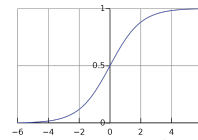
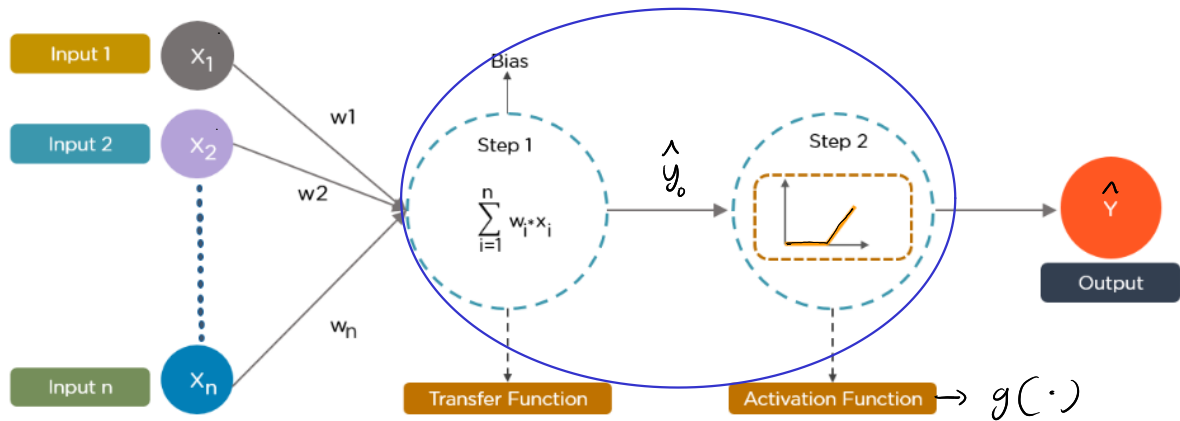


Forward Pass



Tanh
Sigmoid σ
Relu \angle
Leaky Relu
Gelu

2.1 Neuron or perceptron



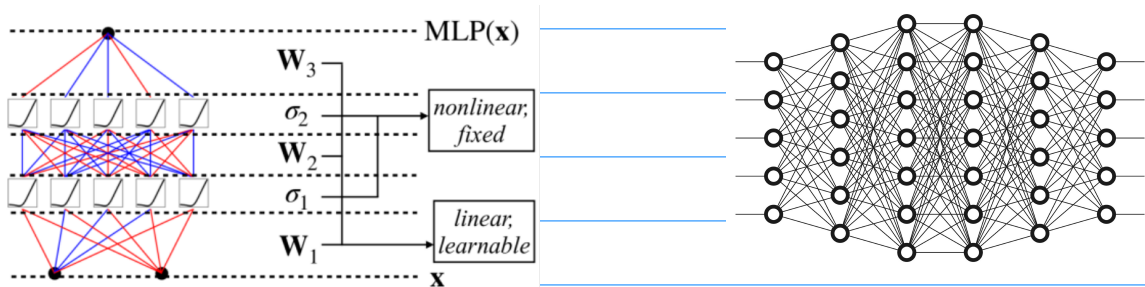
$$\hat{y}_0 = w_1 x_1 + w_2 x_2 + \dots + w_n x_n + b = \sum_{i=1}^n w_i x_i + b$$

$$\hat{y}_0 = w_1 x_1 + b$$

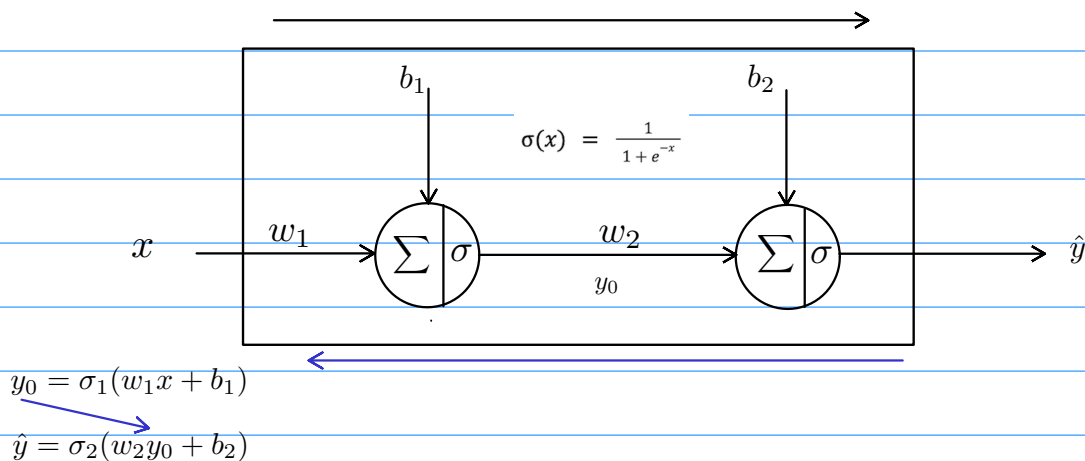
$$y_0 = mx + c$$

$$\hat{y} = g\left(\sum_{i=1}^n w_i x_i + b\right)$$

2.2 Neural Network or Multi Layer Perceptron

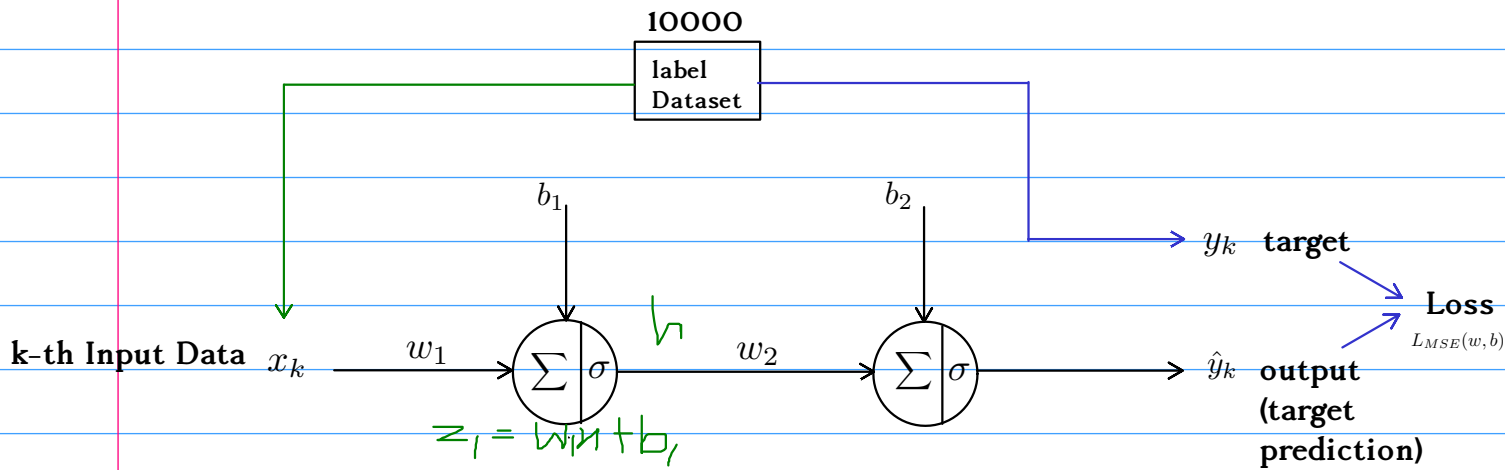


$$MLP(x) = (W_3 \circ \sigma_2 \circ W_2 \circ \sigma_1 \circ W_1)(x)$$



$$\hat{y} = \sigma_2(w_2(\sigma_1(w_1 x + b_1)) + b_2)$$

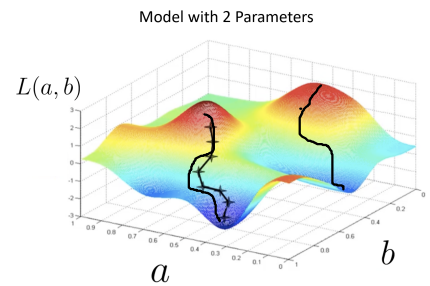
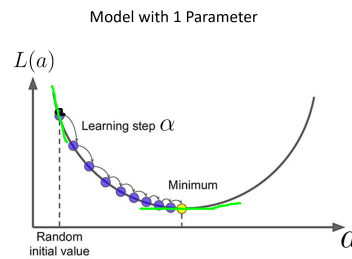
Backward Pass



Mean Squared Error (MSE) Loss

$$\hat{y} = \sigma_2(w_2(\sigma_1(w_1 x + b_1)) + b_2)$$

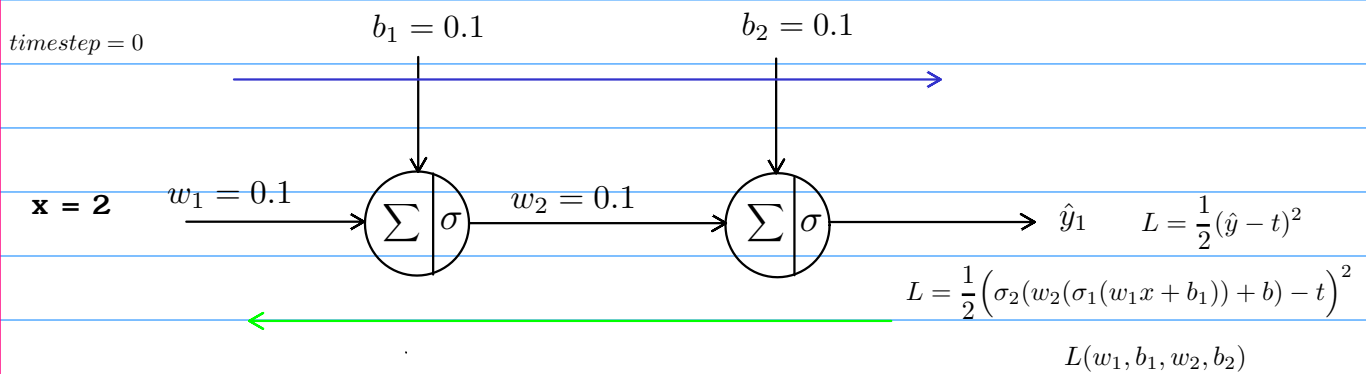
$$L_{MSE}(w, b) = \frac{1}{n} \sum_{i=1}^n (\hat{y}_i - y_i)^2$$



$$w_{t+1} = w_t - \alpha \frac{\partial L}{\partial w_t}$$

$$\alpha = 0.001$$

Backpropagation



$$\frac{\partial L(w_1, b_1, w_2, b_2)}{\partial w_1} = \frac{\partial L}{\partial w_1}$$

$$w_{1,t+1} = w_{1,t} - \alpha \frac{\partial L}{\partial w_1} \quad b_{1,t+1} = b_{1,t} - \alpha \frac{\partial L}{\partial b_1}$$

$$w_{2,t+1} = w_{2,t} - \alpha \frac{\partial L}{\partial w_2} \quad b_{2,t+1} = b_{2,t} - \alpha \frac{\partial L}{\partial b_2}$$

Chain rule

$$\frac{dy}{dx} = \frac{dy}{du} \frac{du}{dx}$$

$$\frac{dy}{dx} \quad \text{derivative of } y \text{ with respect to } x$$

$$\frac{dy}{du} \quad \text{derivative of } y \text{ with respect to } u$$

$$\frac{du}{dx} \quad \text{derivative of } u \text{ with respect to } x$$

$$\frac{\partial L}{\partial w_1} = \frac{\partial L}{\partial h_2} \frac{\partial h_2}{\partial h_1} \frac{\partial h_1}{\partial w_1}$$

$$L = \frac{1}{2}(y - t)^2 = \frac{1}{2}(\sigma_2(w_2(\sigma_1(w_1x + b_1)) + b) - t)^2 = L(w_1, b_1, w_2, b_2)$$

$$\frac{\partial L}{\partial y} = y - t$$

$$\frac{\partial L}{\partial w_2} = \frac{\partial L}{\partial y} \frac{\partial y}{\partial w_2} = \frac{\partial L}{\partial y} \frac{\partial y}{\partial z_2} \frac{\partial z_2}{\partial w_2} = (y - t)y(1 - y)h$$

$$w_{2,t+1} = w_{2,t} - \alpha \frac{\partial L}{\partial w_2}$$

$$\frac{\partial L}{\partial b_2} = \frac{\partial L}{\partial y} \frac{\partial y}{\partial b_2} = \frac{\partial L}{\partial y} \frac{\partial y}{\partial z_2} \frac{\partial z_2}{\partial b_2} = (y - t)y(1 - y)w_2$$

$$b_{2,t+1} = b_{2,t} - \alpha \frac{\partial L}{\partial b_2}$$

$$\frac{\partial L}{\partial w_1} = \frac{\partial L}{\partial h} \frac{\partial h}{\partial w_1} = \frac{\partial L}{\partial h} \frac{\partial h}{\partial z_1} \frac{\partial z_1}{\partial w_1} = (y - t)y(1 - y)w_2h(1 - h)x$$

$$w_{1,t+1} = w_{1,t} - \alpha \frac{\partial L}{\partial w_1}$$

$$\frac{\partial L}{\partial b_1} = \frac{\partial L}{\partial h} \frac{\partial h}{\partial b_1} = \frac{\partial L}{\partial h} \frac{\partial h}{\partial z_1} \frac{\partial z_1}{\partial b_1} = (y - t)y(1 - y)w_2h(1 - h)$$

$$b_{1,t+1} = b_{1,t} - \alpha \frac{\partial L}{\partial b_1}$$

$$\hat{y} = \sigma_2(w_2(\sigma_1(w_1x + b_1)) + b_2)$$

$$y = \sigma(z_2) = \frac{1}{1 + e^{-z_2}}$$

$$z_2 = w_2h + b_2$$

$$h = \sigma(z_1)$$

$$z_1 = w_1x + b_1$$

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

$$\sigma'(x) = \frac{d}{dx} \sigma(x) = \sigma(x)(1 - \sigma(x))$$