## ORIGINAL SOURCE OF THE DATA SETS AND Background IS :-

http://archive.ics.uci.edu/ml/datasets/Human+Activity+Recognition+Using+Smartphones

And the data:-

https://d396qusza40orc.cloudfront.net/getdata%2Fprojectfiles%2FUCl%20HAR%20Dataset.zip

See reference at end of this README.

This data has been transformed, by taking the mean of the variables grouped by one of 1 - 30 subjects, and the activity undertaken.

Subjectnumber - 1:30 - denotes the number of the subject(person) undertaking an activity

Activity - 6 levels, Laying, Sitting, Standing, Walking, Walking\_Uphill, Walking\_Downhill,

In order to understand the remaining variables:-

T prefix denotes time

F prefix denote frequency domain signals

Mean suffix denotes the mean of the variables below

Std suffix denotes the standard deviation of the variables below

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The original data in the dataset was created as follows

The features selected for this database come from the accelerometer and gyroscope 3-axial raw signals tAcc-XYZ and tGyro-XYZ.

The acceleration signal was then separated into body and gravity acceleration signals (tBodyAcc-XYZ and tGravityAcc-XYZ)

Subsequently, the body linear acceleration and angular velocity were derived in time to obtain Jerk signals (tBodyAccJerk-XYZ and tBodyGyroJerk-XYZ). Also the magnitude of these three-dimensional signals were calculated using the Euclidean norm (tBodyAccMag, tGravityAccMag, tBodyGyroJerkMag).

Finally a Fast Fourier Transform (FFT) was applied to some of these signals producing fBodyAcc-XYZ, fBodyAccJerk-XYZ, fBodyGyro-XYZ, fBodyAccJerkMag, fBodyGyroMag, fBodyGyroJerkMag.

These signals were used to estimate variables of the feature vector for each pattern:

'-XYZ' is used to denote 3-axial signals in the X, Y and Z directions.

tBodyAcc-XYZ

tGravityAcc-XYZ

tBodyAccJerk-XYZ

tBodyGyro-XYZ

tBodyGyroJerk-XYZ

**tBodyAccMag** 

tGravityAccMag

tBodyAccJerkMag

**tBodyGyroMag** 

tBodyGyroJerkMag

fBodyAcc-XYZ

fBodyAccJerk-XYZ

fBodyGyro-XYZ

**fBodyAccMag** 

fBodyAccJerkMag

**fBodyGyroMag** 

fBodyGyroJerkMag

Original background on the underlying data

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Human Activity Recognition Using Smartphones Dataset

Version 1.0

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The experiments have been carried out with a group of 30 volunteers within an age bracket of 19-48 years. Each person performed six activities (WALKING, WALKING\_UPSTAIRS, WALKING\_DOWNSTAIRS, SITTING, STANDING, LAYING) wearing a smartphone (Samsung Galaxy S II) on the waist. Using its embedded accelerometer and gyroscope, we captured 3-axial linear

acceleration and 3-axial angular velocity at a constant rate of 50Hz. The experiments have been video-recorded to label the data manually. The obtained dataset has been randomly partitioned into two sets, where 70% of the volunteers was selected for generating the training data and 30% the test data.

The sensor signals (accelerometer and gyroscope) were pre-processed by applying noise filters and then sampled in fixed-width sliding windows of 2.56 sec and 50% overlap (128 readings/window). The sensor acceleration signal, which has gravitational and body motion components, was separated using a Butterworth low-pass filter into body acceleration and gravity. The gravitational force is assumed to have only low frequency components, therefore a filter with 0.3 Hz cutoff frequency was used. From each window, a vector of features was obtained by calculating variables from the time and frequency domain. See 'features\_info.txt' for more details.

For each record it is provided:

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- Triaxial acceleration from the accelerometer (total acceleration) and the estimated body acceleration.
- Triaxial Angular velocity from the gyroscope.
- A 561-feature vector with time and frequency domain variables.
- Its activity label.
- An identifier of the subject who carried out the experiment.

The dataset includes the following files:

## License:

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Use of this dataset in publications must be acknowledged by referencing the following publication [1]

[1] Davide Anguita, Alessandro Ghio, Luca Oneto, Xavier Parra and Jorge L. Reyes-Ortiz. Human Activity Recognition on Smartphones using a Multiclass Hardware-Friendly Support Vector Machine. International Workshop of Ambient Assisted Living (IWAAL 2012). Vitoria-Gasteiz, Spain. Dec 2012

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Jorge L. Reyes-Ortiz, Alessandro Ghio, Luca Oneto, Davide Anguita. November 2012.