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**LAB 3**  
**DIGITAL SYSTEMS AND MICROCONTROLLERS**

**AIM:**

- 1) **Part A :** To design , assemble and test a multiplexer(4:1) also called as mux
- 2) **Part B :** To design , assemble and test a De-multiplexer (1:4) also called as demux
- 3) **Part C :** Combine Multiplexer and De-Multiplexer

**Theory:**

1) **MULTIPLEXER :**

A multiplexer (or mux) is a device that selects one of several analog or digital input signals and forwards the selected input into a single line. A multiplexer with  $2^n$  inputs has  $n$  select lines which are used to select which input line to send to the output .

2) **DE- MULTIPLEXER:**

A demultiplexer (or demux) is a device taking a single input signal and selecting one of many data-output-lines, which is connected to the single input. A multiplexer is often used with a complementary demultiplexer on the receiving end.

**ELECTRONIC COMPONENTS:**

- 1) Arduino
- 2) Led
- 3) Resistor
- 4) Breadboard
- 5) Integrated Circuits(OR gate , 3 input And gate , Not gate )

**REFERENCE CIRCUITS :**

- 1) **Part A :** <https://crcit.net/c/435c6dc135fa4a76a432111fdb71de91>
- 2) **Part B :** <https://crcit.net/c/6467d30c15ff41eb9001743fd80040d5>
- 3) **Part C :** <https://crcit.net/c/5db1b84c69f34173b111258cb0c12ce9>

**PROCEDURE:**

1) **Part A:**

- 1) A 4 to 1 multiplexer consists of two select lines( $S_0$  and  $S_1$ ) and 4 data input lines( $I_0$  to  $I_3$ ) and also a single output line( $Y$ ).The select lines select one of the input line( $D_0$  to  $D_3$ ) to connect to the output line.
- 2) As there are 2 select lines . The combination of them gives 00, 01,10,11.These are used to select the inputs ( $I_0$  to  $I_3$ ). That means that when  $S_0$  and  $S_1 = 0$  input  $I_0$  gives the output etc .Therefore  $Y = I_0(S_1)'(S_0)'$

when S1 and S0 = 0. Similarly I1 to I3 . Thus finally  $Y = I0(S1)'(S0)' + I1(S1)'(S0) + I2(S1)(S0)' + I3(S1)(S0)$ . This is possible iff our connections are made relevant to it . They may vary also.

**3)CODE:**

```
int S1,S2,I0,I1,I2,I3;
void setup()
{
  pinMode(7,OUTPUT);
  pinMode(6,OUTPUT);
  pinMode(5,OUTPUT);
  pinMode(4,OUTPUT);
  pinMode(3,OUTPUT);
  pinMode(2,OUTPUT);
  Serial.begin(9600); //sets the data rate to 9600 bps
}

void loop()
{
  Serial.print("S1=");
  while(Serial.available() == 0){}
  S1 = Serial.read();
  S1 = S1 - '0';
  Serial.println(S1);

  Serial.print("S2=");
  while(Serial.available() == 0){}
  S2 = Serial.read();
  S2 = S2 - '0';
  Serial.println(S2);

  Serial.print("I0=");
  while(Serial.available() == 0){}
  I0 = Serial.read();
  I0 = I0 - '0';
  Serial.println(I0);

  Serial.print("I1=");
  while(Serial.available() == 0){}
  I1 = Serial.read();
  I1 = I1 - '0';
  Serial.println(I1);
```

```

Serial.print("I2=");
while(Serial.available()==0){}
I2 = Serial.read();
I2=I2-'0';
Serial.println(I2);

```

```

Serial.print("I3=");
while(Serial.available()==0){}
I3 = Serial.read();
I3=I3-'0';
Serial.println(I3);

```

```

digitalWrite(2,S1);
digitalWrite(3,S2);
digitalWrite(4,I0);
digitalWrite(5,I1);
digitalWrite(6,I2);
digitalWrite(7,I3);

```

```

Serial.println("Enter the values again:");

```

```

}

```

## 2) Part B :

1) A 1 to 4 De-multiplexer consists of two select lines(S0 and S1) , 1 data input line(I) and 4 Output lines(y0 to y3) .

2) As there are two select lines which give combination such as 00,01,10,11.These specifically give output I for that specific combination . Example: S0 and S1 = 00 implies that only y0 gives I as output and remaining give 0 as output .This may or may not be based on our connections. Similarly others

3)CODE:

```

int S1,S2,I;
void setup()
{
  pinMode(4,OUTPUT);
  pinMode(3,OUTPUT);
  pinMode(2,OUTPUT);
  Serial.begin(9600);//sets the data rate to 9600 bps
}

void loop()

```

```

{
  Serial.print("S1=");
  while(Serial.available() == 0){}
  S1 = Serial.read();
  S1 = S1 - '0';
  Serial.println(S1);

  Serial.print("S2=");
  while(Serial.available() == 0){}
  S2 = Serial.read();
  S2 = S2 - '0';
  Serial.println(S2);

  Serial.print("I=");
  while(Serial.available() == 0){}
  I = Serial.read();
  I = I - '0';
  Serial.println(I);

  digitalWrite(2, S1);
  digitalWrite(3, S2);
  digitalWrite(4, I);

  Serial.println("Enter the values again:");

}

```

### 3) Part C :

1) Connect Multiplexer and De-Multiplexer in a fashion such that output Y of the multiplexer will be connected as the input I to the demultiplexer to give the outputs (y0 to y3) . And also connect the common ground and vcc to both multiplexer and demultiplexer .

2) CODE:

```

int S1, S2, I0, I1, I2, I3;
void setup()
{
  pinMode(7, OUTPUT);
  pinMode(6, OUTPUT);
  pinMode(5, OUTPUT);
  pinMode(4, OUTPUT);
  pinMode(3, OUTPUT);
  pinMode(2, OUTPUT);
  Serial.begin(9600); //sets the data rate to 9600 bps

```

```
}
```

```
void loop()
```

```
{
```

```
  Serial.print("S1=");  
  while(Serial.available()==0){}  
  S1 = Serial.read();  
  S1=S1-'0';  
  Serial.println(S1);
```

```
  Serial.print("S2=");  
  while(Serial.available()==0){}  
  S2 = Serial.read();  
  S2=S2-'0';  
  Serial.println(S2);
```

```
  Serial.print("I0=");  
  while(Serial.available()==0){}  
  I0 = Serial.read();  
  I0=I0-'0';  
  Serial.println(I0);
```

```
  Serial.print("I1=");  
  while(Serial.available()==0){}  
  I1 = Serial.read();  
  I1=I1-'0';  
  Serial.println(I1);
```

```
  Serial.print("I2=");  
  while(Serial.available()==0){}  
  I2 = Serial.read();  
  I2=I2-'0';  
  Serial.println(I2);
```

```
  Serial.print("I3=");  
  while(Serial.available()==0){}  
  I3 = Serial.read();  
  I3=I3-'0';  
  Serial.println(I3);
```

```
  digitalWrite(2,S1);  
  digitalWrite(3,S2);
```

```
digitalWrite(4,I0);
digitalWrite(5,I1);
digitalWrite(6,I2);
digitalWrite(7,I3);
```

```
Serial.println("Enter the values again:");
```

```
}
```

## CONCLUSION:

### 1) Part A :

S1	S2	Y
0	0	I3
0	1	I1
1	0	I2
1	1	I0

### 2) Part B :

S0	S1	y0	y1	y2	y3
0	0	I	0	0	0
0	1	0	I	0	0
1	0	0	0	I	0
1	1	0	0	0	I

### 3) Part C :

S0	S1	y0	y1	y2	y3
0	0	I0	0	0	0
0	1	0	I1	0	0
1	0	0	0	I2	0
1	1	0	0	0	I3

## LINK TO THE TINKERCAD SIMULATION :

### 1) Part A :

[https://www.tinkercad.com/things/1Tehh45mGX6-lab3-parta/editel?sharecode=PznEOBkGnnkUD8hzFzhvFB-\\_lk9magqM4f3rfh8uhl](https://www.tinkercad.com/things/1Tehh45mGX6-lab3-parta/editel?sharecode=PznEOBkGnnkUD8hzFzhvFB-_lk9magqM4f3rfh8uhl)

### 2) Part B :

<https://www.tinkercad.com/things/IMek3Q0W9ZF-lab3-partb/editel?sharecode=hABv6OQxehFcSRxy8T0hRtGYAmJ0-d3U1Lh7DTI6KqA>

### 3) Part C :

<https://www.tinkercad.com/things/e605m1xoqgE-lab3-partc/editel?sharecode=1rcg5fWHUC1DibPSxXNP2QLq5Xzlxg25KJTsOW6ozKE>

