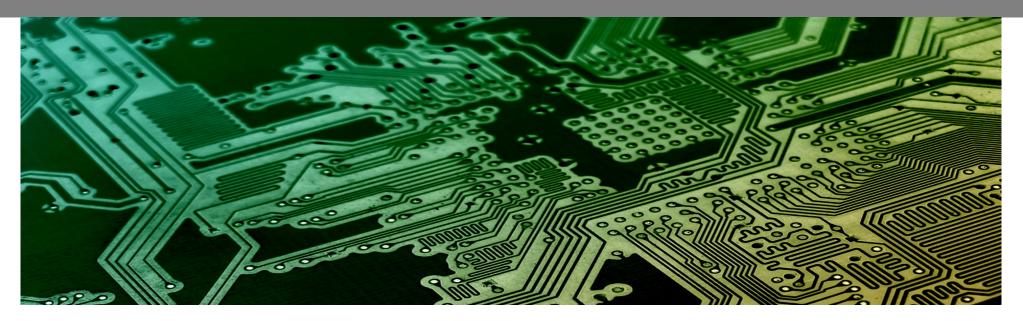


Evolutionary Hypergraph Partitioning

Presentation · December 12, 2017 **Robin Andre**

Institute of Theoretical Informatics ·



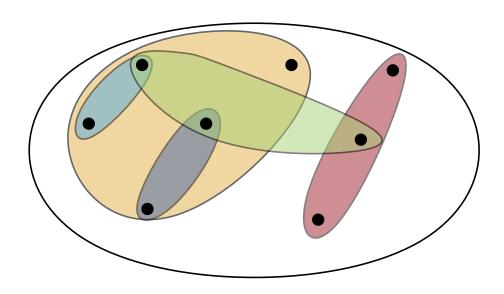
Hypergraph Partitioning



Hypergraph Partitioning

A k partition of a hypergraph is $H = V_1 \cup V_2 \cup ... \cup V_k$

A partition is balanced if $\forall 1 \le i \le k : c(V_i) \le (1 + \epsilon) \lceil \frac{c(V)}{k} \rceil$



Hypergraph Partitioning

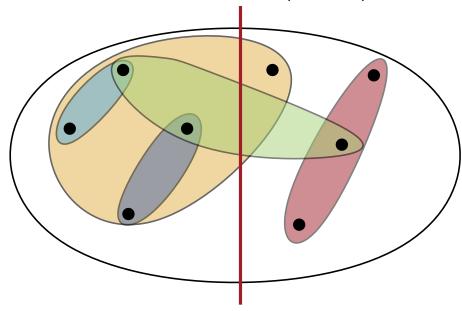


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$$k = 2$$
; $cut = 2$; $(\lambda - 1) = 2$



Hypergraph Partitioning

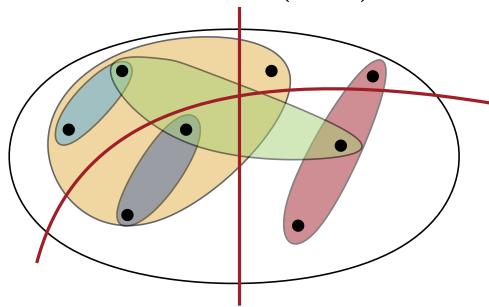


Hypergraph Partitioning

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A partition is balanced if $\forall 1 \le i \le k : c(V_i) \le (1 + \epsilon) \lceil \frac{c(V)}{k} \rceil$

$$k = 4$$
; $cut = 3$; $(\lambda - 1) = 5$

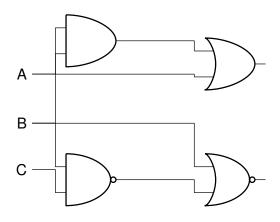


Motivation



- Hypergraph partitioning is NP-hard
- Many applications benefit from the best possible solution
- Evolutionary Algorithms are generating high quality solutions

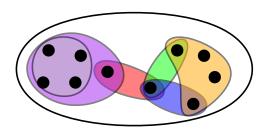
VLSI Design



Scientific Computing

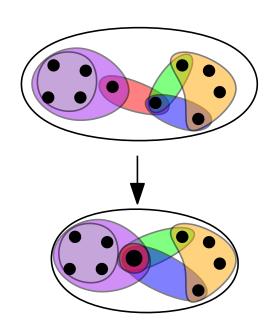
$$\begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 \end{pmatrix}$$





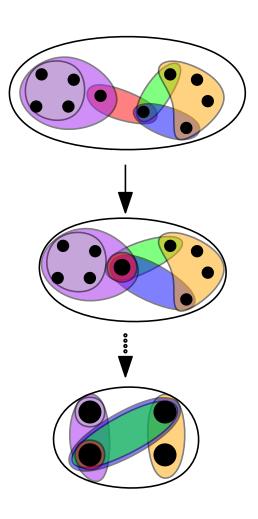
- \blacksquare H is reduced to a smaller problem H_C
- n-level coarsening
- lacksquare H_C should be sufficiently small





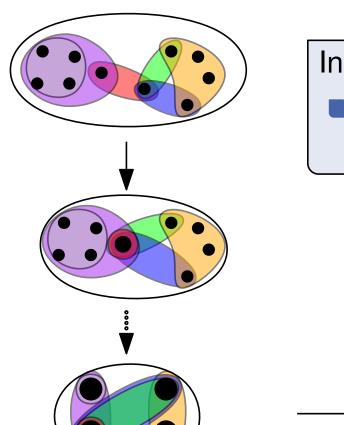
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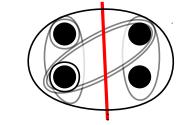
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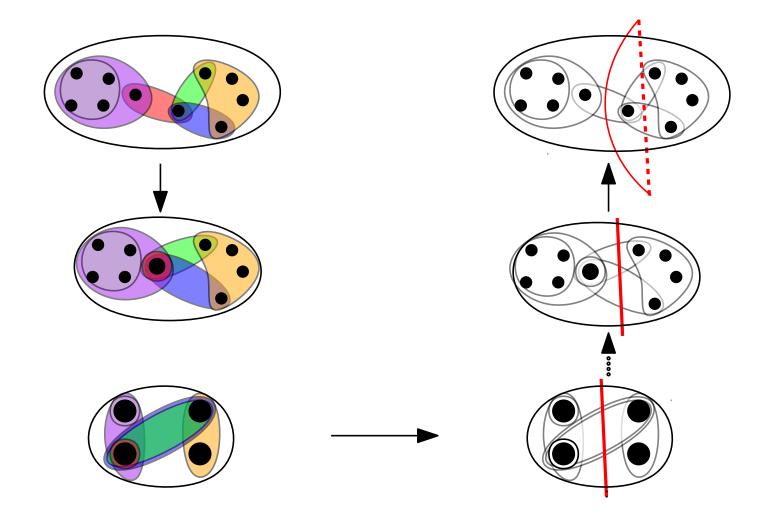


Initial Partitioning:

• An algorithm generates an Initial Partitioning for H_C

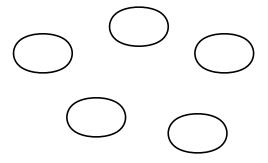






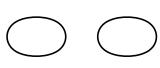


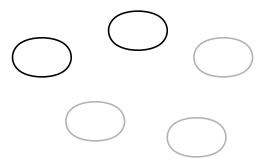
Choose individuals for recombination





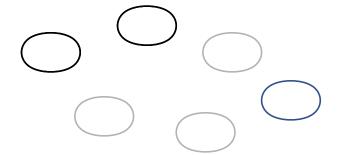
Choose individuals for recombination







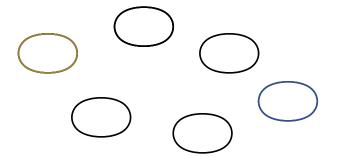
- Choose individuals for recombination
- Generate offspring O





- Choose individuals for recombination
- Generate offspring O
- Perform mutations M

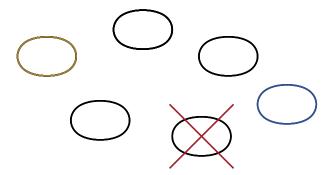
$$\bigcirc \quad \bigcirc \quad \Rightarrow \quad \bigcirc$$



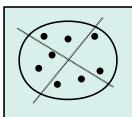


- Choose individuals for recombination
- Generate offspring O
- Perform mutations M
- Select survivors

$$\bigcirc \quad \bigcirc \quad \Rightarrow \quad \bigcirc$$



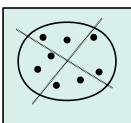




Population P

- KaHyPar generates multiple partitions
- dynamic allocation $\delta = 15\%$
- balances time/hypergraph size





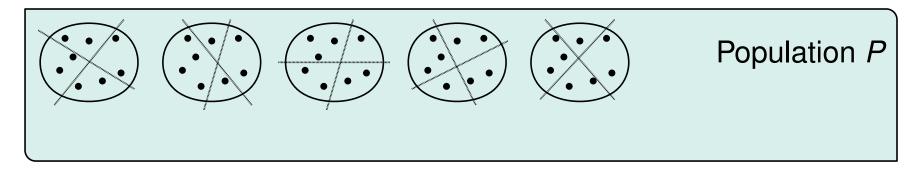
Population P

3.1s
$$time = 100s$$

- ~ 5 iterations

- KaHyPar generates multiple partitions
- dynamic allocation $\delta = 15\%$
- balances time/hypergraph size

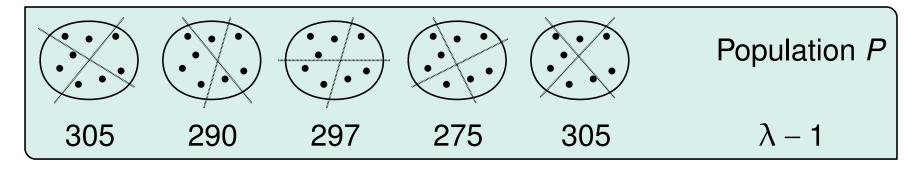




3.1s $time = 100s \sim 5$ iterations

- KaHyPar generates multiple partitions
- dynamic allocation $\delta = 15\%$
- balances time/hypergraph size

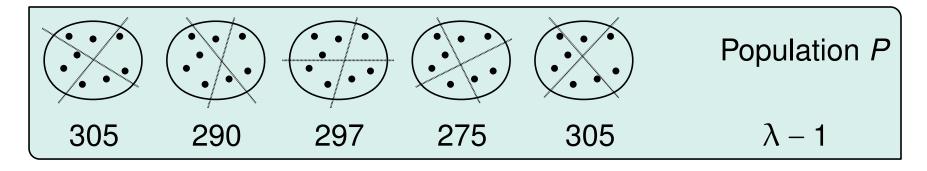




3.1s
$$time = 100s \sim 5$$
 iterations

- KaHyPar generates multiple partitions
- **dynamic allocation** $\delta = 15\%$
- balances time/hypergraph size



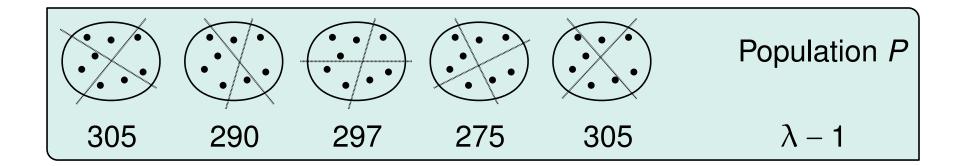


3.1s
$$time = 100s \sim 5$$
 iterations

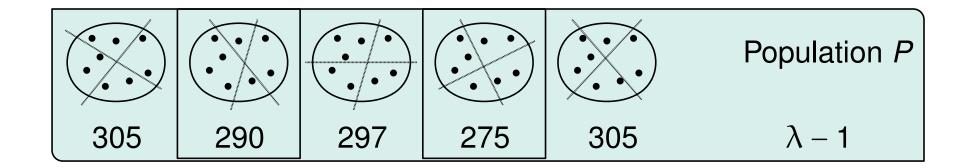
- KaHyPar generates multiple partitions
- dynamic allocation $\delta = 15\%$
- balances time/hypergraph size

high quality solutions



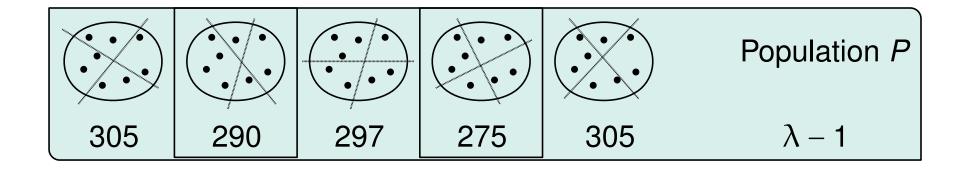


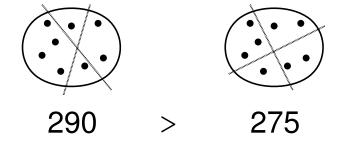




Select 2 random individuals

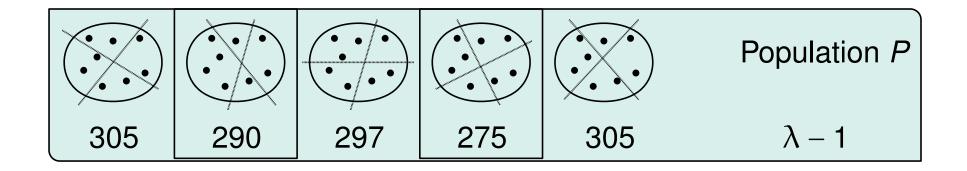


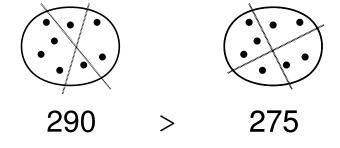




- Select 2 random individuals
- Compare their fitness

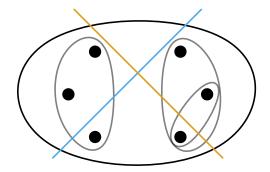


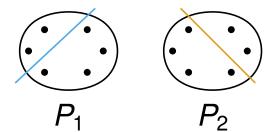




- Select 2 random individuals
- Compare their fitness
- Choose the better individual

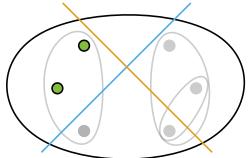


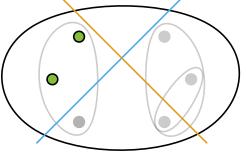




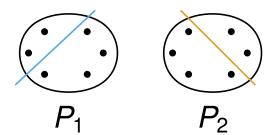
- \blacksquare contractions must respect $P_1 \& P_2$
- does not change solution quality





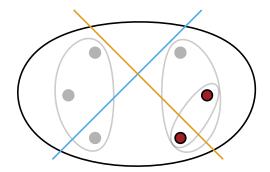


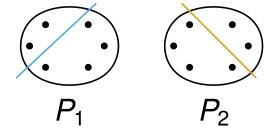




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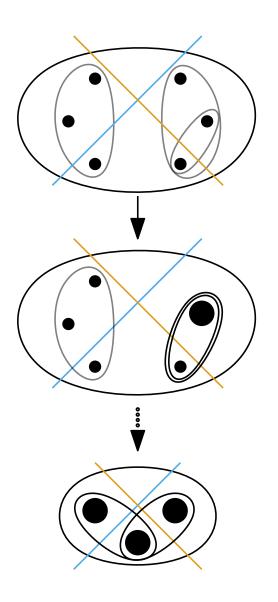


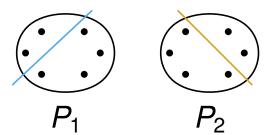


Invalid Contraction

- \blacksquare contractions must respect $P_1 \& P_2$
- does not change solution quality

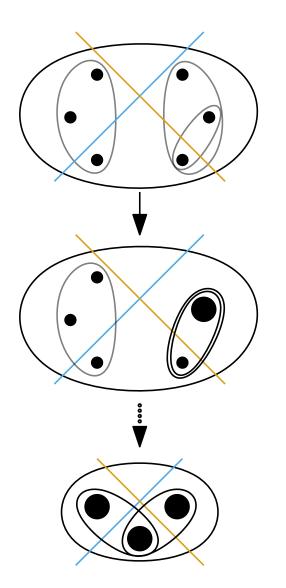


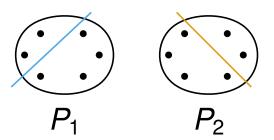




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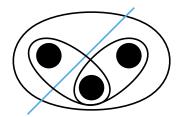




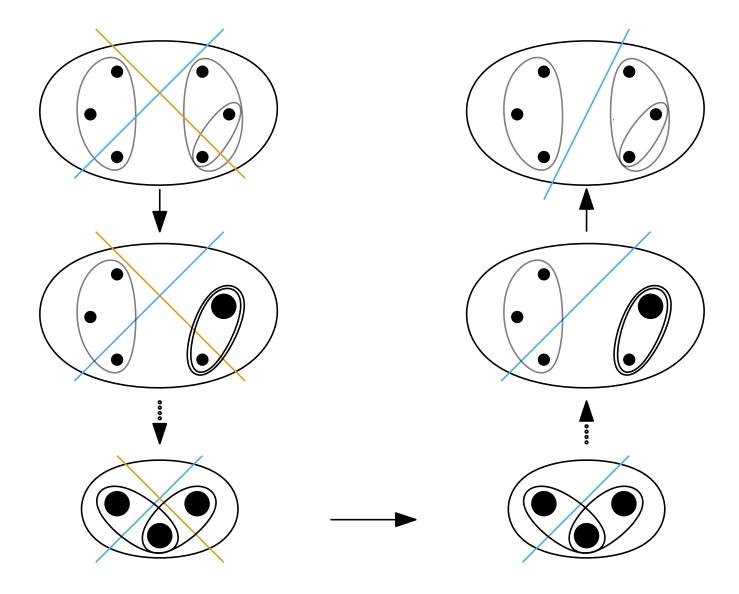


Initial Partitioning:

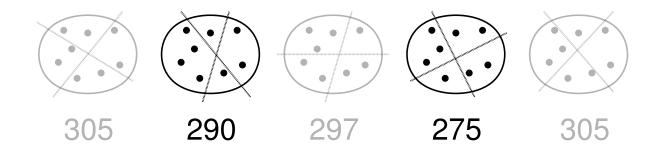
- Use the better parent partition (P_1)
- Maintains solution quality











- We inspect the $\sqrt{|P|}$ best individuals of P
- Each hyperedge *e* is analyzed on its frequency in the selected elements



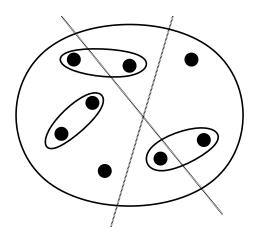


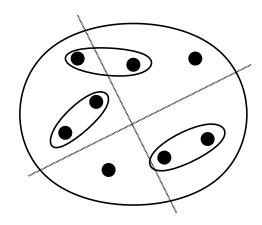












- Frequent edges are beneficial to the solution quality
- Contracting frequent edges may be detrimental to solution quality
- Additionally it may limit other contractions



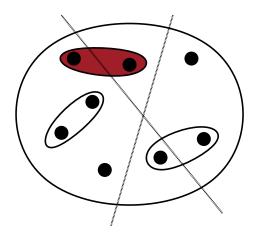


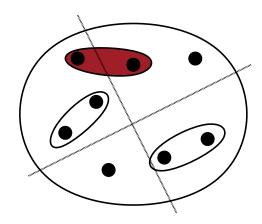












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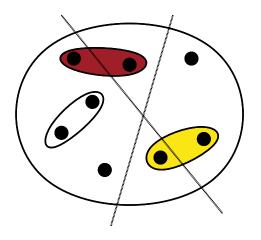


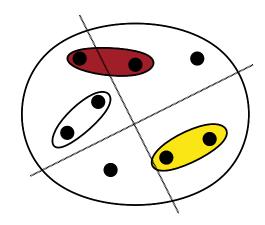












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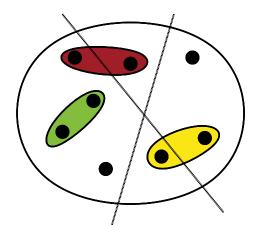


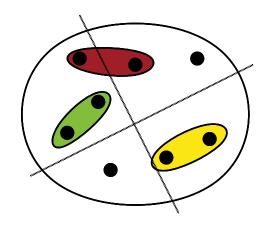






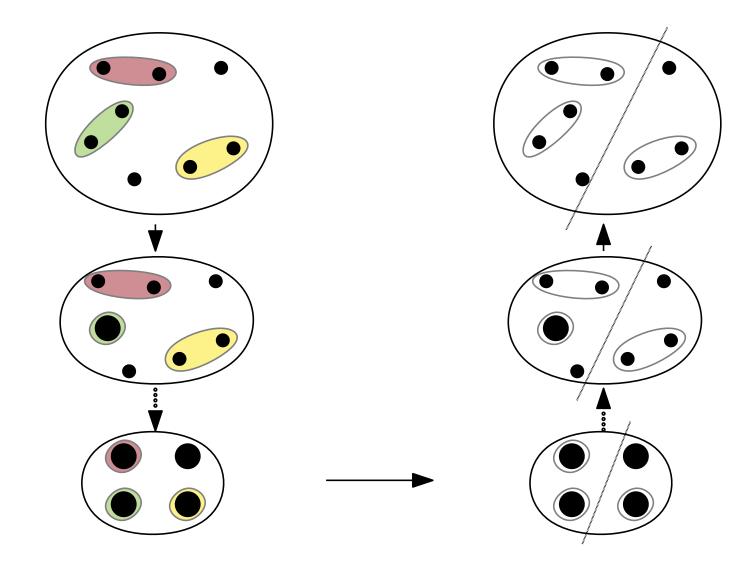






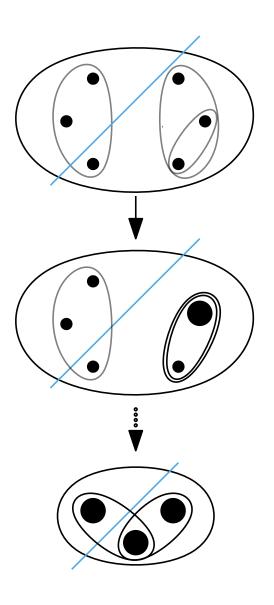
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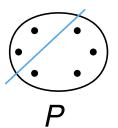




V-Cycle (+ New Initial Partitioning)



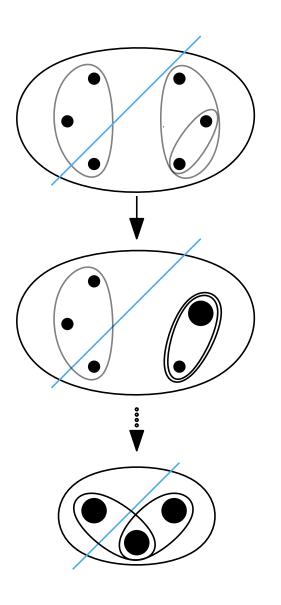




- Contractions must respect P
- Does not change solution quality

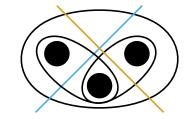
V-Cycle (+ New Initial Partitioning)





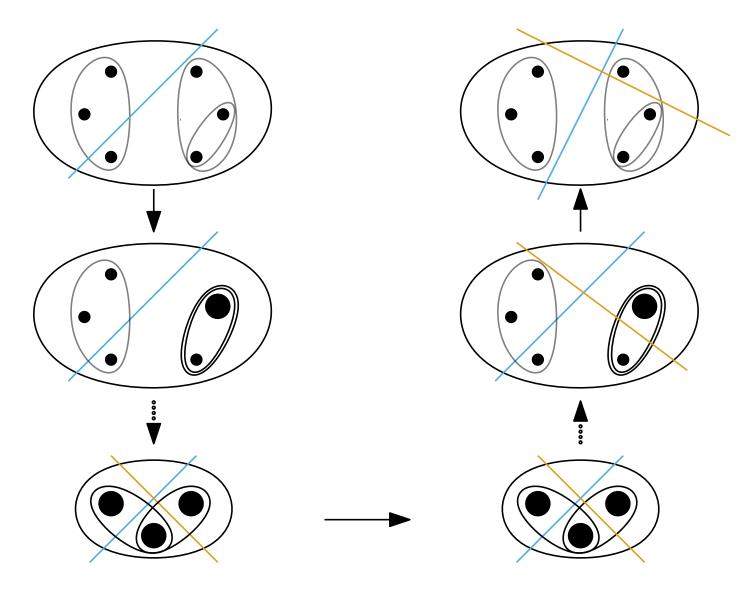
Initial Partitioning:

- V-Cycle can generate a new initial partitioning
- Or keep the current partition (maintains solution quality)



V-Cycle (+ New Initial Partitioning)





Experimental Setup

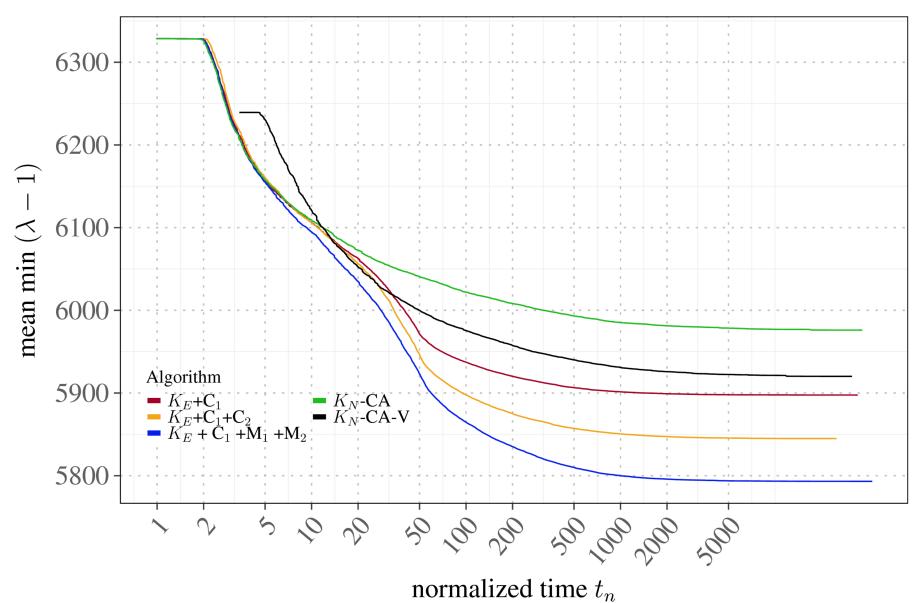


- $k = \{2, 4, 8, 16, 32, 64, 128\}; \epsilon = 0.03$
- 90 hypergraphs
- Comparison against repeated KaHyPar-CA

- The run time is normalized $t_n = \frac{time}{t_1}$; $t_1 := duration of first iteration.$
 - Allows comparing differently sized hypergraphs
 - Algorithmic components can be analyzed on run time

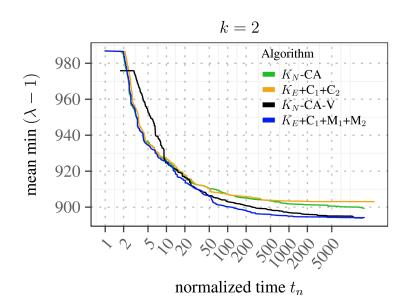
Results

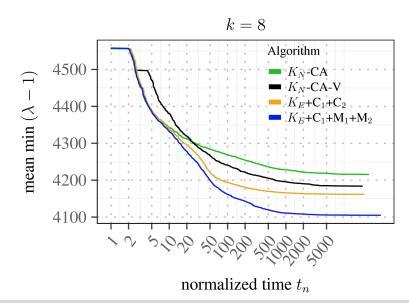


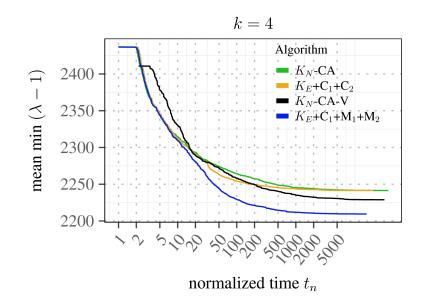


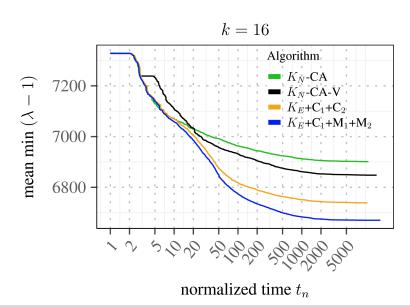
Results





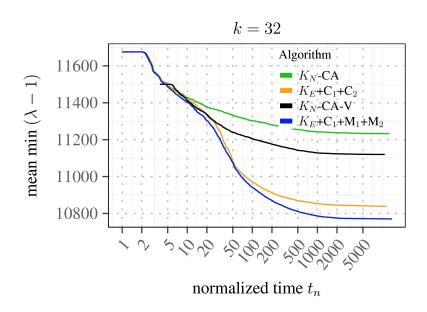


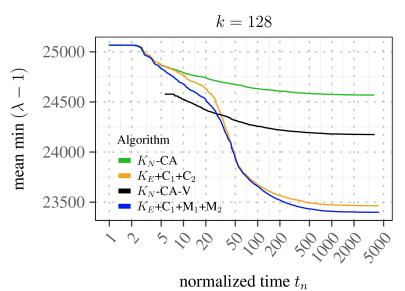




Results







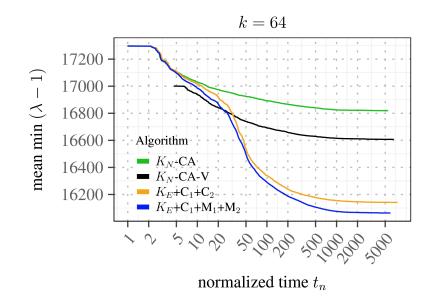


Table of Improvements



	$K_E + C_1 + C_2$		$K_E + C_1 + M_1 + M_2$	
k	K _N -CA-V	K_N -CA	K _N -CA-V	K_N -CA
all <i>k</i>	1.7%	2.7%	2.2%	3.2%
2	-0.2%	0.4%	0.2%	0.8%
4	-0.2%	0.3%	0.9%	1.3%
8	0.7%	1.6%	1.9%	2.7%
16	1.9%	2.8%	2.6%	3.5%
32	2.9%	3.9%	3.2%	4.2%
64	3.2%	4.7%	3.4%	4.8%
128	3.3%	5.0%	3.3%	5.0%

Conclusion



Conclusion

- High integration of evolutionary aspects in the multilevel approach

Future Work

- Added parallelization for faster partitioning
- Different approach for generating the initial population
- Time cost analysis for evolutionary operators