

## 1. Description

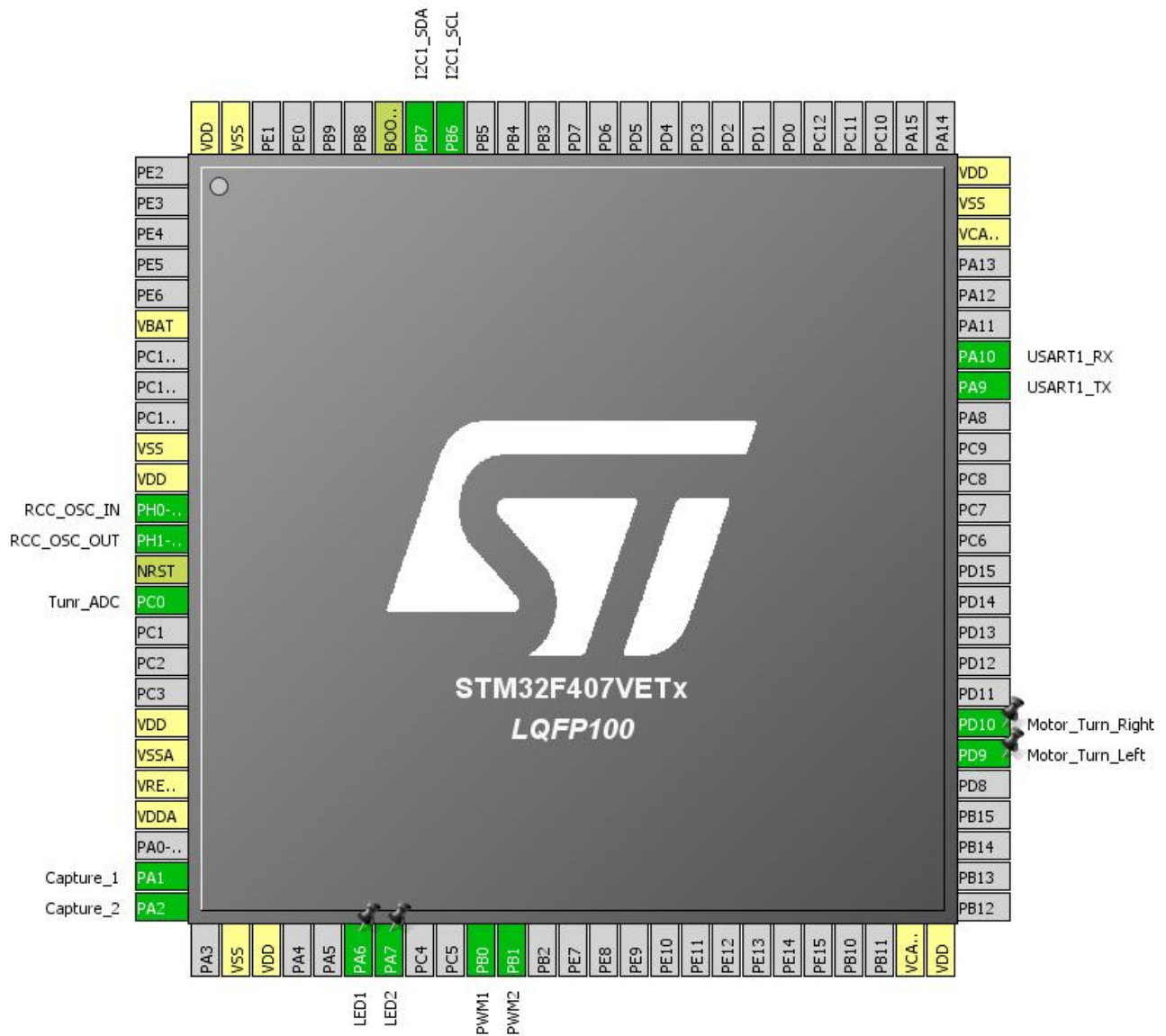
### 1.1. Project

Project Name	Balance_Car_CUBE
Board Name	Balance_Car_CUBE
Generated with:	STM32CubeMX 4.24.0
Date	03/12/2018

### 1.2. MCU

MCU Series	STM32F4
MCU Line	STM32F407/417
MCU name	STM32F407VETx
MCU Package	LQFP100
MCU Pin number	100

## 2. Pinout Configuration

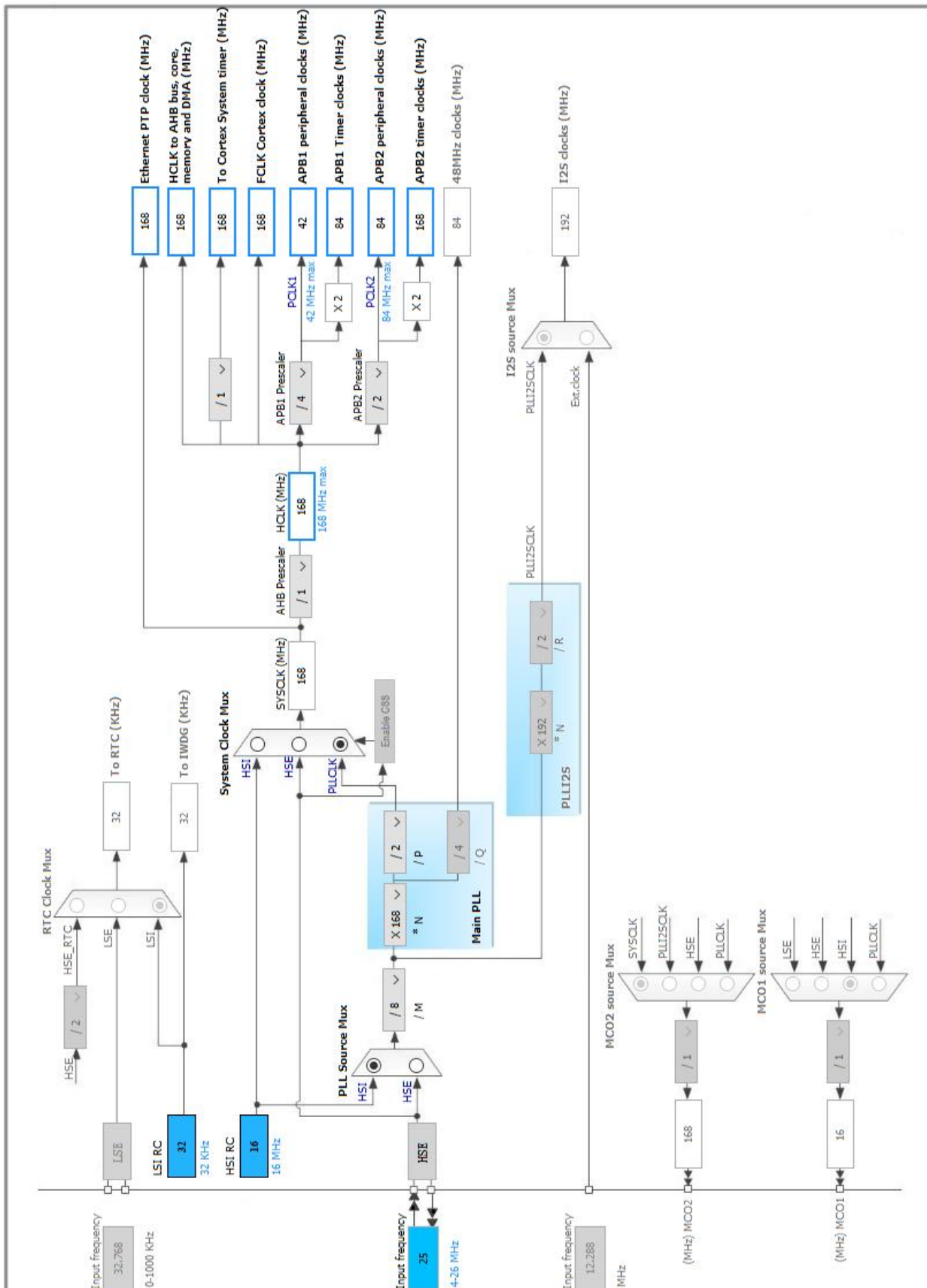


### 3. Pins Configuration

Pin Number LQFP100	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
6	VBAT	Power		
10	VSS	Power		
11	VDD	Power		
12	PH0-OSC_IN	I/O	RCC_OSC_IN	
13	PH1-OSC_OUT	I/O	RCC_OSC_OUT	
14	NRST	Reset		
15	PC0	I/O	ADC2_IN10	Tunr_ADC
19	VDD	Power		
20	VSSA	Power		
21	VREF+	Power		
22	VDDA	Power		
24	PA1	I/O	TIM2_CH2	Capture_1
25	PA2	I/O	TIM5_CH3	Capture_2
27	VSS	Power		
28	VDD	Power		
31	PA6 *	I/O	GPIO_Output	LED1
32	PA7 *	I/O	GPIO_Output	LED2
35	PB0	I/O	TIM3_CH3	PWM1
36	PB1	I/O	TIM3_CH4	PWM2
49	VCAP_1	Power		
50	VDD	Power		
56	PD9 *	I/O	GPIO_Output	Motor_Turn_Left
57	PD10 *	I/O	GPIO_Output	Motor_Turn_Right
68	PA9	I/O	USART1_TX	
69	PA10	I/O	USART1_RX	
73	VCAP_2	Power		
74	VSS	Power		
75	VDD	Power		
92	PB6	I/O	I2C1_SCL	
93	PB7	I/O	I2C1_SDA	
94	BOOT0	Boot		
99	VSS	Power		
100	VDD	Power		

\* The pin is affected with an I/O function

## 4. Clock Tree Configuration



## 5. IPs and Middleware Configuration

### 5.1. ADC1

mode: Temperature Sensor Channel

#### 5.1.1. Parameter Settings:

##### ADCs\_Common\_Settings:

Mode Independent mode

##### ADC\_Settings:

Clock Prescaler PCLK2 divided by 4

Resolution 12 bits (15 ADC Clock cycles)

Data Alignment Right alignment

Scan Conversion Mode Disabled

Continuous Conversion Mode Disabled

Discontinuous Conversion Mode Disabled

DMA Continuous Requests Disabled

End Of Conversion Selection EOC flag at the end of single channel conversion

##### ADC\_Regular\_ConversionMode:

Number Of Conversion 1

External Trigger Conversion Source Regular Conversion launched by software

External Trigger Conversion Edge None

Rank 1

Channel Channel Temperature Sensor

Sampling Time 3 Cycles

##### ADC\_Injected\_ConversionMode:

Number Of Conversions 0

##### WatchDog:

Enable Analog WatchDog Mode false

### 5.2. ADC2

mode: IN10

#### 5.2.1. Parameter Settings:

##### ADCs\_Common\_Settings:

Mode	Independent mode
<b>ADC_Settings:</b>	
Clock Prescaler	PCLK2 divided by 4
Resolution	12 bits (15 ADC Clock cycles)
Data Alignment	Right alignment
Scan Conversion Mode	Disabled
Continuous Conversion Mode	Disabled
Discontinuous Conversion Mode	Disabled
DMA Continuous Requests	Disabled
End Of Conversion Selection	EOC flag at the end of single channel conversion
<b>ADC_Regular_ConversionMode:</b>	
Number Of Conversion	1
External Trigger Conversion Source	Regular Conversion launched by software
External Trigger Conversion Edge	None
Rank	1
Channel	Channel 10
Sampling Time	3 Cycles
<b>ADC_Injected_ConversionMode:</b>	
Number Of Conversions	0
<b>WatchDog:</b>	
Enable Analog WatchDog Mode	false

## 5.3. I2C1

### I2C: I2C

#### 5.3.1. Parameter Settings:

<b>Master Features:</b>	
I2C Speed Mode	Standard Mode
I2C Clock Speed (Hz)	100000
<b>Slave Features:</b>	
Clock No Stretch Mode	Disabled
Primary Address Length selection	7-bit
Dual Address Acknowledged	Disabled
Primary slave address	0
General Call address detection	Disabled

## 5.4. RCC

### High Speed Clock (HSE): Crystal/Ceramic Resonator

#### 5.4.1. Parameter Settings:

##### System Parameters:

VDD voltage (V)	3.3
Instruction Cache	Enabled
Prefetch Buffer	Enabled
Data Cache	Enabled
Flash Latency(WS)	5 WS (6 CPU cycle)

##### RCC Parameters:

HSI Calibration Value	16
HSE Startup Timeout Value (ms)	100
LSE Startup Timeout Value (ms)	5000

##### Power Parameters:

Power Regulator Voltage Scale	Power Regulator Voltage Scale 1
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## 5.5. SYS

### Timebase Source: SysTick

## 5.6. TIM2

### Clock Source : Internal Clock

### Channel2: Input Capture direct mode

#### 5.6.1. Parameter Settings:

##### Counter Settings:

Prescaler (PSC - 16 bits value)	168-1 *
Counter Mode	Up
Counter Period (AutoReload Register - 32 bits value )	0xFFFFFFFF *
Internal Clock Division (CKD)	No Division

##### Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

##### Input Capture Channel 2:

Polarity Selection	Rising Edge
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IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter (4 bits value)	0

## 5.7. TIM3

**Clock Source : Internal Clock**

**Channel3: PWM Generation CH3**

**Channel4: PWM Generation CH4**

### 5.7.1. Parameter Settings:

#### Counter Settings:

Prescaler (PSC - 16 bits value)	<b>168-1 *</b>
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value )	<b>200-1 *</b>
Internal Clock Division (CKD)	No Division

#### Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

#### PWM Generation Channel 3:

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High

#### PWM Generation Channel 4:

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High

## 5.8. TIM5

**mode: Clock Source**

**Channel3: Input Capture direct mode**

### 5.8.1. Parameter Settings:



#### Counter Settings:

Prescaler (PSC - 16 bits value)	168-1 *
Counter Mode	Up
Counter Period (AutoReload Register - 32 bits value )	0xFFFFFFFF *
Internal Clock Division (CKD)	No Division

#### Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

#### Input Capture Channel 3:

Polarity Selection	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter (4 bits value)	0

## 5.9. TIM9

### mode: Clock Source

#### 5.9.1. Parameter Settings:

#### Counter Settings:

Prescaler (PSC - 16 bits value)	16800-1 *
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value )	500-1 *
Internal Clock Division (CKD)	No Division

## 5.10. USART1

### Mode: Asynchronous

#### 5.10.1. Parameter Settings:

#### Basic Parameters:

Baud Rate	115200
Word Length	8 Bits (including Parity)
Parity	None
Stop Bits	1

**Advanced Parameters:**

Data Direction	Receive and Transmit
Over Sampling	16 Samples

\* User modified value

## 6. System Configuration

### 6.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
ADC2	PC0	ADC2_IN10	Analog mode	No pull-up and no pull-down	n/a	Tunr_ADC
I2C1	PB6	I2C1_SCL	Alternate Function Open Drain	Pull-up	<b>Very High</b> *	
	PB7	I2C1_SDA	Alternate Function Open Drain	Pull-up	<b>Very High</b> *	
RCC	PH0-OSC_IN	RCC_OSC_IN	n/a	n/a	n/a	
	PH1-OSC_OUT	RCC_OSC_OUT	n/a	n/a	n/a	
TIM2	PA1	TIM2_CH2	Alternate Function Push Pull	No pull-up and no pull-down	<b>Medium</b> *	Capture_1
TIM3	PB0	TIM3_CH3	Alternate Function Push Pull	<b>Pull-down</b> *	<b>Medium</b> *	PWM1
	PB1	TIM3_CH4	Alternate Function Push Pull	<b>Pull-down</b> *	<b>Medium</b> *	PWM2
TIM5	PA2	TIM5_CH3	Alternate Function Push Pull	No pull-up and no pull-down	<b>Medium</b> *	Capture_2
USART1	PA9	USART1_TX	Alternate Function Push Pull	Pull-up	<b>Very High</b> *	
	PA10	USART1_RX	Alternate Function Push Pull	Pull-up	<b>Very High</b> *	
GPIO	PA6	GPIO_Output	Output Push Pull	<b>Pull-up</b> *	Low	LED1
	PA7	GPIO_Output	Output Push Pull	<b>Pull-up</b> *	Low	LED2
	PD9	GPIO_Output	Output Push Pull	<b>Pull-up</b> *	<b>Medium</b> *	Motor_Turn_Left
	PD10	GPIO_Output	Output Push Pull	<b>Pull-up</b> *	<b>Medium</b> *	Motor_Turn_Right

### 6.2. DMA configuration

nothing configured in DMA service

### 6.3. NVIC configuration

Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Pre-fetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	0	0
System tick timer	true	0	0
TIM1 break interrupt and TIM9 global interrupt	true	1	0
TIM2 global interrupt	true	0	0
TIM5 global interrupt	true	1	0
PVD interrupt through EXTI line 16	unused		
Flash global interrupt	unused		
RCC global interrupt	unused		
ADC1, ADC2 and ADC3 global interrupts	unused		
TIM3 global interrupt	unused		
I2C1 event interrupt	unused		
I2C1 error interrupt	unused		
USART1 global interrupt	unused		
FPU global interrupt	unused		

\* User modified value

## ***7. Power Consumption Calculator report***

### 7.1. Microcontroller Selection

Series	STM32F4
Line	STM32F407/417
MCU	STM32F407VETx
Datasheet	022152_Rev8

### 7.2. Parameter Selection

Temperature	25
Vdd	3.3

## 8. Software Project

### 8.1. Project Settings

Name	Value
Project Name	Balance_Car_CUBE
Project Folder	D:\BalanceCar\TextCode\Balance_Car_CUBE
Toolchain / IDE	MDK-ARM V5
Firmware Package Name and Version	STM32Cube FW_F4 V1.19.0

### 8.2. Code Generation Settings

Name	Value
STM32Cube Firmware Library Package	Copy only the necessary library files
Generate peripheral initialization as a pair of '.c/.h' files	Yes
Backup previously generated files when re-generating	No
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power consumption)	No

## ***9. Software Pack Report***