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IBM 18CS052  
AI Lab Test

Write up

goal state =  $\begin{bmatrix} [1, 2, 3], \\ [4, 5, 6], \\ [7, 8, 0] \end{bmatrix}$       start state =  $\begin{bmatrix} [8, 2, 3], \\ [0, 4, 6], \\ [7, 5, 1] \end{bmatrix}$

def distance(huzzle, item-to-col, total-cal):

    t = 0

    for row in range(3):

        for col in range(3):

            val = huzzle.get(row, col) - 1

            target\_col = val % 3

            target\_row = val / 3

            if target\_row < 0:

                target\_row = 2

            t += item-to-col(row, target\_row,  
                                    col, target\_col)

    return total-cal(t)

me

```
def manhattan(puzzle):
```

```
    return distance ( puzzle, lambda x,
```

```
        tx, y, ty : abs(tx-x) + abs(ty-y),
```

```
        lambda t : t )
```

```
class SlidePuzzle():
```

```
    # class contains all functions for generating  
    # and swapping
```

```
    def generate_sol_path (self, path):
```

```
        if self.parent is None:
```

```
            return path
```

```
        else:
```

```
            path.append (self)
```

```
            return self.parent.generate_
```

```
                sol_path (path)
```

```
    def generate_moves (self):
```

```
        free = self.get_legal_moves()
```

```
        zero = self.find(0)
```

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```
def swap (self, pos-first, pos-second):
```

```
    temp = self.peek(pos-first)
```

```
    self.poke(pos-first[0], pos-first[1],  
              self.peak(pos-second))
```

```
    self.poke(pos-second[0], pos-second[1],  
              temp)
```

```
def main():
```

```
    p = slidePuzzle()
```

```
    p.startState = [[8, 2, 3], [0, 4, 6],  
                    [7, 5, 1]]
```

```
    hunt(p)
```

```
    path, count = p.solve('manhattan')
```

```
    path.reverse()
```

```
    for i in path:
```

```
        hunt(i)
```

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