

Linear Algebra

—HOFFMAN AND RAY KUNZE

ManJack

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前言

这是数学系线性代数的笔记，写给自己。如有错误请见谅，这些只是作为分享。

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第一章 Linear Equations

1.1 环和域

1.1.1 加群和环的定义

Definition 1.1.1 (加群)

假如一个 *Abel* 群的代数运算为加法，并且用符号 ‘+’ 表示，则该群叫做加群。

Remark 1.1.1

加群的单位元 e 是唯一的，且 $e=0$ 。称作零元，我们有以下的计算规则：

$$0 + a = a + 0 = a$$

Definition 1.1.2 (环)

一个集合 R 称之为环满足：

1. R 是一个加群
2. R 对一个乘法来说是一个半群 (半群是一个群胚 + 结合律)
3. 在集合 R 上，乘法对加法满足分配率 $a(b+c)=(ab+ac)$

1.1.2 交换元、单位元、零因子、整环

Definition 1.1.3 (交换环)

一个环叫做一个交换环，假如：

$$ab = ba$$

在环中乘法运算下的单位元，叫做环的单位元。

Definition 1.1.4 (单位元)

环中的单位元 e ，假如对于 R 的任意元素 a 来说，有：

$$e a = a e = a$$

Definition 1.1.5 (零因子)

一个环中的两个元素 a, b 之间如果有一个是 0 , 那么 $ab=0$. 但反之不成立.

$$ab = 0 \not\Rightarrow a = 0 \text{ or } b = 0$$

Example 1.1.1

例如模 n 的剩余类环: 假设 $n=ab$

若 n 不是素数, 假设:

$$[a] \neq [0], [b] \neq [0], [a][b] = [ab] = [n] = [0]$$

则我们可以得知 $ab = 0 \not\Rightarrow a = 0 \text{ or } b = 0$

Remark 1.1.2

若是在一个环里,

$$a \neq 0, b \neq 0, ab = 0$$

则 a 被称为左零因子, b 被称为右零因子

Definition 1.1.6 (整环)

一个环叫做整环, 满足:

1. 乘法交换律:

$$ab = ba$$

2. R 有单位元 1 :

$$1a = a1 = a$$

3. R 没有零因子:

$$ab = 0 \implies a = 0 \text{ or } b = 0$$

Remark 1.1.3

a, b 可以是任意 R 中的元.

1.1.3 除环、域**Definition 1.1.7 (除环)**

一个环 R 叫做一个除环, 满足:

1. R 至少包含一个不为 0 的元

2. R 有一个单位元

↑
单位元
↑

3. R 的每个不等于 0 的元有一个逆元

Definition 1.1.8 (除环)

一个集合 F 被称为域, 如果满足以下条件:

1. 加法封闭性: $\forall a, b \in F$, 有 $a + b \in F$ 。
2. 加法可交换性: $\forall a, b \in F$, 有 $a + b = b + a$ 。
3. 加法单位元素: 存在加法单位元素 0 , 使得 $\forall a \in F$, 有 $a + 0 = a$ 。
4. 加法逆元素: $\forall a \in F$, 存在加法逆元素 $-a$, 使得 $a + (-a) = 0$ 。
5. 乘法封闭性: $\forall a, b \in F$, 有 $a \cdot b \in F$ 。
6. 乘法可交换性: $\forall a, b \in F$, 有 $a \cdot b = b \cdot a$ 。
7. 乘法单位元素: 存在乘法单位元素 1 , 使得 $\forall a \in F$, 有 $a \cdot 1 = a$ 。
8. 乘法逆元素: $\forall a \in F$, 对于非零元素, 存在乘法逆元素 a^{-1} , 使得 $a \cdot a^{-1} = 1$ 。
9. 分配律: $\forall a, b, c \in F$, 满足 $(a + b) \cdot c = a \cdot c + b \cdot c$ 。

Definition 1.1.9 (Subfield)

设 F 是一个域。如果 $K \subseteq F$ 满足以下条件, 则称 K 是 F 的子域:

1. K 非空, 并且包含域 F 中的加法单位元素 0 和乘法单位元素 1 。
2. 对于任意的 a 和 b 属于 K , $a + b$ 和 $a \cdot b$ 也都属于 K (其中 $+$ 和 \cdot 分别表示域 F 中的加法和乘法运算)。
3. 对于任意的 a 属于 K , 它的相反元素 $-a$ 也属于 K 。
4. 对于任意的非零元素 a 属于 K , 它的乘法逆元素 a^{-1} 也属于 K 。

Definition 1.1.10 (Characteristic)

In abstract algebra, "characteristic" is an important concept for a ring or a field. The characteristic is used to describe the smallest positive integer n for which n times the multiplicative identity 1 equals the additive identity (usually denoted as 0) in the algebraic structure.

For a ring (a set with addition and multiplication operations, satisfying certain algebraic rules), the characteristic refers to the smallest positive integer n such that n times 1 equals 0 (or defined as 0 if there is no such n).

For a field (a special type of ring where every non-zero element has a multiplicative inverse), the characteristic is also a positive integer n or zero, representing n times 1 equals 0 or having

characteristic zero if there is no such n .

The significance of the characteristic lies in its impact on the properties and structure of the ring or field. Particularly, in the case of a field, the characteristic is either a prime number or zero. This distinction is useful as it allows us to differentiate between fields of different characteristics and has important applications in properties of algebraic equations and polynomials.

1.2 System of linear Equations

Suppose F is a field, We consider the problem of finding n scalars (element of F) x_1, \dots, x_n which satisfy the conditions

$$\begin{aligned} A_{11} + A_{12}x_1 + \cdots + A_{1n}x_n &= 0 \\ A_{21} + A_{22}x_1 + \cdots + A_{2n}x_n &= 0 \\ &\vdots \\ A_{m1} + A_{m2}x_1 + \cdots + A_{mn}x_n &= 0 \end{aligned} \tag{1.1}$$

where y_1, y_2, \dots, y_n and $A_{ij}, 1 \leq i, j \leq n$ are given elements of F . We call 1.1 this a **system of m linear equations** in n unknowns. Any n -tuple (x_1, x_2, \dots, x_n) of elements of F which satisfies each of the equation in 1.1 is called a solution of the system. If $y_1 = y_2 = \cdots = y_m = 0$, we say that the system is **homogeneous**, or that each of equations is homogenous,

Definition 1.2.1 (*linear combination*)

For the 1.1, suppose we select m scalars c_1, \dots, c_m , multiply the j th equation by c_j and then add.

$$(c_1A_{11} + \cdots + c_mA_{m1})x_1 + \cdots + (c_1A_{1n} + \cdots + c_mA_{mn})x_n = c_1y_1 + \cdots + c_my_m$$

Note: Evidently, any solution of the entire system of equations 1.1 will also be a solution of this new equation

Definition 1.2.2 (*Linear equivalent*)

Let us say that two systems of linear equations are **linearly equivalent** if each equation of one is a linear combination of the equations of the other.

$$\begin{aligned} B_{11} + B_{12}x_1 + \cdots + B_{1n}x_n &= z_1 \\ B_{21} + B_{22}x_1 + \cdots + B_{2n}x_n &= z_2 \\ &\vdots \\ B_{m1} + B_{m2}x_1 + \cdots + B_{mn}x_n &= z_m \end{aligned} \tag{1.2}$$

Theorem 1.2.1

Equivalent system of linear equations have exactly the same solutions.

1.3 Matrix and Elementary Row Operations

there is no need to continue writing the 'unkonwns' x_1, x_2, \dots, x_n in the system of linear equations 1.1, since one actually compute onlu with the coefficient A_{ij} and the scalars y_i

We shall now abbreviate the system 1.1 by writing:

$$AX = Y$$

where:

$$A = \begin{bmatrix} A_{11} & A_{12} & \cdots & A_{1n} \\ A_{21} & A_{22} & \cdots & A_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ A_{m1} & A_{m2} & \cdots & A_{mn} \end{bmatrix} \quad (1.3)$$

A is the matrix of coefficient of the system

$$X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad \text{and} \quad Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

Remark 1.3.1

1. The entries of the matrix A are the scalars $A(i,j) = A_{ij}$
2. The matrix A is an $m \times n$ matrix
3. The matrix X is an $n \times 1$ matrix
4. The matrix Y is an $m \times 1$ matrix
5. The $AX = Y$ is nothing more than a compact way of writing the system of linear equations 1.3

The elementary row operations on an $m \times n$ matrix A over the field F :

1. multiply of one row of A by a none-zero scalar c ;
2. interchange of two rows of A ;
3. replacement of the r th row of A by row r plus c time row s , c any scalar and $r \neq s$,

An elementary row operation is thus a special type of function with domain the set of all $m \times n$ matrices over F and range the same set. One can describe e in the three cases as follow:

1. $e(A)_{ij} = A_{ij}$ if $i \neq r, e(A)_{rj} = cA_{rj}$
2. $e(A)_{ij} = A_{ij}$ if $i \neq r, s, e(A)_{rj} = A_{sj}, e(A)_{sj} = A_{rj}$
3. $e(A)_{ij} = A_{ij}$ if $i \neq r, e(A)_{rj} = A_{rj} + cA_{sj}$