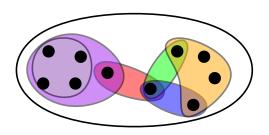


Evolutionary Hypergraph Partitioning

Presentation · **December 7, 2017 Robin Andre**

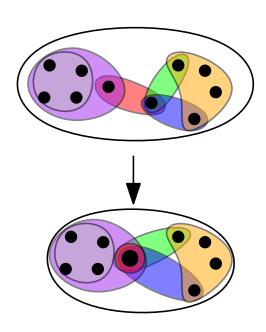
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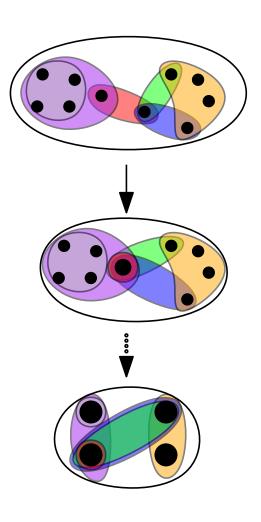
- lacktriangleright H is reduced to a smaller problem H_C
- only one node is contracted per step
- lacktriangleq until H_C is sufficiently small





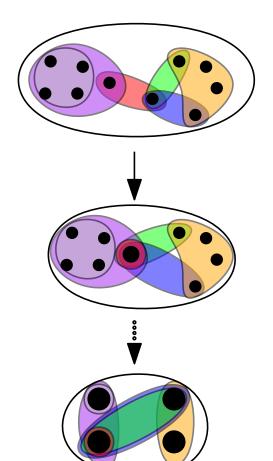
- lacktriangleright H is reduced to a smaller problem H_C
- only one node is contracted per step
- lacktriangle until H_C is sufficiently small





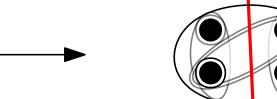
- lacktriangleright H is reduced to a smaller problem H_C
- only one node is contracted per step
- lacktriangleq until H_C is sufficiently small





Initial Partitioning:

An algorithm generates
 an Initial Partitioning for
 H_C

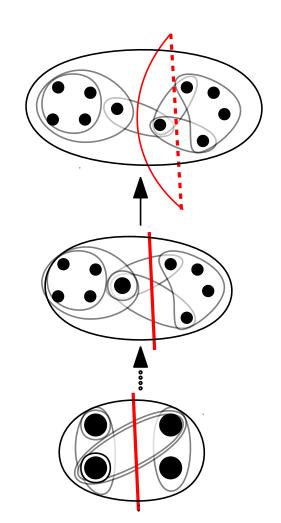




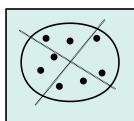
Refinement

- The coarsening steps are reverted
- Local search algorithms try to improve the solution



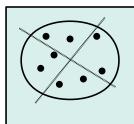






Population P



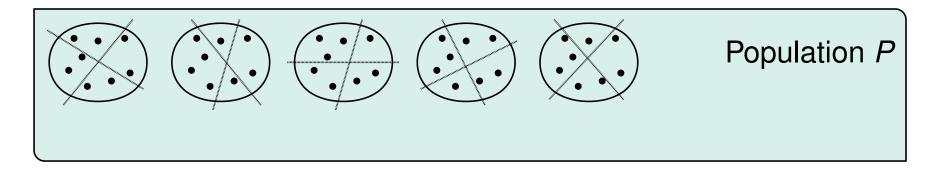


Population P

3.1s
$$time = 100s$$

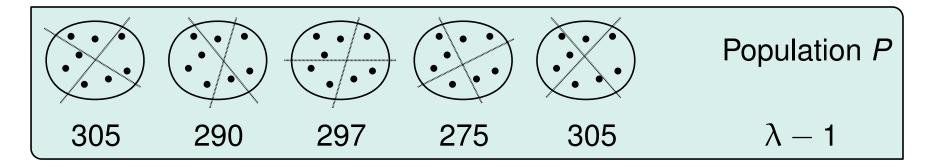
 \sim 5 iterations





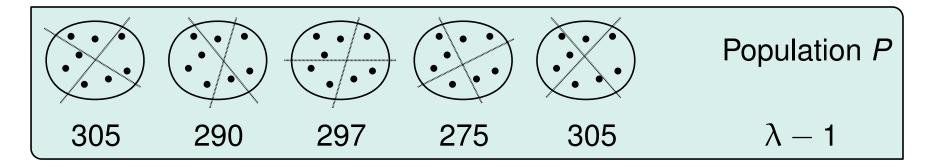
3.1s $time = 100s \longrightarrow \sim 5$ iterations





3.1s
$$time = 100s \longrightarrow \sim 5$$
 iterations



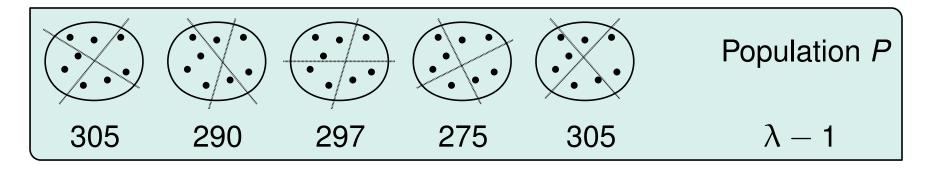


3.1s
$$time = 100s \longrightarrow \sim 5$$
 iterations

KaHyPar generates multiple partitions dynamic allocation $\delta = 15\%$

balances time/hypergraph size





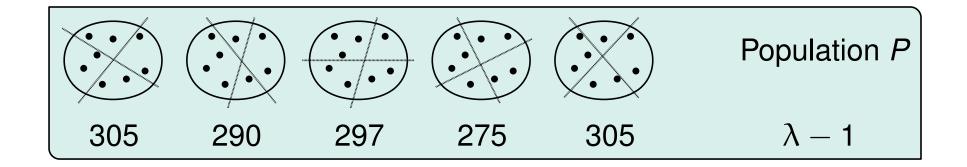
3.1s $time = 100s \longrightarrow \sim 5$ iterations

KaHyPar generates multiple partitions dynamic allocation $\delta = 15\%$

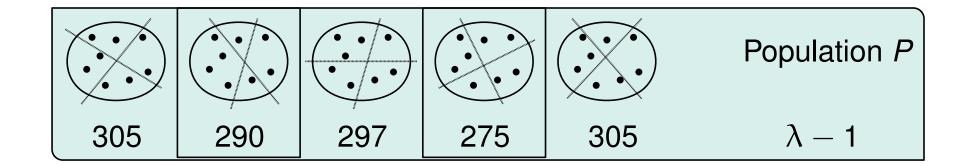
high quality solutions

balances time/hypergraph size



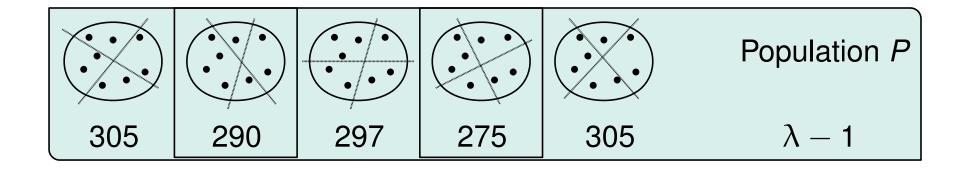


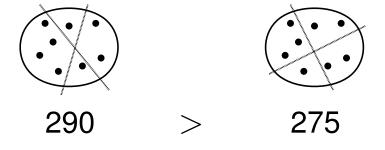




select 2 random Individuals

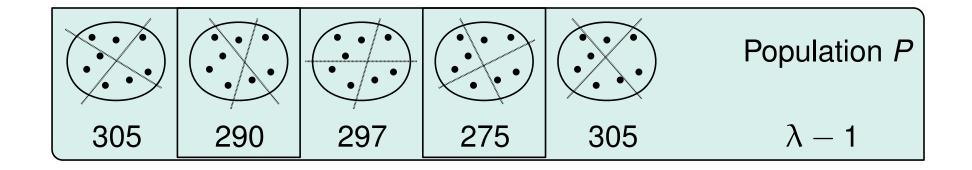






select 2 random Individuals compare their fitness

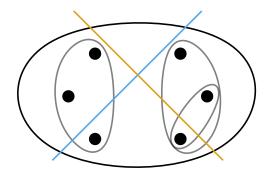


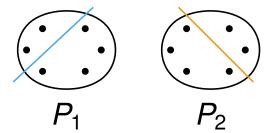




select 2 random Individuals
compare their fitness
choose the better Individual

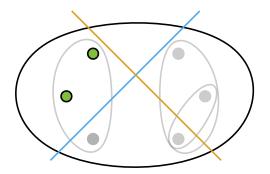




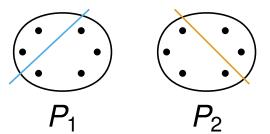


- \blacksquare contractions must respect $P_1 \& P_2$
- does not change solution quality



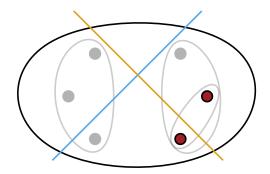


Valid Contraction

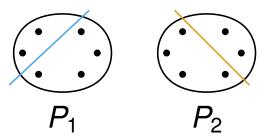


- contractions must respect P₁ & P₂
- does not change solution quality



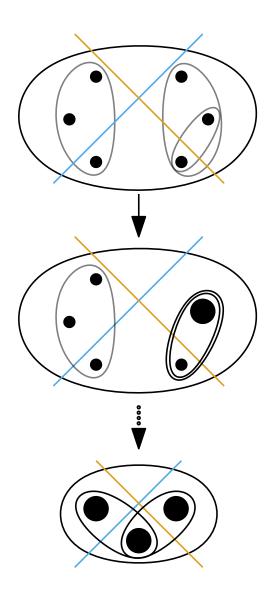


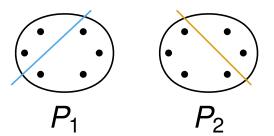
Invalid Contraction



- \blacksquare contractions must respect $P_1 \& P_2$
- does not change solution quality

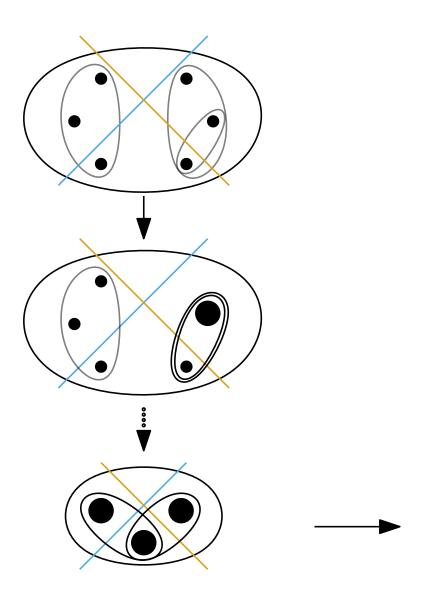


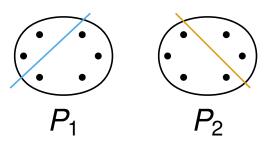




- \blacksquare contractions must respect $P_1 \& P_2$
- does not change solution quality

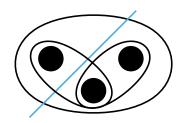






Initial Partitioning:

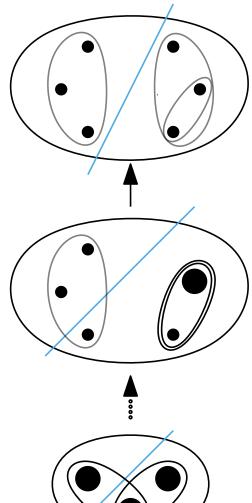
- Use the better parent partition (P_1)
- Maintains solution quality

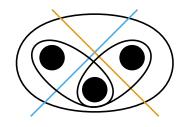




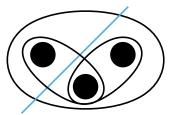
Refinement:

- Local search improvements
- will not decrease solution quality





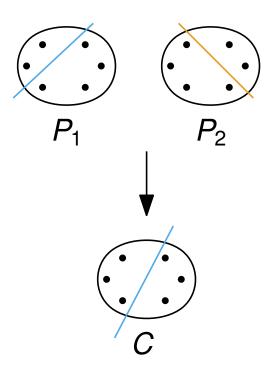






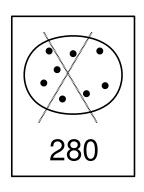
Benefits:

- local search
- structure preservation

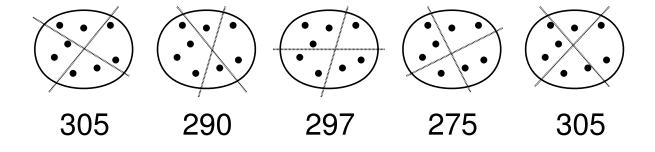


Replacement Strategy





New individual has to be placed in *P*

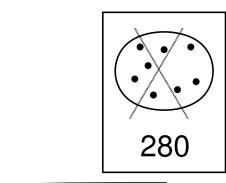


Population P

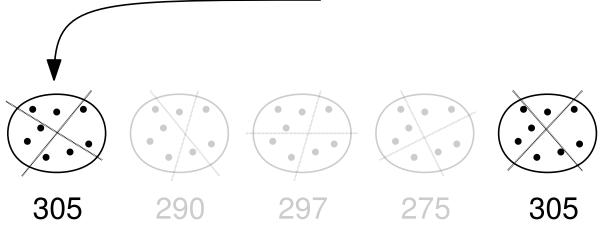
 $\lambda - 1$

Replacement Strategy





Replace the worst element in *P*

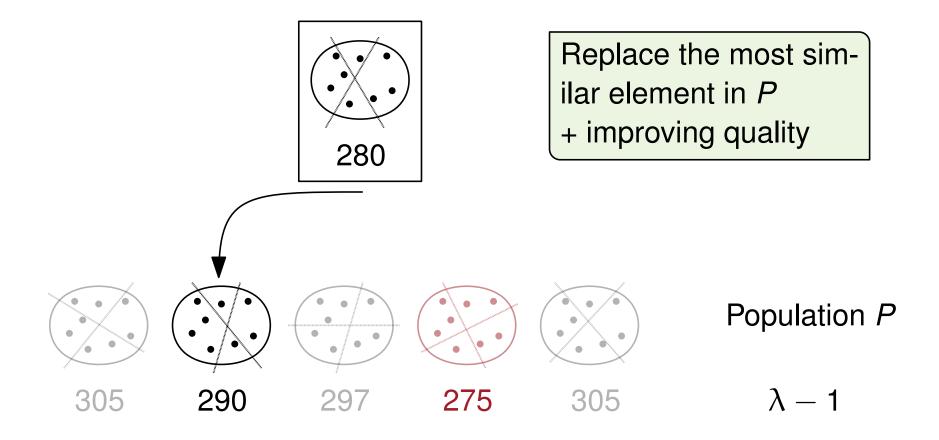


Population P

 $\lambda - 1$

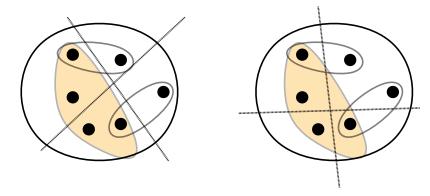
Replacement Strategy





Diversity





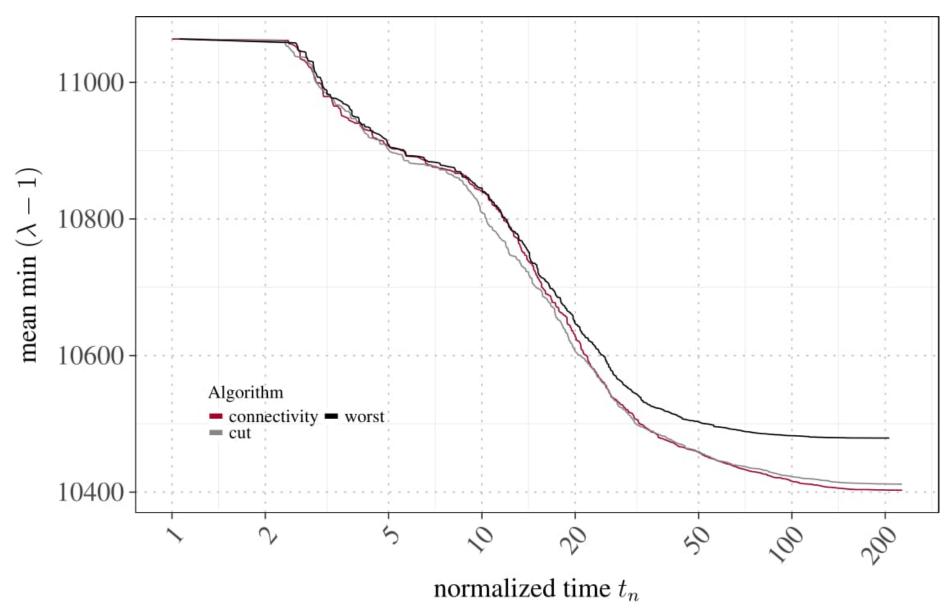
			difference
cut	1, 1, 1	1, 1, 1	0,0,0=0
connectivity	2,2,2	2,3,2	0,1,0=1

There are two approaches for difference:

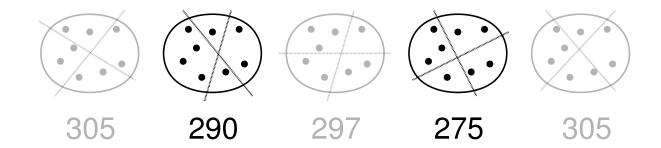
- count the different cut edges
- count the different blocks of cut edges

Test Results









We inspect the $\sqrt{|P|}$ best individuals of P



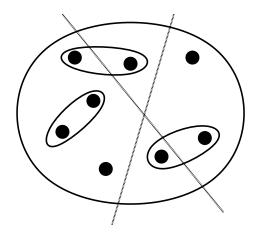


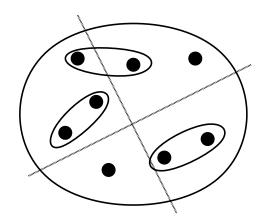














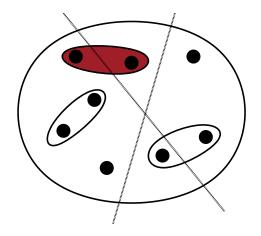


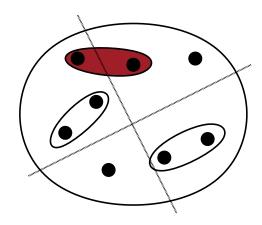














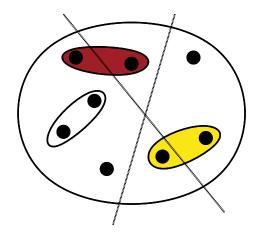


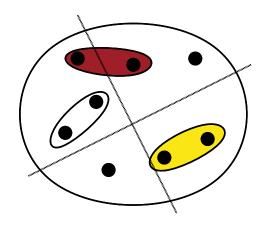














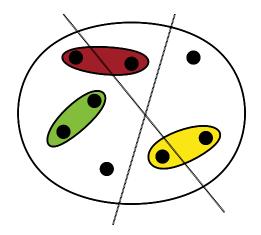


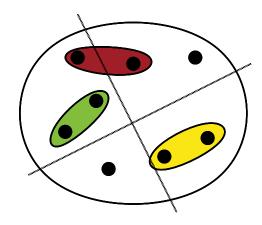




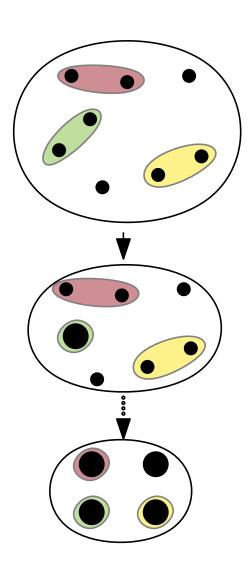








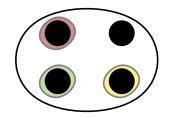


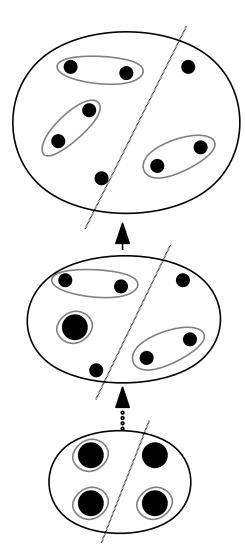


- the frequency of e discourages contracting e
- low frequency edges are contracted first



Initial Partitioning and Refinement are performed as in KaHyPar

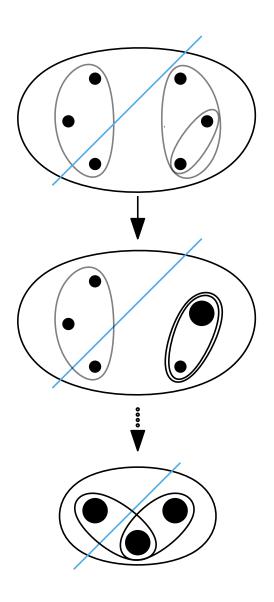


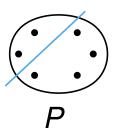




V-Cycle (+ New Initial Partitioning)



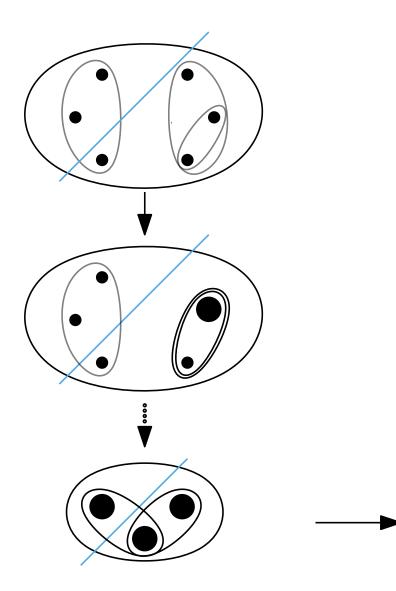




- contractions must respect P
- does not change solution quality

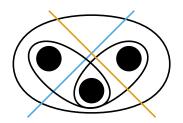
V-Cycle (+ New Initial Partitioning)





Initial Partitioning:

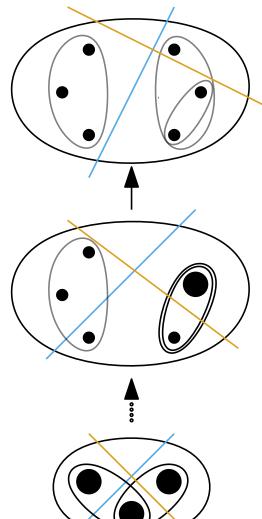
- V-Cycle can generate a new initial partitioning
- Or keep the current partition (maintains solution quality)

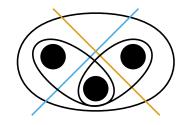


V-Cycle (+ New Initial Partitioning)

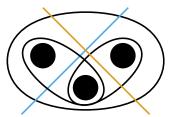


A new initial partitioning can generate worse solutions



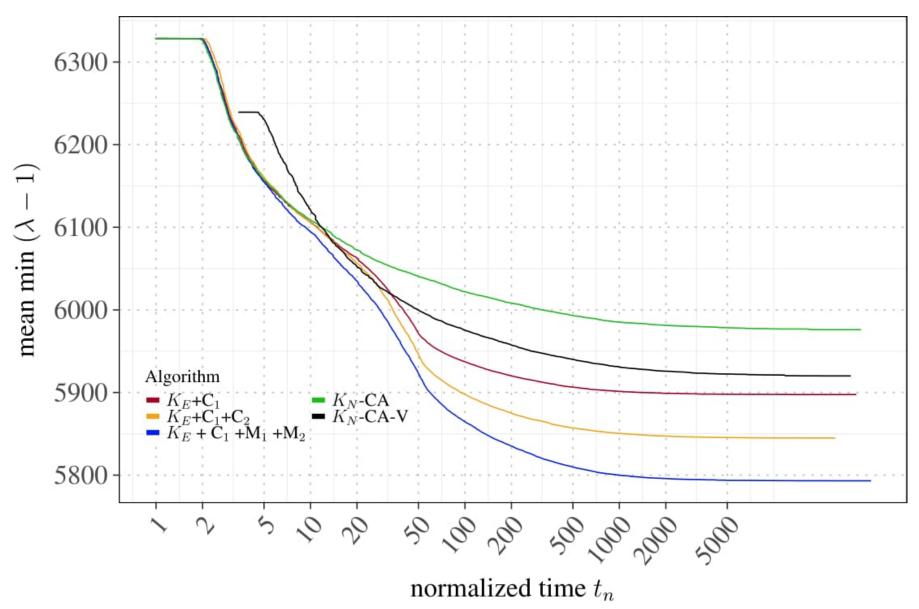






Results





Results



