

# Map Generation Using Binary Space Partitioning

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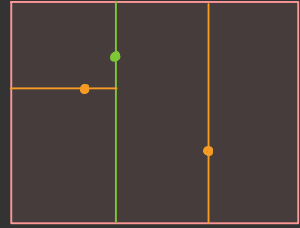
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### Core Algorithm :

- Choose a random direction  
(eg vertical or horizontal)
- Choose a random position in 2D space
- Split the space into two sections



### Detailed Algorithm :

- 1) A 2D space of some  $w$  width and  $h$  height. Add to the queue
- 2) Get a section from the queue
- 3) Ensure section contains more than enough space for two rooms. If not, then continue
- 4) Choose a random direction  
(eg vertical or horizontal)
- 5) Choose a random position in 2D space.
- 6) Split the space into two sections.  
Ensure both sections can fit a room  
Repeat Steps 5-6 until a room fits
- 7) Repeat Steps 2-6 until the queue is empty, or if we have  $n$  sections
- 8) All sections contains a room.

Pros :

- Obtains a list of sections that contains a room
- Rooms will be evenly spaced out.  
Meaning they won't be too close nor too far.
- No overlapping rooms
- Can easily manage the number of sections created, unlike QuadTree

Each division creates one more section

Cons :

- A complex algorithm to implement