COL351

Assignment 2

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Question 1

Question. Alice, Bob, and Charlie have decided to solve all exercises of the Algorithms Design book by Jon Kleinberg, Éva Tardos. There are a total of n chapters, [1, ..., n], and for $i \in [1, n]$, x_i denotes the number of exercises in chapter i. It is given that the maximum number of questions in each chapter is bounded by the number of chapters in the book. Your task is to distribute the chapters among Alice, Bob, and Charlie so that each of them gets to solve nearly an equal number of questions.

Device a polynomial time algorithm to partition [1, ..., n] into three sets S_1, S_2, S_3 so that $\max\{\sum_{i \in S_1} x_i, \sum_{i \in S_2} x_i, \sum_{i \in S_3} x_i\}$ is minimized.

Solution. We propose a Dynamic Programming solution for this problem. The idea is to generate all possible combinations of S_1, S_2, S_3 and then find the best combination of out them. The naïve solution will have an exponential complexity $(O(3^n))$ and hence it needs to be modified so that it can be executed in polynomial time complexity.

We make the following observations to optimise our solution:

- 1. To find the optimal paritition of S, only the sum of each of S_1, S_2, S_3 matters
- 2. Order of picking elements for each set doesn't affect the solution
- 3. Fixing the sum of S_1 and S_2 uniquely identifies the sum of S_3

Using these observations we come up with the following DP table:

$$dp(i, s1, s2) = dp(i - 1, s1 - S[i], s2) \lor dp(i - 1, s1, s2 - S[i]) \lor dp(i - 1, s1, s2)$$

$$\forall i \in \{1, \dots, n\}; s1, s2 \in \{1, \dots, sum(S)\}$$

$$dp(i, p, q) = \bot, \ \forall i \in \{1, \dots, n\}; p, q < 0$$

$$dp(0, 0, 0) = \top$$

$$(1)$$

where dp(i, s1, s2) is \top if we can generate at least one partition using the first i elements such that any two partitions have sums s1 and s2

Claim 1.1. The dp table generated using the Equation 1 is correct, i.e., $dp(i, s1, s2) = \top$ iff there exists a partition using the first i elements with sums s1, s2, sum(S[1:i]) - (s1 + s2)

Proof. We will prove the correctness of the claim by induction on i.

Base case: i = 0

dp(0, s1, s2) is \top only when s1 = s2 = 0 and \bot otherwise. We know that we can generate only three empty sets using the first 0 elements and thus their sums will all be 0. Therefore the base case is true.

Induction step: Assume that the claim is true for i-1. Consider dp(i, s1, s2), The ith element will be present in exactly one of S_1, S_2, S_3 . Therefore, we have three cases:

1. S[i] is in S_1 , then the sum of S_1 upto the first i-1 elements will be $s_1-S[i]$ and the sum of the other two sets doesn't change

- 2. S[i] is in S_2 , then the sum of S_2 upto the first i-1 elements will be $s_2 S[i]$ and the sum of the other two sets doesn't change
- 3. S[i] is in S_3 , then the sum of S_3 upto the first i-1 elements will be sum(S[1:(i-1)]) (s1+s2) and the sum of the other two sets doesn't change

Thus, the only possibilities for valid partition sums using the first i elements are exactly those when we can generate at least one of the above three partitions using the first i-1 elements. The transition equation given in Equation 1 exactly captures this. We have shown that for dp(i, s1, s2) to be \top , at least one of dp(i-1, s1-S[i], s2), dp(i-1, s1, s2-S[i]), dp(i-1, s1, s2) must be \top . From induction, we know that the $(i-1)^{\text{th}}$ row of the table is true iff there exists a valid partition. Therefore, if $dp(i, s1, s2) = \top$ then there exists a partition using the first i elements with sums s1, s2, sum(S[1:i]) - (s1 + s2). (\Longrightarrow)

We still have to prove the converse, i.e., if there exists a partition using the first i elements with sums s1, s2, sum(S[1:i]) - (s1 + s2), then $dp(i, s1, s2) = \top$.

To prove this, we observe that the dp table considers all possible sums since s1, s2 iterate in the range $\{1, \ldots, sum(S)\}$. Therefore, if there exists a valid solution, the dp table considers it and is assigned \top . Else it is assigned \bot . $(\Leftarrow=)$

Now that we have proved the correctness of Equation 1, we present an algorithm for computing the same:

Algorithm 1 DP solution for partitioning

```
1: procedure Partition(S)
        n \leftarrow size(S)
 3:
         s \leftarrow sum(S)
         dp \leftarrow \text{table of size } (n+1) \times (s+1) \times (s+1) \text{ initialised with } \bot
 4:
         dp(0,0,0) \leftarrow \top
        for i in [1, n] do
 6:
             for s1 in [0, s] do
 7:
                  for s2 in [0,s] do
 8:
                      dp(i, s1, s2) \leftarrow dp(i - 1, s1, s2)
 9:
10:
                      if s1 \geq S[i] then
                           dp(i, s1, s2) \leftarrow dp(i, s1, s2) \lor dp(i - 1, s1 - S[i], s2)
11:
                      end if
12:
                      if s2 \geq S[i] then
13:
                           dp(i, s1, s2) \leftarrow dp(i, s1, s2) \lor dp(i - 1, s1, s2 - S[i])
14:
                      end if
15:
                  end for
16:
             end for
17:
        end for
18:
```

```
bestPair \leftarrow (-1, -1)
19:
        leastMax \leftarrow \infty
20:
        for all (s1, s2) \in [0, s] \times [0, s] do
21:
            if dp(n, s1, s2) = \top and \max(s1, s2, s - (s1 + s2)) < leastMax then
22:
                leastMax \leftarrow \max(s1, s2, s - (s1 + s2))
23:
24:
                bestPair \leftarrow (s1, s2)
            end if
25:
        end for
26:
        return Backtrack(dp, S, bestPair) > return the partition after backtracking on the
27:
    DP table
28: end procedure
```

The Backtrack routine used in the last step generates the partitions which give the optimal values of the sum. It is given as:

Algorithm 2 Backtracking to generate parition

```
procedure BACKTRACK(dp, S, (s1, s2))
    n \leftarrow size(S)
    S_1 \leftarrow \{\}
    S_2 \leftarrow \{\}
    S_3 \leftarrow \{\}
    for i in [n,1] do
        if s1 \ge S[i] and dp(i-1, s1 - S[i], s2) = \top then
             S_1 \leftarrow add(S_1, i)
             s1 \leftarrow s1 - S[i]
         else if s2 \geq S[i] and dp(i-1, s1, s2 - S[i]) = \top then
             S_2 \leftarrow add(S_2, i)
             s2 \leftarrow s2 - S[i]
         else
             S_3 \leftarrow add(S_3, i)
         end if
    end for
    assert (s1 = 0 \text{ and } s2 = 0)
    return (S_1, S_2, S_3)
end procedure
```

We have shown the correctness of the DP table in Claim 1.1, therefore, to prove correctness of Algorithm 1, we need to show the correctness of the for loop from lines 21-26 and Algorithm 2. The for loop iterates over all possible states of (s1, s2) and finds the best state out of the valid states (where $dp(i, s1, s2) = \top$). Since the states explored by the for loop are exhaustive, the optimal solution is selected.

To prove the correctness of Algorithm 2, we notice that dp(i, s1, s2) is \top only if there exists a valid partitioning. Therefore, when updating i, s1, s2 in the for loop, we move from one valid partition to another. Therefore, Algorithm 2 generates the correct partitioning. This

completes the proof of correctness for Algorithm 1.

Space complexity: We create a dp table of size $(n+1) \times (s+1) \times (s+1)$ in Algorithm 1 and we generate the sets S_1, S_2, S_3 which have a total size of n in Algorithm 2. We use constant space everywhere else. Therefore the total space complexity of the solution is

$$O(n \times s \times s) + O(n) = O(n \times s^2) = O(n \times (n \times \max(S))^2) = O(n \times (n \times n)^2) = O(n^5)$$
 (2)

Time complexity: We run nested for loop in Algorithm 1 (lines 6-18) having a total of $n \times (s+1) \times (s+1)$ iterations and each iteration taking O(1) time. We run another for loop (lines 21-26) which has $(s+1) \times (s+1)$ iterations and each iteration again takes O(1) time. We run a for loop of n iterations in Algorithm 2 and each iteration takes O(1) time (add can be implemented in O(1) using a list or vector). All other operations take O(1). Therefore the total time complexity is given by:

$$O(n \times s \times s) + O(s \times s) + O(n) = O(n \times s^2) = O(n^5)$$
(3)

We have thus obtained a polynomial time algorithm for parititioning the given set S into S_1, S_2, S_3 such that $\max\{\sum_{i \in S_1} x_i, \sum_{i \in S_2} x_i, \sum_{i \in S_3} x_i\}$ is minimized.

2.1 2.1

2.1	
Question. insert question	
Solution. Proof is left as an exercise.	

2.2 2.2

2.2	
Question. insert question	
Solution. Proof is left as an exercise.	

2.3 2.3

2.3	
Question. insert question	
Solution. Proof is left as an exercise.	

Suppose you are a trader aiming to make money by taking advantage of price differences between different currencies. You model the currency exchange rates as a weighted network, wherein, the nodes correspond to n currencies — c_1, \ldots, c_n , and the edge weights correspond to exchange rates between these currencies. In particular, for a pair (i,j), the weight of edge (i,j), say R(i,j), corresponds to total units of currency c_i received on selling 1 unit of currency c_i .

3.1 3.1

Question 3.1

Question. Design an algorithm to verify whether or not there exists a cycle $(c_{i_1}, \ldots, c_{i_k}, c_{i_{k+1}} = c_{i_1})$ such that exchanging money over this cycle results in positive gain, or equivalently, the product $R(i_1, i_2) \cdot R(i_2, i_3) \cdots R(i_{k-1}, i_k) \cdot R(i_k, i_1)$ is larger than 1.

Solution. Consider the transformation function $t: \mathbb{R}^+ \to \mathbb{R}$,

$$t(x) = -\log(x) \tag{4}$$

We observe that t is a strictly decreasing function. Applying this transformation function on the edges in the given graph G (the function can be applied since all edges R(i,j) are positive), we get the condition for *positive gain* as:

$$R(i_{1}, i_{2}) \cdot R(i_{2}, i_{3}) \cdots R(i_{k-1}, i_{k}) \cdot R(i_{k}, i_{1}) > 1$$

$$\iff t(R(i_{1}, i_{2}) \cdot R(i_{2}, i_{3}) \cdots R(i_{k-1}, i_{k}) \cdot R(i_{k}, i_{1})) < t(1)$$

$$\iff \sum_{j=1}^{k} t(R(i_{j}, i_{j+1})) < 0$$
(5)

Therefore, after applying the transformation on the edges, our problem reduces to finding a cycle of negative weight in the graph G.

We assume that the given graph is strongly connected, since it makes sense to be able to perform currency exchange between any two currencies i, j. This ensures that all cycles present in G are accessible from any vertex i. To find a cycle of negative weight, we will run Bellman Ford algorithm for |V| = n iterations and if there is a change in the distances between any pair of the vertices in the last iteration, we will report detection of cycle with negative weight.

Algorithm 3 Detect cycle with negative weight

- 1: **procedure** DetectCycle(G)
- 2: $u \leftarrow \text{any vertex of } G$
- $n \leftarrow |V|$
- 4: $d \leftarrow \text{array of size } n \text{ initialised with } \infty$
- 5: $d[u] \leftarrow 0$

```
for i in [1, n-1] do
6:
           for all (x, y) \in E do
7:
              if d[y] > d[x] + t(R(x,y)) then
8:
                  d[y] \leftarrow d[x] + t(R(x,y))
9:
               end if
10:
           end for
11:
       end for
12:
       for all (x, y) \in E do
13:
           if d[y] > d[x] + t(R(x,y)) then
14:
              return True
15:
           end if
16:
       end for
17:
       return False
18:
19: end procedure
```

To prove the correctness of the above algorithm, we will prove the following claim:

Claim 3.1. There exists a walk of shortest length from a source vertex u to a vertex v using atmost n-1 edges if there is no cycle of negative weight.

Proof. Let G have no cycle of negative weight. Now, consider a walk W of shortest length using more than n-1 edges. If no such walk exists then we have trivially proved the claim. Since W uses more than n-1 edges, there exists a vertex w which appears at least twice in W. Let the walk and its length be given as:

$$W = \{u, \dots, w, x_1, \dots, x_k, w, \dots, v\}$$

$$\implies d(W) = length(\{u, \dots, w\}) + length(\{w, x_1, \dots, x_k, w\}) + length(\{w, \dots, v\})$$
(6)

Now consider the length of walk W' given by $\{u, \ldots, w, \ldots, v\}$ (after removing the cycle at w):

$$d(W') = length(\{u, ..., w\}) + length(\{w, ..., v\})$$

$$\implies d(W') = d(W) - length(\{w, x_1, ..., x_k, w\})$$

$$\implies d(W') \le d(W), \text{ no negative cycle exists in } G$$

$$\implies d(W') = d(W), d(W) \text{ is the shortest length of any walk}$$
(7)

We know that |E(W')| < |E(W)| and thus we have found another walk of shortest length using lesser number of edges than W. Note that W' might still use more than n-1 edges. Now, we repeat the above procedure to obtain a walk W_0 such that no vertex in W_0 appears twice. Therefore, $|E(W_0)| \le n-1$. Therefore, we have found the walk of shortest length using at most n-1 edges. This completes the proof of the claim.

Now, if G has no cycle of negative weight, then Algorithm 3 will have no improvement in the last for loop, using Claim 3.1. Additionally, by the contrapositive of Claim 3.1, there will be an update in the n^{th} iteration given by lines 13-18 of Algorithm 3.

Time and Space Complexities: The time and space complexities of the algorithm are identical to those of the Bellman-Ford algorithm. The time complexity is $O(|V| \times |E|)$ and the space complexity is O(|V|).

3.2 3.2

4.1 4.1

4.1

Question. You are given a set of k denominations. Devise a polynomial time algorithm to count the number of ways to make change for Rs.n., given an infinite amount of coins/notes of denominations, d[1], ..., d[k].

Solution. The assumptions made are that the number of coins of every denomination are infinite and they are integral values.

We solved this problem using dynamic programming. Given the cost n and array of possible denominations denom with size k, we create dpTable which is an (n+1) array. dpTable[i]counts the number of ways to generate value i using the given denominations. The answer is obtained by observing value of the last element dpTable[n].

Algorithm 4 Find total possible combinations of denominations to achieve value of n

```
procedure Combinations(denom, n)
      k \leftarrow size(denom)
                                                            ▶ number of types of denominations
      dpTable \leftarrow 1D-zero array of size (n+1)
      dpTable[0] \leftarrow 0
                                                  \triangleright there is trivially one way to generate sum 0
      for i in [1, n + 1) do
         for j in [1, k + 1) do
             if i \geq denom[j] then
                                                   ▶ denomination should not be greater than i
                 dpTable[i] \leftarrow dpTable[i] + dpTable[i - denom[j]]
             end if
         end for
      end for
      return dpTable[n][k]
  end procedure
                                                                                                 Proof of correctness.
```

Proof of termination. Here, we have a finite table of size (n+1). We iterate through the entire table and exit successfully in any case. Hence the algorithm terminates.

Time Complexity. Deciding factors for time-complexity in big-Oh notation are going through the entire dpTable and running a for loop with k iterations at each index of the table. Time complexity = $O(n \times k)$

This is a polynomial time solution.

Space Complexity. We create a dpTable of size n+1 and use constant space everywhere else. Space complexity = O(n)

4.2 4.2

4.2

Question. You are given a set of k denominations. Device a polynomial time algorithm to find a change of Rs.n using the minimum number of coins.

Solution. The assumptions made are that the number of coins of every denomination are infinite and they are integral values.

```
Algorithm 5 Find total possible combinations of denominations to achieve value of n
```

```
procedure LeastCurr(denom, n)

k \leftarrow size(denom) ▷ number of types of denominations

dpArr \leftarrow array of size n+1 initialised with \infty

dpArr[0] \leftarrow 0 ▷ Base case: no coin needed n=0

for index in [1, n+1] do

for i in [0, k) do

if index - denom[i] \ge 0 then

dpArr[index] \leftarrow min(dpArr[index], dpArr[index - denom[i]] + 1)

end if
end for
end for
return dpArr[n]
end procedure
```

Proof of correctness.

Proof of termination. We iterate through the entire array of size n and exit successfully in any case. Hence the algorithm terminates. \Box

Time Complexity. Deciding factors for time-complexity in big-Oh notation are going through the entire dpArray and running a for loop of k iterations for each index.

Time complexity = $O(n \times k)$

This is a polynomial time solution.

Space Complexity. We create a dpArray of size n+1 and use constant space everywhere else. Space complexity = O(n)