

Task 1)

$$g) \quad \sigma = \sqrt{\frac{1}{N} \sum (x_i - \mu)^2} \quad , \quad \mu = \frac{\sum x_i}{N} =$$

Braker python:

Script

```
1 #Excercise 1 for TTT4280
2
3 import numpy as np
4 import matplotlib.pyplot as plt
5
6 #1.1
7 #Find the mean value and standard deviation of the data set
8 data = np.loadtxt('Øving 1/data.txt', delimiter=',')
9 meanDataValue = data.mean()
10 stdDataValue = data.std()
11 print("Mean value: ", meanDataValue)
12 print("Standard deviation: ", stdDataValue)
13 |
```

Result

```
Eier@MacBook-Air-2 Sensorer og instrumentering % /usr/
crvpy.py"
Mean value: 20.485
Standard deviation: 0.10618380290797719
Eier@MacBook-Air-2 Sensorer og instrumentering % |
```

b)

$$CI = \bar{X} \pm t_p \frac{s}{\sqrt{n}} \quad , \quad t_p = 2.093$$

$$CI = 20.485 \pm 2.093 \cdot \frac{0.106}{\sqrt{20}} = \underline{\underline{[20.435, 20.534]}}$$

$$c) \quad T \in \mu_T \pm z \cdot \sigma \sqrt{1 + \frac{1}{n}} = \underline{\underline{[20.258, 20.711]}}$$



Task 2)

a) Use same code as before with new values:

Result:

```
crpy.py"
Mean value: 20.330000000000002
Standard deviation: 0.095393920141694
Eier@MacBook-Air-2 Sensorer og instrumentering %
```

$$CI = \bar{x} \pm t_{\alpha} \frac{s}{\sqrt{n}} = 20.33 \pm 2.093 \cdot \frac{0.095}{\sqrt{20}} = \underline{\underline{[20.285, 20.374]}}$$

b) No the two CI's are not overlapping. This suggest that there is a statistically significant difference between the mean's measured by Olav and Ove.

We can also see that Ove's system is closest to the ideal temp 20° and has a smaller standard deviation.

c) Only using the first value.

New code:

```
11 #1.2c
12 #Calculate for half the data set
13 halfData = data[:int(len(data)/2)]
14 meanHalfDataValue = halfData.mean()
15 stdHalfDataValue = halfData.std()
16 print("Mean value half: ", meanHalfDataValue)
17 print("Standard deviation half: ", stdHalfDataValue)
18
```

Ove's result's

```
Eier@MacBook-Air-2 Sensorer og instrumentering %
Mean value half: 20.380000000000003
Standard deviation half: 0.07483314773547865
Eier@MacBook-Air-2 Sensorer og instrumentering %
```

Olav's result:

```
Eier@MacBook-Air-2 Sensorer og instrumentering %
Mean value half: 20.509999999999998
Standard deviation half: 0.12206555615733793
```



Ove's new CI:

$$CI: \bar{X} \pm t_p \frac{s}{\sqrt{n}} \quad , \quad t_{0.90} = 2.262$$

$$= 20.380 \pm 2.262 \cdot \frac{0.07483}{\sqrt{10}} = [20.326, 20.433]$$

Olav's new CI:

$$CI: \bar{X} \pm t_p \frac{s}{\sqrt{n}}$$

$$20.510 \pm 2.262 \cdot \frac{0.1220}{\sqrt{10}} = [20.422, 20.597]$$

Now they overlap!



### Task 3)

a)  $\max: 10k\Omega + 1\%10k\Omega = \underline{\underline{10.1k\Omega}}$

$\min: 10k\Omega - 1\%10k\Omega = \underline{\underline{99.9k\Omega}}$

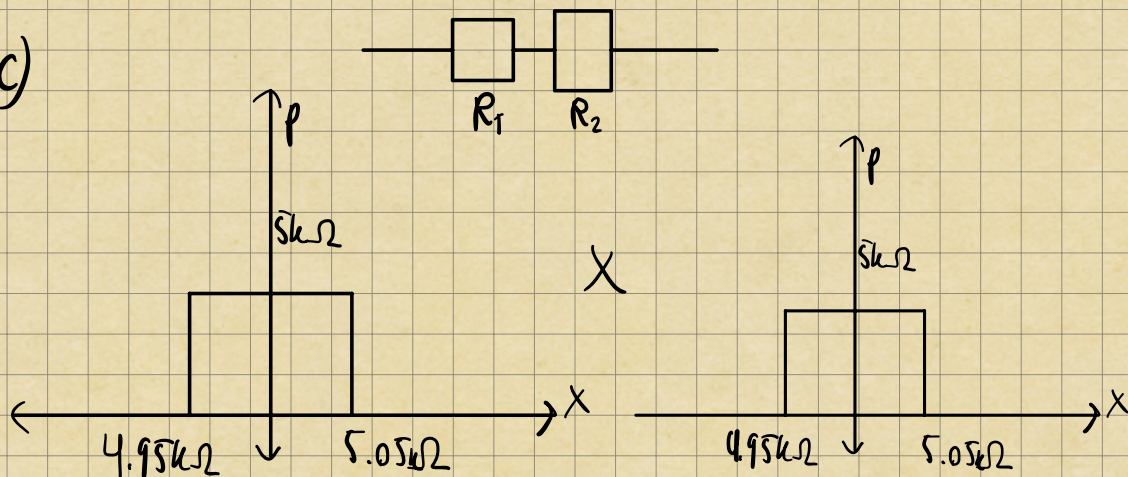
Standard deviation for uniform distribution:

$$\sigma = \sqrt{\frac{(\max - \min)^2}{12}} = \underline{\underline{57.7\Omega}}$$

b)

$$RSD = \frac{\sigma}{|m|} \cdot 100\% = \frac{57.7\Omega}{10 \cdot 10^3\Omega} \cdot 100\% = \underline{\underline{0.577\%}}$$

c)



$$g(x) = f(x) * f(x)$$

This is stuu so I do it in python.



Code:

```
#1.3c

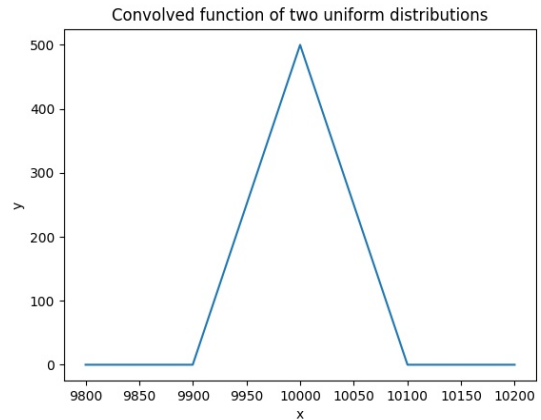
# Example usage
x_values = np.linspace(4900, 5100, 1000) # Generate 1000 points from 4900 to 5100
y_values = continuous_uniform_distribution(x_values)

# Convolve the distribution with itself
convolved = np.convolve(y_values, y_values, mode='full')

# Generate new x values for the convolved function
convolved_x_values = np.linspace(2*x_values[0], 2*x_values[-1], len(convolved))

# Plot the convolved function
plt.plot(convolved_x_values, convolved)
plt.xlabel('x')
plt.ylabel('y')
plt.title('Convolved function of two uniform distributions')
plt.show()
```

Result



d)

$$\text{Var}(X|Y) = \text{Var}(X) + \text{Var}(Y)$$

```
#1.4c
rng = default_rng()
delta_r = 100

resistor = 5000
deviationToResistor = resistor * 0.01

totaleValues = 6000

Rvalue1 = resistor + 2*deviationToResistor*(rng.random(totaleValues)-0.5)
Rvalue2 = resistor + 2*deviationToResistor*(rng.random(totaleValues)-0.5)

r_values = Rvalue1 + Rvalue2
#Find the relative standard deviation
RelativeStandardDeviation = r_values.std()/r_values.mean()*100
print("Relative standard deviation: ", RelativeStandardDeviation)
```

```
branch 'main' set up to track 'origin/main'.
• Eier@dhcp-10-24-20-139 Sensorer og intrumentering % /usr/bin/
Elsys/Sensorer og intrumentering/Øving 1/scrypy.py"
Relative standard deviation: 0.41237072246253687
```