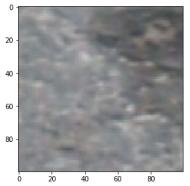
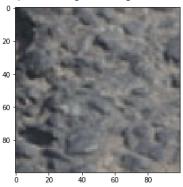
```
from google.colab import drive
drive.mount('/content/drive')
     Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/content/drive", force remount=True).
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
import skimage
from skimage.io import imshow, imread
%matplotlib inline
import matplotlib.pyplot as plt
import os
import glob
from skimage import io, color
from skimage.feature.texture import greycomatrix, greycoprops
import numpy as np
import pandas as pd
from scipy.stats import kurtosis
from scipy.stats import skew
from scipy.stats import entropy
import cv2
import pandas as pd
import numpy as np
from sklearn.model_selection import train_test_split
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers, callbacks
import PIL
import skimage
get_ipython().run_line_magic('matplotlib', 'inline')
import os, sys
from IPython.display import display
from IPython.display import Image as _Imgdis
from PIL import Image
import numpy as np
from time import time
from time import sleep
train_path='/content/drive/MyDrive/mod_ravelling_dataset/train'
Non_raveling_img_path='/content/drive/MyDrive/mod_ravelling_dataset/train/Non_raveling/image1.jpg'
Reveling_img_path='/content/drive/MyDrive/mod_ravelling_dataset/train/Raveling/image100.jpg'
categories=['Non_raveling','Raveling']
from skimage import io, color
image = io.imread(Non_raveling_img_path)
imshow(image)
```

## <matplotlib.image.AxesImage at 0x7f025af38160>

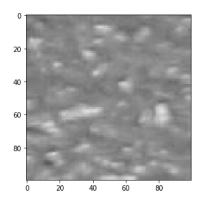


```
image = io.imread(Reveling_img_path)
imshow(image)
```

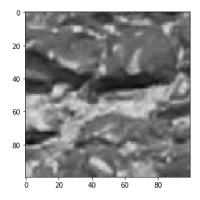
<matplotlib.image.AxesImage at 0x7f025826cd60>



import os
NonRaveling\_directory = '/content/drive/MyDrive/raveling-detection-ce784a-2023/mod\_ravelling\_dataset/train/Non\_raveling'
for filename in os.listdir(NonRaveling\_directory):
 if filename.endswith(".jpg") or filename.endswith(".png"):
 filepath = os.path.join(NonRaveling\_directory, filename)
 image = io.imread(filepath)
 io.imshow(image)



import os
Raveling\_directory = '/content/drive/MyDrive/raveling-detection-ce784a-2023/mod\_ravelling\_dataset/train/Raveling'
for filename in os.listdir(Raveling\_directory):
 if filename.endswith(".jpg") or filename.endswith(".png"):
 filepath = os.path.join(Raveling\_directory, filename)
 image = io.imread(filepath)
 io.imshow(image)



```
#convert images to grayscale
# from PIL import Image
# import os
# def convert_to_grayscale(path1):
# for filename in os.listdir(path1):
```

```
with Image.open(f"{path1}/{filename}") as im:
              im = im.convert("L")
#
              im.save(f"{path1}/{filename}")
#
# convert_to_grayscale("/content/drive/MyDrive/raveling-detection-ce784a-2023/mod_ravelling_dataset/train/Non_raveling")
#convert images to grayscale
# def convert to grayscale(path2):
#
      for filename in os.listdir(path2):
          with Image.open(f"{path2}/{filename}") as im:
#
              im = im.convert("L")
              im.save(f"{path2}/{filename}")
# convert to grayscale("/content/drive/MyDrive/raveling-detection-ce784a-2023/mod ravelling dataset/train/Raveling")
features = {}
features['redMean'] = []
features['blueMean'] = []
features['greenMean'] = []
features['redStd'] = []
features['blueStd'] = []
features['greenStd'] = []
features['redSkew'] = []
features['blueSkew'] = []
features['greenSkew'] = []
features['redKurt'] = []
features['blueKurt'] = []
features['greenKurt'] = []
features['Entropy0'] = []
# features['Entropy1'] = []
# features['Entropy2'] = []
# features['Entropy3'] = []
# features['Entropy4'] = []
# features['Entropy5'] = []
# features['Entropy6'] = []
# features['Entropy7'] = []
# features['blueEntropy'] = []
# features['greenEntropy'] = []
features['Classes'] = []
for i in range(len(categories)):
 path = os.path.join(train_path,categories[i],'*')
 path = glob.glob(path)
  for p in path:
    features['Classes'].append(i)
    image = io.imread(p)
   img_gs = cv2.imread(p,cv2.IMREAD_GRAYSCALE)
    img_gs = skimage.feature.greycomatrix(img_gs, [1], [np.pi/2])
    features['Entropy0'].append(skimage.measure.shannon_entropy(np.reshape(img_gs,(256,256))))
    imgR = image[:,:,0]
    features['redMean'].append(np.mean(imgR))
    features['redStd'].append(np.std(imgR))
    features['redSkew'].append(np.mean(skew(imgR)))
    features['redKurt'].append(np.mean(kurtosis(imgR)))
    imgB = image[:,:,1]
    features['blueMean'].append(np.mean(imgB))
    features['blueStd'].append(np.std(imgB))
    features['blueSkew'].append(np.mean(skew(imgB)))
    features['blueKurt'].append(np.mean(kurtosis(imgB)))
    imgG = image[:,:,2]
    features['greenMean'].append(np.mean(imgG))
    features['greenStd'].append(np.std(imgG))
```

```
features['greenSkew'].append(np.mean(skew(imgG)))
  features['greenKurt'].append(np.mean(kurtosis(imgG)))

train_dataFrame = pd.DataFrame.from_dict(features)

train_dataFrame.head()
```

redStd redMean blueMean greenMean blueStd greenStd redSkew blueSkew greenSkew redKurt 96.6887 99 7035 104.2558 12.577575 11.161585 10.243074 1.435075 1 372324 1.197007 3.328718 1 131.9528 132.7625 133.1749 30.126762 30.161474 30.040721 0.769982 0.778120 0.770225 0.715707 **2** 127.2294 132.1558 136.5937 23.110586 20.868625 19.783271 0.223935 0.179741 0.066978 0.025122 **3** 126.4984 126.8334 126.2913 23.424577 21.329089 19.565184 0.548684 0.595919 0.641238 0.242112 **4** 123.5977 124.9423 125.9379 18.149156 18.759424 18.432288 0.456985 0.470760 0.490505 1.518233



```
X_train = train_dataFrame.drop('Classes', axis=1)
y_train = train_dataFrame.Classes
input_shape = [X_train.shape[1]]
model = keras.models.Sequential()
model.add(tf.keras.layers.BatchNormalization(input_shape = input_shape))
model.add(tf.keras.layers.Dense(128,activation = 'relu'))
model.add(tf.keras.layers.Dropout(0.3))
model.add(tf.keras.layers.BatchNormalization())
model.add(tf.keras.layers.Dense(64,activation = 'relu'))
model.add(tf.keras.layers.Dropout(0.3))
model.add(tf.keras.layers.BatchNormalization())
model.add(tf.keras.layers.Dense(32,activation = 'relu'))
model.add(tf.keras.layers.Dropout(0.3))
model.add(tf.keras.layers.BatchNormalization())
model.add(tf.keras.layers.Dense(16,activation = 'relu'))
model.add(tf.keras.layers.Dropout(0.2))
model.add(tf.keras.layers.BatchNormalization())
model.add(tf.keras.layers.Dense(8,activation = 'relu'))
model.add(tf.keras.layers.Dropout(0.1))
model.add(tf.keras.layers.BatchNormalization())
model.add(tf.keras.layers.Dense(1,activation = 'sigmoid'))
model.compile(optimizer=tf.keras.optimizers.Adam(),loss="binary_crossentropy",metrics=['accuracy'])
model.fit(X_train,y_train,batch_size = 20,epochs = 1000)
```

```
Epoch 537/1000
    35/35 [==============] - 0s 6ms/step - loss: 0.2700 - accuracy: 0.8857
   Epoch 538/1000
    35/35 [=============== ] - 0s 6ms/step - loss: 0.2192 - accuracy: 0.9071
    Epoch 539/1000
   Epoch 540/1000
    35/35 [============== ] - 0s 6ms/step - loss: 0.2111 - accuracy: 0.9214
   Epoch 541/1000
    35/35 [============= ] - 0s 4ms/step - loss: 0.2516 - accuracy: 0.8971
    Epoch 542/1000
    35/35 [============== ] - 0s 4ms/step - loss: 0.2282 - accuracy: 0.9057
    Epoch 543/1000
    35/35 [============= ] - 0s 4ms/step - loss: 0.2175 - accuracy: 0.9129
    Epoch 544/1000
    35/35 [============= ] - 0s 4ms/step - loss: 0.2132 - accuracy: 0.9157
   Epoch 545/1000
   35/35 [============ ] - 0s 4ms/step - loss: 0.2301 - accuracy: 0.9200
    Epoch 546/1000
    35/35 [============= ] - 0s 4ms/step - loss: 0.2794 - accuracy: 0.8986
    Epoch 547/1000
    35/35 [============== ] - 0s 4ms/step - loss: 0.2396 - accuracy: 0.9029
   Epoch 548/1000
    Epoch 549/1000
   35/35 [========== ] - 0s 4ms/step - loss: 0.2685 - accuracy: 0.8943
    Epoch 550/1000
    Epoch 551/1000
    35/35 [============= ] - 0s 4ms/step - loss: 0.2073 - accuracy: 0.9157
   Epoch 552/1000
    35/35 [============= ] - 0s 4ms/step - loss: 0.2225 - accuracy: 0.9143
    Epoch 553/1000
   Epoch 554/1000
    35/35 [============ ] - 0s 4ms/step - loss: 0.2083 - accuracy: 0.9214
   Epoch 555/1000
    35/35 [============== ] - 0s 4ms/step - loss: 0.2763 - accuracy: 0.8814
   Epoch 556/1000
   test_path = '/content/drive/MyDrive/mod_ravelling_dataset/test'
featuresTest = {}
featuresTest['redMean'] = []
featuresTest['blueMean'] = []
featuresTest['greenMean'] = []
featuresTest['redStd'] = []
featuresTest['blueStd'] = []
featuresTest['greenStd'] = []
featuresTest['redSkew'] = []
featuresTest['blueSkew'] = []
featuresTest['greenSkew'] = []
featuresTest['redKurt'] = []
featuresTest['blueKurt'] = []
featuresTest['greenKurt'] = []
featuresTest['Entropy0'] = []
# featuresTest['Entropy1'] = []
# featuresTest['Entropy2'] = []
# featuresTest['Entropy3'] = []
# features['Entropy2'] = []
# features['Entropy3'] = []
# features['Entropy4'] = []
# features['Entropy5'] = []
# features['Entropy6'] = []
# features['Entropy7'] = []
# featuresTest['blueEntropy'] = []
# featuresTest['greenEntropy'] = []
featuresTest['filename'] = []
for img in (os.listdir(test_path)):
 p = os.path.join(test_path,img)
 #path = glob.glob(path)
```

```
image = io.imread(p)
 img_gs = cv2.imread(p,cv2.IMREAD_GRAYSCALE)
 img_gs = skimage.feature.greycomatrix(img_gs, [1], [np.pi/2])
 featuresTest['Entropy0'].append(skimage.measure.shannon_entropy(np.reshape(img_gs,(256,256))))
 # featuresTest['Entropy1'].append(skimage.measure.shannon_entropy(np.reshape(img_gs,(256,256))))
 # featuresTest['Entropy2'].append(skimage.measure.shannon_entropy(np.reshape(img_gs,(256,256))))
 # featuresTest['Entropy3'].append(skimage.measure.shannon_entropy(np.reshape(img_gs,(256,256))))
 imgR = image[:,:,0]
 featuresTest['redMean'].append(np.mean(imgR))
  featuresTest['redStd'].append(np.std(imgR))
  featuresTest['redSkew'].append(np.mean(skew(imgR)))
 featuresTest['redKurt'].append(np.mean(kurtosis(imgR)))
 imgB = image[:,:,1]
  featuresTest['blueMean'].append(np.mean(imgB))
  featuresTest['blueStd'].append(np.std(imgB))
  featuresTest['blueSkew'].append(np.mean(skew(imgB)))
  featuresTest['blueKurt'].append(np.mean(kurtosis(imgB)))
 imgG = image[:,:,2]
 featuresTest['greenMean'].append(np.mean(imgG))
  featuresTest['greenStd'].append(np.std(imgG))
 featuresTest['greenSkew'].append(np.mean(skew(imgG)))
 featuresTest['greenKurt'].append(np.mean(kurtosis(imgG)))
 featuresTest['filename'].append(img)
test_dataFrame = pd.DataFrame.from_dict(featuresTest)
```

test\_dataFrame.head()

	redMean	blueMean	greenMean	redStd	blueStd	greenStd	redSkew	blueSkew	greenSkew	redKu
0	127.3126	128.2218	127.9632	35.946294	31.602579	27.632822	0.311149	0.198299	-0.055981	-0.4459
1	136.7490	134.8682	130.5521	43.689308	41.688996	39.067212	-0.224221	-0.221600	-0.229627	-0.6538
2	129.2429	126.6656	125.1148	35.356410	34.518206	32.500277	0.349248	0.393751	0.414430	-0.2476
3	106.2044	105.7387	104.1821	27.319788	25.921628	23.716322	0.825809	0.855422	0.816398	0.5150
4	134.2944	131.7906	127.8910	21.932440	20.634669	18.014914	-0.704286	-0.687406	-0.602224	0.1877



		filename	clas	s 🎢			
	0	101.jpg	Ravelin	g			
	1	108.jpg	Ravelin	g			
	2	110.jpg	Non_raveling	g			
	2	444:00	Non maralin	~			
<pre>df_sub.to_csv('Submission', index = False)</pre>							

✓ 0s completed at 9:14 PM