

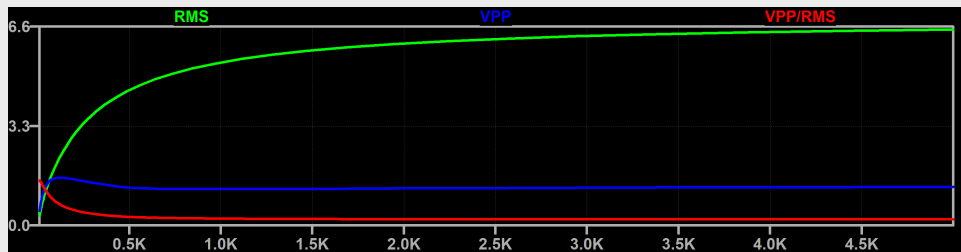
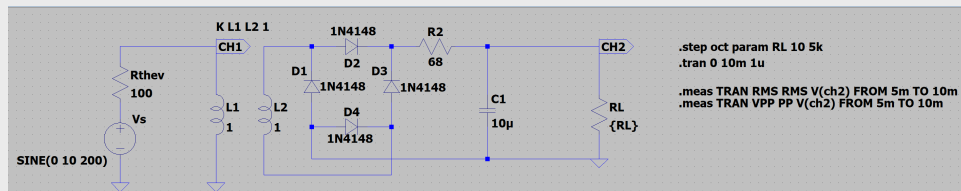
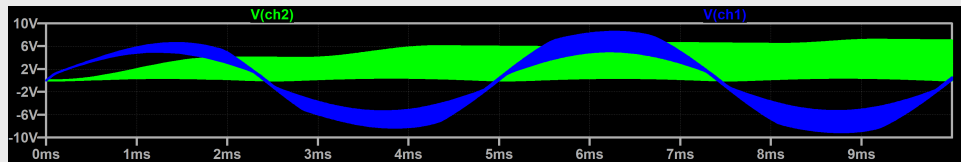
PHSX 536: Homework #6

March 6, 2025

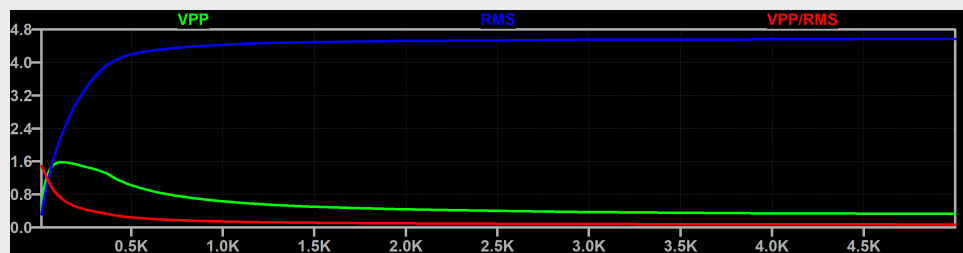
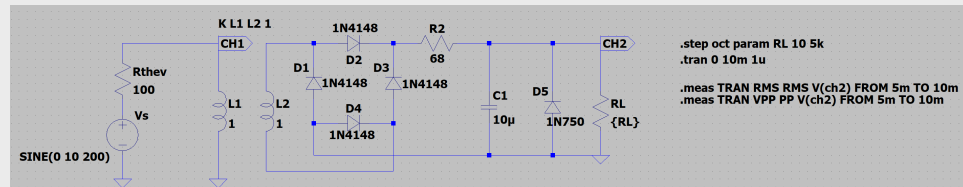
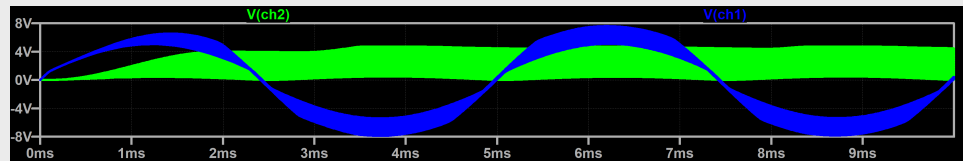
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Use LTSpice to simulate the Zener diode regulated power supply circuit shown below. Assume a 1:1 transformer configuration with an effective impedance of the (primary circuit + transformer) ($R_{th\text{ev}}$ in the figure) set to the value that you determined in Experiment 5. Plot, as a function of the load resistance, with R_L varying between $10\ \Omega$ and $5000\ \Omega$ in octave steps, the voltage across the load both with and without the Zener diode in place. Determine the Thevenin equivalent values for your circuit when the Zener is NOT present. The results from this simulation are to be compared to your subsequent experimental results.

Solution #1, Without Zener:



Solution #2, With Zener:



Discussion of Circuits and Rthev:

Comparing the peak to peak and RMS curves, we can tell the zener introduces a "kink" in PP and RMS curves, and helps achieve better passive stabilization in the resulting signal. It is a little difficult to tell using LTSpice's default axes labels, but with a keen eye it's clear that "VPP" converges significantly faster beyond the $500\ \Omega$ resistance regime. The RMS also goes from a logarithmic curve to something which appears to flatten at load resistances beyond $500\ \Omega$ due to the nature of voltage drops across diodes.

Without attempting to simplify anything, I'll just attack the voltage throughout the secondary, where V is the voltage output on the secondary, and V_d is the drop across the diodes in the rectifier.

$$V = 2V_d + i_1 R_2 + i_1 Z_C - i_2 Z_C$$

$$0 = i_2 Z_C - i_1 Z_C + i_2 R_L$$

$$V_{th} = i_2 R_L$$

$$\begin{aligned}
0 &= \frac{V_{th}}{R_L} Z_C - i_1 Z_C + \frac{V_{th}}{R_L} R_L \\
0 &= \frac{V_{th} Z_C}{R_L} - i_1 Z_C + V_{th} \\
i_1 &= \frac{V_{th} Z_C}{R_L Z_C} + \frac{V_{th}}{Z_C} = V_{th} \left(\frac{1}{R_L} + \frac{1}{Z_C} \right) \\
V &= 2V_d + V_{th} \left(\frac{1}{R_L} + \frac{1}{Z_C} \right) R_2 + V_{th} \left(\frac{1}{R_L} + \frac{1}{Z_C} \right) Z_C - \frac{V_{th}}{R_L} Z_C \\
V &= 2V_d + V_{th} \left[\frac{R_2}{R_L} + \frac{R_2}{Z_C} + \frac{Z_C}{R_L} + 1 - \frac{Z_C}{R_L} \right] \\
V &= 2V_d + V_{th} \left[\frac{R_2}{R_L} + \frac{R_2}{Z_C} + 1 \right] \\
V_{th} &= \frac{V - 2V_d}{\frac{R_2}{R_L} + \frac{R_2}{Z_C} + 1} \\
V_{th} &= \frac{(V - 2V_d) R_L Z_C}{R_2 Z_C + R_2 R_L + R_L Z_C}
\end{aligned}$$

And to determine the thevenin equivalent in the secondary, replacing the rectifier and additional diode D5 with shorts, we'd have a resistance given as

$$\begin{aligned}
Z_S = R_{th} &= R + \frac{R_L Z_C}{Z_C + R_L} \\
&= R + \frac{R_L (1/j\omega C)}{(1/j\omega C) + R_L} \\
&= R + \frac{(R_L/j\omega C)}{(1 + R_L j\omega C)/j\omega C} \\
&= R + \frac{R_L}{1 + R_L j\omega C} \\
&= R + \frac{R_L}{1 + R_L j\omega C} \frac{1 - R_L j\omega C}{1 - R_L j\omega C} \\
&= R + \frac{R_L - R_L j\omega C}{1 + (R_L \omega C)^2} \\
&= R + \frac{R_L}{1 + (R_L \omega C)^2} - j \frac{R_L \omega C}{1 + (R_L \omega C)^2}
\end{aligned}$$

And we know that $\left(\frac{N_S}{N_P} \right)^2 = \frac{Z_S}{Z_P}$, so in this case we should expect $Z_P = Z_S$ for an optimal configuration.

As a note to myself on the confusing and poorly documented nature of LTSpice, to produce plots with measured values, one must open the log (ctrl+L) and right click to access this separate plotting interface.