

Assignment 1 Assignment 1

1

Using the code given in the appendix we created the scatterplot in figure 1.

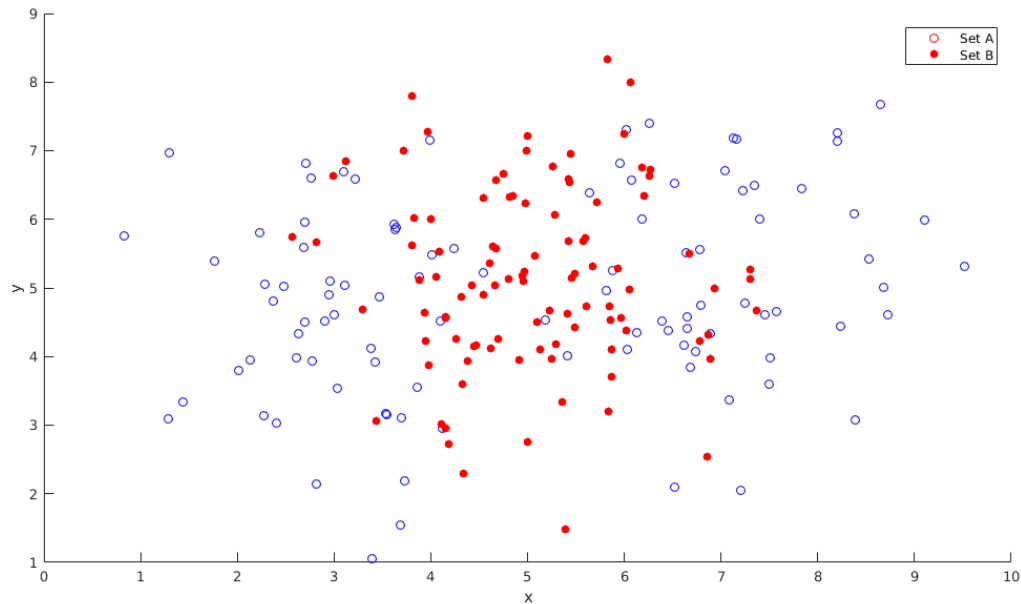


Figure 1: Scatterplot for the two classes.

The plot shows that there are at least three prototypes needed to approach a fairly well classification of these data. Two for set A, which should probably be located around $(3, 4.5)$ and $(7.5, 5.5)$, and one for set B somewhere around $(5, 5)$.

2

The code in the appendix shows our implementation of the LVQ1 algorithm. We acquired the following results for the different settings.

a 1 Prototype for class A and 1 prototype for class B

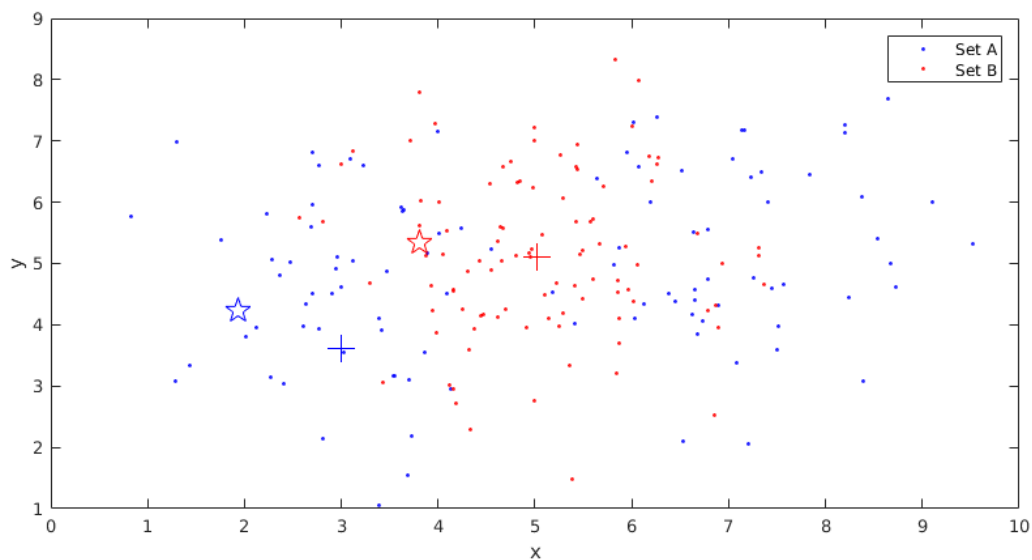


Figure 2: Scatterplot for the two classes.

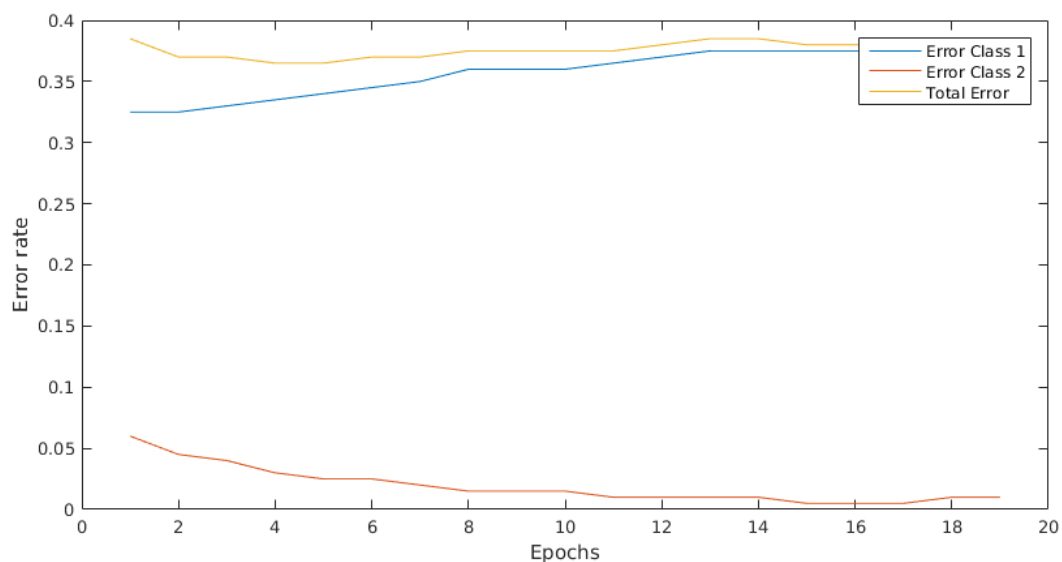


Figure 3: Training error rate to number of epochs.

As is expected with only one prototype per class, the prototype for class A is formed quite well, allowing it to correctly classify at least the data points that belong to class A. However, since class B is distributed in two groups, with A in between them, the prototype for class B is formed in the center of one of the two clusters, which means it can only correctly classify that cluster correctly. The other cluster will be incorrectly classified as class A.

b

Appendix

../Code/Ass1_1.m

```
1 hold off;
2 hold on;
3 scatter(matA(:,1),matA(:,2), 'blue');
4 scatter(matB(:,1),matB(:,2), 'red', 'filled');
5 xlabel('x'); ylabel('y'); legend('Set_A', 'Set_B');
```

../Code/Ass1_2.m

```
1 load('data_lvq_A') % matA
2 load('data_lvq_B') % matB
3
4 close all
5 figure;
6 plot(matA(:,1),matA(:,2), 'bp', 'markersize', 2);
7 hold on;
8 plot(matB(:,1),matB(:,2), 'rp', 'markersize', 2);
9 xlabel('x'); ylabel('y');
10 legend('Set_A', 'Set_B');
11
12 data = [matA ; matB];
13 data_labels = (floor((0:length(data)-1) * 2 / length(data))).';
14 data = [data data_labels];
15
16 % The prototypes
17 w_A = 1;
18 w_B = 1;
19 w = zeros(w_A + w_B, ndims(data)+1);
20
21 eta = 0.01;
22 nrEpochs = 500;
23
24 E_1 = zeros(1,nrEpochs);
25 E_2 = zeros(1,nrEpochs);
26
27 % Randomly initialize the prototypes between the minimum and maximum values
28 % last value being their class
29 for i = 1 : size(w,1)
30     if i <= w_A
31         w(i,:) = [mean(matA) + rand()*2*std(matA)-std(matA) 0];
32     else
33         w(i,:) = [mean(matB) + rand()*2*std(matB)-std(matB) 1];
34     end
35 end
36
37 plot(w(1:w_A,1), w(1:w_A,2), 'b+', 'markersize', 15);
38 plot(w(w_A+1:size(w,1),1), w(w_A+1:size(w,1),2), 'r+', 'markersize', 15);
39
40 for epoch = 1:nrEpochs
41     % Training
42     for point = 1 : size(data,1)
```

```

43     % Find the row with the nearest prototype
44     rowMin = find(pdist2(data(point,1:2), w(:,1:2)) == min(pdist2(data(point
45         ,1:2), w(:,1:2))),1);
46     % If the classes of the data point and the nearest prototype are the same
47     if w(rowMin,end) == data(point, end)
48         % Move the row closer to the data point
49         w(rowMin,1:2) = w(rowMin,1:2) + eta * (data(point,1:2) - w(rowMin,1:2));
50     else
51         w(rowMin,1:2) = w(rowMin,1:2) - eta * (data(point,1:2) - w(rowMin,1:2));
52     end
53 end
54 % Testing
55 for point = 1 : size(data,1)
56     % Find the row with the nearest prototype
57     rowMin = find(pdist2(data(point,1:2), w(:,1:2)) == min(pdist2(data(point
58         ,1:2), w(:,1:2))),1);
59     if w(rowMin,end) ~= data(point, end)
60         if point <= size(matA,1)
61             E_1(epoch) = E_1(epoch) + 1;
62         else
63             E_2(epoch) = E_2(epoch) + 1;
64         end
65     end
66 end
67 E = E_1 + E_2;
68 if (epoch > 10 && var(E(:,epoch-4:epoch)) < 0.05)
69     epoch
70     E_1(:,epoch+1:end) = [];
71     E_2(:,epoch+1:end) = [];
72     E(:,epoch+1:end) = [];
73     break
74 end
75 end
76
77 plot(w(1:w_A,1), w(1:w_A,2), 'bp', 'markersize', 15);
78 plot(w(w_A+1:size(w,1),1), w(w_A+1:size(w,1),2), 'rp', 'markersize', 15);
79
80 figure;
81 plot(E_1/200)
82 hold on;
83 plot(E_2/200);
84 plot(E/200);
85 legend('Training_Error_Class_1', 'Training_Error_Class_2', 'Total_training_Error');
86 xlabel('Epochs')
87 ylabel('Error_rate')

```

Pattern Recognition Practical 4

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