

Subroutines

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<next instruction>
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Call and Return using an Address Register

```
caller:
        lea next,a1
        jmp subroutine
next    ...
```

```
callee:

subroutine    ...
              jmp (a1)
```

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subroutine    ...  
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caller:
    lea next,a1
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next    ...
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```
callee:

subroutine    ...
              jmp (a1)
```

- Pros
 - simple, fast
- Cons
 - forces programmer to keep track of return address
 - can't perform nested (or recursive) calls

Call and Return Using a Mailbox

caller:

```
mailbox    ds.1    1
           move.l  #next,mailbox
           jmp     subroutine
next       ...
```

callee:

```
subroutine ...
           movea.l mailbox,a1
           jmp  (a1)
```

- Pros
 - allows for nested calls
- Cons
 - slow compared to register approach
 - can't perform recursive calls
 - Memory space grows with number of functions (not with level of nesting)

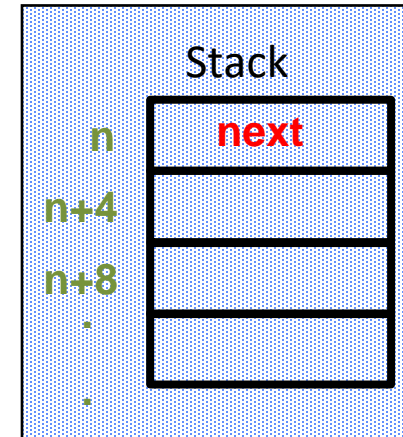
Call and Return Using a Stack

caller:

```
move.l #next, -(SP)
```

```
jmp     subroutine
```

```
next    ...
```



callee:

```
subroutine ...
```

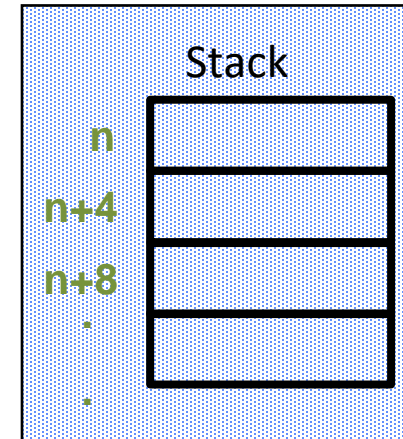
```
movea.l (sp)+, a1
```

```
jmp (a1)
```

Call and Return Using a Stack

caller:

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                move.l #next, -(SP)
                jmp     subroutine
next            ...
```



callee:

```
subroutine      ...
                movea.l (sp)+, a1
                jmp     (a1)
```

- Pros
 - allows nested and recursive calls
 - space grows with level of nesting
- Cons
 - slow compared to register approach

Jump to Subroutine Instruction

JSR Jump to subroutine

Syntax: JSR <ea>

Operation: $SP = SP - 4$
 Memory[SP] = Program Counter
 Program Counter = <ea>

Dn	An	(An)	(An)+	-(An)	d(An)	d(An,Xn)	ABS.W	ABS.L	Imm
		✓			✓	✓	✓	✓	

Branch to Subroutine

BSR Branch to Subroutine

Syntax: BRS <label>
 BRS <literal>

Name	Displacement	Machine Language	Operation Performed
BRS.S	8-bit	61XX	SP \leftarrow SP - 4 Memory[SP] = PC PC \leftarrow PC + displacement
BRS.L	16-bit	6100 XXXX	

Return from Subroutine Instruction

RTS Return from subroutine

Syntax: RTS

Operation: Program Counter = Memory[SP]
 SP = SP + 4

Example

- Write a subroutine to calculate $2X^2$
 - Assumptions
 - Subroutine is to be called SQR
 - X is a 16-bit signed value
 - X is to be passed to the subroutine using D0
 - $2X^2$ is to be returned to the subroutine using D0

Trace

Memory

```
8000      org      $8000
8000      move     #4,d0
8004      jsr      sqr
8008      nop
```

*** subroutine SQR ***

```
800A      sqr      muls     d0,d0
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pc

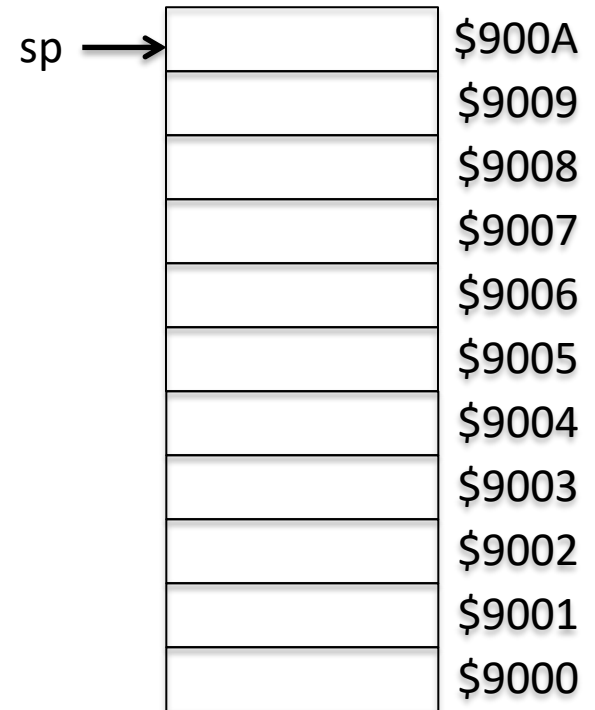
00	00	80	00
----	----	----	----

d0

XX	XX	XX	XX
----	----	----	----

a7

00	00	90	0A
----	----	----	----



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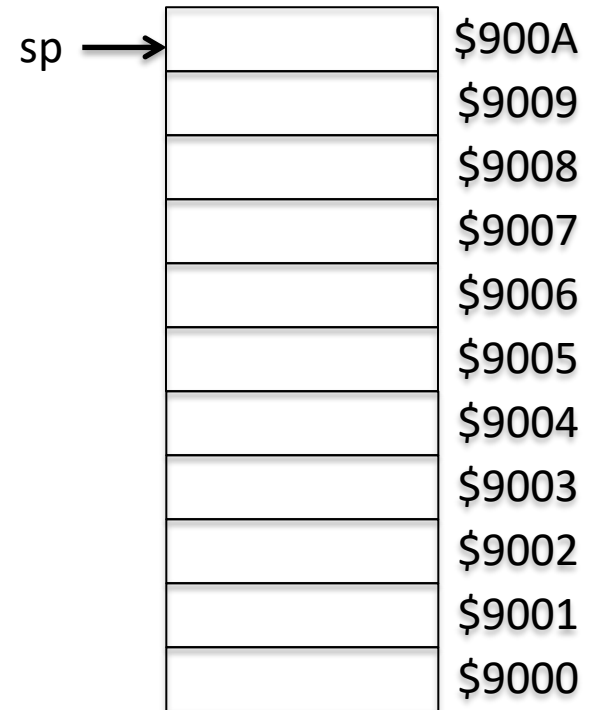
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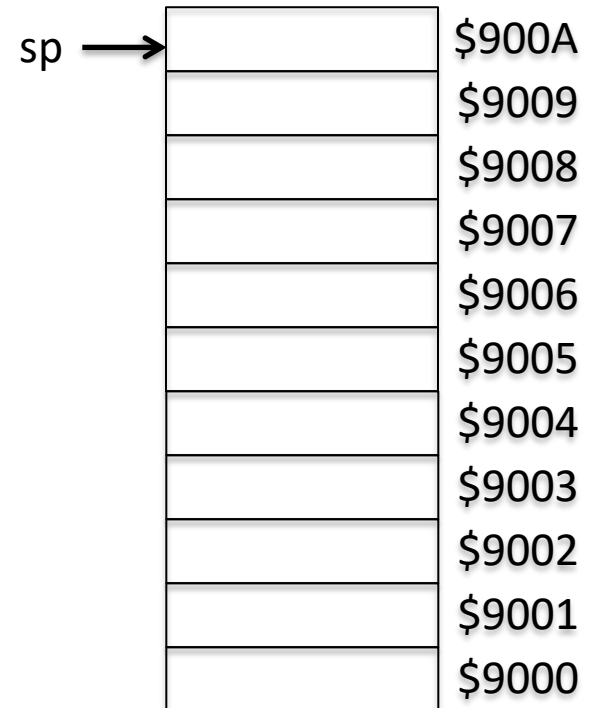
00	00	80	04
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d0

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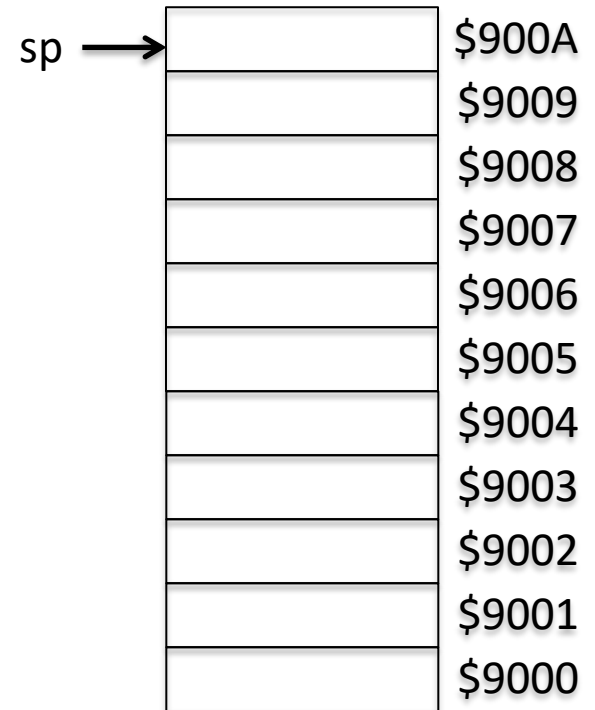
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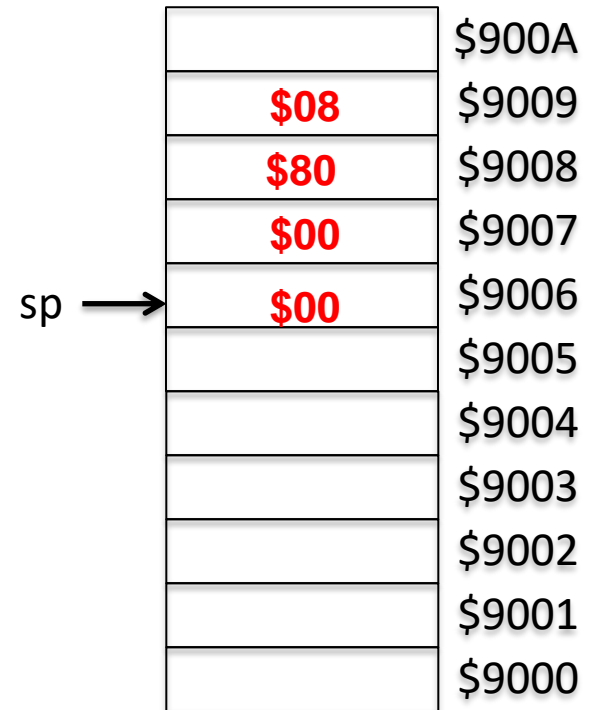
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00	00	90	06
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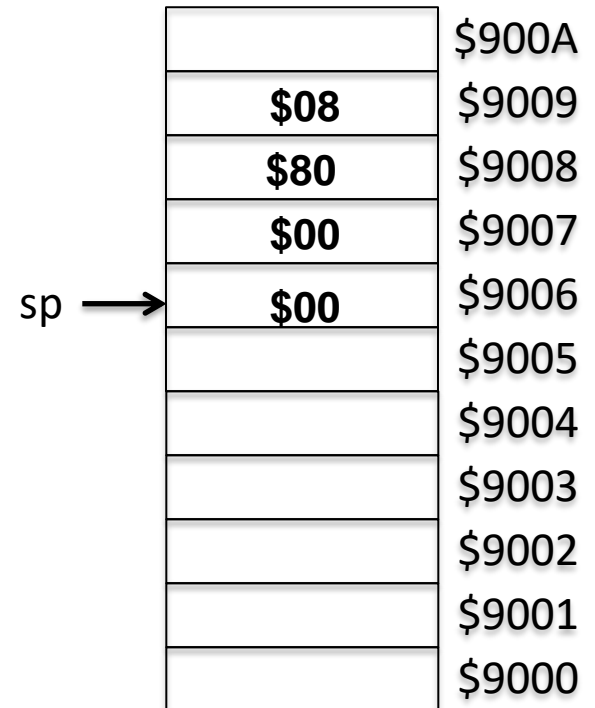
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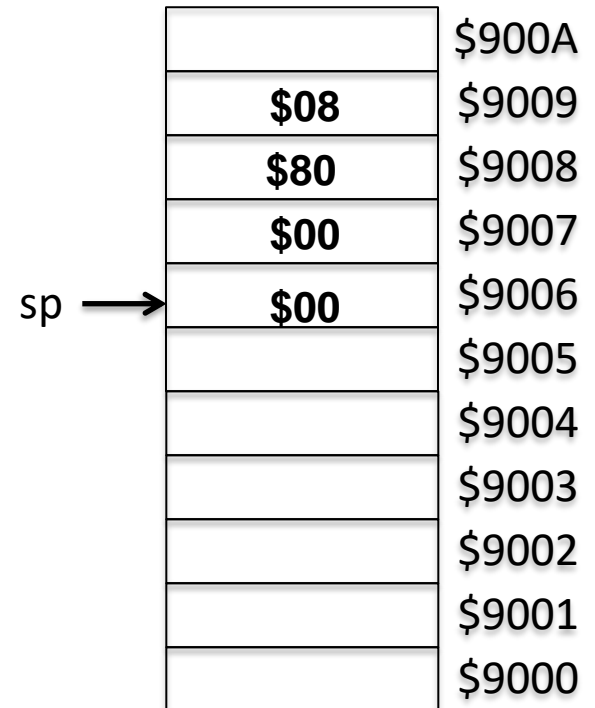
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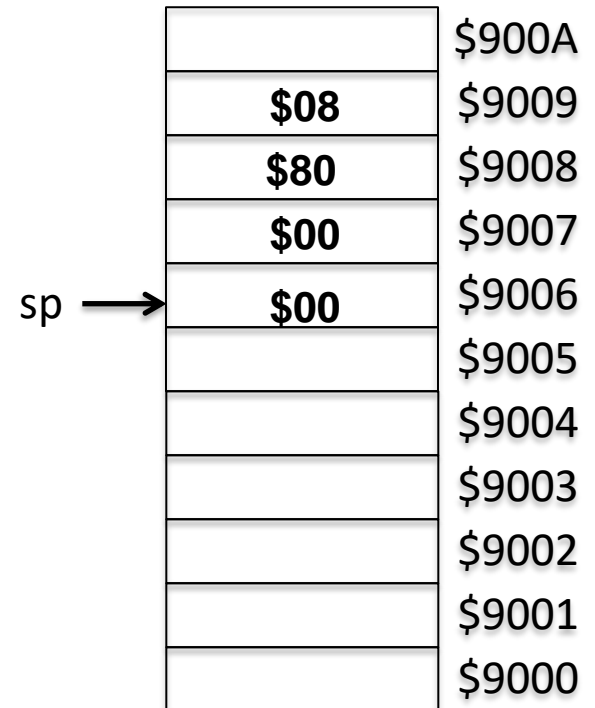
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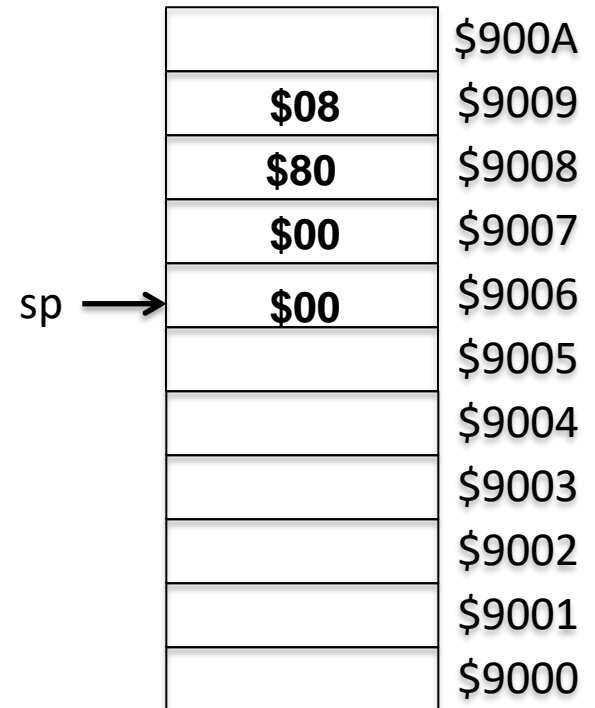
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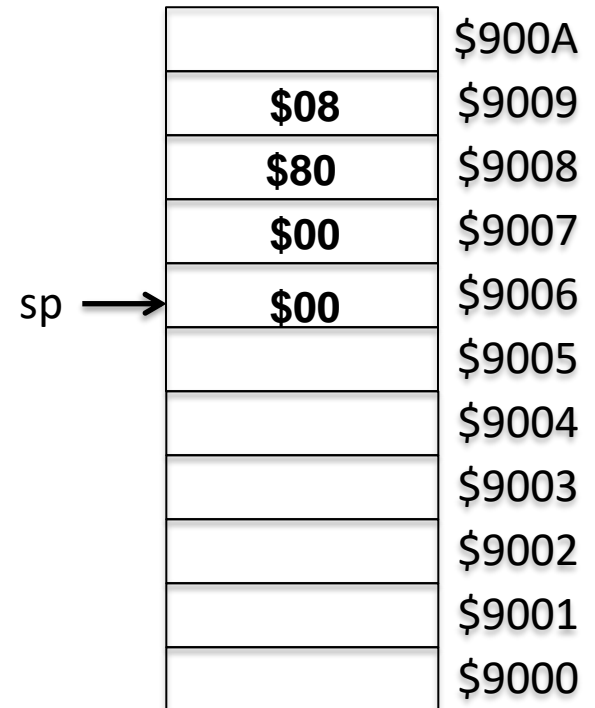
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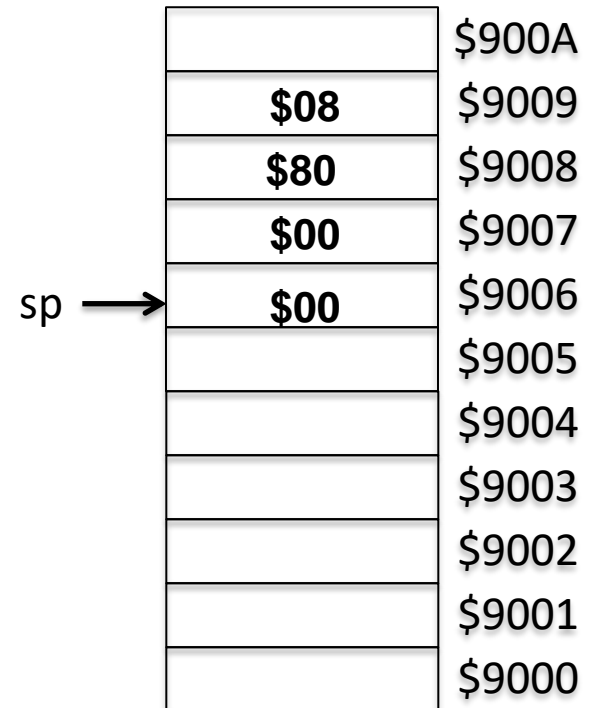
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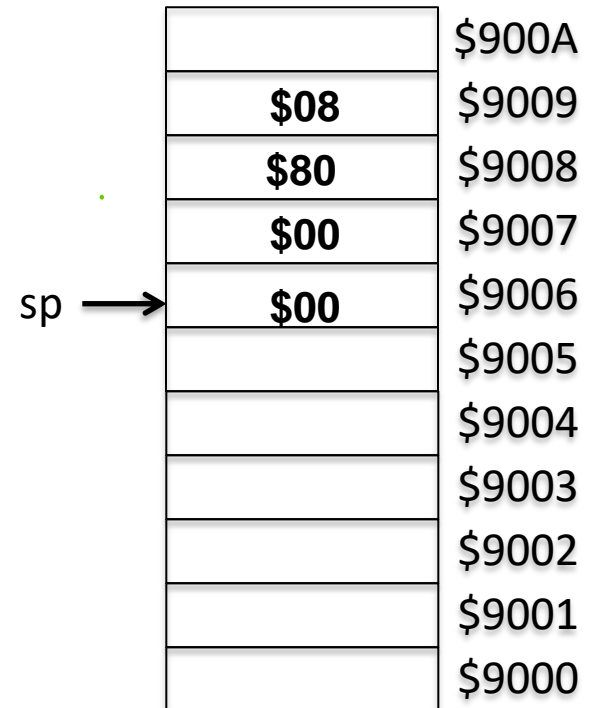
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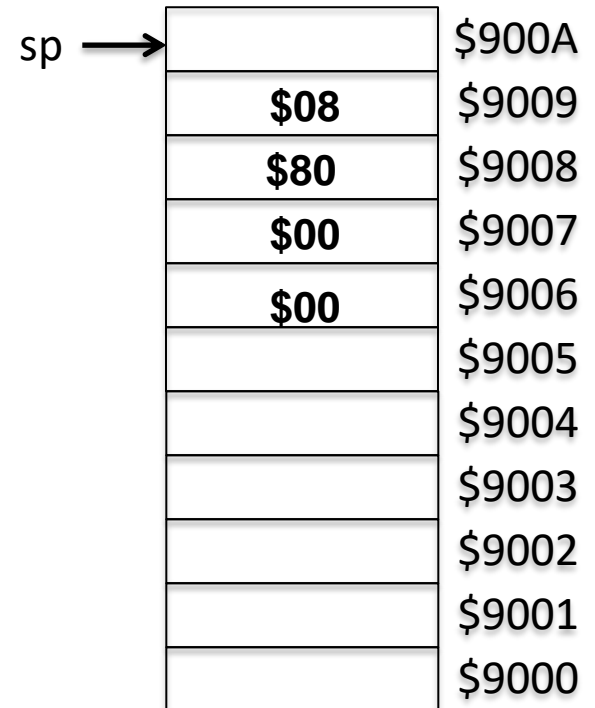
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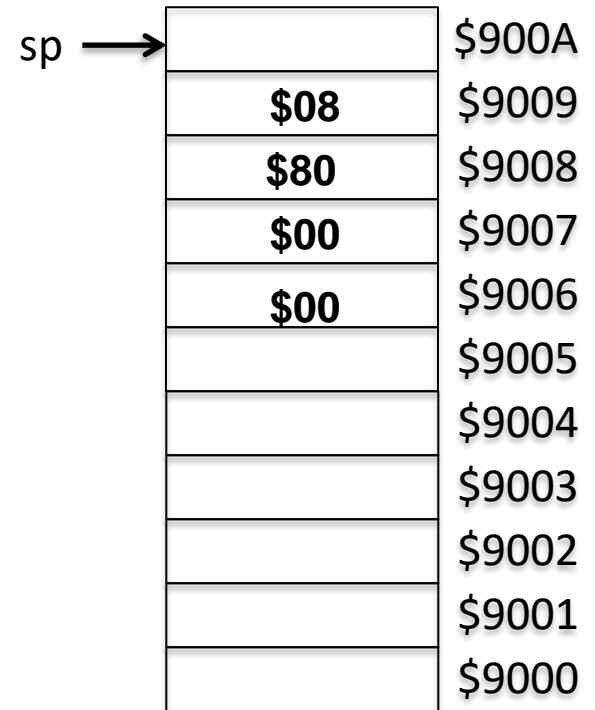
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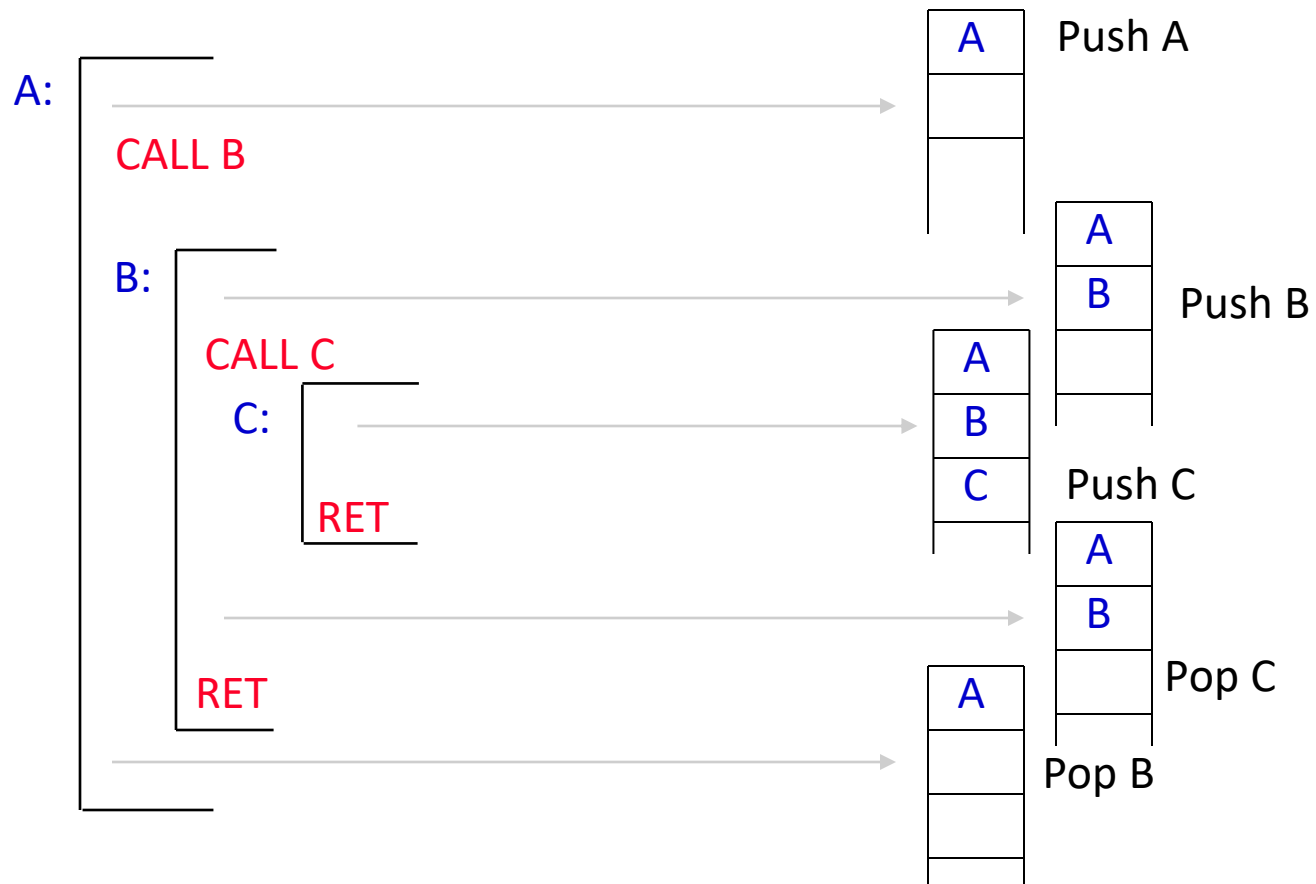
MEMORY

Nested Subroutine (Stack) Calls

- The stack grows downward and shrinks upward to accommodate nested subroutine calls

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Summary

- A subroutine is analogous to a C function
 - a piece of code that can be called **by NAME**
 - can be called from one or more locations in a program whenever its functionality is required
- Stack is preferred way to store return address
 - Allows for nested function calls
 - Allows for recursive function calls
 - Allows amount of memory for return address to grow proportional to number of nested/recursive calls
- JSR and BSR are used to call a subroutine
 - both have the same purpose, to transfer control to the beginning of the called subroutine and to save the return address on the runtime stack
 - Each differ in how they specify the starting address of the subroutine
- RTS are used to return to the calling code
 - Restores the PC from the runtime stack (but must be careful!)