

Q6b ;  $z_i(t) \triangleq \beta x_i(t) + v_i(t)$  where  $i = 1, \dots, n$ . Q1

$\dot{z}_i(t) = 0, i \in R$

$\dot{z}_i(t) = - \sum_{j \in R \cup F} a_{ij}[k] [z_i(t) - z_j(k)]$  ,  $i \in F$ .

Q6b123127

$\bar{z} \triangleq \max_{i \in R} z_i$  ,  $\bar{x} \triangleq \max_{i \in R} x_i$  &  $s_i \triangleq x_i - \bar{x}$  ,  $i \in F$ .

$z_i - \bar{z}$  is bounded ;  $z_i - \bar{z} \leq 0$  ;  $f_i(t) = z_i - \bar{z}$

$\Rightarrow \dot{s}_i(t) + \beta s_i(t) = f_i(t)$  ;  $x_i(t) \otimes, i \in R$  are constant.

$\Rightarrow \dot{s}_i(t) = -\beta s_i(t) + f_i(t) \Rightarrow s_i(t) = e^{-\beta t} s_i(0) + \int_0^t e^{-\beta(t-\tau)} f_i(\tau) d\tau$ .

$\lim_{t \rightarrow \infty} s_i(t) = \lim_{t \rightarrow \infty} e^{-\beta t} s_i(0) + \lim_{t \rightarrow \infty} \int_0^t e^{-\beta(t-\tau)} f_i(\tau) d\tau$   
 $= \lim_{t \rightarrow \infty} \frac{\int_0^t e^{\beta \tau} f_i(\tau) d\tau}{e^{\beta t}} = \lim_{t \rightarrow \infty} \frac{e^{\beta t} f_i(t)}{\beta e^{\beta t}} = \lim_{t \rightarrow \infty} \frac{f_i(t)}{\beta}$

where all limits are under " $t \rightarrow \infty$ ".

$\Rightarrow \left\{ \begin{array}{l} \beta > 0 \\ f_i(t) > 0 \end{array} \right. \Rightarrow s_i(t) \leq 0 \Rightarrow x_i(t) \leq \bar{x}(t) \Rightarrow x_i(t) \leq \max_{j \in R} x_j(t)$  ;  
as  $t \rightarrow \infty$

$\Rightarrow x_i(t) \geq \min_{j \in R} x_j(t) \Rightarrow$  Therefore, all followers will converge to the convex hull formed by the leaders in any high-dimensional system.