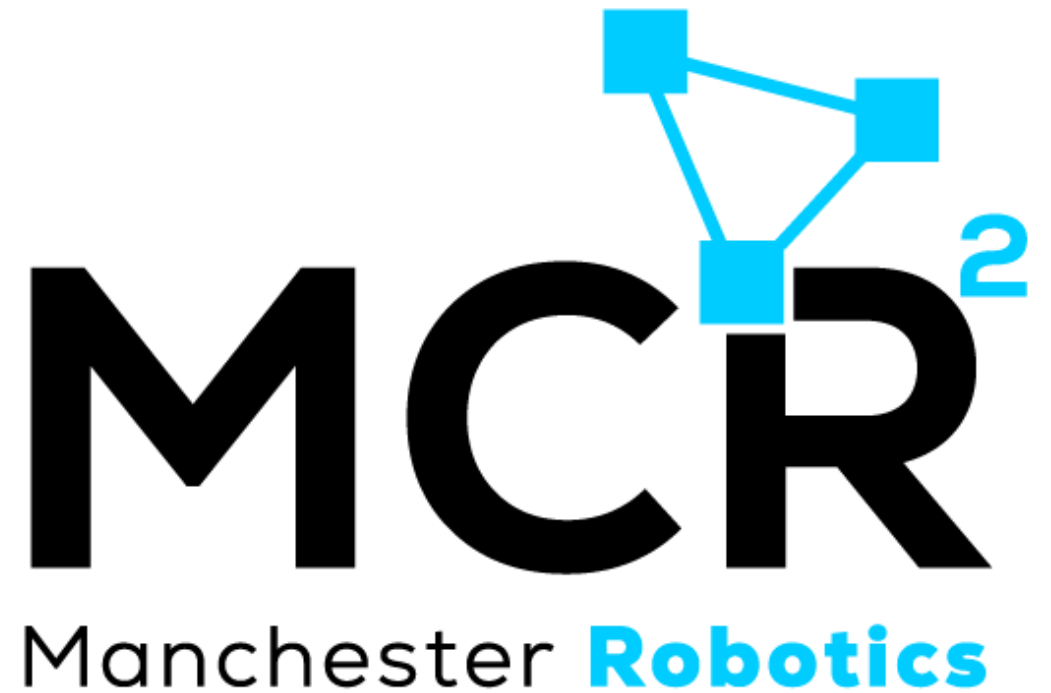


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Getting Started with ROS

Installation

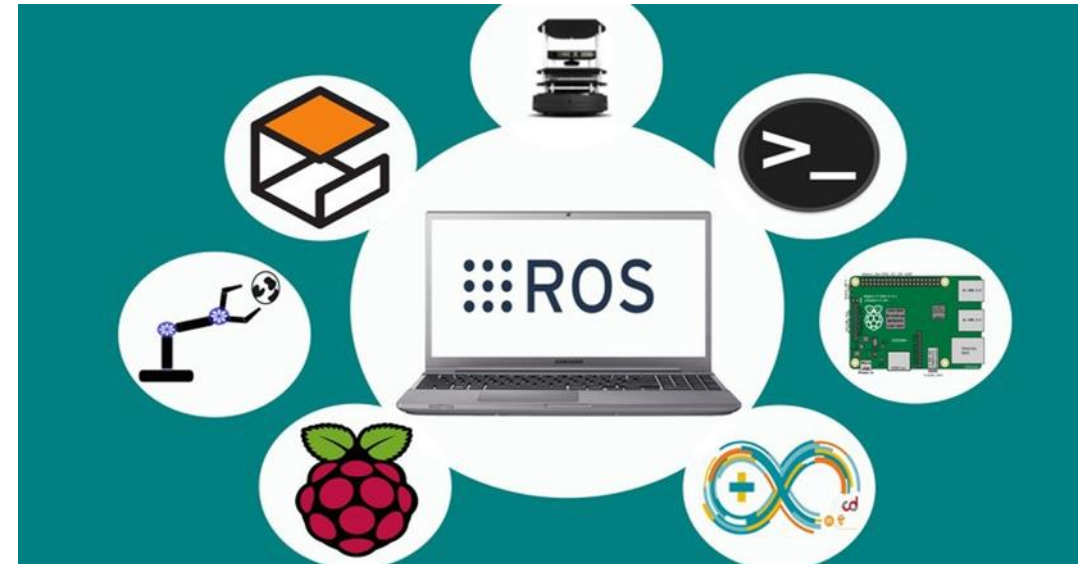




What is ROS?



- **R**obot **O**perating **S**ystem
- Contrary to popular belief, ROS is not an operating system.
- “The ROS is a set of software libraries and tools that help you build robot applications. From drivers to state-of-the-art algorithms, and with powerful developer tools, ROS has what you need for your next robotics project. And it's all open source.”



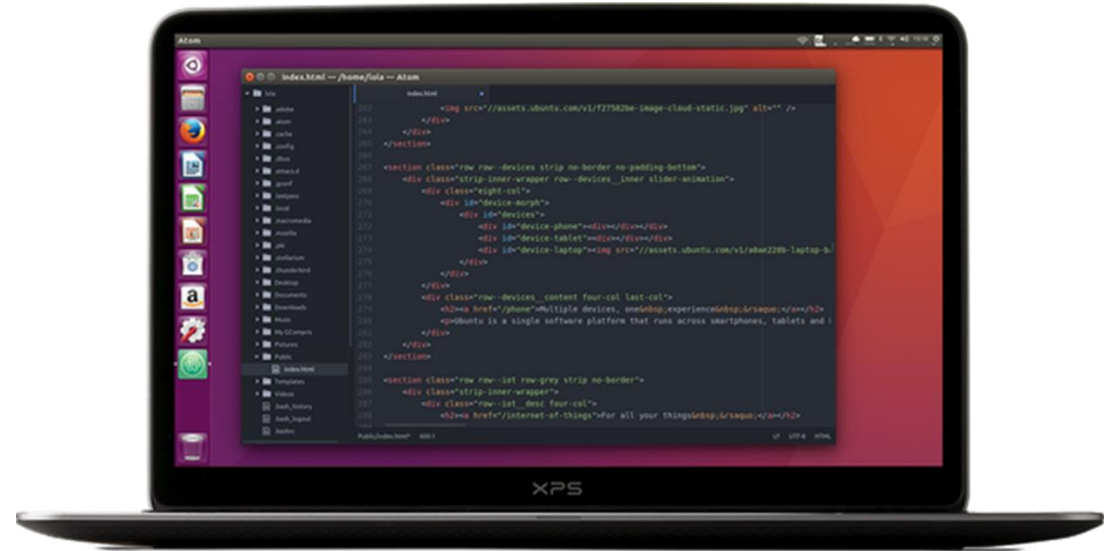


Getting Started with ROS



What do we need to start working?

- Minimum Requirements*:
 - Processor: i5 or higher
 - RAM: 8 GB or higher
 - Storage: 20 Gb
 - Graphics: Dedicated GPU



*These requirements are the minimum for the activities designed.

Getting Started with ROS

- A new version of ROS is released with each Linux distribution. We will use ROS Melodic in this course (released with Ubuntu 18.04).
- Currently, another version of ROS is available, Ubuntu 22.04.
- A revision of the ROS structure, known as ROS2, that aims to increase the robustness of the framework for industrial applications and distributed systems.
- Furthermore, ROS2 allows real-time applications.

ROS Melodic Morenia
Released May, 2018
LTS, supported until May, 2023
Recommended for Ubuntu 18.04



ROS Noetic Ninjemys
Released May, 2020
Latest LTS, supported until May, 2025
Recommended for Ubuntu 20.04





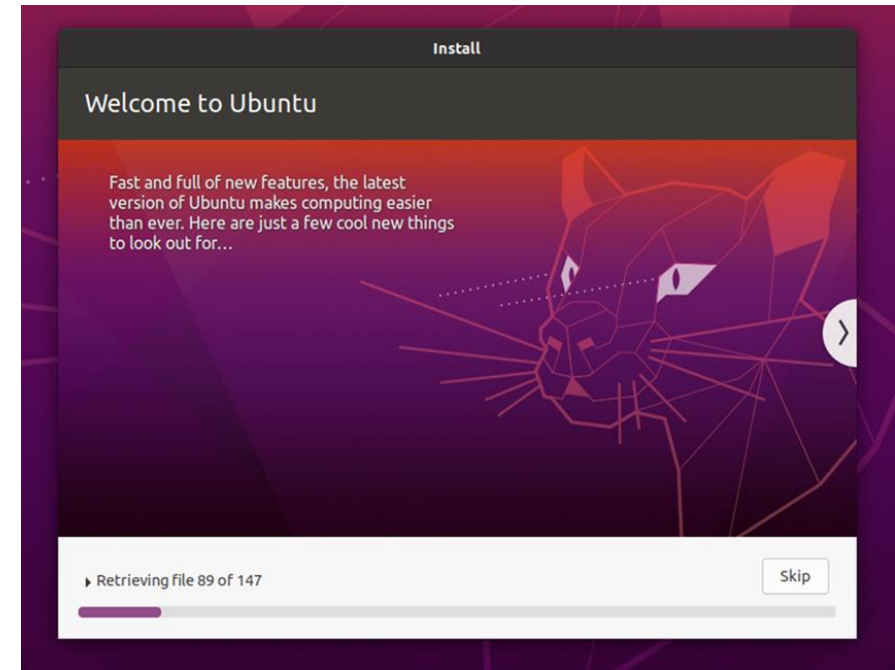
Installing Ubuntu



Installing Ubuntu

The recommended way of installing Ubuntu for robotics is as the main operating system or by dual booting it alongside the default Windows or Mac OS.

It can also run on a virtual machine, but this will limit features, and the performance speed could be affected.





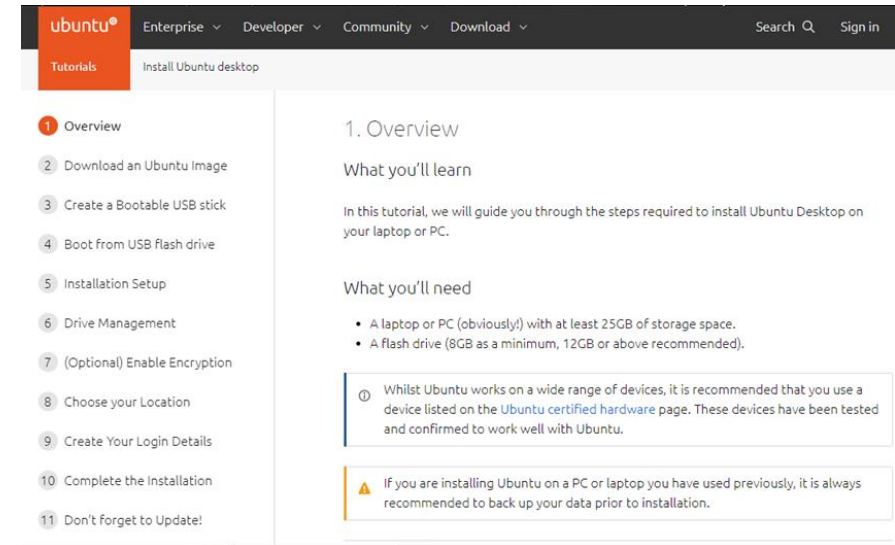
Installing Ubuntu



Quick Installation Guide Ubuntu as Main OS

Follow the [tutorial](#) on the official ubuntu website. Download the ubuntu 18.04 image [here](#).

- On the left side of the webpage, all the steps for the installation are detailed.
- Once you click on each step, the installation details are described in the right panel.
- **PROS:** Easy installation, access in full to hardware.
- **“CONS”:** Not possible if you need windows installed on the same machine.





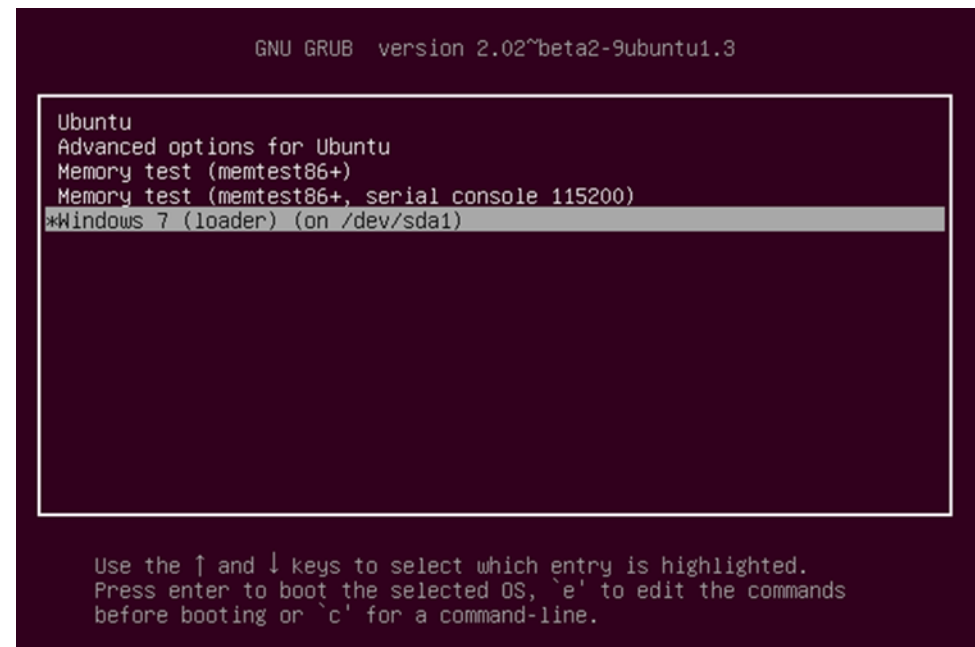
Installing Ubuntu



Dual Boot Installation

This installation requires preparing the computer first. This may vary depending on the computer brand, but the main steps are:

- Prepare the USB as the [website](#) indicates. (Step 1-4)
- You may need to modify some parameters from the BIOS configuration.
- Depending on how many partitions or how full the disc is, you may want to defrag and partition your hard drive using Windows. More info [here](#).
- Change the booting option from the computer and keep following the steps on the [website](#).
 - **PROS:** Relatively easy install, access in full to hardware .
 - **CONS:** a problem if you must use windows and don't have another machine.





Installing Ubuntu (VM)

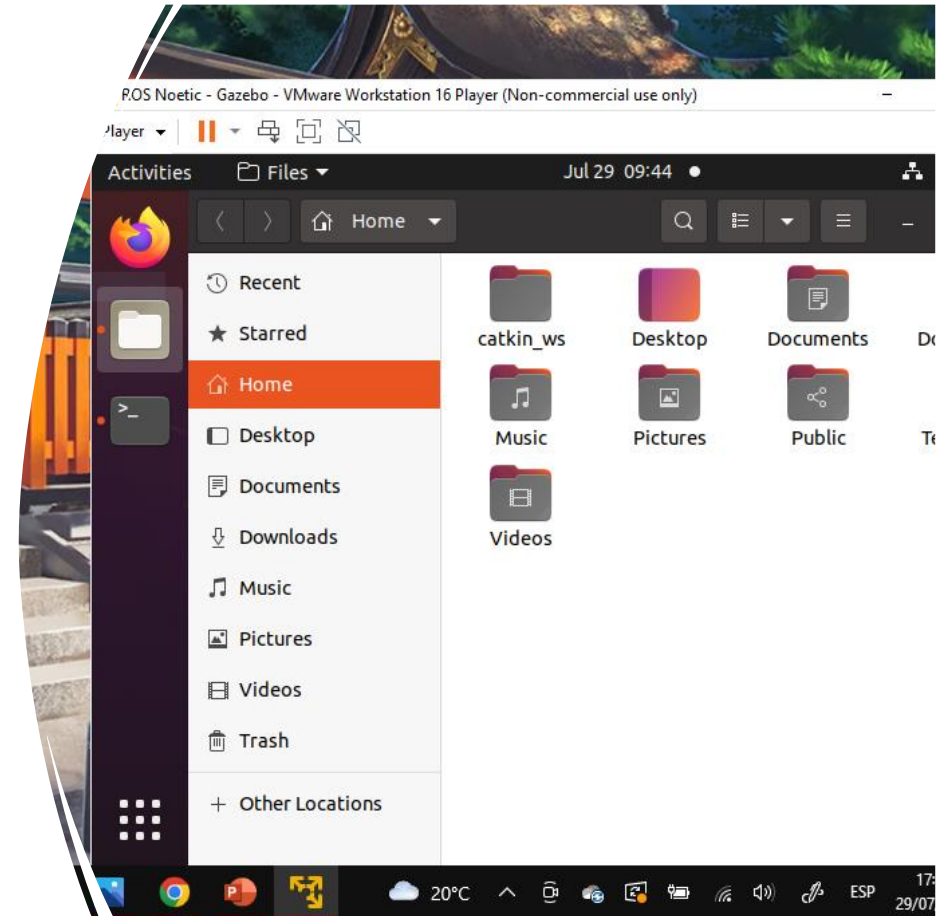


Virtual Machine vs. Standard Installation

A Virtual Machine (VM or guest OS) is an emulated Operated System done by software (Virtual Box and VMware most popular) installed in the main OS (host OS).

This could be helpful as a starting point (or a last resort), but it has some cons:

- The host OS and guest OS **share the same resources**, affecting both operations (especially for heavy simulations).
- VM requires drivers to **access the peripheral** (USB, Serial), which could be **not supported** or not fully working.
- The VM cannot have the same network as the host (main operative system), which would be a **problem for ROS projects that require multiple devices that communicate** with each other.



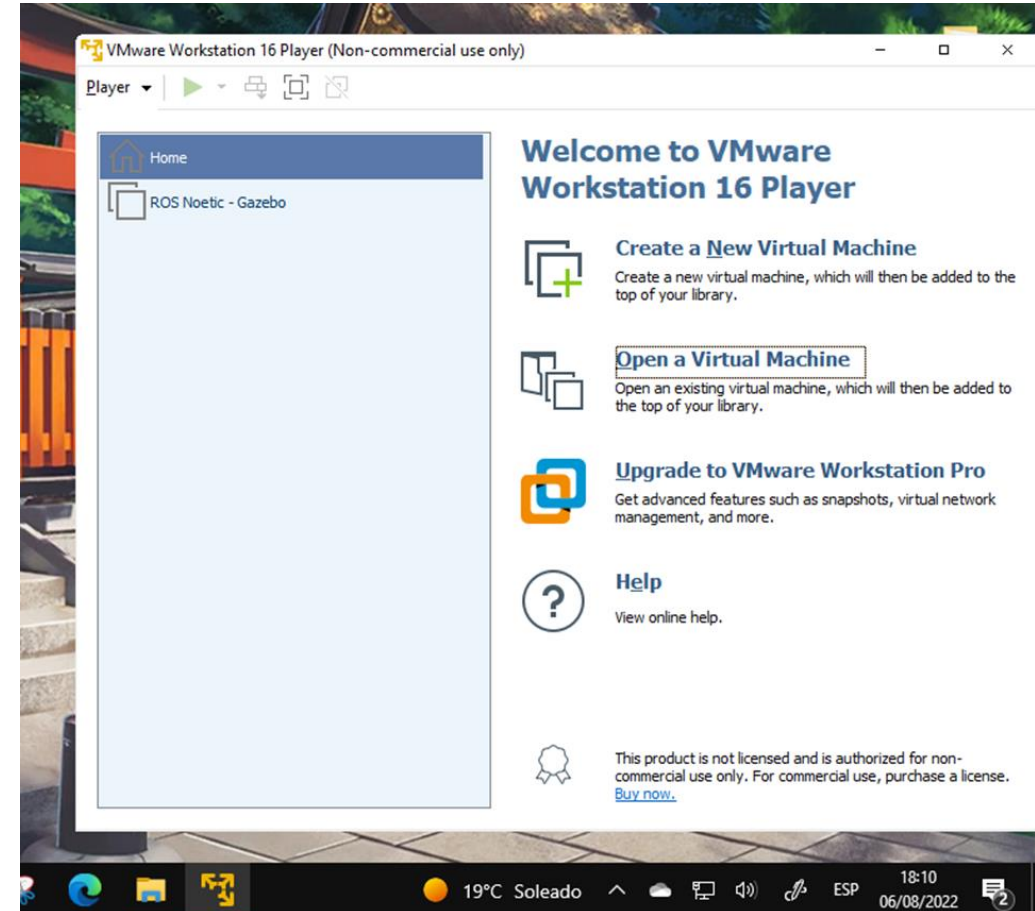


Installing Ubuntu Generic VM



Virtual Machine Installation

- Download the files:
[VMware software executable](#)
 - Install the VMware software.
 - Open software to finish the installation.
NOTE: Select personal “non-commercial” use
 - Click on “create a virtual machine”.
 - Select the OS iso file and installation folder, and the installation will start.
- Note: The disk space and ram could be modified in this step. We recommend 20 GB and at least 4 GB (half the ram of the host)
- Once Ubuntu starts, you need to choose the user and password to continue the installation. After a restart, the VM should be working.





MCR2 Virtual Machine Installation



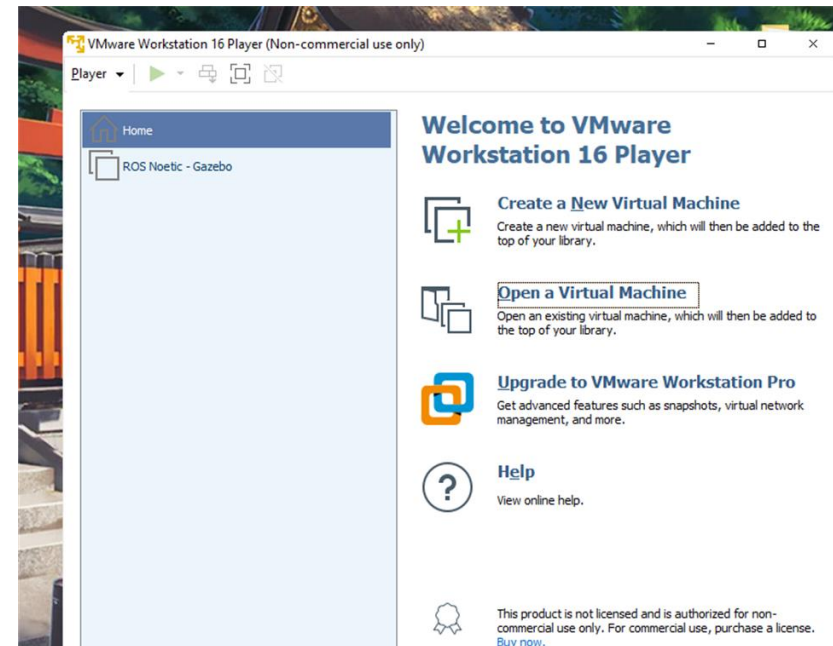
- Download and unzip the files:

[VMware software executable](#)
[Preinstalled VM zip file](#)

(NOTE: This is a long file (~ 6GB).)

- Install the VMware software.
- Open the software, finish the setup, and license.
NOTE: Select personal “non-commercial” use
- Click on “open virtual machine” and open the “Preinstalled VM” (you only must do this once). The virtual machine will start to be set up.
NOTE: Choose the option “I copied it”
- The virtual machine should start up with Ubuntu and ROS installed!

USER: Student
PASSWORD: admin





Quick installation guide for ROS



ROS Installation

- Follow the [tutorial](#) on the official ROS website.
- The ROS installation is done using the terminal.
- In section 1.4, use the command for installing Desktop-Full Install.
- This will install Gazebo too.
- The following package is needed for this unit:

```
$ sudo apt-get install ros-melodic-ros-control ros-melodic-ros-controllers
```

ROS.org

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Ubuntu install of ROS Melodic

We are building Debian packages for several Ubuntu platforms, listed below. These packages are more efficient than source-based builds and are our preferred installation method for Ubuntu. Note that there are also packages available from Ubuntu upstream. Please see [UpstreamPackages](#) to understand the difference.

Ubuntu packages are built for the following distros and architectures.

Distro	amd64	arm64	armhf
Artful	X		
Bionic	X	X	X

If you need to install from source (**not recommended**), please see [source \(download-and-compile\)](#) installation instructions.



If you rely on these packages, please support OSRF.

These packages are built and hosted on infrastructure maintained and paid for by the [Open Source Robotics Foundation](#), a 501(c)(3) non-profit organization. If OSRF were to receive one penny for each downloaded package for just two months, we could cover our annual costs to manage, update, and host all of our online services. Please consider [donating to OSRF](#) today.

ROS 2 Documentation

The ROS Wiki is for ROS 1. Are you using ROS 2 (Dashing/Foxy/Rolling)? [Check out the ROS 2 Documentation](#)

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[Raw Text](#)



ROS is installed



How do I know it is working correctly?

- If you finished the installation and everything went smoothly.
- Then, try the following command to start ROS:
 - `roscore`
- If the terminal displays a similar output to this image in the slide: Congratulations, you have Ubuntu and ROS running!

```
roscore http://varhowto-com:11311/
File Edit View Search Terminal Help
vh@varhowto-com:~$ roscore
... logging to /home/vh/.ros/log/0b706622-ab8c-11ea-b7e5-0800
27e1313c/roslaunch-varhowto-com-10761.log
Checking log directory for disk usage. This may take a while.
Press Ctrl-C to interrupt
Done checking log file disk usage. Usage is <1GB.

started roslaunch server http://varhowto-com:37309/
ros_comm version 1.14.5

SUMMARY
=====

PARAMETERS
* /rostdistro: melodic
* /rosversion: 1.14.5

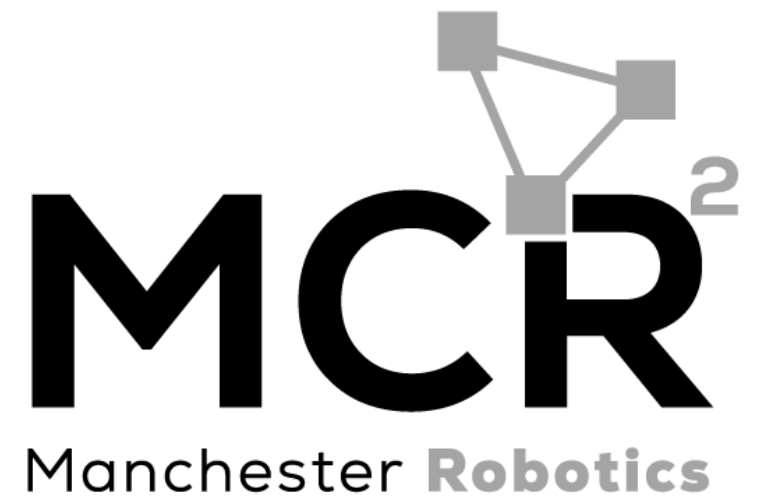
NODES

auto-starting new master
process[master]: started with pid [10772]
ROS_MASTER_URI=http://varhowto-com:11311/

setting /run_id to 0b706622-ab8c-11ea-b7e5-080027e1313c
process[rosout-1]: started with pid [10783]
started core service [/rosout]
```

Thank you

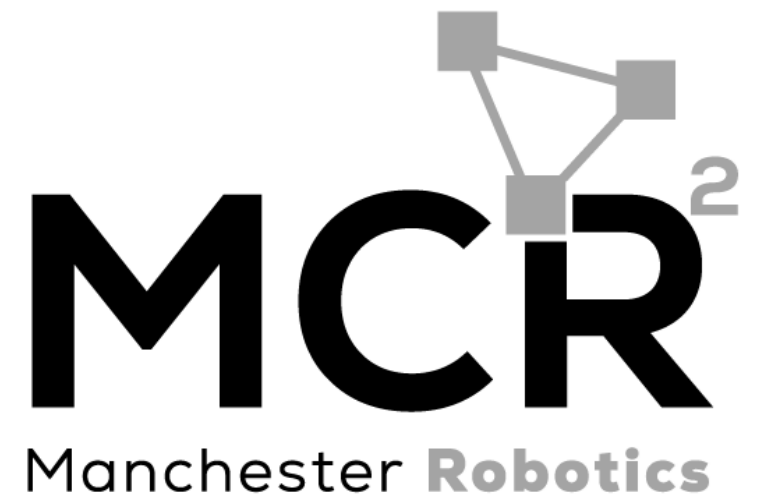
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T&C

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