Assignment 06

Name: Manav Kothari

UIN: 133008008

Problem 10.8.1

Inputs

Parameter	Value
S	imulation Input
Problem	1
NONLIN	0 (Linear)
ITERMAX	25
Epsilon	0.001
GAMA1 (Acceleration Parameter)	0.5
GAMA2 (Penalty Term)	10^8
	Domain Input
X0	0
YO	0
X_length	6
Y_length	2
	Mesh Input
NX	10
NY	6
NPE	4
DX	[1 1 1 1 0.5 0.5 0.25 0.25 0.25 0.25]
DY	[0.25 0.25 0.5 0.5 0.25 0.25]
NDF	2
IEL	1
NGPF	2
NGPR	1
Lo	pading Condition
DP	1
F = [FX FY]	[0 0]
MU	1
Essentia	l Boundary Conditions
NSPV	39
ISPV	[1 77 76 75 74 73 72 71 70 69 68 67 56 45 34 23
	12 1 2 34 5 6 7 8 9 10 11 77 76 75 74 73 72 71 70
	69 68 67; 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 2 2 2 2
	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2]'
VSPV	[00000000000000000000000000000000000000
	0 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1]'

Natural Boundary Condition							
NSSV 31							
ISSV	[1 2 3 4 5 6 7 8 9 10 11 22 33 44 55 66 77 1 11 22						
	33 44 55 66 77 67 56 45 34 23 12; 1 1 1 1 1 1 1 1						
	1111111112222222222222]						
VSSV	zeros(max(size(ISSV)),1)						

Results

v	Gar	ma = 1	Gama	= 100	Gama = 10^8		
X	10*6 - L4	5*3 - Q9	10*6 - L4	5*3 - Q9	10*6 - L4	5*3 - Q9	
1.00	0.0303	0.0310	0.6563	0.6513	0.7576	0.7505	
2.00	0.0677	0.0691	1.3165	1.3062	1.5135	1.4992	
3.00	0.1213	0.1233	1.9911	1.9769	2.2756	2.2557	
4.00	0.2040	0.2061	2.6960	2.6730	3.0541	3.0238	
4.50	0.2611	0.2631	3.0718	3.0463	3.4648	3.4307	
5.00	0.3297	0.3310	3.4347	3.3956	3.8517	3.8029	
5.25	0.3674	0.3684	3.6120	3.5732	4.0441	3.9944	
5.50	0.4060	0.4064	3.7388	3.6874	4.1712	4.1085	
5.75	0.4438	0.4443	3.8316	3.7924	4.2654	4.2160	
6.00	0.4793	0.4797	3.8362	3.7862	4.2549	4.1937	

Table 1: Vx (x,0)

	10 ³	*6 - L4	5*3 - Q9			
У	Vx (x = 4)	Vx (x = 6)	Vx (x = 4)	Vx (x = 6)		
0	3.0541	4.2549	3.0238	4.1937		
0.25	3.0074	4.2127	2.9796	4.1719		
0.5	2.8526	4.0360	2.8250	3.9621		
1	2.2655	3.4093	2.2446	3.3808		
1.5	1.3051	2.1793	1.2897	2.1208		
1.75	0.6979	1.5183	0.6893	1.4559		
2	0.0000	0.0000	0.0000	0.0000		

Table 2: Horizontal velocity Vx (x,y) vs vertical distance y

	10*6	6 - L4		5*3 - Q9			
x	Top Plate	Centerline	x	Top Plate	Centerline		
	Pressure	Pressure		Pressure	Pressure		
0.500	8.0304	7.3828	0.423	7.9839	7.3238		
1.500	7.7064	6.9978	1.577	7.5964	6.8854		
2.500	6.8346	6.2573	2.423	6.8666	6.2635		
3.500	5.8653	5.0972	3.577	5.7138	4.9424		
4.250	4.4726	4.0086	4.211	4.5390	4.0165		
4.750	4.3387	3.0012	4.789	4.2338	2.8925		
5.125	2.9554	2.2705	5.106	3.1200	2.2742		
5.375	4.5657	1.4866	5.394	4.4606	1.4509		
5.625	2.9580	0.8717	5.606	3.0684	0.9609		
5.875	7.5452	0.0069	5.894	7.2777	-0.0140		

Table 3: Pressure vs Horizontal distance x (Near top plate & centerline)

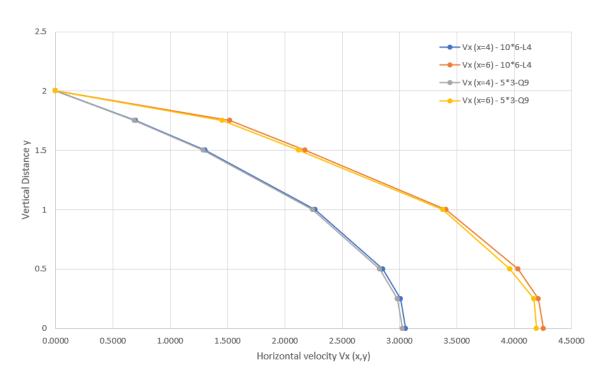


Figure 1: Horizontal Velocity field Vx at x = 4 & x = 6

Top Plate Pressure vs x

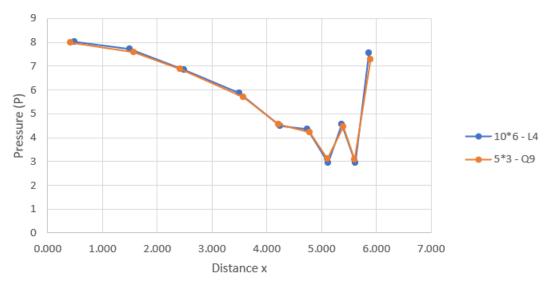


Figure 2: Top Plate Pressure vs x

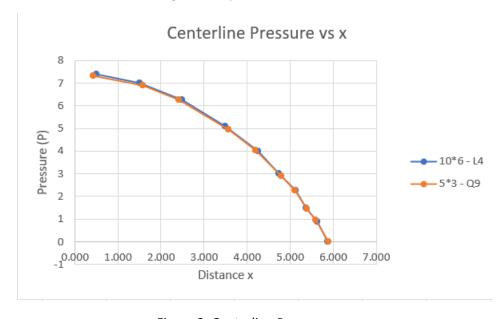


Figure 3: Centerline Pressure vs x

Problem 10.8.4

Inputs

111					
Parameter	Value				
Simulati	on Input				
Problem	2				
NONLIN	1				
ITERMAX	25				
Epsilon	0.001				

GAMA1 (Acceleration Parameter)	0.5
GAMA2 (Penalty Term)	10^8
	Domain Input
X0	0
Y0	0
X_length	
Y_length	1
	Mesh Input
NX	8
NY	10
NPE	9
DX	0.125*ones(1,NX)
DY	[0.125 0.125 0.125 0.125 0.125 0.125 0.0625 0.0625 0.0625 0.0625]
NDF	2
IEL	2
NGPF	3
NGPR	2
	eding Condition
DP	[0 500 1000]
F = [FX FY]	[0 0]
MU	1
	Boundary Conditions
NSPV	144
ISPV	[1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 34 51 68 85 102 119 136 153 170 187 204 221 238 255 272 289 306 323 340 357 356 355 354 353 352 351 350 349 348 347 346 345 344 343 342 341 324 307 290 273 256 239 222 205 188 171 154 137 120 103 86 69 52 35 18 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 34 51 68 85 102 119 136 153 170 187 204 221 238 255 272 289 306 323 340 357 356 355 354 353 352 351 350 349 348 347 346 345 344 343 342 341 324 307 290 273 256 239 222 205 188 171 154 137 120 103 86 69 52 35 18; 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
VSPV	[0000000000000000000000000000000000000

Natural Boundary Condition						
NSSV 0						
ISSV	[]					
VSSV	[]					

Results

у	Mesh: 8*8 - L4								М	esh: 4*4 - C	19											
Re ->	Linear	25	250		500		750		750		750		750		750		25	0	50	10	75	0
	Linear	DI	NI	DI	NI	DI	NI	Linear	DI	NI	DI	NI	DI	NI								
0.125	-0.0579	-0.0367	-0.0367	-0.0239	-0.0235	-0.0128	-0.0121	-0.0615	-0.0412	-0.0410	-0.0131	-0.0120	0.0146	0.0151								
0.250	-0.0988	-0.0688	-0.0689	-0.0502	-0.0498	-0.0320	-0.0310	-0.1039	-0.0851	-0.0848	-0.0520	-0.0502	0.0017	0.0031								
0.375	-0.1317	-0.0944	-0.0947	-0.0733	-0.0732	-0.0533	-0.0526	-0.1393	-0.1283	-0.1283	-0.1133	-0.1119	-0.0481	-0.0459								
0.500	-0.1471	-0.0911	-0.0915	-0.0696	-0.0701	-0.0569	-0.0573	-0.1563	-0.1305	-0.1311	-0.1284	-0.1295	-0.1086	-0.1079								
0.625	-0.0950	-0.0176	-0.0177	0.0043	0.0037	0.0020	0.0010	-0.1118	-0.0437	-0.0442	-0.0494	-0.0517	-0.0901	-0.0908								
0.750	0.0805	0.0469	0.0479	0.0414	0.0414	0.0323	0.0322	0.0481	0.0753	0.0753	0.1042	0.1042	0.0549	0.0517								
0.875	0.4500	0.2616	0.2617	0.1712	0.1714	0.1207	0.1198	0.4186	0.2833	0.2838	0.2139	0.2133	0.1495	0.1482								

Table 4: velocity Vx(0.5,y) for different Reynold's number

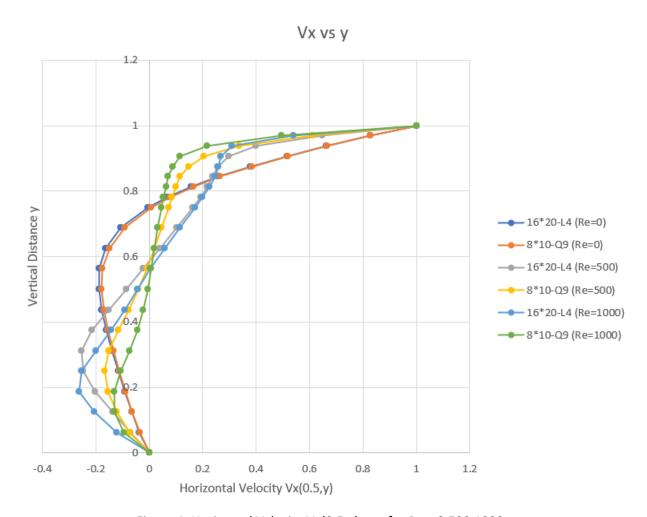


Figure 4: Horizontal Velocity Vx(0.5,y) vs y for Re = 0,500,1000

Pressure vs x

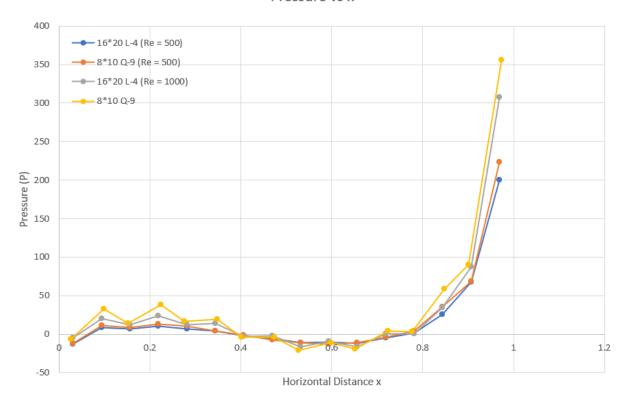


Figure 5: Plot of Pressure P along the top wall of the cavity

```
%% Pseudo Code
% Do not run this
Give all Inputs
Call MeshR function to generate 2D Rectangular Mesh
Call PlotMesh function to get visual reprsentation of the ✓
generated mesh
Define DOF NOD matrix
% DOF NOD matrix is but a matrix similar to NOD matrix, but ✓
rather than
% mapping global node number with element number, it maps∠
global degree of
% freedom with element number
Initialize current and previous iteration solution (GCU & GPU)
%% Big Loop
for NL = 1:NLS % Initiate load step loop
   Define required constants like Rho and Mu
    while iter<=ITERMAX && convergence == 0 % Initiate/
iterative loop
        Initialize GLK and GLF matrices
        for N = 1:NEM
            Calculate ELU matrix from GPU & GCU & Acceleration ✓
parameter (GAMA1)
            Define ELXY from GLXY
            Call FLUIDMATRICS function to calculate ELK and ELF
            Perform Assembly of ELK & ELF into GLK & GLF
        end
```

```
Call FLUIDBCS function to apply Essential and Natural ✓
BCs
        Calculate current iteration solution GCU
        Null out VSPV for NI after 1st iteration
        Calculate error and check for convergence
        iter = iter+1;
    end % END OF ITERATIVE LOOP
    %% Post Processing of converged solution
    if IGRAD ~= 0 % Check if post-processing is required by the
user or not
        for I = 1:NEM % Calculate for all elements
            Define ELXY and ELU
            Call STRESS2D function to calculate Pressure for ✓
all the gaussian points in the element
            Call Press Calc script to print the required✓
Pressure values
            % Note Press Calc is question specific and needs to√
be changed
            % if we solve any other question (except 10.8.1 &∠
10.8.4)
        end
    end
end % END OF LOAD STEP LOOP
PRINT SOLUTIONS
```

```
응 🗸
        ---- 응
function [ELK,ELF] = FLUIDMATRICS(NDF,NPE,NONLIN,ELXY,ELU,√
RHOAMU, NGPF, GAMA2)
Initialize ELK and ELF
% Full integration
for NI = 1:NGPF
   for NJ = 1:NGPF
       Calculate ELF and part of ELK matrix
       if NONLIN > 1
          Calculate TANG matrix as well
       end
   end
end
% Reduced Integration
for NI = 1:NGPR
   for NJ = 1:NGPR
       Calcuate the penalty term in ELK
   end
end
if NONLIN > 1
   Calculate final TANG matrix and Residual matrix
end
end
응 🗸
```