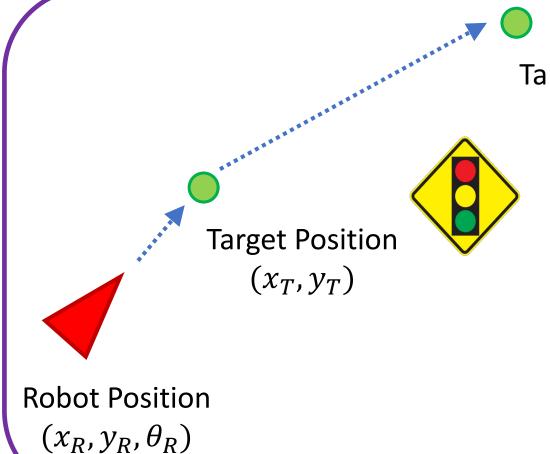


Challenge: Reactive Navigation







Target Position (x_T, y_T)

Target Position (x_T, y_T)

In this small challenge you will have to combine the previous activities. Add a decision-making layer to you point-to-point navigation code by detecting the color of the traffic light. The expected behavior is:

- Red: Stop until you see a green light.
- Green: Continue with the path.

Note that you should remain stopped until you see a green light!