

HEART RATE MONITOR

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<https://github.com/Manarabdelaty/HeartMonitor>

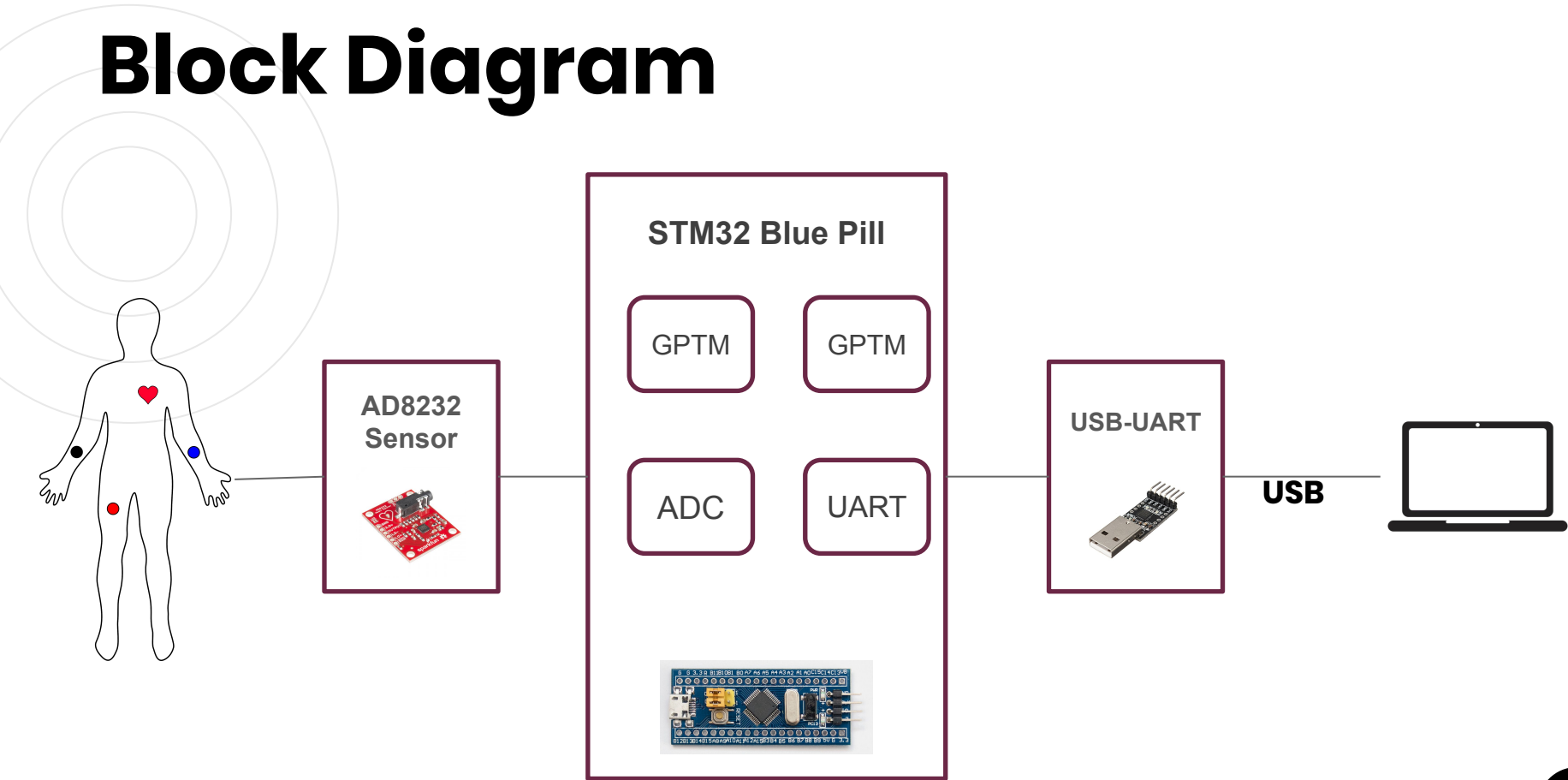


Requirements

- Set ADC sample rate [150 SPS -- 1000 SPS]
- Collect ADC data for one minute
- Send ADC data over UART
- UART Baud rate at least (40 KHz)
- Display ECG signal real-time
- Calculate heart beats per minute

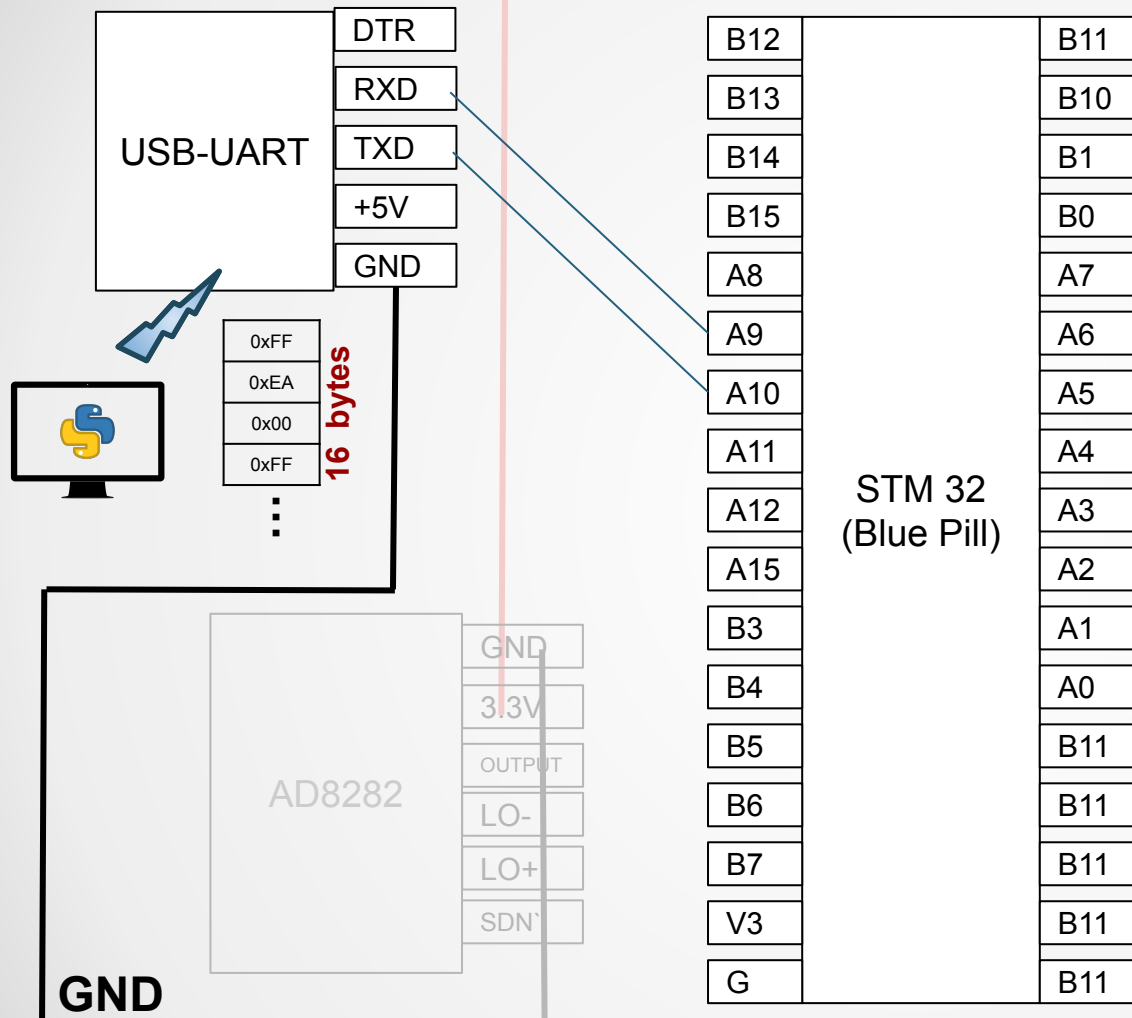


Block Diagram





Design

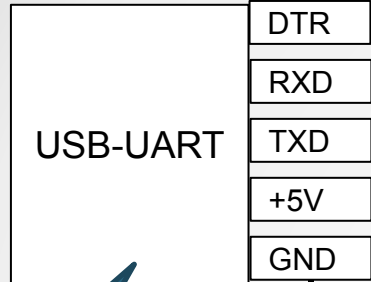


- Fixed Length 16-byte commands
 - Rate="{new_rate}";
 - Data;
 - hbpm;
- UART receive IT fired when all the 16-bytes are sent.

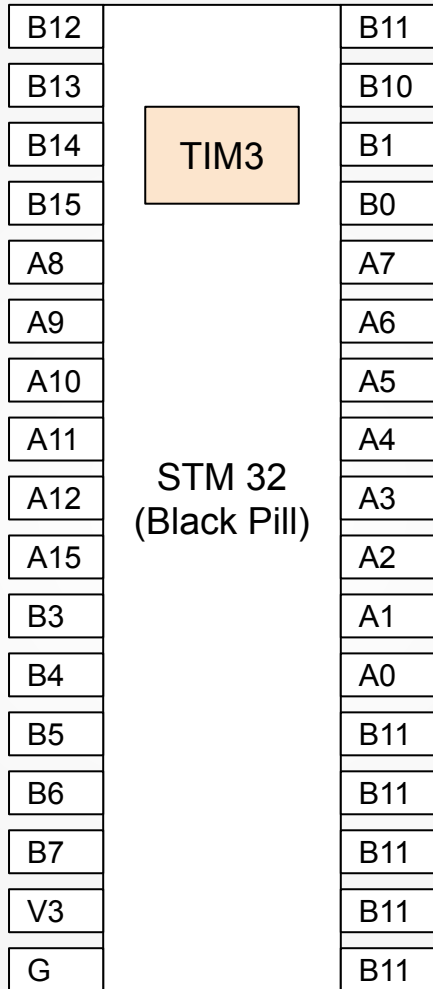
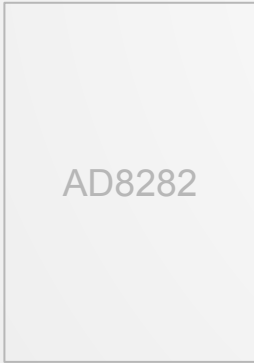
TIM3

3.3V

rate={new_rate};



GND



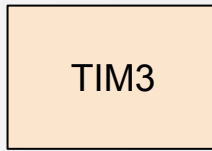
1) Sample Rate Command
rate={new_rate};

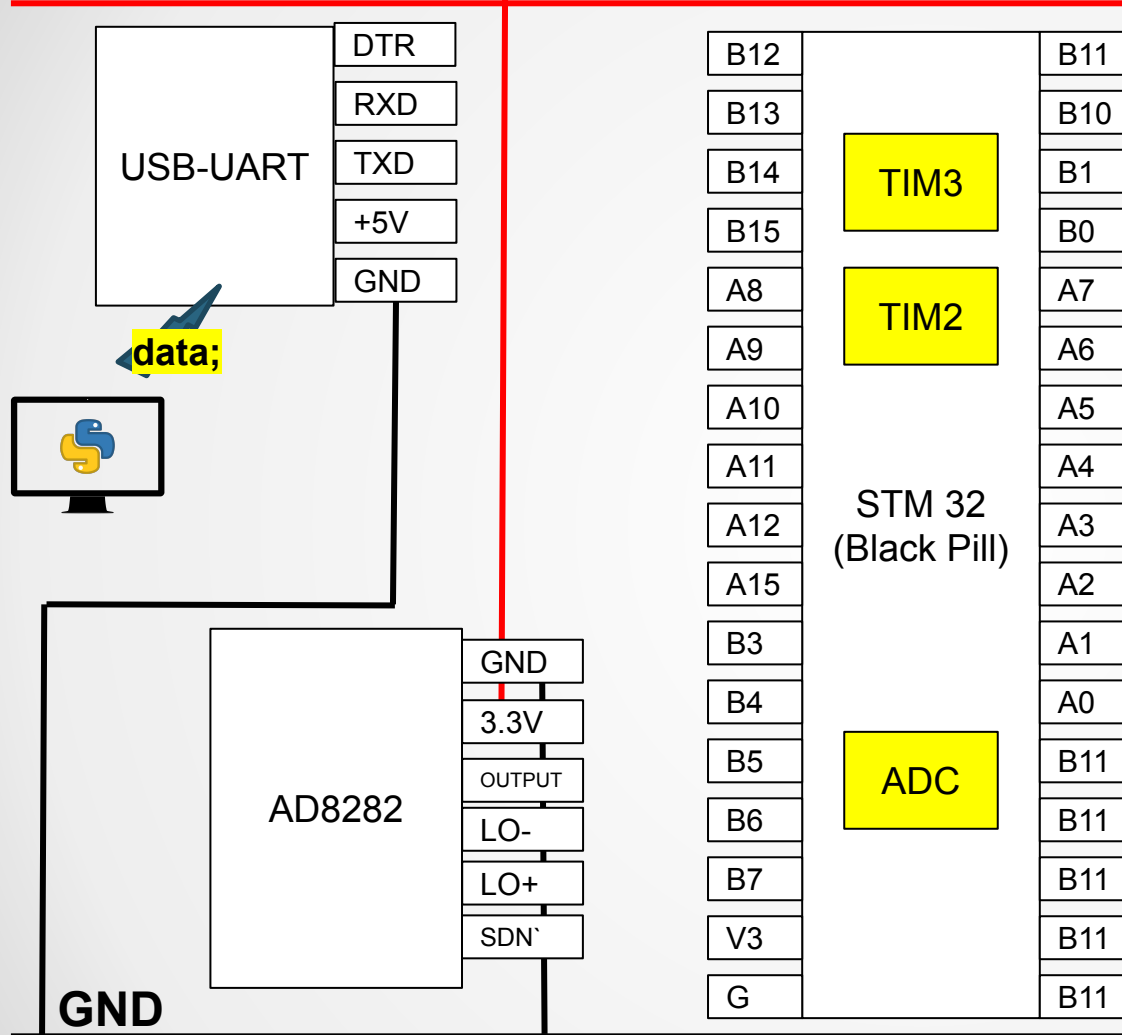
$ARR = Sysclk / \text{pre-scaler} / \text{new_rate}$

Prescaler
3999

Sysclk
8MHz

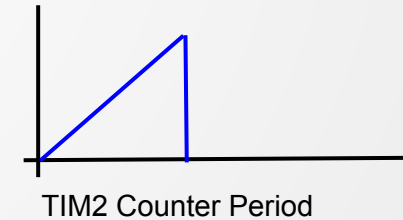
ARR
??

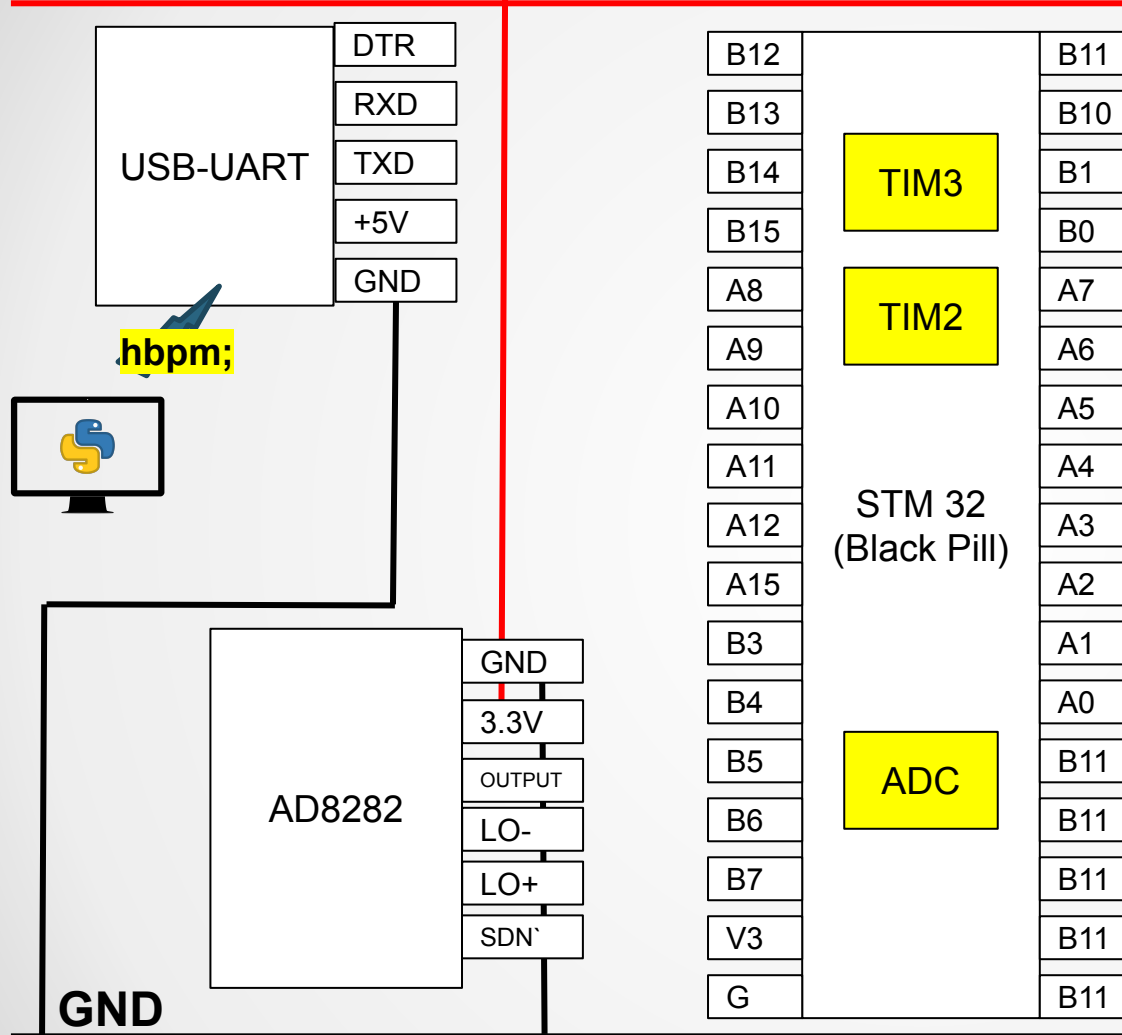




2) Collect Data Command “data;”

- start TIM3 to trigger ADC conversion
- start TIM2 to count for one minute
- stop two timers after one minute elapses



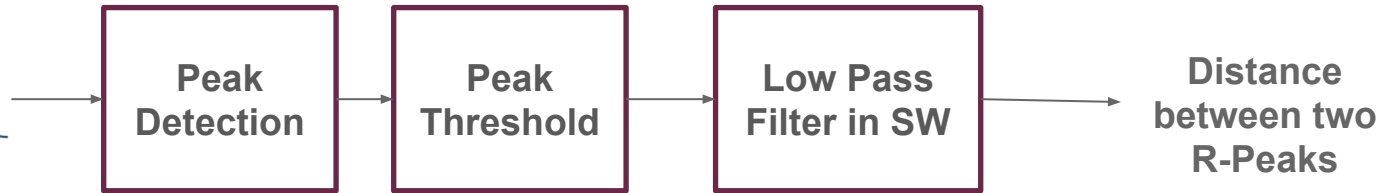
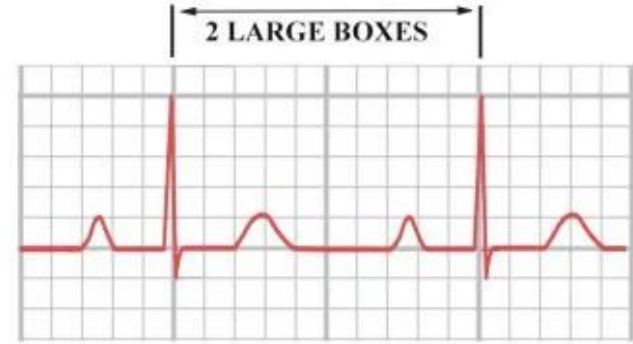


3) Compute heartbeats per minute Command "hbpm;"

- start TIM3 to trigger ADC conversion
- start TIM2 to measure distance between two peaks.
- stop two timers after calculating the heart rate

Heart Rate Calculation

$$\text{Bpm} = 60 / \text{peak_distance}$$



The image features a large white circle centered on a black background. To the left of the circle, there is a series of overlapping circles in shades of gray, with the number '3' in white. To the right, there are several concentric white circles. The text 'SW' and 'Architectre' is centered within the white circle.

3

SW
Architectre



Round Robin with Interrupts

- **UART_Receive_Interrupt**
 - Receives commands from the Python application.
- **TIM2_Period_Elapsed_Interrupt**
 - Generated when one minute passes
- **ADC_Conversion_Interrupt**
 - Generated on one complete ADC conversion



```

void HAL_UART_RxCpltCallback(UART_HandleTypeDef* huart){
    if(huart->Instance == USART1){
        decode(); // first decode instruction
        HAL_UART_Receive_IT(&huart1,
            (uint8_t *)rxBuffer,
            16);
    }
}

```

UART_Receive_Interrupt

```

void decode(){
    // fixed length commands
    char command [COMMAND_LENGTH+1] = {rxBuffer[0],
        rxBuffer[1], rxBuffer[2], rxBuffer[3], rxBuffer[4], '\0'};
    if(strcmp(command, "rate=") == 0){
        // set new sample rate
        char sample_rate_str [MAX_UART];
        for (int i= COMMAND_LENGTH; i<MAX_UART; i++){
            set_sample_rate = 1;
            new_sample_rate = atoi(sample_rate_str);
        } else if (strcmp(command, "hbpm;" ) == 0){
            // compute heart beats
            compute_bpm = 1;
        } else if (strcmp(command, "data;" ) == 0){
            // collect one minute of data
            collect_data = 1;
        }
        else {
            // Invalid command
        }
    }
}

```

```

37 void HAL_TIM_PeriodElapsedCallback(TIM_HandleTypeDef * htim){
38     if(htim->Instance == TIM2){
39         reset = reset + 1;
40         if(__HAL_TIM_GET_FLAG(&htim2, TIM_FLAG_CC1) != RESET){
41             timer_done = timer_done + 1;
42             HAL_TIM_Base_Stop(&htim3); // stop ADC trigger timer
43             HAL_TIM_Base_Stop_IT(&htim2); // stop one minute timer
44         }
45     }
46 }

```

TIM2_Period_Elapsed_Interrupt

```

]void HAL_ADC_ConvCpltCallback(ADC_HandleTypeDef* hadc){
]  if(hadc->Instance == ADC1){
    adc_value = HAL_ADC_GetValue(&hadc1);
]  if (transmit_adc){ // if data command triggered ADC
    sprintf(value, "%d\n\r", adc_value);
    HAL_UART_Transmit(&huart1, (uint8_t *)value, strlen(value), 10);
}else if(detect_peak){ // if hbpm command triggered ADC
    adc_values[count] = adc_value;
]    if(count <= 2) {
        countPeaks();
    }
    count = (count + 1) % MIN_SAMPLES_RR;
}
    sample_count++;
- }
-}

```

ADC_Conversion_Complete_Interrupt



```

void countPeaks() {
    if((adc_values[count-1] > adc_values[count-2]) &&
        (adc_values[count-1] > adc_values[count])){ // if the previous point is a peak
        if(adc_values[count-1] > PEAK_THRESHOLD){ // if the previous point is above threshold
            curr_peak = __HAL_TIM_GET_COUNTER(&htim2) / 1000.0; // get current time
            peak_distance = curr_peak - prev_peak; // Compute RR-Interval
            if(peak_distance > MIN_RR_INTERVAL){ // if the RR-Interval is greater than minimum
                num_peaks++; // count it as a peak
                if (num_peaks >= 2) {
                    computed_bpm = 60.0 / (peak_distance); // 300-method for bpm
                    transmit_bpm = 1;
                    sprintf(bpm, "bpm: %d\n\r", computed_bpm);
                    HAL_UART_Transmit(&huart1, (uint8_t *)bpm, strlen(bpm), 10);
                }
                prev_peak = curr_peak;
            }
        }
    }
}

```

Count Peaks


```
if(collect_data){
    sample_count = 0;
    transmit_adc = 1;
    // start TIM3 & TIM2 for one minute
    HAL_TIM_Base_Start(&htim3);
    HAL_TIM_Base_Start_IT(&htim2);

    __HAL_UART_DISABLE_IT(&huart1, UART_IT_RXNE);
    collect_data = 0;
    __HAL_UART_ENABLE_IT(&huart1, UART_IT_RXNE);
}
```

```
if (compute_bpm) {
    // start adc sample rate timer; it is stopped
    detect_peak = 1;

    HAL_TIM_Base_Start(&htim3);
    HAL_TIM_Base_Start_IT(&htim2);

    __HAL_UART_DISABLE_IT(&huart1, UART_IT_RXNE);
    compute_bpm = 0;
    __HAL_UART_ENABLE_IT(&huart1, UART_IT_RXNE);
}
```

```
if(set_sample_rate){
    // change ARR value of TIM3
    new_counter_period = ((float) counter_clk / (float)new_sample_rate) - 1;
    __HAL_TIM_SET_AUTORELOAD(&htim3, new_counter_period);

    __HAL_UART_DISABLE_IT(&huart1, UART_IT_RXNE);
    set_sample_rate = 0;
    __HAL_UART_ENABLE_IT(&huart1, UART_IT_RXNE);
}
```

Main Loop

Python Application

- **Pyserial**
 - UART communication
- **Matplotlib Animation**
 - Real-time plotting
- **tkinter**
 - GUI



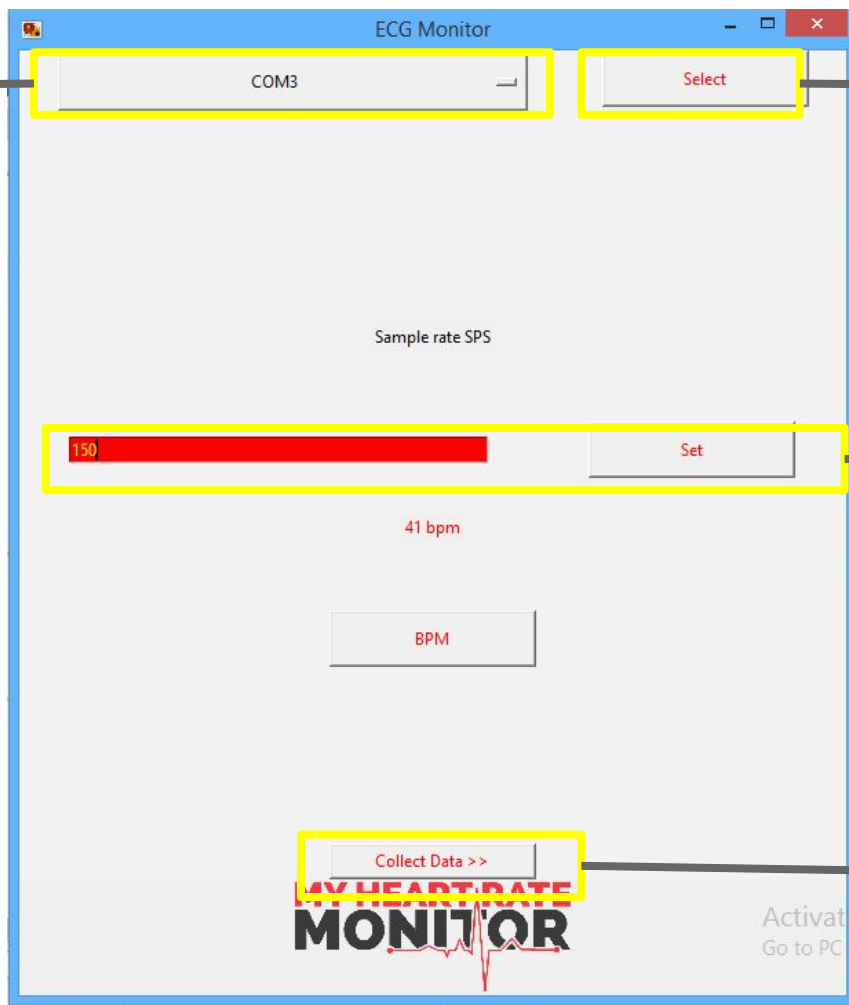
Available ports list

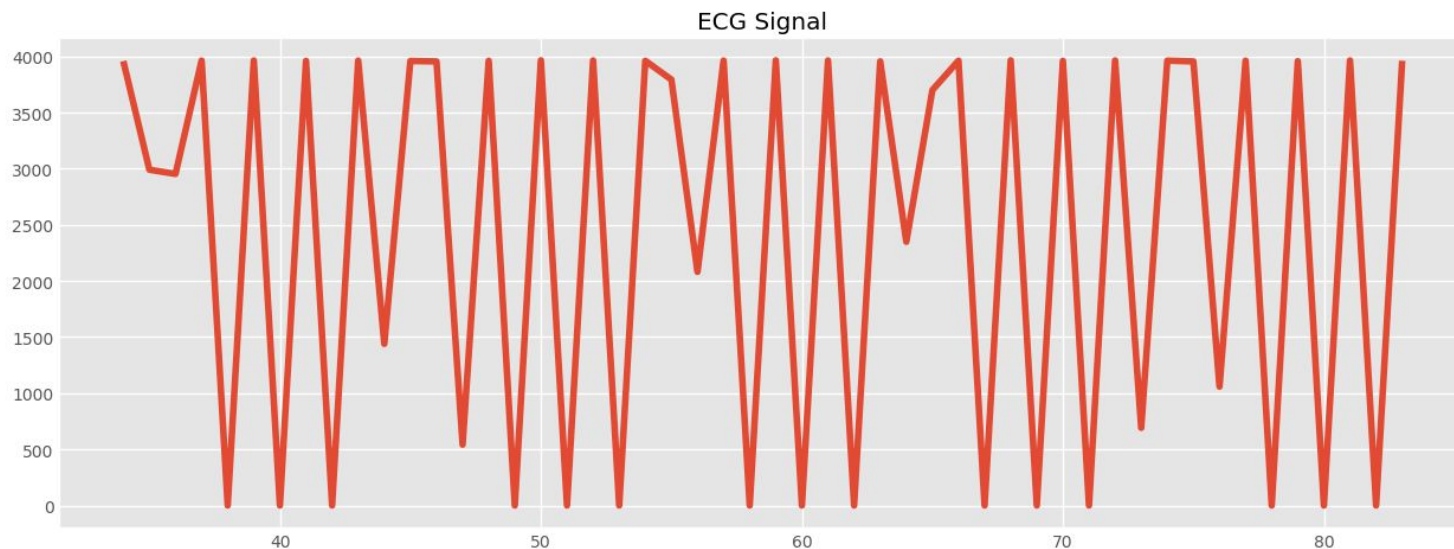
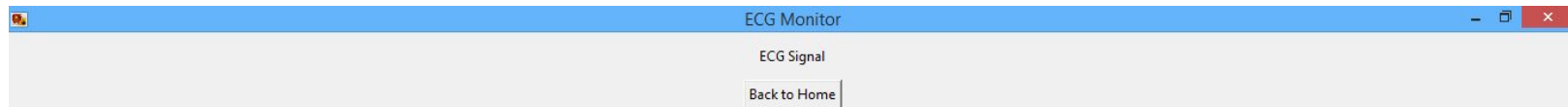
Opens the selected port.

Sends the rate command

Opens a new page to collect one minute of data

Main Page





x=70.8097 y=2793.53

**MY HEART RATE
MONITOR**

Activate Windows
Go to PC settings to activate Windows.

Real-Time Display



DEMO

