Chapter 4 – Control Flow

1 Introduction

With the instructions we have seen so far, we can only write programs as purely linear sequences of instructions. However most algorithms need to break this purely sequential pattern in order to make choices during execution. For example the programmer might want to do one thing *or* another, depending on some condition. To express such choices, general-purpose programming languages offer various syntax constructs known as **control structures**:

- if-then-else
- for loops
- while loops
- switch-case statements

The goal for today is to understand how control structures are implemented at the assembly level.

2 Branch instructions

Idea To implement control structures, the SCAT processor provides **branch** (aka **jump**) instructions. Instead of incrementing the PC to advance to the next instruction, a *branch* instruction overwrites the PC with a well-chosen value. As a result, the CPU will appear to *jump* to that location and continue executing from there.

Syntax The simplest of these jumps is called "branch always". Its syntax is the mnemonic bra followed by an **offset** e.g. "bra +8" or "bra -12". Its effect is to *add* the offset to the PC, instead of adding 4 like ordinary instructions. For instance, "bra +8" will *skip* the following instruction, and jump to the one after that. Similarly, "bra -12" will rewind execution by three instructions.

Note 1: "bra +0" is effectively an infinite loop that will jump to itself forever. When this happens, our simulator stops executing.

Note 2: in practice, the CPU itself does not know about bra, it is an example of a **pseudo-instruction**. What happens is the assembler translates every bra into an addi with PC as destination register.

Conditional jump instructions are useful to implement choices: the jump is either taken or ignored, depending on some condition on the values of registers. For instance "beq ri, rj, offset" jumps if and only if the values of Ri and Rj are equal. The other possible conditions are listed in the table below.

asm	Name	comp code	Description
beq	Branch if equal	0000	if (rd == rs1) PC += sxt(imm)
bne	Branch if not equal	0001	if (rd != rs1) PC += sxt(imm)
blt	Branch if lower than	0010	if (rd < rs1) PC += sxt(imm)
bge	Branch if greater or equal	0011	if (rd >= rs1) PC += sxt(imm)

In machine code, conditional jumps are encoded as follows:

- bits 31–28 are always 0b0011 to indicate a type 3 instruction.
- bits 27-24 indicate the desired comparison.
- bits 23–20 and 19–16 indicate which registers to compare.
- the remaining 16 bits encode the offset i.e. the desired jump distance, should the jump be taken.

31	28	27 24	23 20	19 16	15 0
0 0	1 1	comp	rd	rs1	imm

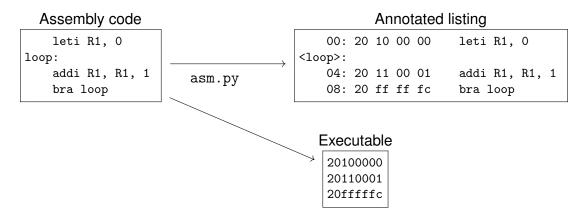
Exercise Choose two numbers *A* and *B* between 0 and 1000. Write a program that uses the leti pseudo-instruction to assign these numbers to R3 and R4 (syntax: leti rd, imm). Then, using conditional and/or mandatory jump(s), set register R5 to the maximum of *A* and *B*. Use bra +0 to halt execution where needed.

Reminder: in the simulator, the step command executes just one instruction.

3 Symbolic labels

As you may have noticed, calculating jump offsets by hand is not practical. Fortunately with most assemblers (ours included) the programmer can freely associate a **label name** to any program location, and use that name as a jump destination. When generating machine code, the assembler keeps track of where each label is located in memory, and computes all offsets accordingly.

The syntax is illustrated below. Observe how both leti and bra pseudo-instructions get translated into addi (opcode 0x20). To help with debugging, the annotated listing shows both label names and numeric addresses.



Exercise Given a positive integer N, its factorial N! is defined as the product of all the positive integers up to N. In other words, $N! = N \times (N-1) \times ... \times 2 \times 1$. For example, $5! = 5 \times 4 \times 3 \times 2 \times 1 = 120$. Write a program that uses a loop to compute the factorial of an integer initially stored in R1. You may find these simulator commands useful:

- step to execute one instruction
- continue to execute the program until it stops by itself
- breakpoint addr_or_label to place a new break point at some location
- help cmd_name to get help on another command

Exercise (bonus) What is the largest value of *N* such that computing *N*! does not overflow?

4 Putting it all together: Euclid's GCD Algorithm

In this part you're going to write a program involving both an if-then-else construct and a while loop. Our excuse is compute the *greatest common divisor* of two integers i.e. to find out the largest integer that divides both numbers. But instead of performing repeated divisions, we will follow Euclid's algorithm. To quote Wikipedia¹:

"The method introduced by Euclid for computing greatest common divisors is based on the fact that, given two positive integers a and b such that a > b, the common divisors of a and b are the same as the common divisors of a - b and b.

So, Euclid's method for computing the greatest common divisor of two positive integers consists of replacing the larger number by the difference of the numbers, and repeating this until the two numbers are equal: that is their greatest common divisor. "

Example Let's unroll the algorithm on a=12 and b=8.

- As stated above, gcd(12, 8) is the same as gcd(12 8, 8) i.e. gcd(4, 8).
- We then repeat this step: gcd(4, 8) is the same as gcd(4, 8 4) i.e. gcd(4, 4).
- In conclusion, we find that gcd(12, 8) = gcd(4, 4) = 4

Exercise (pen & paper) With the same technique, compute gcd(48, 18) and gcd(1071, 462).

¹https://en.wikipedia.org/wiki/Greatest_common_divisor. Go look it up!

Exercise (assembly) Write a program to compute gcd(a, b) for any values of a and b. Your code will start by initializing two registers, as illustrated below:

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leti R1, 48 ; argument a leti R2, 12 ; argument b ...
```

Don't hesitate to reuse some of the code you wrote for the previous exercises (maximum, factorial).