

October 16, 2025

Master Degree in Bionics Engineering

Course of Principles of Bionics and Biorobotics Engineering

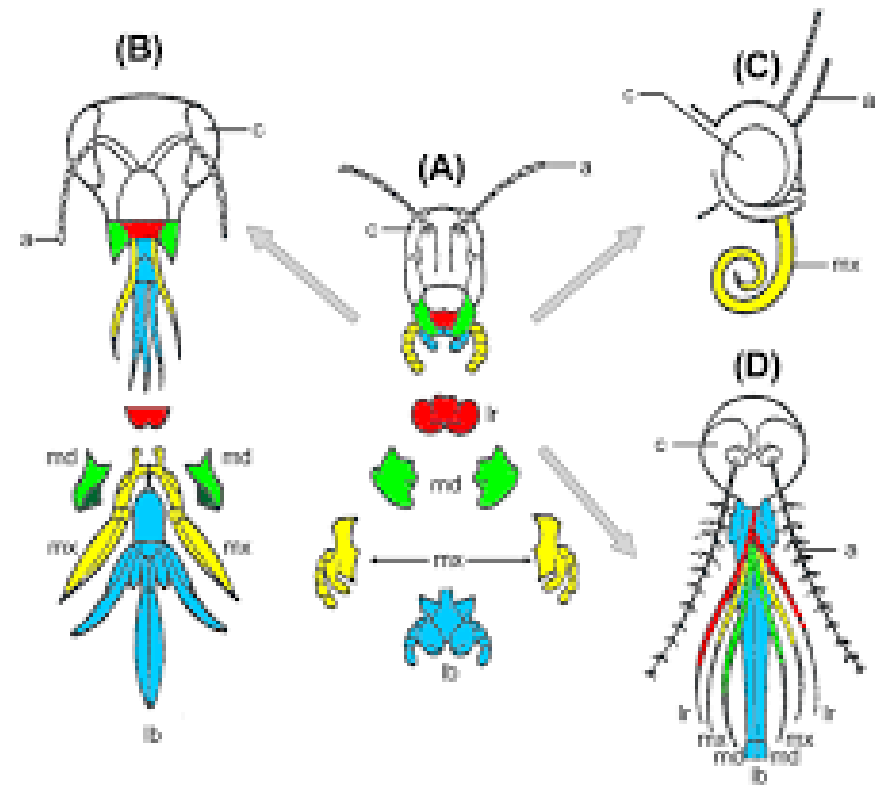
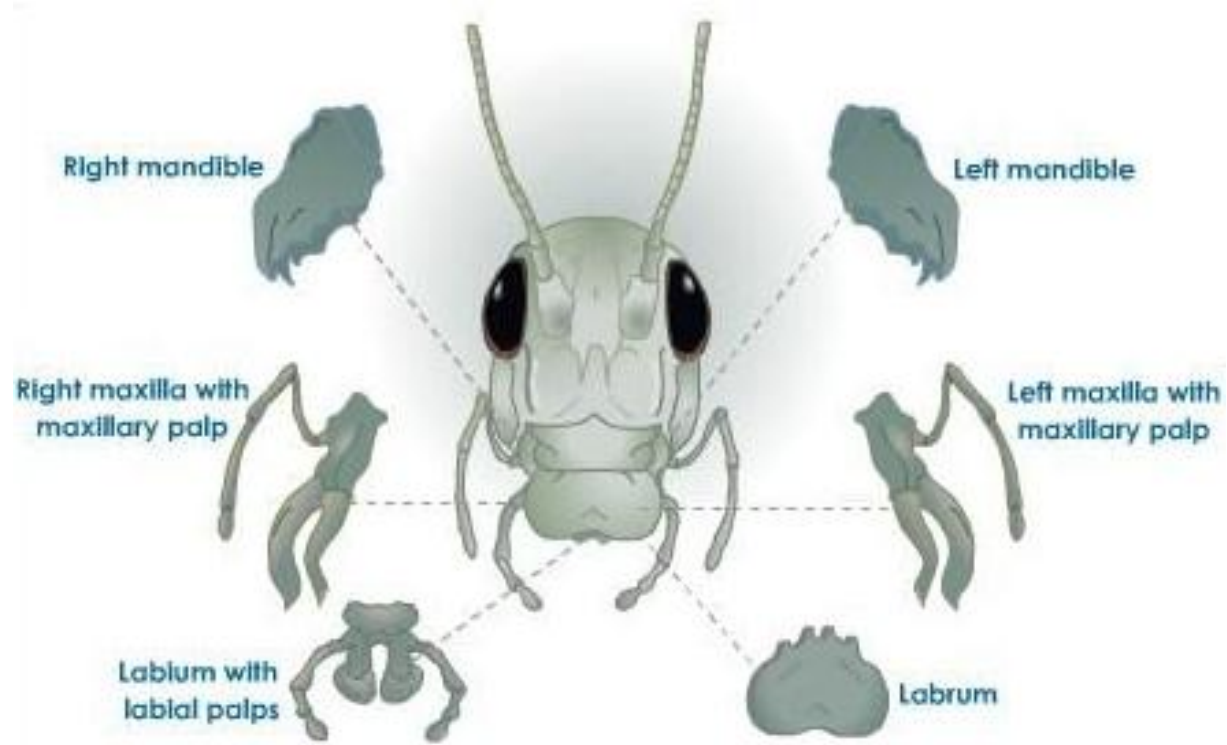
Lesson title:

Bionic locomotion principles – Terrestrial legged locomotion

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Head

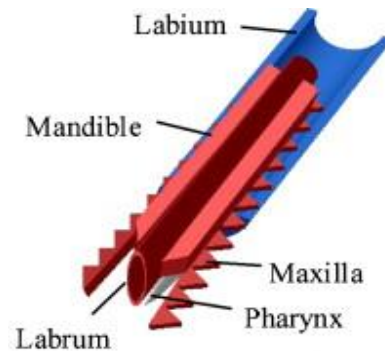


Mosquitoes inspired Needles

Ever notice how a mosquito can bite you without you even knowing it?

BIOLOGY:

A mosquito's proboscis includes an **internal tubular labrum** (that does the bloodsucking), which is sheathed between two serrated maxillae – one on either side. The **maxillae are what first penetrate** the skin and then sink into it, after which **the labrum slides down between them**. Because the maxillae have a jagged outer surface, they present a **minimum amount of surface area** to nerves in the skin.

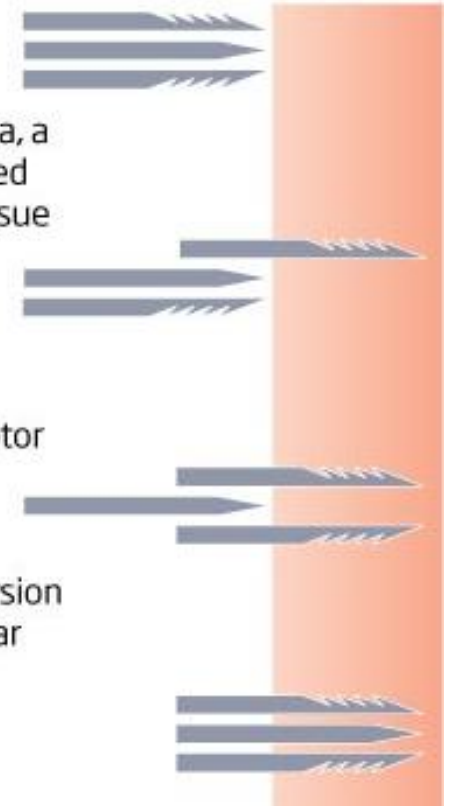


Like a mosquito's maxilla, a motor pushes one jagged outer shank into the tissue

Next, the opposite harpoon-like shank is inserted by another motor

Finally, a sharpened version of the mosquito's tubular labrum delivers drugs

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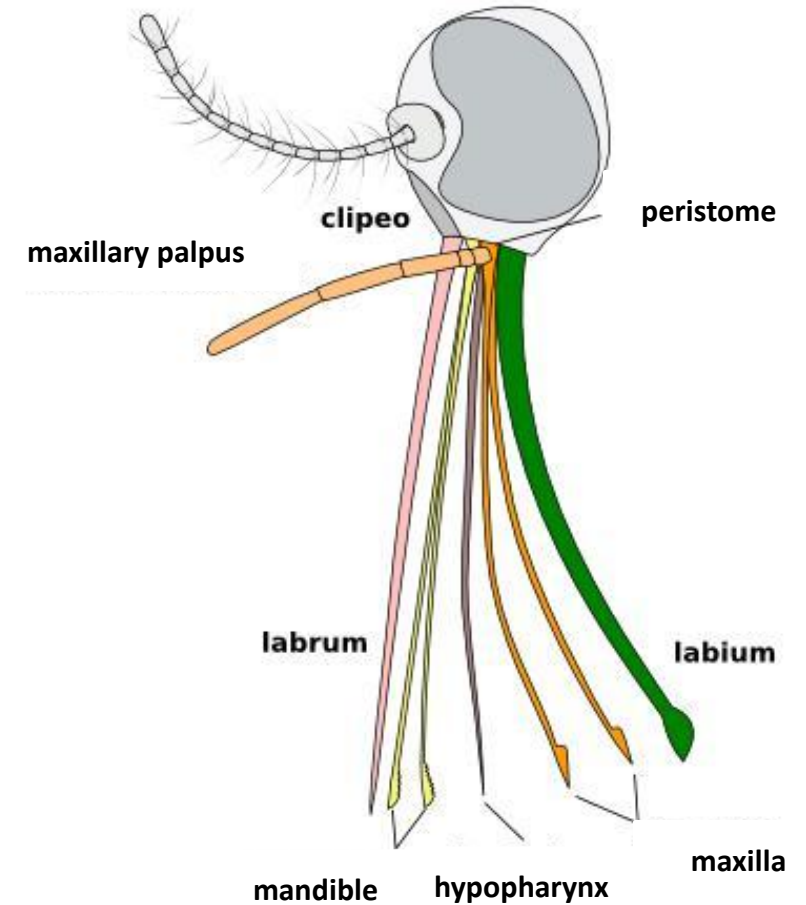
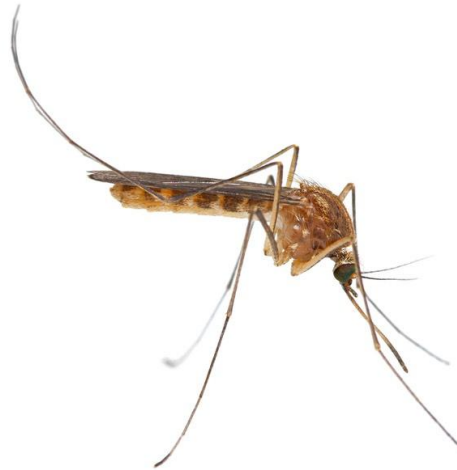


Mosquitoes inspired Needles

Ever notice how a mosquito can bite you without you even knowing it?

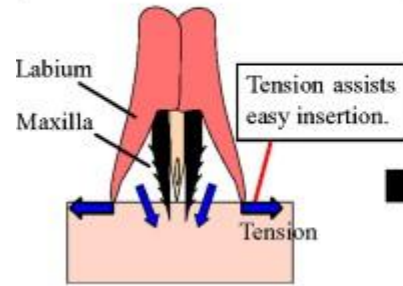


I= labrum
m= mandible
h= hypopharynx
mx= maxilla
li= labium

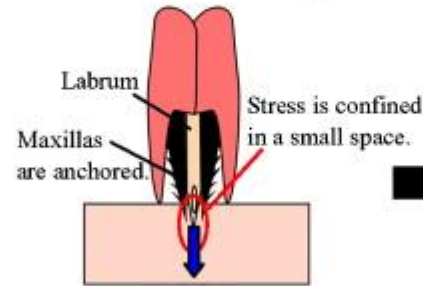


Mosquitoes inspired Needles

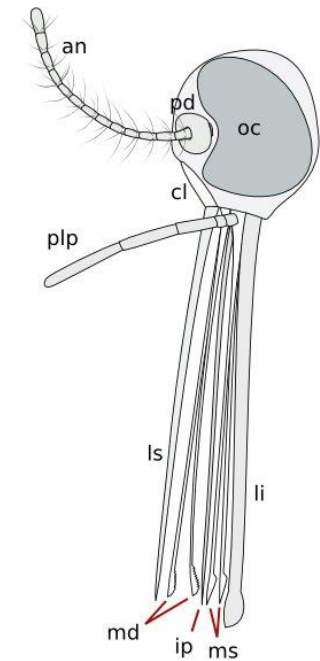
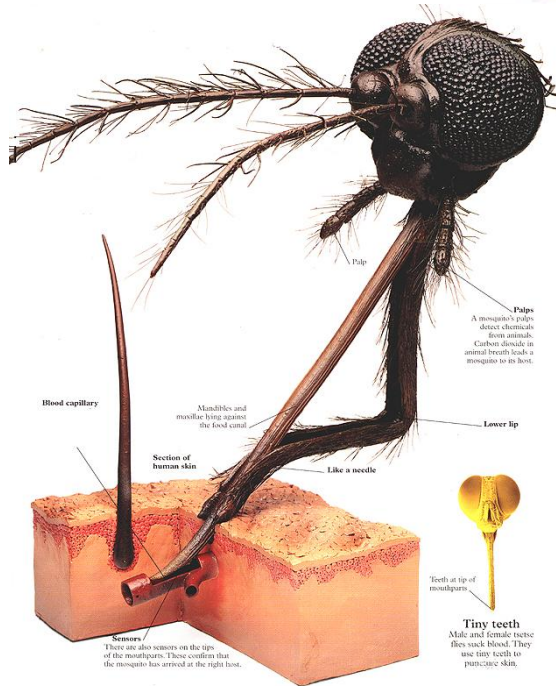
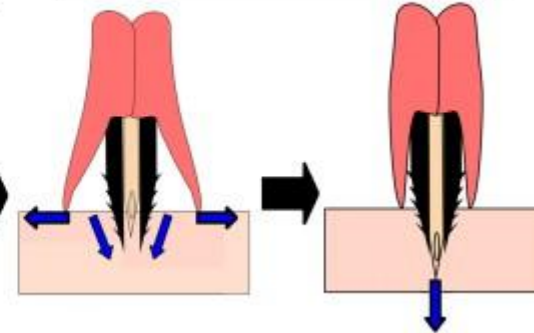
Jagged shape of maxilla is effective for generating stress concentration.



The stress distribution is confined between two anchored maxillas, which promotes stress concentration at labrum tip.

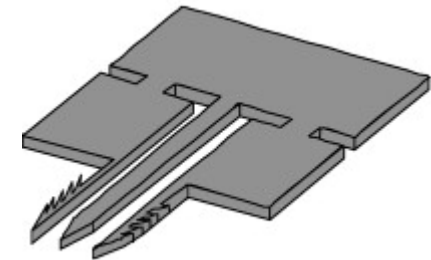
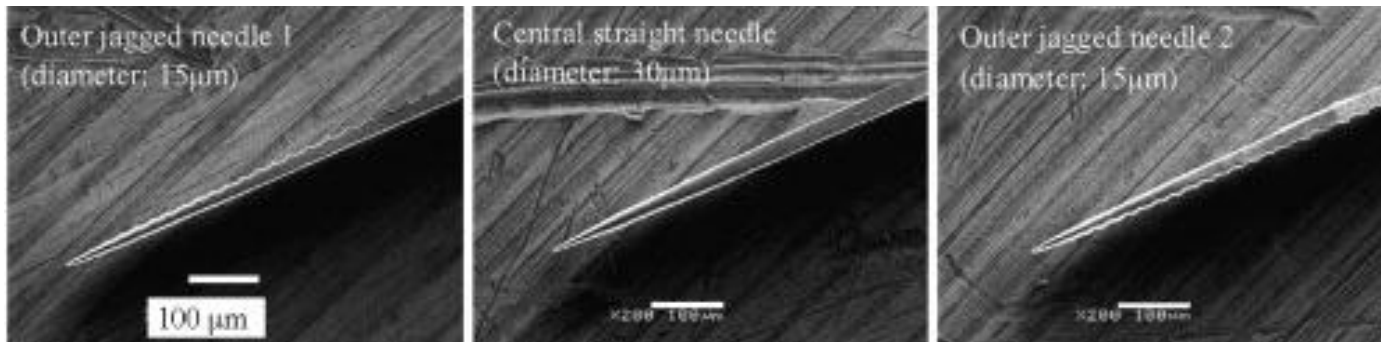


The repetition organizes the vibration at 30 Hz based on a saw-tooth waveform.



TECHNOLOGY:

Japanese microengineers created a **minute needle** just **1mm long** and with a diameter of **0.1 mm**. They etched slices of **silicon dioxide into a jagged shape** and bonded them together. There are two serrated shanks that form the outer surface of the needle. A **central shaft then slides between them to inject** or withdraw the sample. The needle is connected to a **small reservoir** that is equipped with an optical sensor to analyze samples.



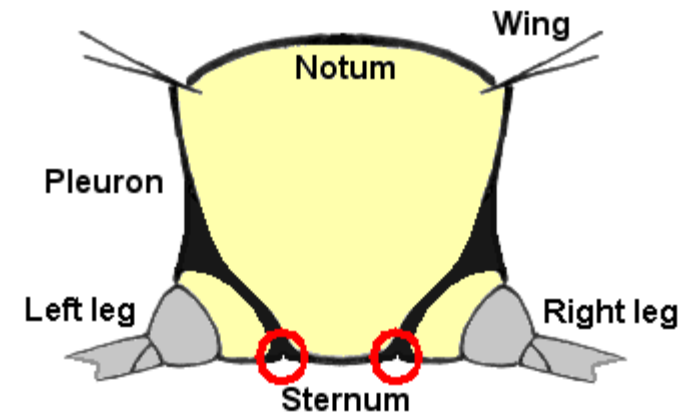
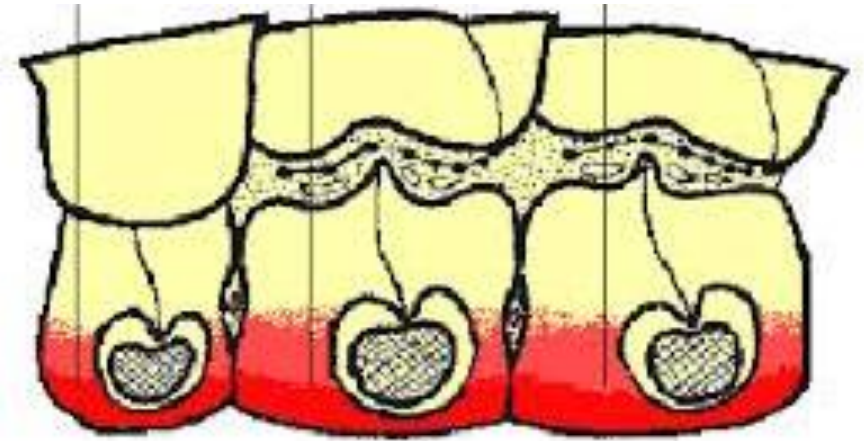
Thorax

The insect thorax has three segments:

1. Prothorax.
2. Mesothorax.
3. Metathorax.

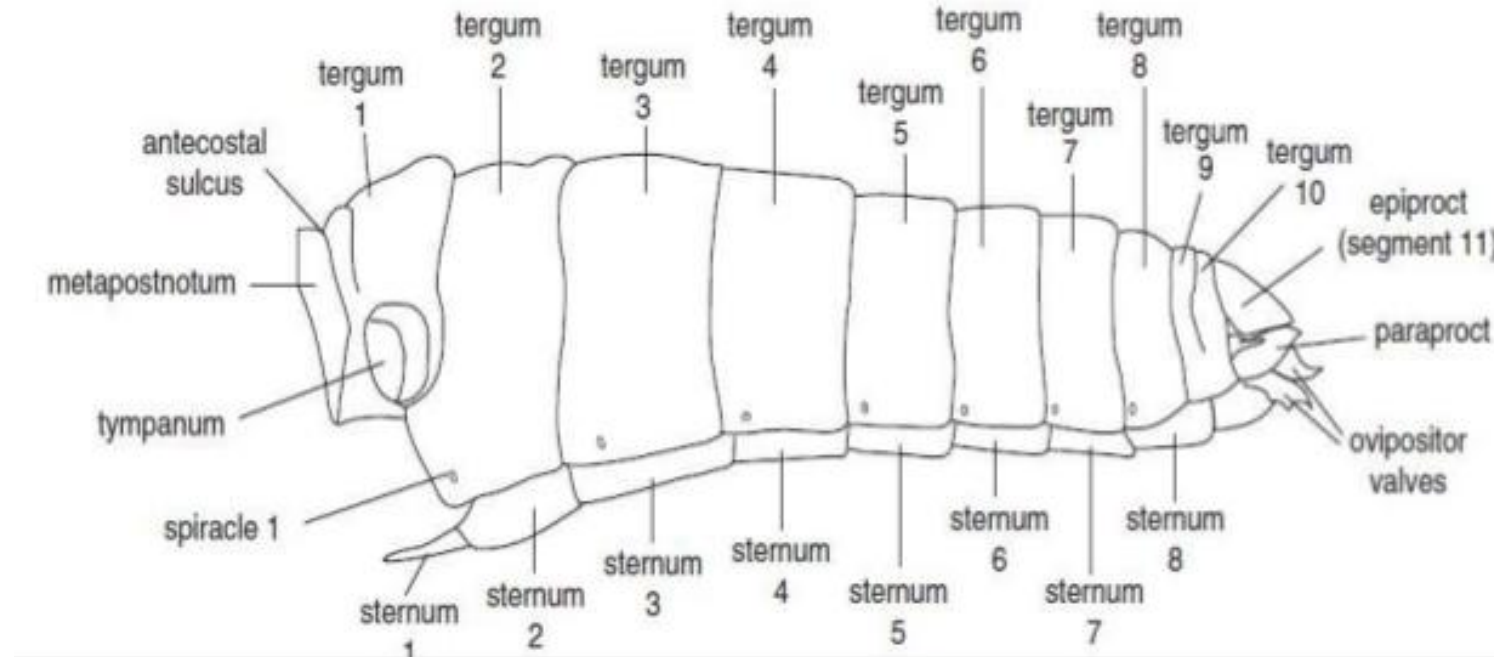
Each segment is delineated by an intersegmental suture. Each segment has four basic regions:

- Tergum (or notum), to distinguish it from the abdominal terga).
- Two lateral pleura (singular: pleuron).
- Sternum.

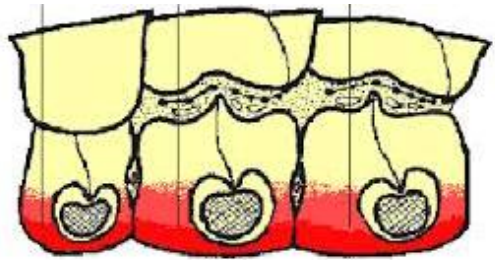
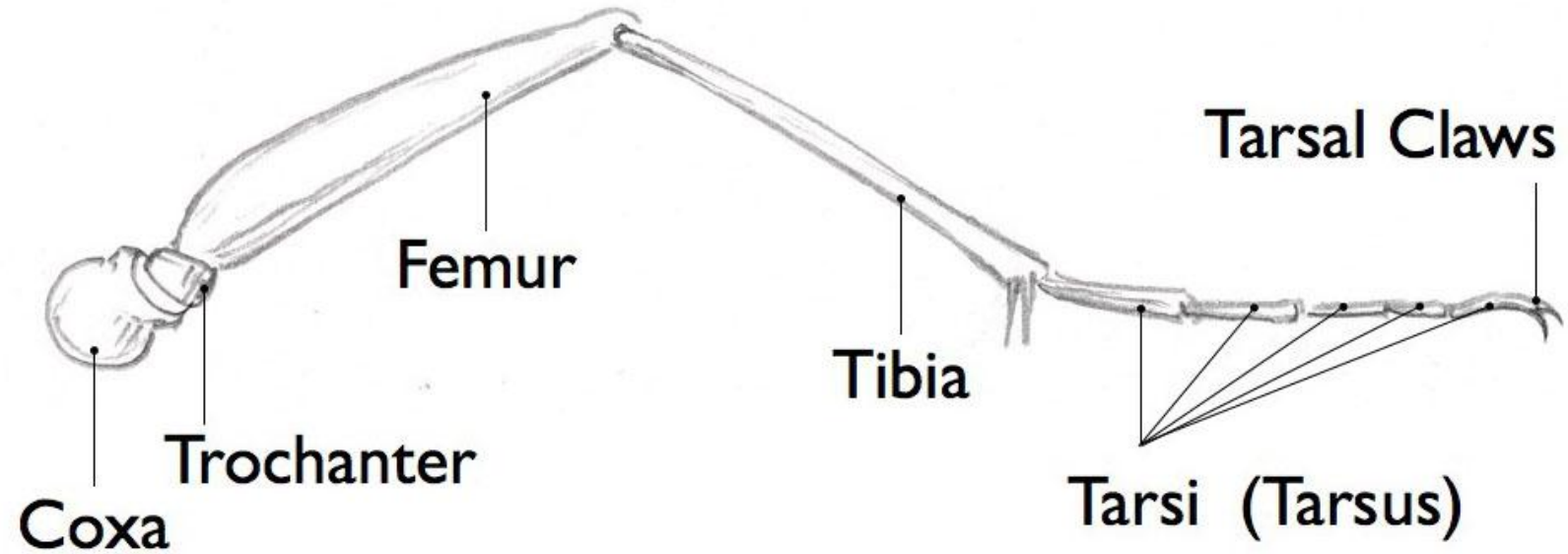
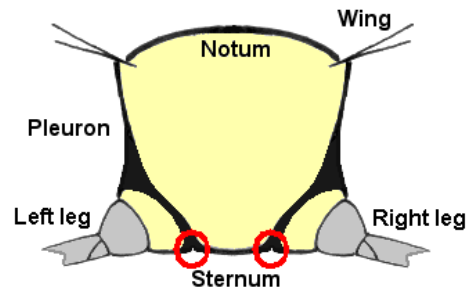


Abdomen

consists of 11–12 segments and is less sclerotized than the head or thorax.

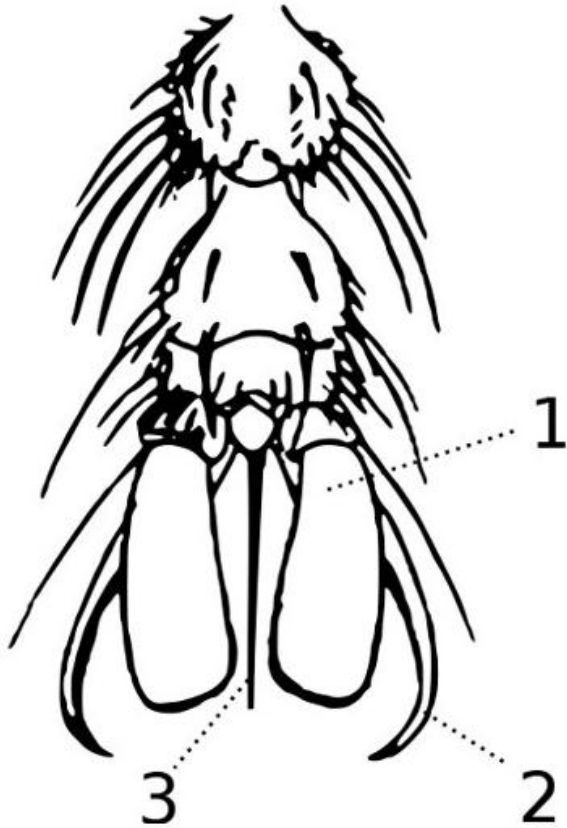


Legs



Legs

Pulvilli are lobes or pads that are located between the tarsal claws of many insects. The pads have adhesive properties, including the use of an adhesive fluid, and this helps the insect stick to the surface on which it is standing.



Legend

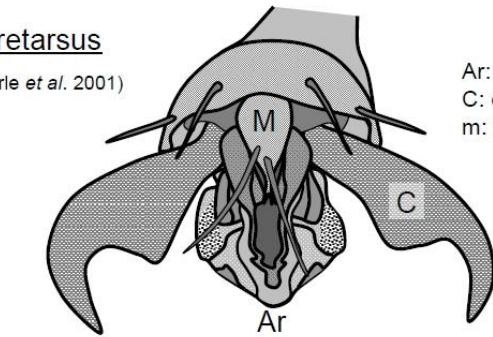
- 1. Pulvilli
- 2. Claw
- 3. Empodium



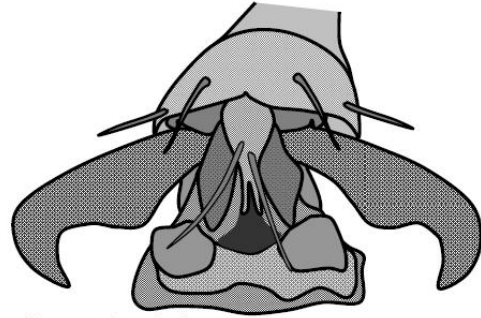
The Ant Pretarsus

(Based on Federle *et al.* 2001)

Ar: arolium
C: claw
m: manubrium

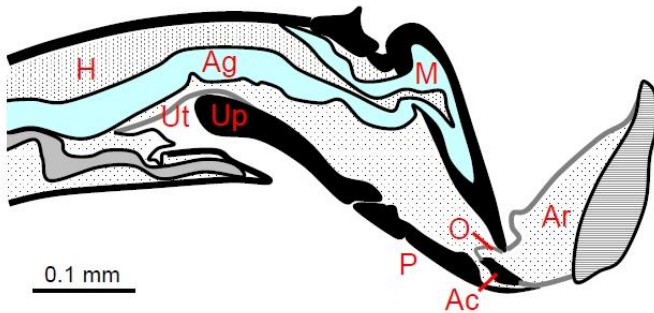


Arolium retracted



Arolium extended

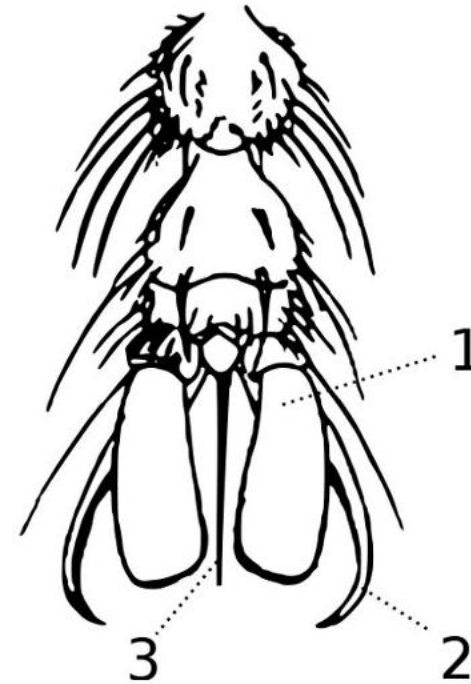
0.1 mm



Above: longitudinal section through pretarsus. Ac: arcus sclerite, Ag: arolium gland, Ar: arolium, H: haemocoel, M: manubrium, O: opening, P: planta, Up: unguitractor plate; Ut: unguitractor tendon

Legs

Many insects possess a lobe or spine between the two claws at the end of the tarsus (the final segment in the leg of the insect). This lobe or spine is called an **empodium**.



Legend

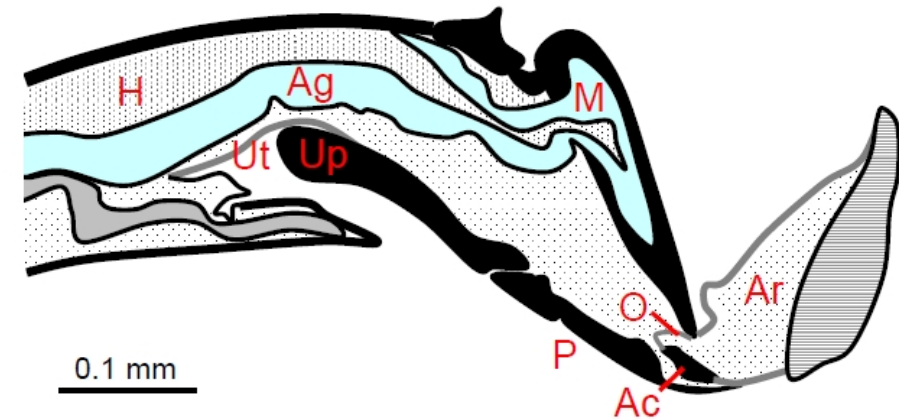
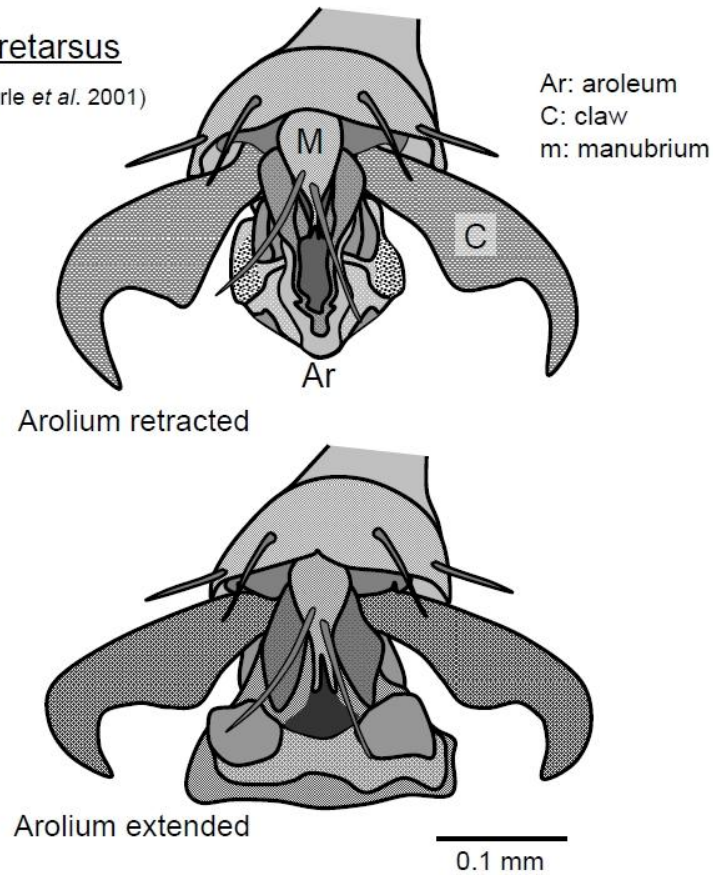
- 1. Pulvilli
- 2. Claw
- 3. Empodium

Legs

Above the unguitractor plate the pretarsus expands forward into a median lobe, the **arolium**. The arolium, and pulvilli are adhesive organs enabling their possessors to climb smooth or steep surfaces.

The Ant Pretarsus

(Based on Federle *et al.* 2001)



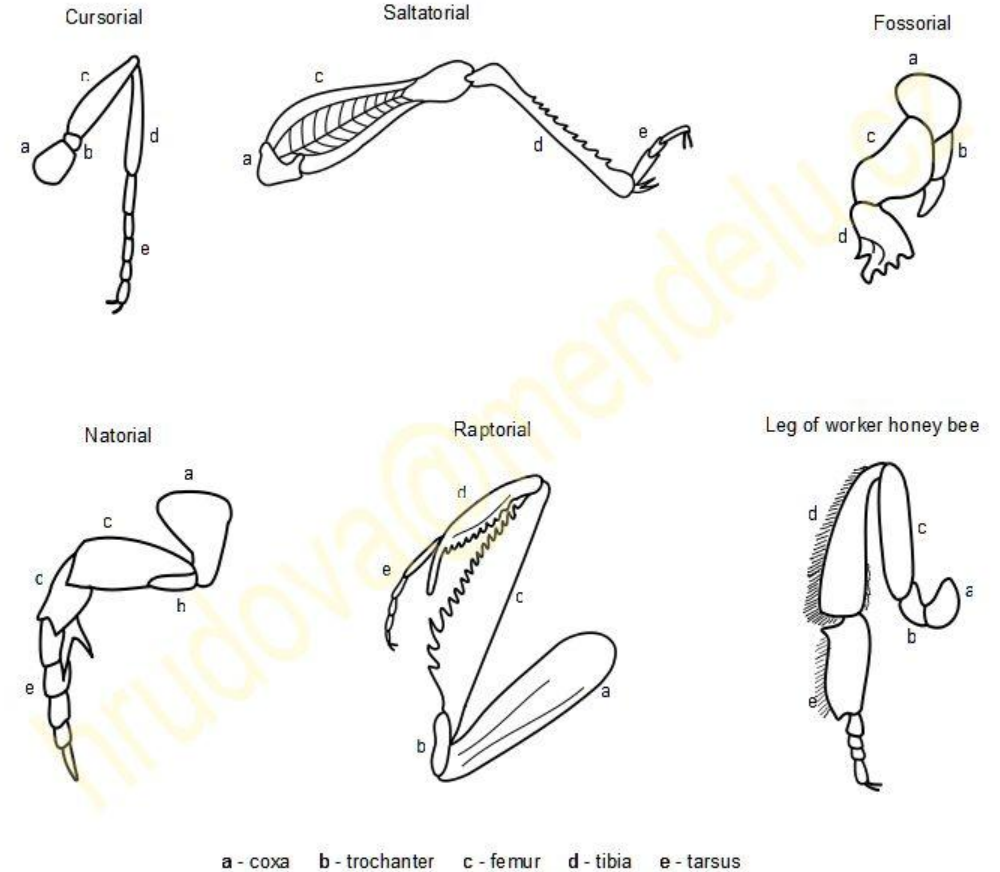
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Legs

Various modifications for various of functions



Types of insect legs

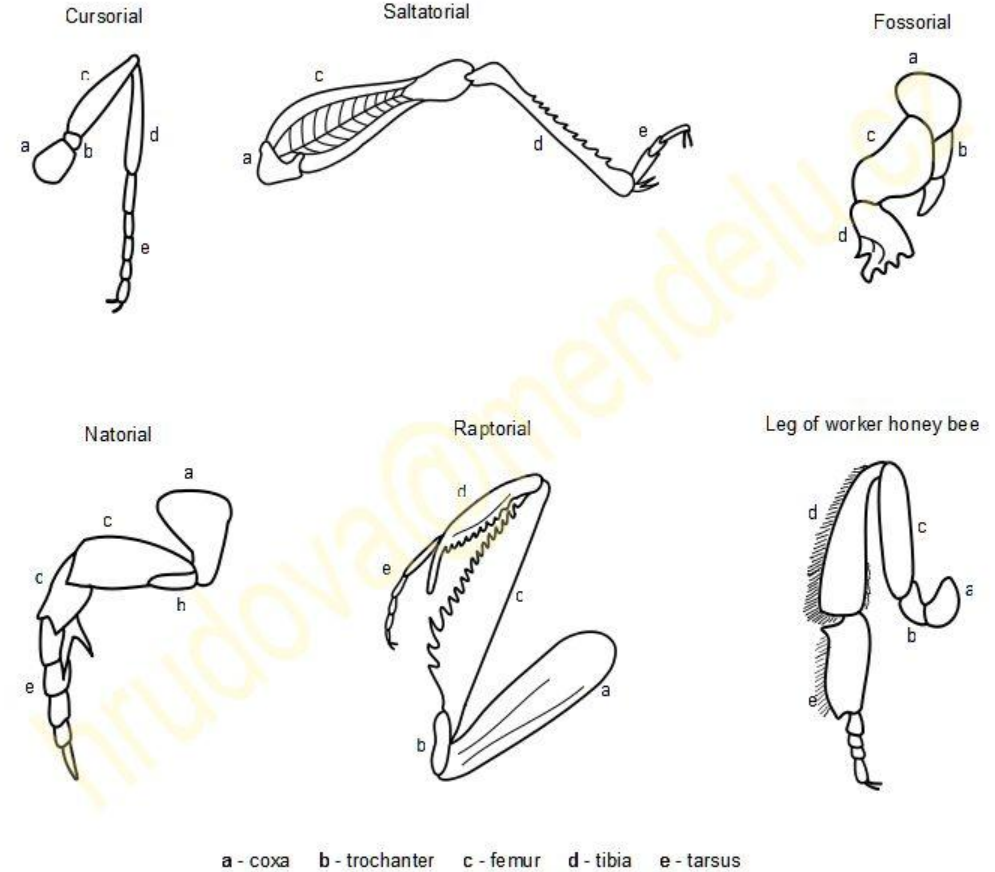


Legs

Various modifications for various of functions



Types of insect legs

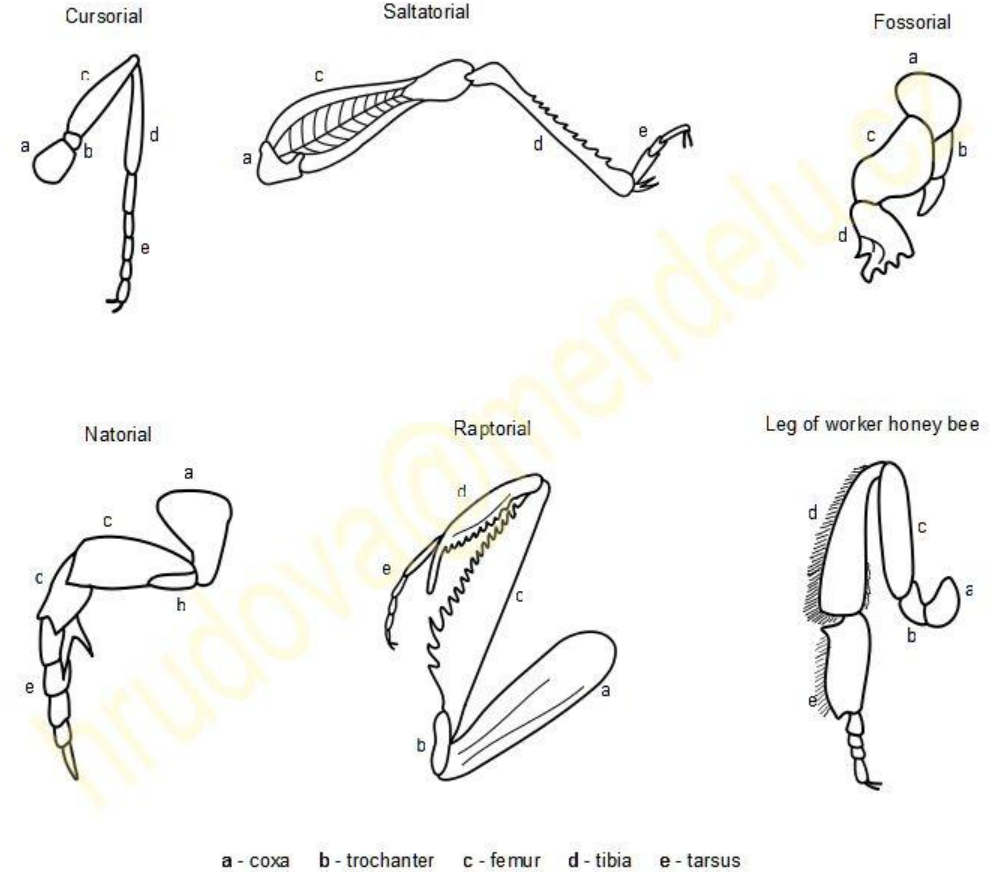


Legs

Various modifications for various of functions



Types of insect legs



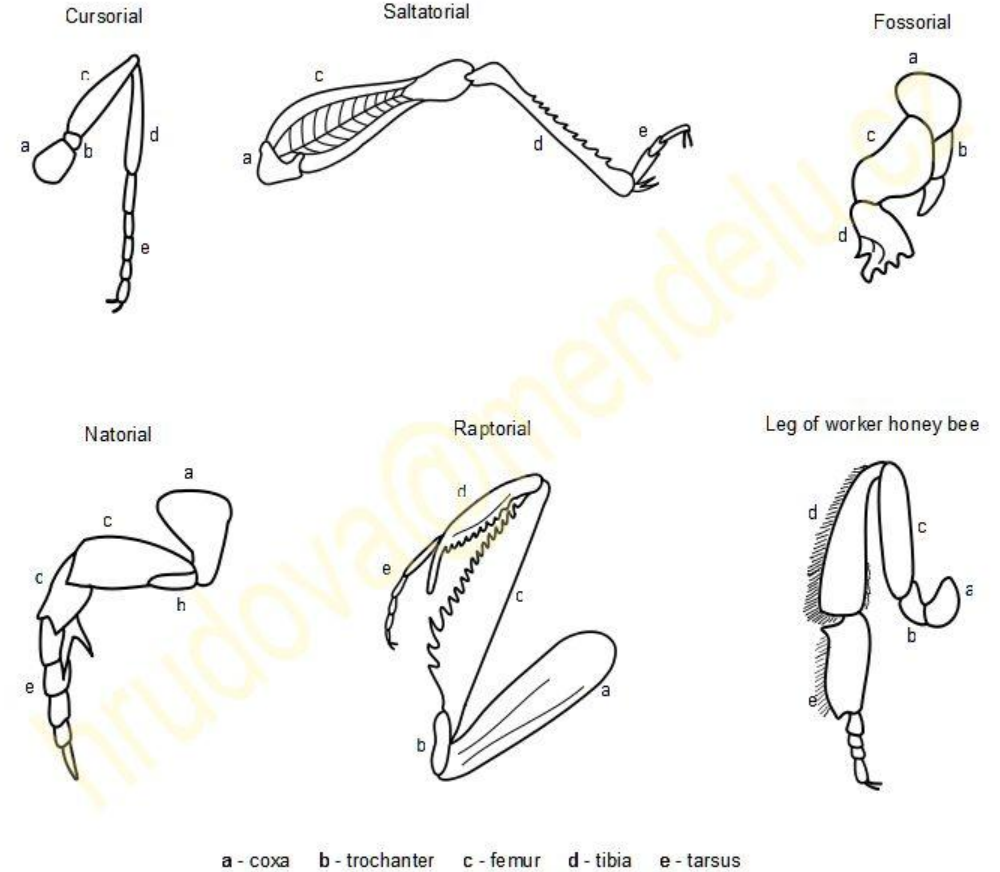
Legs

Various modifications for various of functions



Trichocorixa sexcincta

Types of insect legs

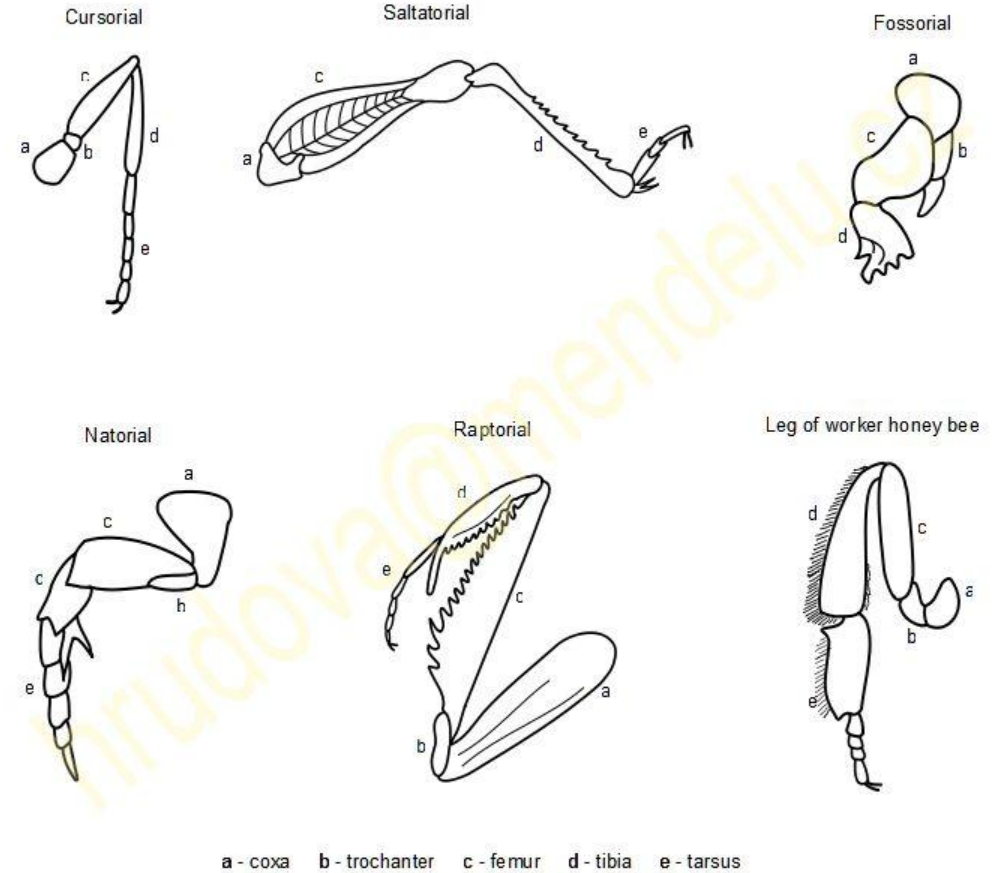


Legs

Various modifications for various of functions



Types of insect legs

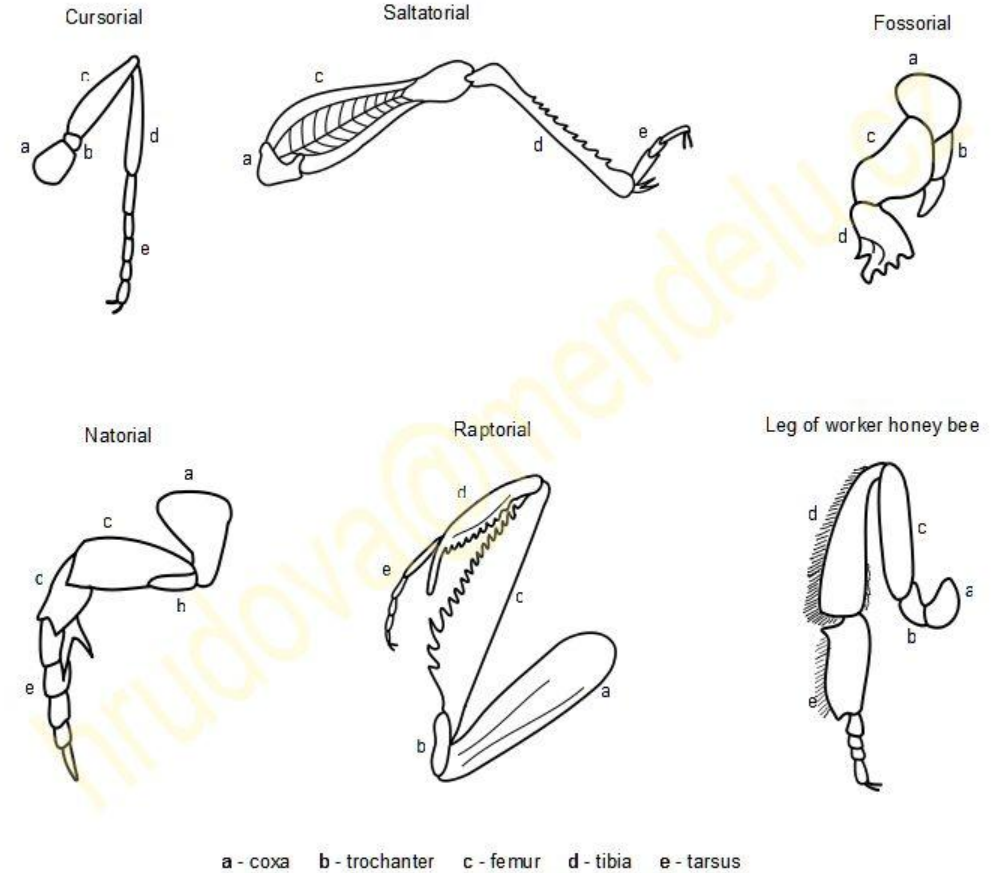


Legs

Various modifications for various of functions

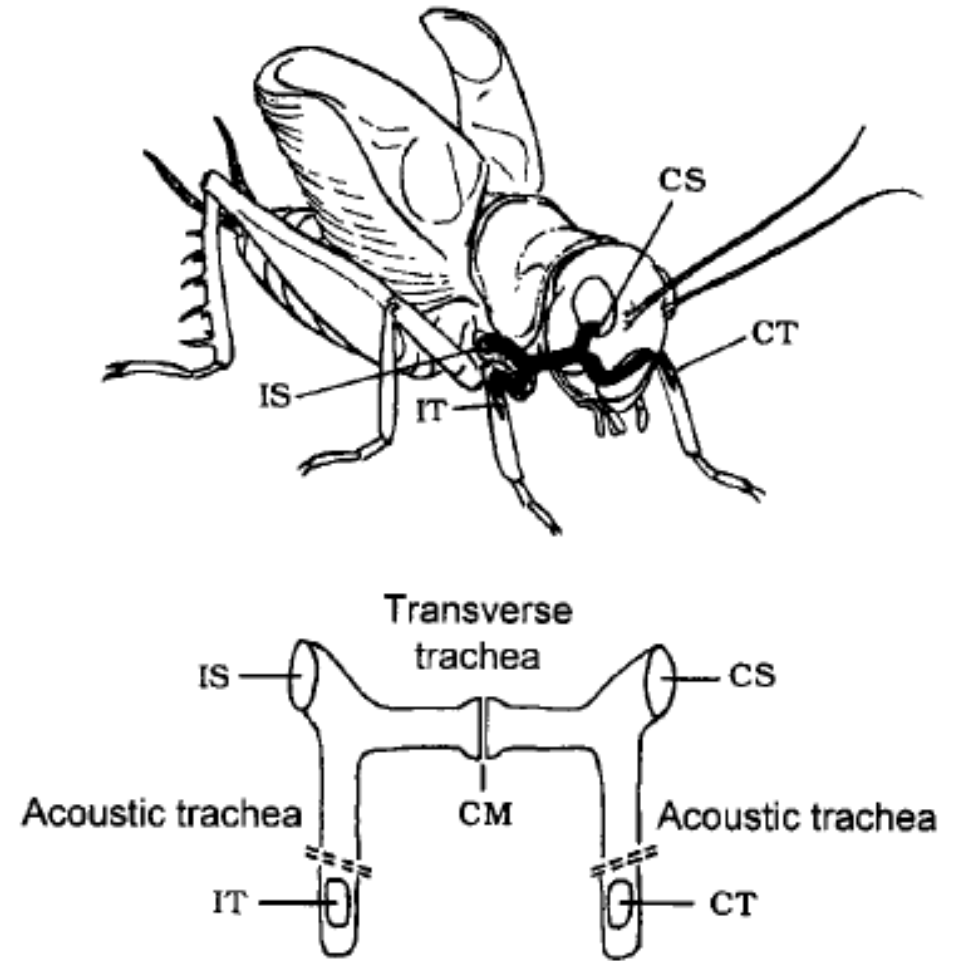


Types of insect legs



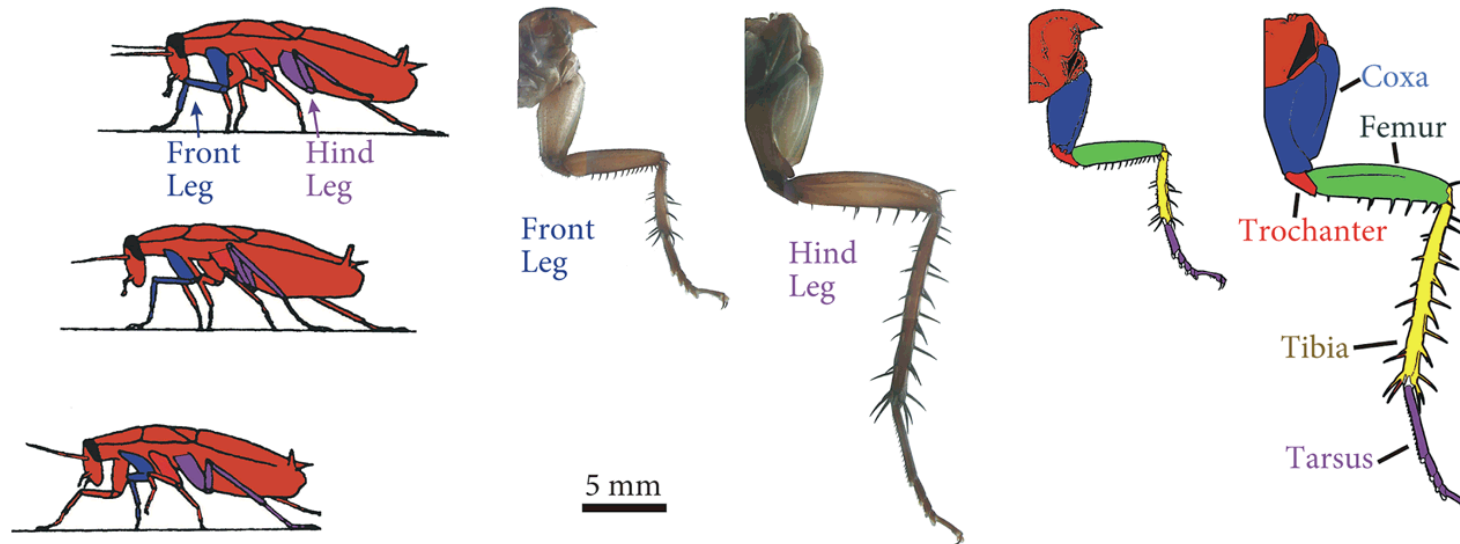
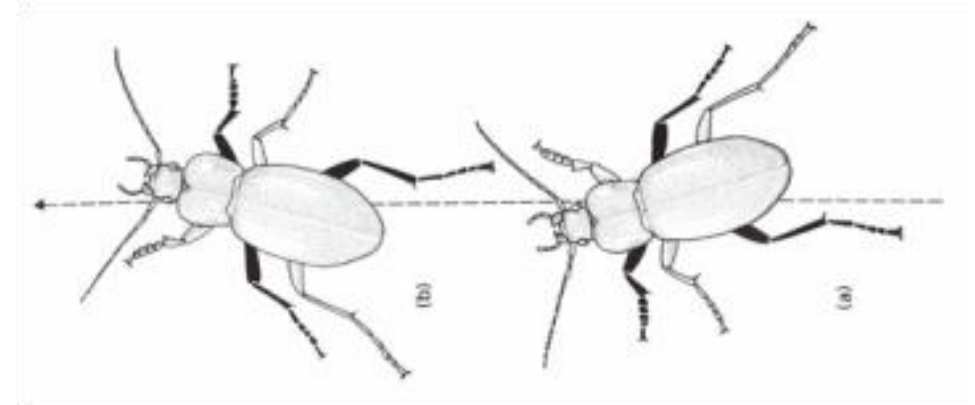
Auditory legs

The cricket ear is located in the front legs and is a sound receiver with four acoustic inputs. In the case of the right ear, one input is the external surface of the eardrum (IT: ipsilateral tympanum). Sound also propagates through the acoustic trachea from the ipsilateral spiracle (IS) to the inner surface of the eardrum. Finally, sound from the contralateral spiracle (CS) and contralateral ear (CT) may reach the inner surface of the eardrum by propagating through the transverse trachea and the acoustic trachea. Note that the sound from the contralateral inputs has to pass a (double) central membrane (CM) in the transverse trachea.



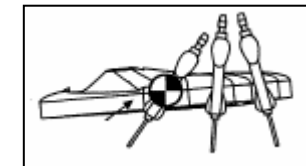
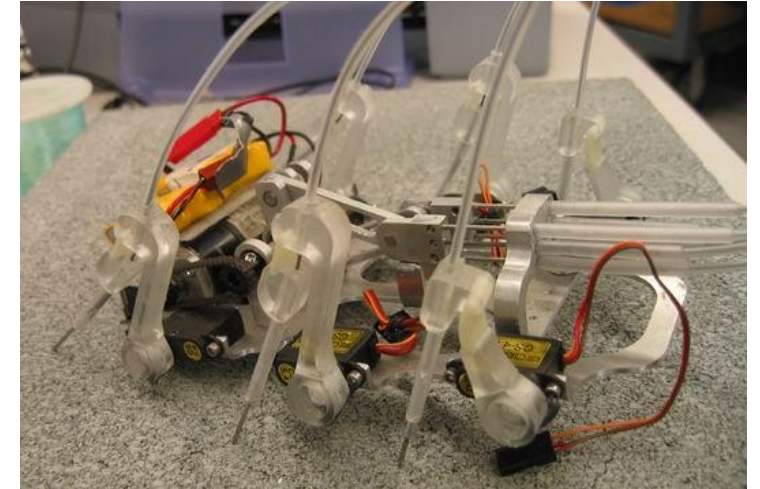
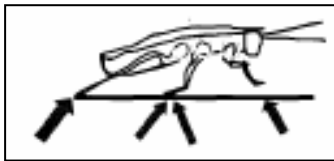
Terrestrial legged locomotion

- Most insects have three pairs of legs positioned laterally in a wide stance.
- The body's center of mass is low and well within the perimeter of support for optimal stability.
- Each leg serves both as a strut to support the body's weight and as a lever to facilitate movement.



Terrestrial legged locomotion

RELIABILITY and ROBUSTNESS thanks to suspension systems and compliant legs. Intrinsic mechanical stabilization systems, called PREFLEXES ^[1], are exploited to minimize control complexity for locomotion in unstructured environments ^[2]



[1] Full, TU, Mechanics of a rapid running insect: two, four and Six-legged locomotion, *J. Exp. Biol.*, 156, 215-231, (1991)

[2] J.G. Cham, J.K. Karpick, M.R. Cutkosky, Stride Period Adaptation for a Biomimetic Running Hexapod, *The International Journal of Robotics Research*, 32(2), 1-13, (2004)

Terrestrial legged locomotion

At very **slow walking** speeds an insect moves only one leg at a time, keeping the other five in contact with the ground.

At **intermediate speeds**, two legs may be lifted simultaneously, but to maintain balance, at least one leg of each body segment always remains stationary. This results in a wave-like pattern of leg movements known as the metachronal gait.

When **running**, an insect moves three legs simultaneously. This is the tripod gait, so called because the insect always has three legs in contact with the ground: front and hind legs on one side of the body and middle leg on the opposite side.

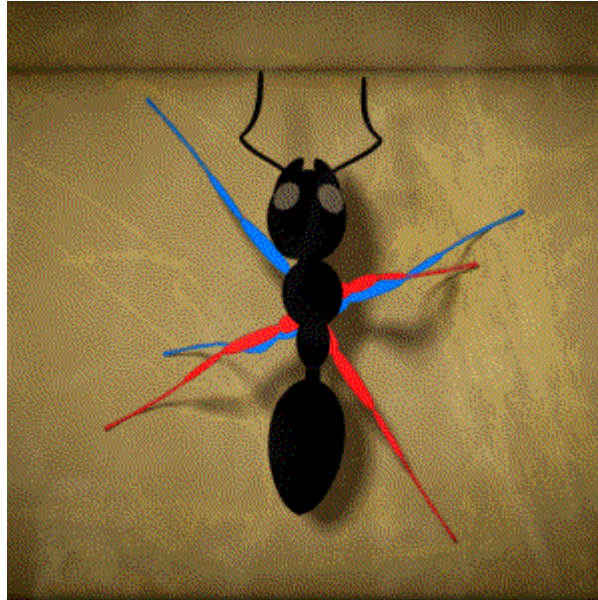


Terrestrial legged locomotion

Coordination of leg movements is regulated by networks of neurons that can produce rhythmic output without needing any external timing signals. Such networks are called **central pattern generators** (CPGs).

There is at least one CPG per leg.

Individual networks are linked together via interneurons and output from each CPG is modified as needed by sensory feedback from the legs.



Terrestrial legged locomotion



Festo BionicANTs

