4/22/23, 3:30 PM CE784_ES_CNN.ipynb - Colaboratory

Driver drowsiness detection using CNN with resnet architecture

Importing drive

from google.colab import drive drive.mount('/content/drive')

Mounted at /content/drive

Importing libraries

import tensorflow as tf from tensorflow import keras from tensorflow.keras import layers from google.colab import drive import numpy as np import pandas as pd import matplotlib.pyplot as plt from keras.preprocessing.image import ImageDataGenerator as data_augment

Defining training and validation dataset

!unzip -uq "/content/drive/MyDrive/Driver_Drowsiness.zip"

drive 'Driver Drowsiness Dataset (DDD)' sample_data

image_size = (180, 180) batch_size = 64 train_data = tf.keras.preprocessing.image_dataset_from_directory("Driver Drowsiness Dataset (DDD)",

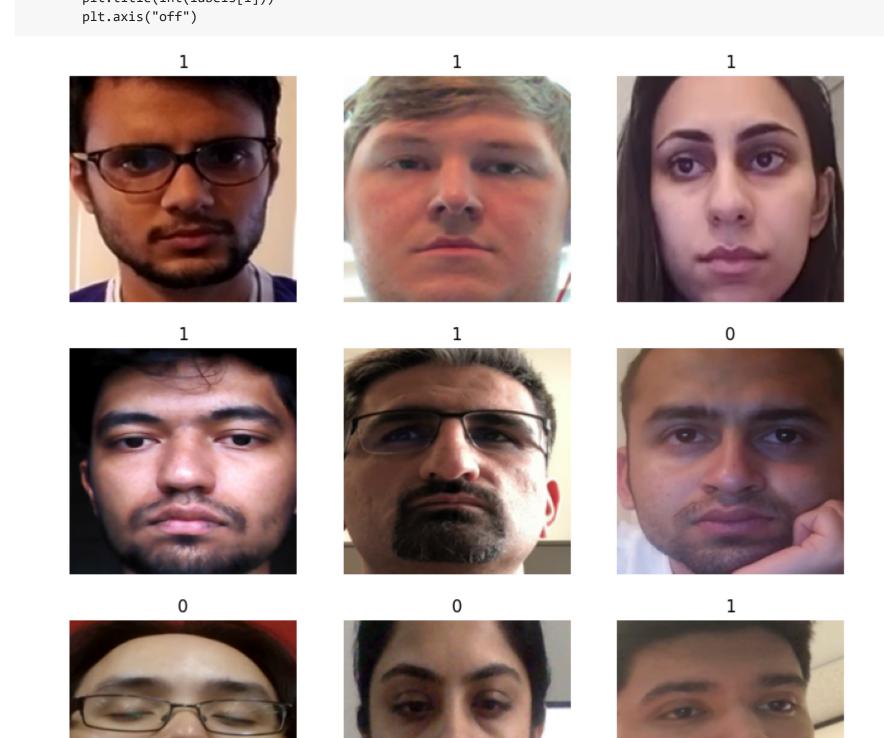
validation_split=0.2, subset="training", seed=1337, image_size=image_size, batch_size=batch_size, val_data = tf.keras.preprocessing.image_dataset_from_directory(

validation_split=0.2, subset="validation", seed=1337, image_size=image_size, batch_size=batch_size,

Found 41788 files belonging to 2 classes. Using 33431 files for training. Found 41788 files belonging to 2 classes. Using 8357 files for validation.

"Driver Drowsiness Dataset (DDD)",

plt.figure(figsize=(10, 10)) for images, labels in train_data.take(1): for i in range(9): ax = plt.subplot(3, 3, i + 1)plt.imshow(images[i].numpy().astype("uint8")) plt.title(int(labels[i]))

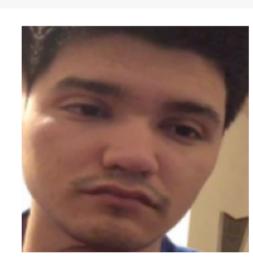


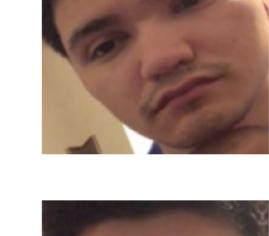
Data augmentation

data_augmentation = keras.Sequential(layers.experimental.preprocessing.RandomFlip("horizontal"), layers.experimental.preprocessing.RandomRotation(0.1),

plt.figure(figsize=(10, 10)) for images, _ in train_data.take(1): for i in range(9): augmented_images = data_augmentation(images) ax = plt.subplot(3, 3, i + 1)plt.imshow(augmented_images[0].numpy().astype("uint8"))

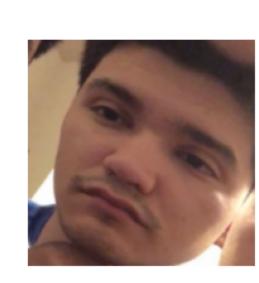












train_data = train_data.prefetch(buffer_size=64) val_data = val_data.prefetch(buffer_size=64)

Creating the model using Resnet architecture

base_model = keras.applications.ResNet152V2(weights="imagenet",input_shape=(180, 180, 3), include_top=False,)

base_model.trainable = True inputs = keras.Input(shape=(180, 180, 3)) x = data_augmentation(inputs)

mean = np.array([127.5] * 3)var = mean ** 2

norm_layer = keras.layers.experimental.preprocessing.Normalization(mean=mean, variance=var) $x = norm_layer(x)$

x = base_model(x, training=False) x = keras.layers.GlobalAveragePooling2D()(x) x = keras.layers.Dropout(0.5)(x)

outputs = layers.Dense(1, activation='sigmoid')(x) model = keras.Model(inputs, outputs)

Downloading data from https://storage.googleapis.com/tensorflow/keras-applications/resnet/resnet152v2_weights_tf_dim_ordering_tf_kernels_notop.h5

Training the model

callbacks = [keras.callbacks.ModelCheckpoint("save_model_DDD.p1"),] model.compile(optimizer=keras.optimizers.Adam(1e-5),loss="binary_crossentropy",metrics=["accuracy"],)

history=model.fit(train_data, epochs=4, callbacks=callbacks, validation_data=val_data,) Epoch 1/4

Epoch 2/4 Epoch 3/4 Epoch 4/4

PLotting epoch vs training accuracy

plt.plot(history.history['accuracy']) plt.title('Model accuracy') https://colab.research.google.com/drive/1KjlJlhM9Z2sw4fAHHfjmGlQTwFDgMWyp?authuser=1#scrollTo=eBu5prNW-JSN&printMode=true 4/22/23, 3:30 PM

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plt.ylabel('Accuracy')

plt.xlabel('epoch')

plt.legend(['train'],loc='upper right')
plt.show()

Model accuracy

1.000 - train

0.995 - 0.990 - 0.985 - 0.980 - 0.975 - 0.970 - 0.9

1.0

0.5

1.5

epoch

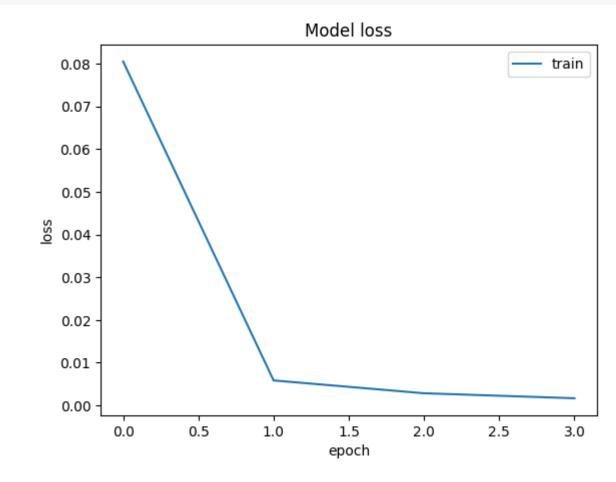
2.0 2.5 3.0

PLotting epoch vs training loss

0.965

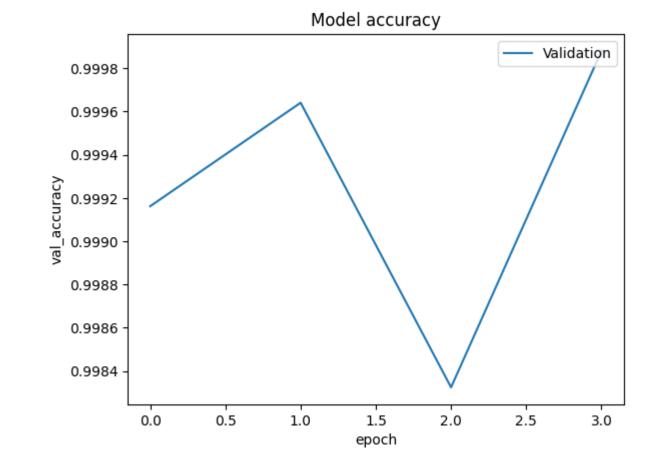
plt.plot(history.history['loss'])
plt.title('Model loss')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train'],loc='upper right')
plt.show()

0.0



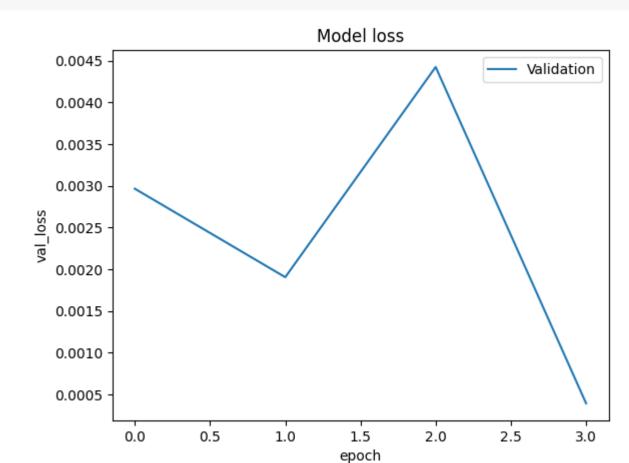
PLotting epoch vs tvalidation accuracy

plt.plot(history.history['val_accuracy'])
plt.title('Model accuracy')
plt.ylabel('val_accuracy')
plt.xlabel('epoch')
plt.legend(['Validation'],loc='upper right')
plt.show()



PLotting epoch vs validation loss

plt.plot(history.history['val_loss'])
plt.title('Model loss')
plt.ylabel('val_loss')
plt.xlabel('epoch')
plt.legend(['Validation'],loc='upper right')
plt.show()



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