \underline{v}_2 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \underline{v}_3 = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$

$\lambda=3$                        $\lambda=0$                        $\lambda=0$

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} = V \Lambda V^{-1} \quad \text{so } V = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

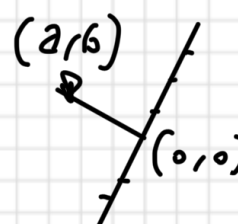
$$V = \left( \underline{v}_2 \mid \underline{v}_3 \mid \underline{v}_1 \right) \Rightarrow \left( \begin{array}{c|c|c} 1 & 0 & 1 \\ 0 & 1 & 1 \\ -1 & -1 & 1 \end{array} \right)$$

$\downarrow$   $\underline{v}_3$                        $\downarrow$   $\underline{v}_3$

non  $\perp$

Ortho basis  
 $\underline{v}_3 \perp \underline{v}_2$   
 $\underline{v}_3 \perp \underline{v}_1$  } CALCULATE  $V^{-1}$

$x_1 + x_2 + x_3 = 0$

$(a, b)$   


$2x + 6y = 0$

$(x, y) \in \mathbb{R}^2$   
 $\perp (a, b)$

$$x_1 - x_2 \geq 0 \quad \boxed{x_1 = x_2}$$

$$\left( \begin{array}{c|c|c} 1 & 1 & 1 \\ 0 & -2 & 1 \\ -1 & 1 & 1 \end{array} \right)$$

$$\begin{pmatrix} 1 & 0 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0 \quad \begin{cases} x_1 - x_3 = 0 \perp \underline{v}_1 \\ x_1 + x_2 + x_3 = 0 \end{cases}$$

$2x_1 + x_2 = 0$   
 $x_2 = -2x_1$

$$V = \left( \begin{array}{c|c|c} 1 & 1 & 1 \\ 0 & -2 & 1 \\ -1 & 1 & 1 \end{array} \right)$$

$\underline{v}_1$      $\underline{v}_2$      $\underline{v}_3$

$$\left. \begin{array}{l} \underline{v}_3 \perp \underline{v}_2 \\ \underline{v}_3 \perp \underline{v}_1 \\ \underline{v}_1 \perp \underline{v}_2 \end{array} \right\} \begin{cases} x_1 = \frac{\underline{v}_1}{\|\underline{v}_1\|_2} \\ x_2 = \frac{\underline{v}_2}{\|\underline{v}_2\|_2} \\ x_3 = \frac{\underline{v}_3}{\|\underline{v}_3\|_2} \end{cases}$$

$$X = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ 0 & -\frac{2}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \end{pmatrix}$$

$x_1$      $x_2$      $x_3$