

# CS410: Parallel Computing

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Shared-Memory Programming (using POSIX Threads)  
contd..

# Pthreads API

- Subroutines grouped into four major categories:

- 1. Thread Management –**

Routines that deal with thread creation, join, detach, etc. Also, query thread attributes

- 2. Mutexes –**

Routines that deal with synchronization. Creating, destroying, locking, and unlocking a mutex (abbr. for “mutual exclusion”). Also, set mutex attributes

- 3. Condition Variables –**

Routines addressing communication between threads that share a mutex. Based upon programmer specified conditions. Includes functions to create, destroy, wait and signal based upon specified variable values. Also, set/query condition variable attributes.

- 4. Synchronization**

Routines that manage read-write locks and barriers



# Mutexes – Protecting Shared Data

- Mutex (“mutual exclusion”) – primary means of protecting data when write occurs

An example of a race condition

| Thread 1                    | Thread 2                    | Balance |
|-----------------------------|-----------------------------|---------|
| Read balance: \$1000        |                             | \$1000  |
|                             | Read balance: \$1000        | \$1000  |
|                             | Deposit \$200               | \$1000  |
| Deposit \$200               |                             | \$1000  |
| Update balance \$1000+\$200 |                             | \$1200  |
|                             | Update balance \$1000+\$200 | \$1200  |

[Mutex Variables Overview | LLNL HPC Tutorials](#)

- Balance must be protected

# Mutexes – Protecting Shared Data

- Mutex variable acts like a lock on the shared data
  - Only one Pthread can lock (or acquire / own) a mutex at a time. All other threads wanting to lock must wait till the thread owning the lock unlocks (or releases)
  - What happens when the thread owning the mutex tries to lock the mutex again?
    - Normal – thread deadlocks
    - Recursive – increment a count on the number of times locked, unlock when count reaches zero
    - Errorcheck –
      - report error when thread tries to lock a mutex it has already locked
      - Report error when thread tries to unlock a mutex that some other thread has locked

# Pthread Mutex APIs

- Variables are of type `pthread_mutex_t`
- Initialized as:
  - `pthread_mutex_t mymutex = PTHREAD_MUTEX_INITIALIZER;`
  - `pthread_mutex_init(&mymutex, attr)`
  - Mutex is unlocked initially
- `pthread_mutex_init(&mutex, attr)`
- `pthread_mutex_destroy(&mutex)`
- `pthread_mutexattr_init(&attr)`
- `pthread_mutexattr_destroy(&attr)`
- `pthread_mutex_lock(&mutex)`
- `pthread_mutexattr_unlock(&mutex)`
- `pthread_mutexattr_trylock(&mutex)`

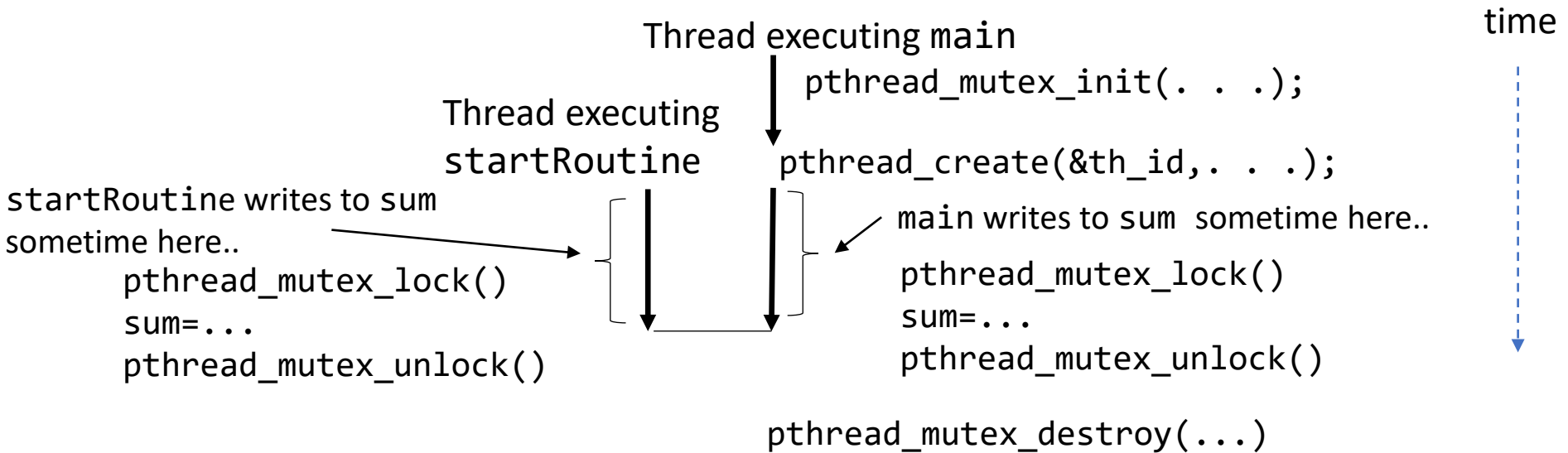
*Exercise: When more than one thread is waiting for a locked mutex, which thread will be granted the lock first after the mutex is released?*

# Synchronization: pthread\_mutex\_t

```
pthread_mutex_t mymutex;
int sum;
int main() {
    //some code here... (optional)
    pthread_mutex_init(&mymutex, NULL);
    //some code here... (optional)
    pthread_create(&th_id, &myattr, startRoutine, NULL);
    //some code here that writes to sum (OR at least
    one of startRoutine or main writing to sum)
    pthread_mutex_lock(&mymutex);
    sum=...
    pthread_mutex_unlock(&mymutex);
    //some code here (optional)
    pthread_mutex_destroy(&mymutex);
}

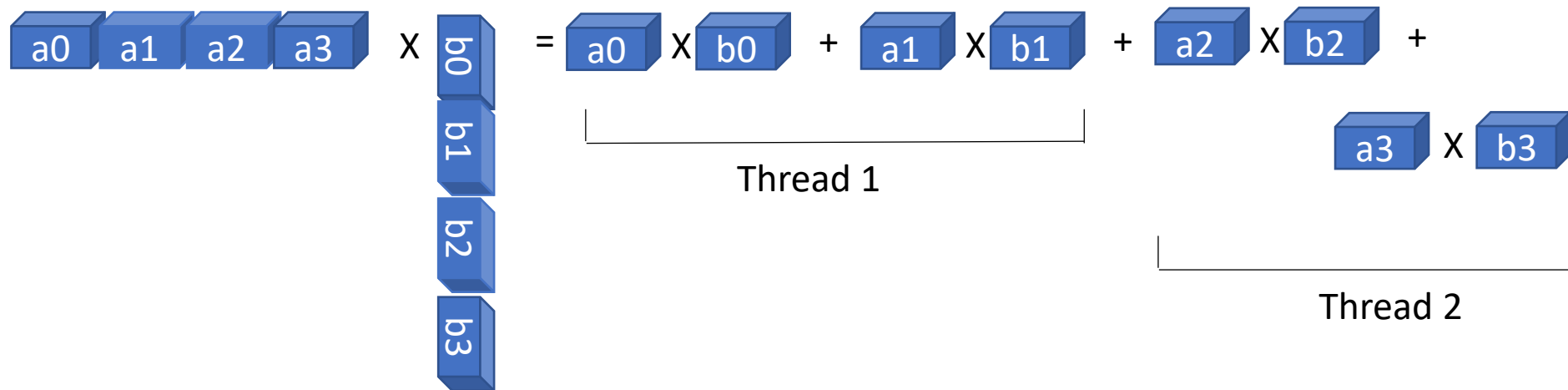
int startRoutine() {
    ...
    pthread_mutex_lock(&mymutex);
    sum=...
    pthread_mutex_unlock(&mymutex);
    ...
}
```

# Synchronization: pthread\_mutex\_t



# Mutex - Example

- Compute Dot Product in Parallel



- Partial result is computed by each thread. Value of the dot product is sum of partial results.
- Demo



# Producer-Consumer Using Mutex Locks

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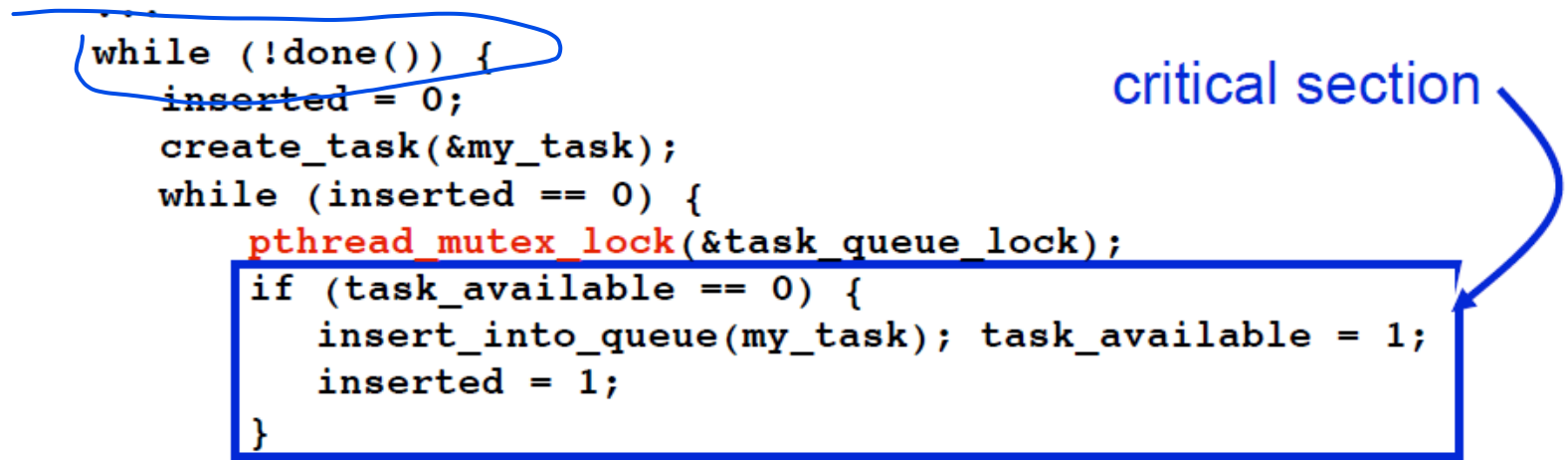
## Constraints

- **Producer thread**
  - must not overwrite the shared buffer until previous task has picked up by a consumer
- **Consumer thread**
  - must not pick up a task until one is available in the queue
  - must pick up tasks one at a time

# Producer-Consumer Using Mutex Locks

```
pthread_mutex_t task_queue_lock;
int task_available;
...
main() {
    ...
    task_available = 0;
    pthread_mutex_init(&task_queue_lock, NULL);
    ...
}

void *producer(void *producer_thread_data) {
    ...
    while (!done()) {
        inserted = 0;
        create_task(&my_task);
        while (inserted == 0) {
            pthread_mutex_lock(&task_queue_lock);
            if (task_available == 0) {
                insert_into_queue(my_task); task_available = 1;
                inserted = 1;
            }
            pthread_mutex_unlock(&task_queue_lock);
        }
    }
}
```



The diagram illustrates the critical section in the producer code. A blue oval highlights the `while (!done())` loop. A blue rectangle highlights the inner loop body, which contains the mutex lock, the availability check, the insertion, and the mutex unlock. A blue arrow points from the text "critical section" to the blue rectangle.

# Producer-Consumer Using Locks

```
void *consumer(void *consumer_thread_data) {
    int extracted;
    struct task my_task;
    /* local data structure declarations */
    while (!done()) {
        extracted = 0;
        while (extracted == 0) {
            pthread_mutex_lock(&task_queue_lock);
            if (task_available == 1) {
                extract_from_queue(&my_task);
                task_available = 0;
                extracted = 1;
            }
            pthread_mutex_unlock(&task_queue_lock);
        }
        process_task(my_task);
    }
}
```

critical section

