Forces with KRR

Malthe Kjær Bisbo

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1 Kernel Ridge Regression

Kernel Ridge Regression (KRR) is basically an upgraded version of regularized linear regression, which is made linear by the kernel trick $x^Tx' \to k(x,x')$, where k(.,.) is the kernel.

Regularized linear regression

In regularized linear (least square) regression we seek the coefficients w that minimizes the cost function

$$\min_{w} \left(\sum_{i}^{N} (\vec{w}^T x_i - y_i)^2 + \lambda \sum_{i}^{N} w_i^2 \right)$$

or

$$\min_{w} \left((X\vec{w} - \vec{y})^2 + \lambda \|\vec{w}\|^2 \right)$$

Where X is the matrix with the x_i^T 's as it's rows. The solution is

$$\vec{w} = X^T (XX^T + \lambda I)^{-1} \vec{y} = X^T \vec{\alpha}$$

Where we define $\vec{\alpha} = (XX^T + \lambda I)^{-1}\vec{y}$. Predictions are then performed using

$$y' = \vec{w}^T x' = (X^T \vec{\alpha})^T x' = \vec{\alpha}^T X x'$$

Result: To train and use the regularized linear regression model as an ML-predictor We thus need two steps.

1. Training:

Calculate $\vec{\alpha}$ from training data.

$$\vec{\alpha} = (XX^T + \lambda I)^{-1}\vec{y}$$

2. Prediction:

Predict new value y' using

$$y' = \vec{\alpha}^T X x'$$

$\mathbf{Kernel\ Trick} \to \mathbf{KRR}$

Applying the kernel trick using the kernel k(.,.) we get

$$XX^T \to \mathbf{K}$$
 where $\mathbf{K}_{ij} = k(\vec{x_i}, \vec{x_j})$

and

$$Xx' \to \vec{\kappa}$$
 where $\kappa_i = k(\vec{x_i}, \vec{x'})$

Result: To use *Kernel Ridge Regression* for training and prediction we need the two results.

1. Training:

Calculate $\vec{\alpha}$ from training data.

$$\vec{\alpha} = (\mathbf{K} + \lambda I)^{-1} \vec{y} \tag{1}$$

2. Prediction:

Predict new value y' using

$$y' = \vec{\alpha}^T \vec{\kappa} \tag{2}$$

Kernel function

One choice is the $Gaussian\ kernel$

$$k(\vec{x}, \vec{x'}) = \exp\left(\frac{d(\vec{x}, \vec{x'})^2}{2\sigma^2}\right) \tag{3}$$

where

$$d(\vec{x}, \vec{x'}) = \sqrt{\sum_{k}^{M} (x_k - x'_k)^2}$$
 (4)

${ m KRR}$ prediction-error estimate

The estimate of the prediction error on a new point x' is

$$\operatorname{err}(x') = \sqrt{|\theta_0[1 - \vec{\kappa}(x') \cdot \vec{\alpha_2}(x')]|} \tag{5}$$

where

$$\vec{\alpha_2}(x') = (\mathbf{K} + \lambda I)^{-1} \vec{\kappa}(x')$$

and

$$\theta_0 = \frac{y \cdot \alpha_1}{N_{train}}$$

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