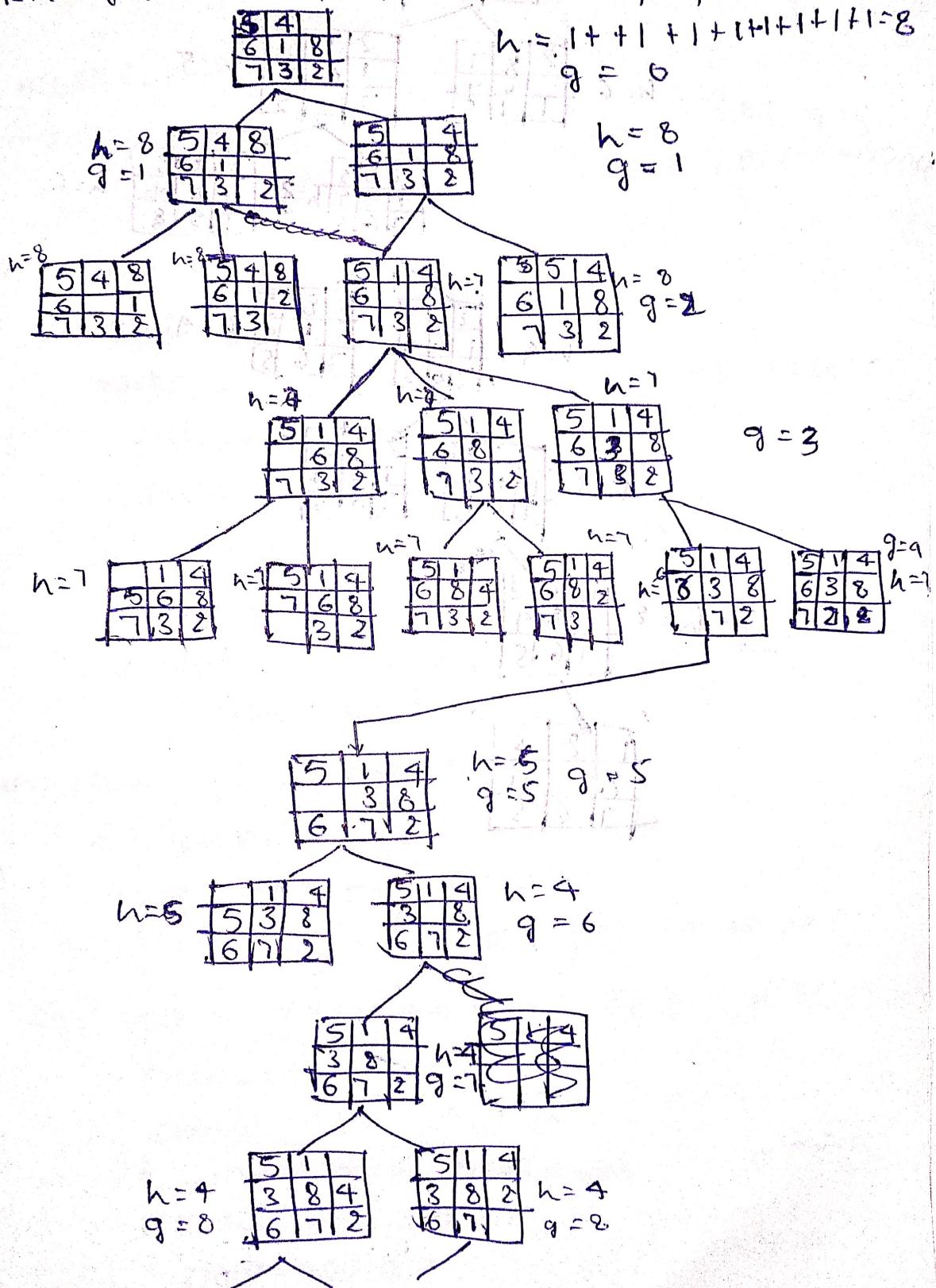


1) Heuristic : Number of tiles out of place



Initial

| | | |
|---|---|---|
| 2 | 8 | 3 |
| 1 | 6 | 4 |
| 7 | 5 | |

goal state

| | | |
|---|---|---|
| 1 | 2 | 3 |
| 8 | | 4 |
| 7 | 6 | 5 |

$$h(n) = 6$$

$$h=6$$

| | | |
|---|---|---|
| 2 | 8 | 3 |
| 1 | 6 | 4 |
| 7 | 5 | |

| | | |
|---|---|---|
| 2 | 8 | 3 |
| 6 | 4 | |
| 1 | 7 | 5 |

| | | |
|---|---|---|
| 2 | 8 | 3 |
| 1 | 6 | 4 |
| 7 | 5 | |

$$h=5$$

| | | |
|---|---|---|
| 2 | 8 | 3 |
| 6 | 4 | |
| 1 | 7 | 5 |

| | | |
|---|---|---|
| 2 | 8 | 3 |
| 1 | 6 | 4 |
| 7 | 5 | |

| | | |
|---|---|---|
| 2 | 8 | 3 |
| 7 | 6 | 5 |
| | | |

$$h=6$$

$$h=4$$

| | | |
|---|---|---|
| 2 | 8 | 3 |
| 1 | 6 | 4 |
| 7 | 5 | |

| | | |
|---|---|---|
| 2 | 8 | 3 |
| 1 | 6 | 4 |
| 7 | 5 | |

$$h=4$$

$$h=3$$

| | | |
|---|---|---|
| 2 | 8 | 3 |
| 1 | 6 | 4 |
| 7 | 5 | |

| | | |
|---|---|---|
| 2 | 8 | 3 |
| 1 | 6 | 4 |
| 7 | 5 | |

$$h=2$$

| | | |
|---|---|---|
| 2 | 8 | 3 |
| 1 | 6 | 4 |
| 7 | 5 | |

| | | |
|---|---|---|
| 2 | 8 | 3 |
| 1 | 6 | 4 |
| 7 | 5 | |

| | | |
|---|---|---|
| 2 | 8 | 3 |
| 1 | 6 | 4 |
| 7 | 5 | |

卷之三

128

Algorithm:

class puzzlestate;

function _init_(board, zfill_pos, q=0, parent=None)

this. board = board

this. zero-pos = zero-par

this. $g = g$

this.h = calculate_misplaced-tiles()

this, $f = g + h$

this.parent = parent

function calculateMisplacedTiles():

goal = [0, 1, 2, 3, 4, 5, 6, 7, 8]

return count of tiles not in

goal position

function get-neighbors();

neighbours = []

row, col = this. zero-per

directions = [(-1, 0), (1, 0), (0, -1), (0, 1)]

for each direction (d_i, d_j) in directions:

$$\text{new_row} = \text{row} + \text{d1}$$

`new_col = col + dc`

- if (`new-row`, `new-col`) is within board boundaries:

new-board = copy of this board

Swap zero tile with neighbor tiles
neighbors.append(puzzlestate($n \times n$))

(new-row, new-col), this.Q +
this))

retain neighbors

function -it-(other):

return this + <other>

function a-star(initial-board)

zero-pos = index of 0 in initial-board

initial-state = puzzlestate(initial-board, zero-pos)

'open-set = priority queue initialized with
initial-state

closed-set = empty set

while open-set is not empty:

current-state = pop the state with
lowest f from open-set

if current-state.h == 0:

print("solution found!")

print-path(current-state)

return current-state.g

add current-state.board + 0 · closed-set

for each neighbor in current-state.get-
neighbors:

if neighborboard is in closed-set:
continue

if neighbor.board is not in open-set:
add neighbor to open-set

return None.

function get-board-input(prompt):

while True:

try:

board = read input and convert
list of integers

if length of board is not 9 or board does
not contain unique integers from 0 to 8;
raise valueError

return board
except valueError
print ("Invalid Input")

main :
initial-board = get-board-input("Enter
goal-board = get-board-input("Enter
set puzzlestate = goal-board
steps = a-star(initial-board)
if steps is not None:
print("solution", steps, "moves")
else:
print("No solution")

for
15/10/2021

Manhattan Distance

Algorithm:

FUNCTION A-STAR(initial-state):

 priority-queue = empty min-heap

 visited = empty set

 h = MANHATTAN-DISTANCE (initial-state)

 g = 0

 f = g + h

 HEAP-PUSH (priority-queue, (f, initial-state, [], 9))

 WHILE priority queue is not empty:

 (f, current-state, path, g) = HEAP-POP (priority-queue)

 PRINT "Exploring state in A*:"

 PRINT-STATE (current-state)

 IF IS-GOAL (current-state)

 RETURN path

 ADD tuple (current-state) to visited

 FOR direction IN ["UP", "down", "left", "right"]:

 new-state = MOVE (current-state, direction)

 IF new-state is not None AND tuple (new-state) not in visited

 new-g = g + 1

 h = MANHATTAN-DISTANCE (new-state)

 new-f = new-g + h

 HEAP-PUSH (priority-queue, (new-f, new-state, path + [direction], new-g))

 RETURN None

FUNCTION MANHATTAN-DISTANCE(state):

 distance = 0

 FOR i FROM 0 TO 2:

 FOR j FROM 0 TO 2:

 IF state[i][j] !=

 goal_i, goal_j = DIVMOD(state[i][j], 3)

 IF state[i][j] == 8

 goal_i, goal_j = 1, 1

 distance += ABS(goal_i - i) + ABS(goal_j - j)

 RETURN distance

(Priority Queue) FUNCTION IS-GOAL(state):

 RETURN state == goal-state

FUNCTION PRINT-STATE(state)

 FOR row IN state:

 PRINT row

 PRINT "\n"

FUNCTION MOVE(state, direction):

 new-state = COPY(state)

 zero-pos = FIND-ZERO(state)

 i, j = zero-pos

 IF direction == "up" AND i > 0:

 SWAP(new-state[i][j], new-state[i-1][j])

 ELSE IF direction == "down" AND i < 2:

 SWAP(new-state[i][j], new-state[i+1][j])

 ELSE IF direction == "left" AND j > 0:

 SWAP(new-state[i][j], new-state[i][j-1])

 ELSE IF direction == "right" AND j < 2:

 SWAP(new-state[i][j], new-state[i][j+1])

 ELSE:

 RETURN None

RETURN new-state

```

FUNCTION FINP-ZERO (state):
    FOR i FROM 0 TO 2^j - 1 DO
        FOR j FROM 0 TO 2^i :
            IF state[i][j] == 0 :
                RETURN (i,j)

```