



*Dissertation on*

**“CAN FUZZING USING SAVVY CAN ON ICSim ”**

*Submitted in partial fulfillment of the requirements for the award of the degree of*

**Bachelor of Technology  
in  
Computer Science & Engineering**

**UE20CS461SC – Automotive Cyber Security**

*Submitted by:*

1	DIVYA SRUJANA	PES1UG22CS832
2	MANASI TAWADE	PES1UG22CS815
3	VANUSHREE DM	PES1UG22CS846
4	VAIBHAVI	PES1UG21EC320

*Under the guidance of*

**Dr. Roopa Ravish**  
Associate Professor  
CSE department

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**DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING  
FACULTY OF ENGINEERING  
PES UNIVERSITY**

## **Introduction:-**

In the rapidly evolving field of automotive technology, ensuring the security and robustness of Controller Area Network (CAN) systems is paramount. CAN networks, which facilitate communication between various electronic components within a vehicle, are critical for the vehicle's operation and safety. However, these networks are vulnerable to various types of cyber-attacks, including the injection of malformed or unexpected CAN frames. To address this, we propose a fuzzing strategy using SavvyCAN on ICSim, a virtualized environment for simulating in-vehicle networks. This approach leverages frame sender, sniffer, and custom frame-sending techniques to test the resilience of CAN systems thoroughly. By systematically injecting and analyzing a range of abnormal CAN frames, we aim to uncover potential vulnerabilities and propose enhancements to fortify the security and reliability of automotive CAN networks.

## **Problem Statement:-**

Developing a fuzzing strategy using SavvyCAN on ICSim to evaluate the robustness of automotive CAN (Controller Area Network) systems. Utilize frame sender, sniffer, and custom frame-sending techniques to inject malformed or unexpected CAN frames. Analyze the impact on ICSim's virtualized vehicle components to identify vulnerabilities, potential crashes, or unexpected behaviors. Document the findings and propose mitigations to enhance the security and reliability of automotive CAN networks.

## **Objective:-**

SavvyCAN on ICSim will be used to test and improve the security of automotive CAN systems.

This involves:

1. Sending unusual CAN frames.
2. Monitoring vehicle responses.
3. Identifying weaknesses.
4. Suggesting improvements.
5. Enhancing testing methods for better automotive cybersecurity.

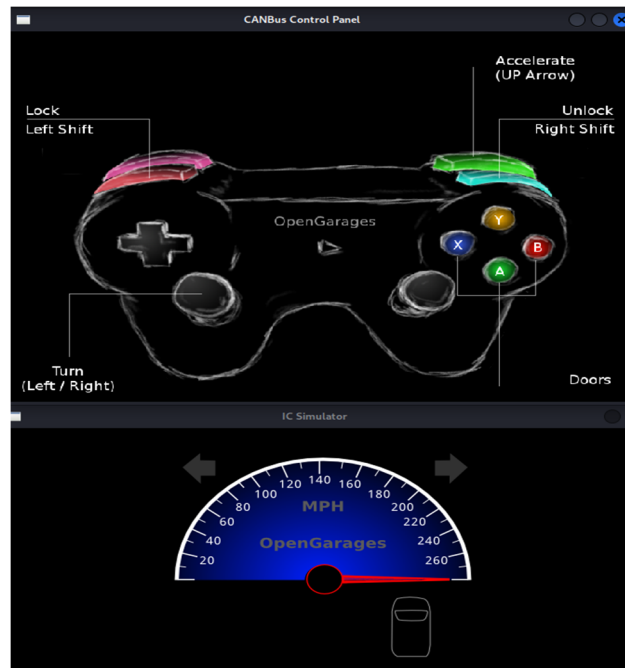
## PROCEDURE:-

- ICSim
- SavvyCAN
- Qt5
- Qtserialbus

### 1. Setting up the Instrument Cluster Simulating

```
manasi@kali: ~/Documents/Car_Hacking/ICSim
File Actions Edit View Help
(manasi@kali)-[~/Documents/Car_Hacking/ICSim]
$ ./icsim vcan0
Using CAN interface vcan0
MESA: error: ZINK: failed to choose pdev
glx: failed to create drisw screen
```

```
manasi@kali: ~/Documents/Car_Hacking/ICSim
File Actions Edit View Help
(manasi@kali)-[~/Documents/Car_Hacking/ICSim]
$ ./icsim vcan0
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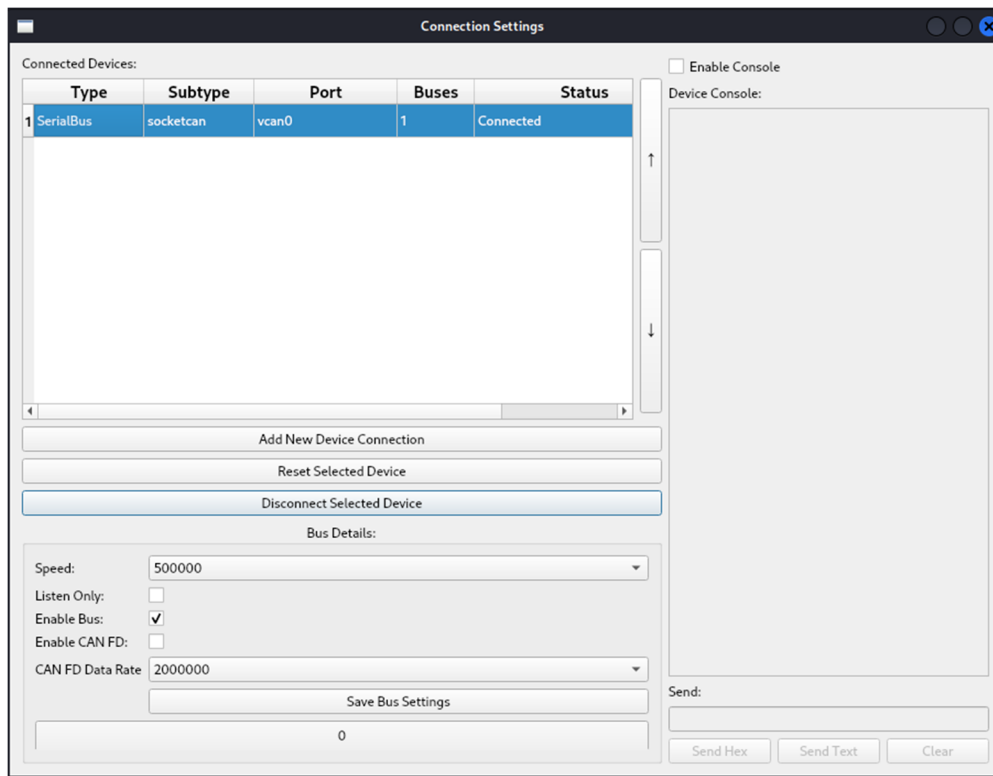
## 2. Installation Of Savvy Can

**SavvyCAN:** SavvyCAN is an open-source tool used for analyzing Controller Area Network (CAN) bus traffic in vehicles. It allows users to monitor, log, and interpret CAN bus data.

### 1. Installation and running in Ubuntu

**wget**

[https://github.com/collin80/SavvyCAN/releases/download/V199.1/SavvyCAN-305dafd-x86\\_64.AppImage](https://github.com/collin80/SavvyCAN/releases/download/V199.1/SavvyCAN-305dafd-x86_64.AppImage)



chmod744SavvyCAN-305dafd-x86\_64.AppImage#and  
./SavvyCAN-305dafd-x86\_64.AppImage

Savvy CAN V213 [Built Jun 7 2024]

File RE Tools Send Frames Connection

	Time Delta	ID	Ext	Cnt	Dir	Bus	Len	ASCII	Data
6	21859	0x183	0	475...	Rx	0	8	.....	00 00 00 06 00 00 10 05
7	27207	0x1A4	0	237...	Rx	0	8	...../	00 00 00 08 00 00 00 2F
8	27052	0x1CF	0	237...	Rx	0	6	.....	80 05 00 00 00 00 0F
9	2341	0x136	0	475...	Rx	0	8	.....	00 02 00 00 00 00 00 1B
10	20653	0x17C	0	475...	Rx	0	8	.....	00 00 00 00 10 00 00 03
11	27217	0x1AA	0	236...	Rx	0	8	.....g	7F FF 00 00 00 00 67 20
12	15568	0x158	0	475...	Rx	0	8	.....	00 00 00 00 00 00 00 0A
13	299755	0x40C	0	16035	Rx	0	8	.....	00 00 00 00 04 00 00 13
14	2425	0x13A	0	475...	Rx	0	8	.....	00 00 00 00 00 00 00 19
15	15675	0x039	0	313...	Rx	0	2	.*	00 2A
16	15285	0x244	0	610...	Tx	0	5	.....	00 00 00 A7 AF
17	34521	0x21E	0	118...	Rx	0	7	..7E..	03 E8 37 45 22 06 01
18	15583	0x161	0	475...	Rx	0	8	...P...	00 00 05 50 01 08 00 0D
19	15556	0x166	0	475...	Rx	0	4	..2...	D0 32 00 09
20	299704	0x454	0	16035	Rx	0	3	##..	23 EF 18
21	496240	0x188	0	11217	Rx	0	4	...	00 00 00 00
22	993095	0x5A1	0	4374	Rx	0	8	.....b/	96 00 00 00 00 00 62 2F
23	20066	0x164	0	475...	Rx	0	8	.....*	00 00 C0 1A A8 00 00 22
24	108738	0x320	0	48113	Rx	0	3	...	00 00 12
25	15325	0x143	0	475...	Rx	0	4	kk..	6B 6B 00 C2
26	21826	0x18E	0	475...	Rx	0	3	..M	00 00 4D
27	20089	0x13F	0	475...	Rx	0	8	.....	00 00 00 05 00 00 00 00
28	27234	0x1D0	0	236...	Rx	0	8	.....	00 00 00 00 00 00 00 0A
29	108736	0x324	0	48113	Rx	0	8	te.....	74 65 00 00 00 00 0E 1A
30	27230	0x1B0	0	236...	Rx	0	7	....f	00 0F 00 00 00 01 66
31	34512	0x294	0	118...	Rx	0	8	....Z..	04 08 00 02 CF 5A 00 0E
32	108389	0x305	0	45195	Rx	0	2	..	80 17
33	15602	0x191	0	475...	Rx	0	7	....A.0	01 00 90 A1 41 00 30
34	15440	0x095	0	475...	Rx	0	8	.....5	80 00 07 F4 00 00 00 35
35	27060	0x1DC	0	237...	Rx	0	4	....	02 00 00 0C
36	97208	0x309	0	48114	Rx	0	8	.....	00 00 00 00 00 00 00 A2

En	Bus	ID	Ext	Rem	Data	Interval	Count
1							0
2							

Connected to 1 buses No packets loaded Press F1 on any screen for help

Total Frames Captured: 36  
Frames Per Second: 2079

Suspend Capturing  
Normalize Frame Timing  
Clear Frames

☒ Keep Filters When Clearing  
☒ Auto Scroll Window  
☒ Overwrite Mode

☐ Interpret Frames

Expand All Rows  
Collapse All Rows

Bus Filtering:  
☒ 0

Frame Filtering:

- ☒ 0x1B0
- ☒ 0x1CF
- ☒ 0x1D0
- ☒ 0x1DC
- ☒ 0x21E
- ☒ 0x244
- ☒ 0x294
- ☒ 0x305
- ☒ 0x309
- ☒ 0x320
- ☒ 0x324
- ☒ 0x333
- ☒ 0x37C
- ☒ 0x405
- ☒ 0x40C
- ☒ 0x428
- ☒ 0x454
- ☒ 0x5A1

All None

### 3. Installing Qt5

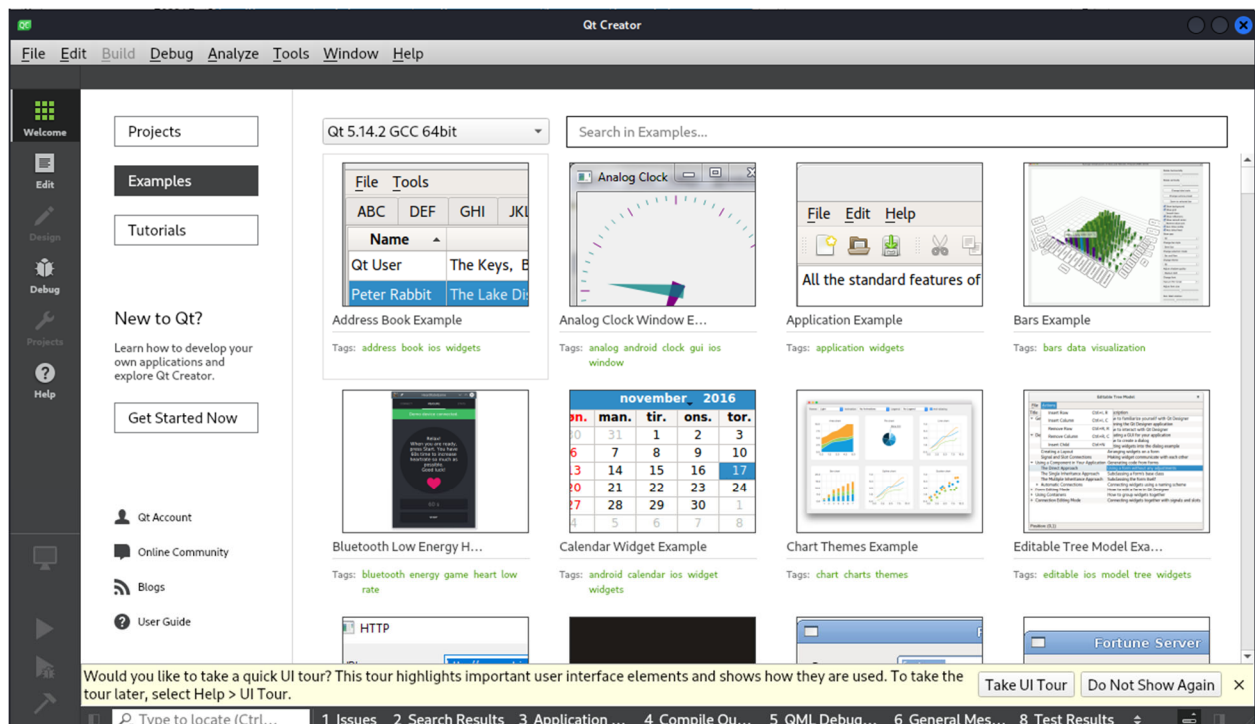
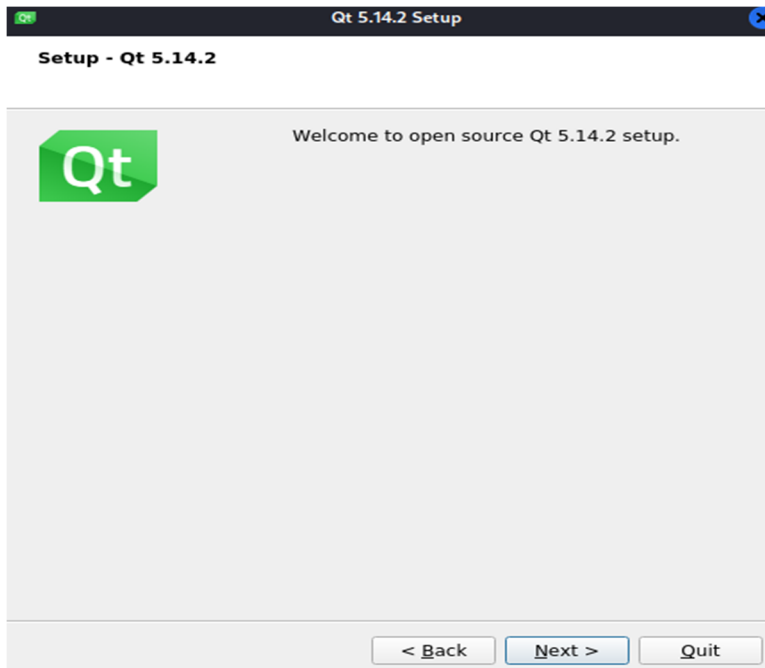
Qt5 is a versatile, cross-platform application framework that is widely used in developing software with a graphical user interface (GUI)

\$ wget [https://download.qt.io/official\\_releases/qt/5.14/5.14.4/qt-opensource-linux-x64-5.14.2.run](https://download.qt.io/official_releases/qt/5.14/5.14.4/qt-opensource-linux-x64-5.14.2.run)

Login using Email and Password .

\$ chmod a+x ./qt-opensource-linux-x64-5.14.2.run

\$ sudo ./qt-opensource-linux-x64-5.14.2.run



#### 4. Install qt serial bus

```
$ sudo apt install qtdeclarative5-dev qtttools5-dev g++
```

```
$ git clone https://github.com/qt/qtserialbus
```

```
$ cd qtserialbus
```

```
$ make
```

```
$ sudo make install
```

#### 5. Build SavvyCAN

In order to use qtserialbus, the SavvyCAN's [AppImage](#) file that we downloaded earlier will not work. SavvyCAN has to be built with qmake.

```
$ git clone https://github.com/collin80/SavvyCAN
```

```
$ cd SavvyCAN
```

```
$ make
```

#### 6. Starting the SavvyCAN

```
$ cd SavvyCAN
```

```
$ ./SavvyCAN
```

#### 7. Adding vcan0 to SocketCAN

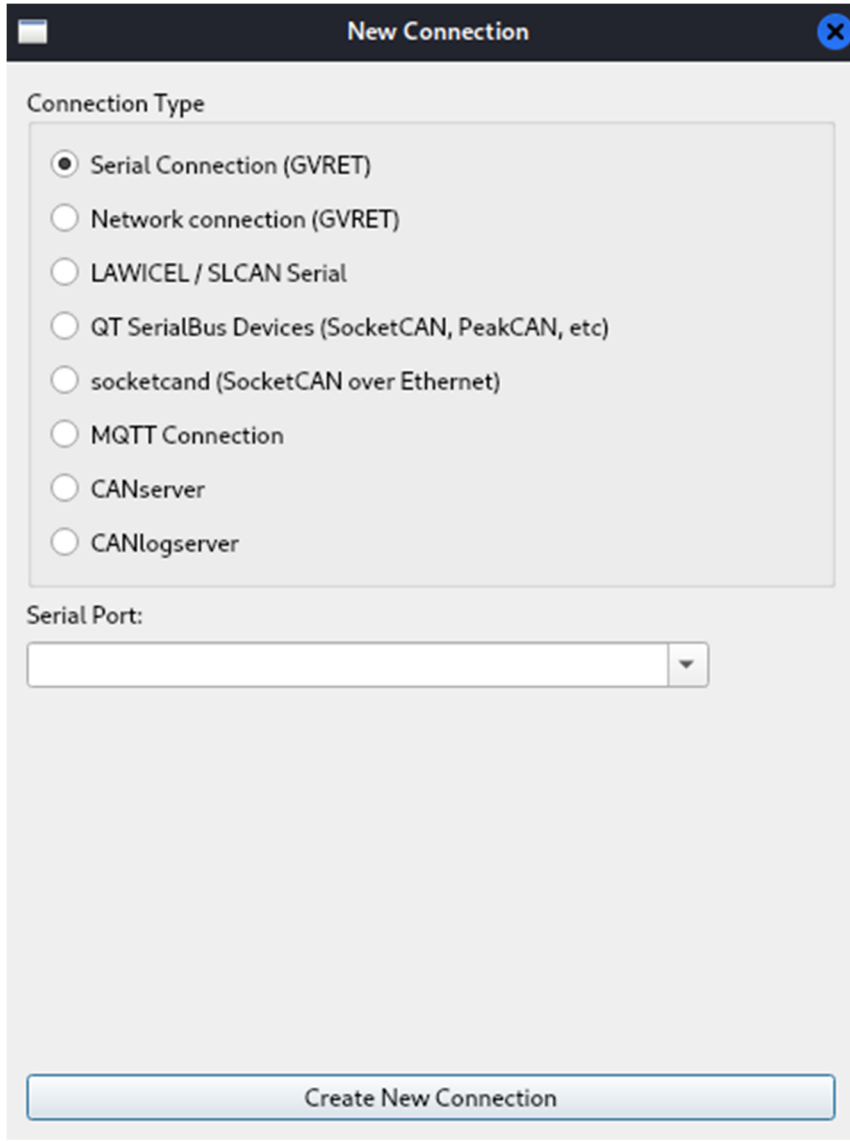
To make a new connection in SavvyCAN,

1. Open the SavvyCAN



2. Goto Connection menu -> Open Connection Window -> Add New Device Connection
3. Choose the connection with the following setting

## Connection Type as QT SerialBus Devices



**New Connection**

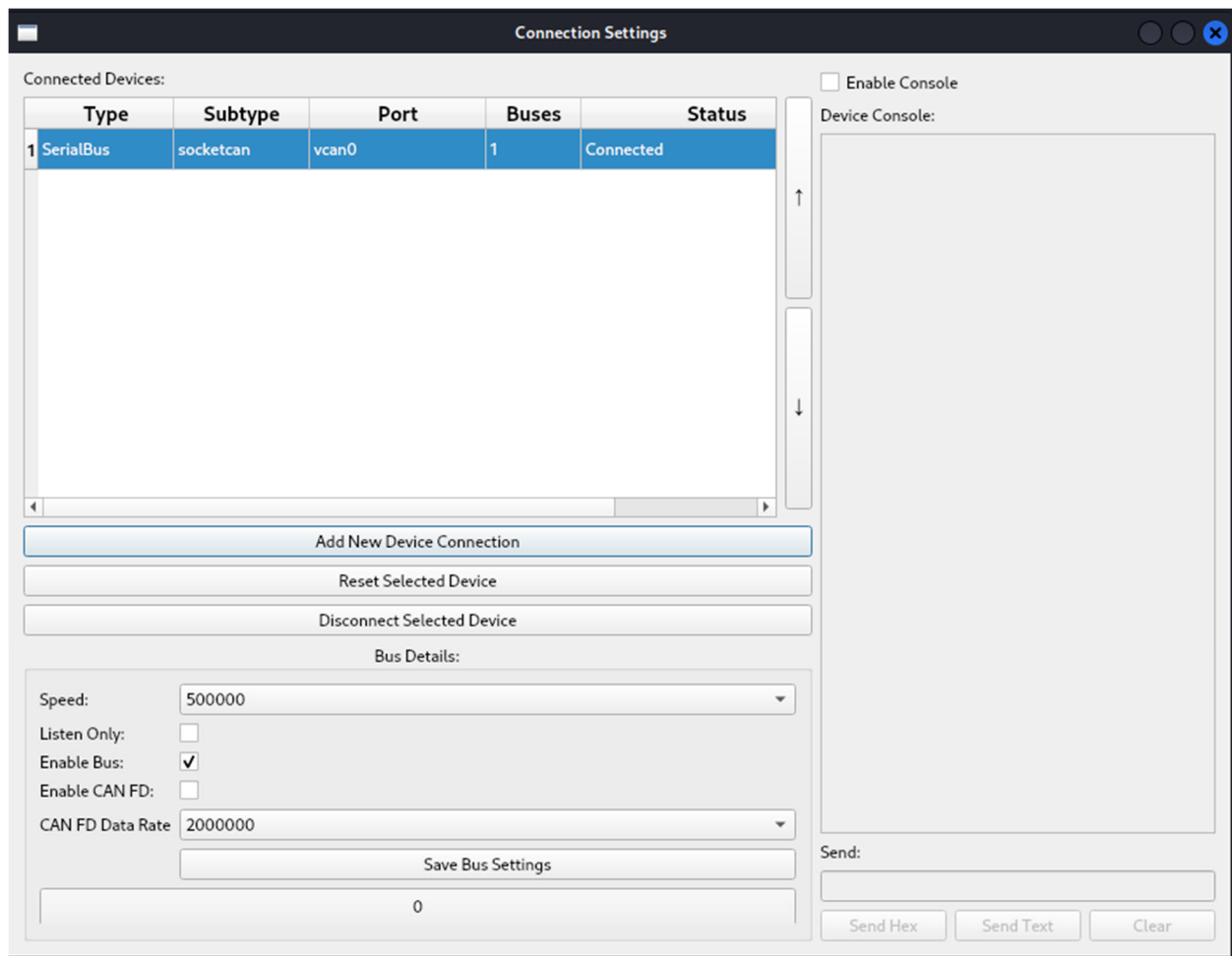
Connection Type

- ☒ Serial Connection (GVRET)
- ☐ Network connection (GVRET)
- ☐ LAWICEL / SLCAN Serial
- ☐ QT SerialBus Devices (SocketCAN, PeakCAN, etc)
- ☐ socketcand (SocketCAN over Ethernet)
- ☐ MQTT Connection
- ☐ CANserver
- ☐ CANlogserver

Serial Port:

Create New Connection

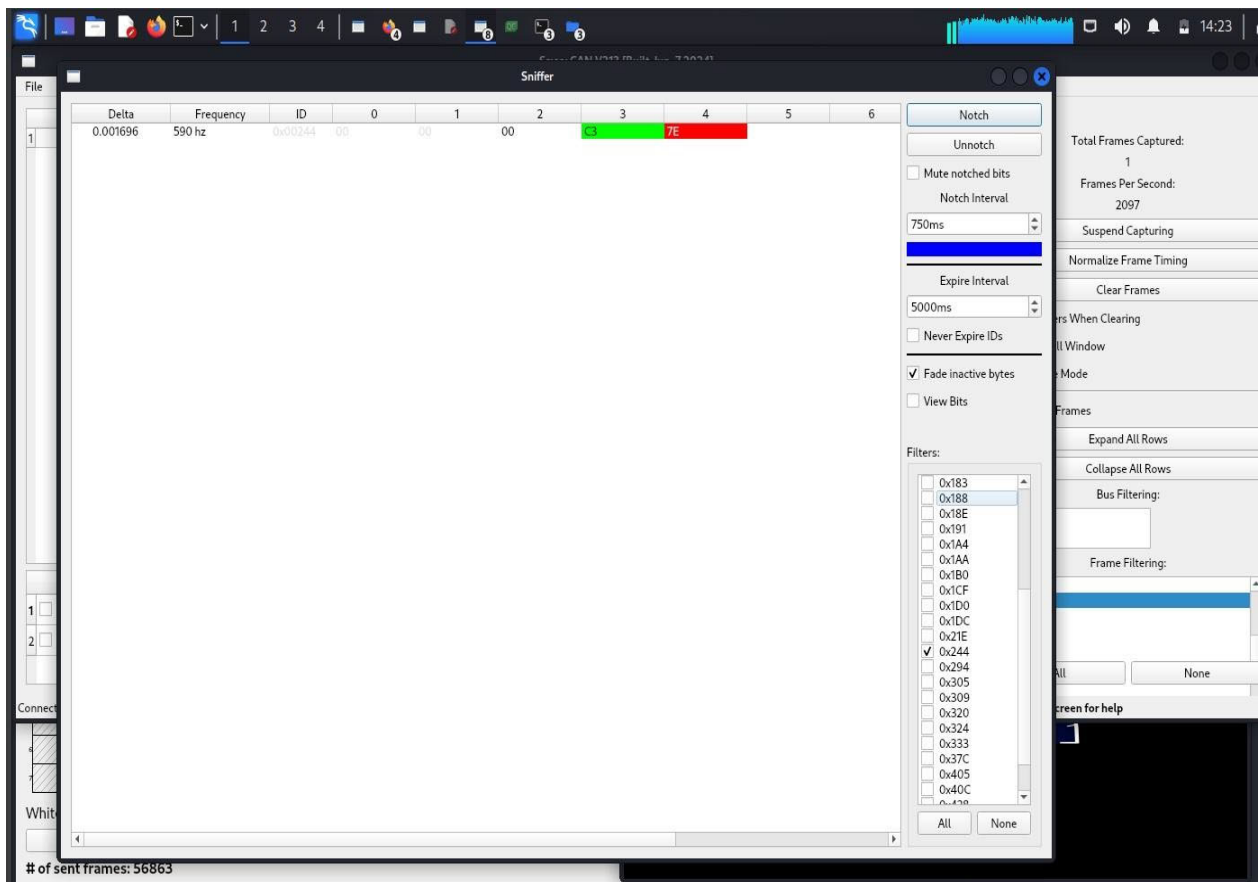
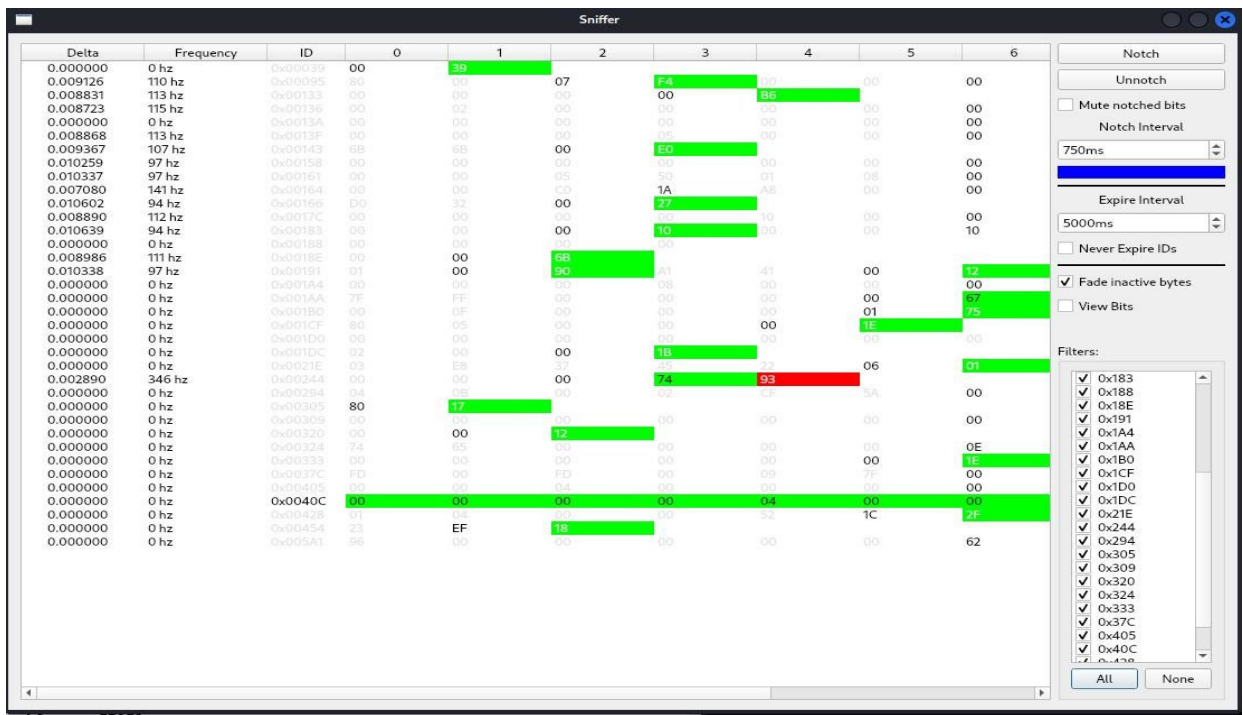
**SerialBus Device Type as socketcan**  
**Port as vcan0**



## 8. Sniffer

A CAN bus sniffer is a tool or software application that listens to the CAN bus network and captures all the messages being transmitted. It does not interfere with the communication but simply monitors the data for analysis purposes. This is analogous to a network packet sniffer used in computer networks.

We find the packet for performing a specific operation , this can be done by splitting packets and here in savvy can we can perform this by selecting the option -> Fade inactive bytes . The green color in the screenshot indicates , the active operation being performed .



## 9.Fuzzing

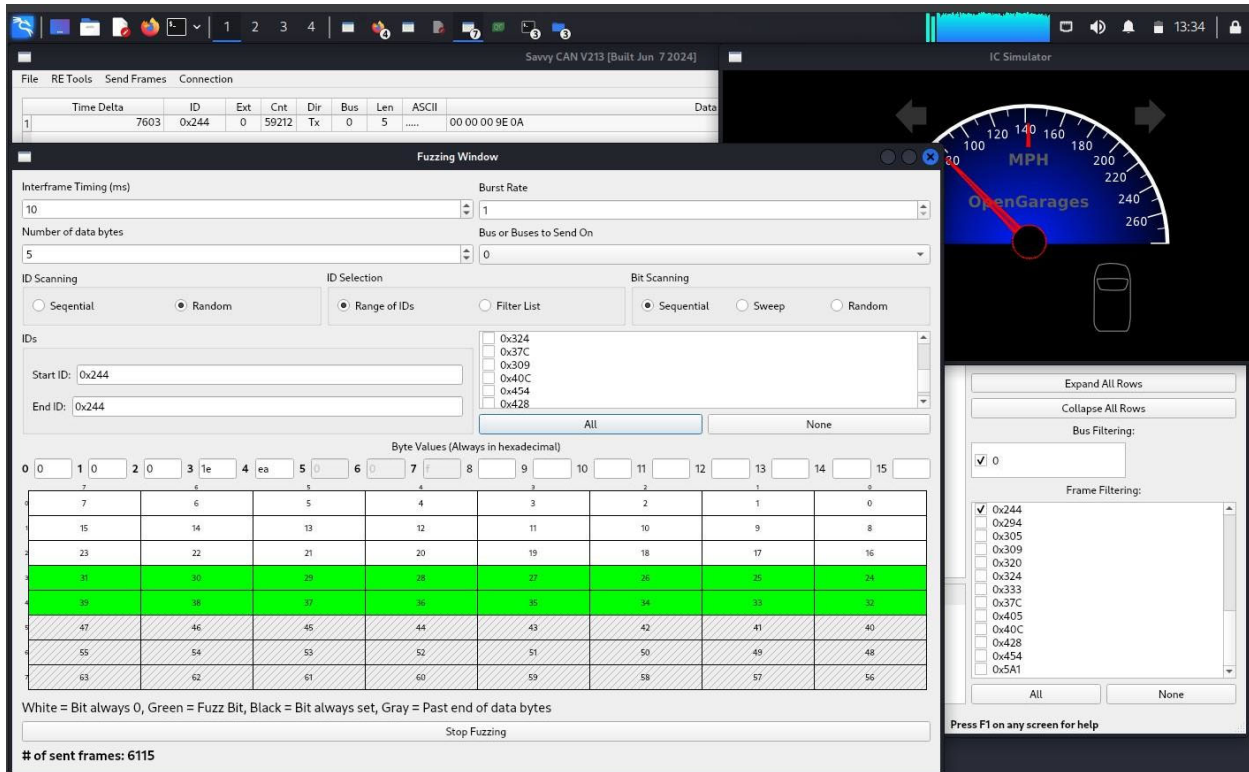
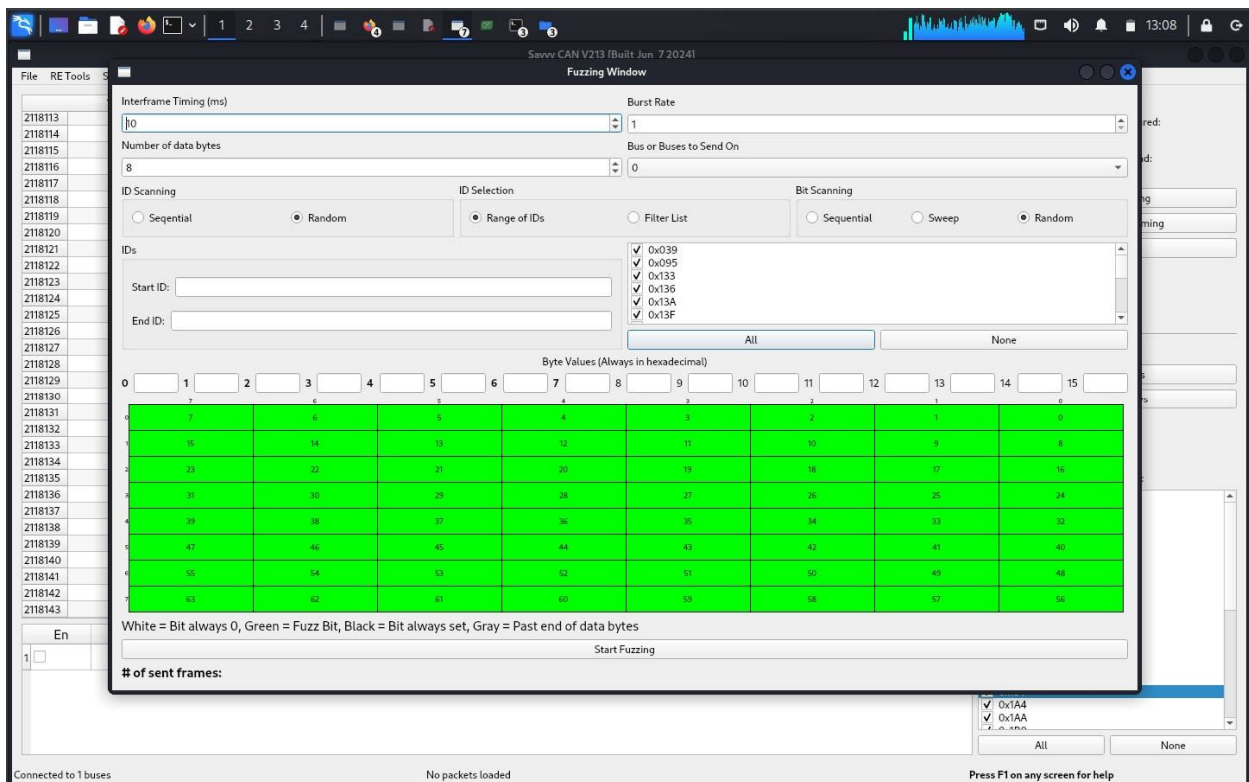
Fuzzing: This is a technique used in software testing where automated or semi-automated processes are used to send unexpected or malformed data (called "fuzz") to a target system in order to find vulnerabilities like buffer overflows, memory leaks, or other potential security issues.

Here in the screenshot ,

We can observe that 3rd and 4th rows are marked green this indicates that we are observing the change of bits only in the last 2 bytes .

Also we have considered only 5 number of data frames , hence we have considered only 5 rows from 0 to 4 .

We have considered the 0x244 bit to indicate the actions being performed , the operation its performing here is “ Tachometer / accelerometer / speedometer “ .



## 10. Sending Custom frames

Example:- here we want to send a Bus 0, ID 0x244 (tachometer), data as 0x00 0x00 0x00 0x00 0x00 and increase the 3rd byte by 2 every time, so on modification you could easily write  $d3=d3+2$ . Once done, make sure to check on Enable (EN) checkbox.

The image shows two screenshots of the SavvyCAN V213 software interface.

The top screenshot is the "Frame Sender" window. It contains a table with columns: En, Bus, ID, MsgName, Len, Ext, Rem, Data, Trigger, Modifications, and Count. Row 1 is selected, showing: En (checked), Bus (0), ID (0x244), MsgName (empty), Len (5), Ext (unchecked), Rem (unchecked), Data (0x00 0x00 0x00 0x00 0x00), Trigger (10ms), Modifications (d3=d3+2), and Count (empty). Below the table are buttons: Enable All, Disable All, Clear Grid, Load to Grid, and Save Grid.

The bottom screenshot is the main SavvyCAN V213 window. The top menu bar includes File, RE Tools, Send Frames, and Connection. The main area shows a table with columns: Time Delta, ID, Ext, Cnt, Dir, Bus, Len, ASCII, and Data. Row 1 shows: Time Delta (13185), ID (0x244), Ext (0), Cnt (397...), Dir (Rx), Bus (0), Len (5), ASCII (.....), and Data (00 00 00 01 9F). On the right, there are statistics: Total Frames Captured: 1, Frames Per Second: 2055. Below these are buttons: Suspend Capturing, Normalize Frame Timing, and Clear Frames. There are also checkboxes for: Keep Filters When Clearing (checked), Auto Scroll Window (checked), Overwrite Mode (checked), and Interpret Frames (unchecked). Below these are buttons: Expand All Rows and Collapse All Rows. There is a "Bus Filtering:" section with a dropdown set to 0. There is a "Frame Filtering:" section with a list box containing 0x1DC, 0x21E, 0x244 (selected), 0x294, 0x305, and 0x324. There are buttons "All" and "None" next to the list box. At the bottom, it says "Connected to 1 buses" and "No packets loaded".

Trigger here , this indicates the number of frames or the action that its performing is delayed by 10 milliseconds .

SavvyCAN's Frame Sender feature allows users to modify packets in real-time while sending custom frames. For instance, we can manipulate the tachometer by altering specific bytes in the frame. By observing how the tachometer responds to changes in certain bytes, such as the 3rd and 4th bytes increasing with throttle, we can send custom frames and dynamically adjust these bytes

to observe the corresponding changes in the tachometer reading. This involves specifying hex values in the data column, formatting the ID as 0x123, setting the trigger value in milliseconds, defining the delay between frames, and detailing the modifications on bytes.

## **CONCLUSION :-**

The project aims to strengthen automotive Controller Area Network (CAN) systems through comprehensive fuzzing with SavvyCAN on ICSim. Methods include injecting malformed frames and dynamically modifying data to uncover vulnerabilities. Objectives include proactive testing, vulnerability identification, and proposing mitigation strategies. The goal is to enhance automotive cybersecurity and pave the way for future advancements, promising immediate improvements and laying the groundwork for evolving CAN security testing methodologies.