

Merge Sort

Algorithm

Design paradigms

- **Paradigm**

- “In science and philosophy, a paradigm is a **distinct set of concepts or thought patterns**, including theories, research methods, postulates, and standards for what constitutes legitimate contributions to a field”- Wikipedia

Types of Design Paradigms

- Incremental Approach
- Greedy approach
- Dynamic Programming
- Divide and Conquer

Incremental approach

- Example: Insertion sort
 - In the **so far sorted subarray**, insert a new single element into its proper place, resulting in the new sorted subarray
 - Example:



Key = A [j]

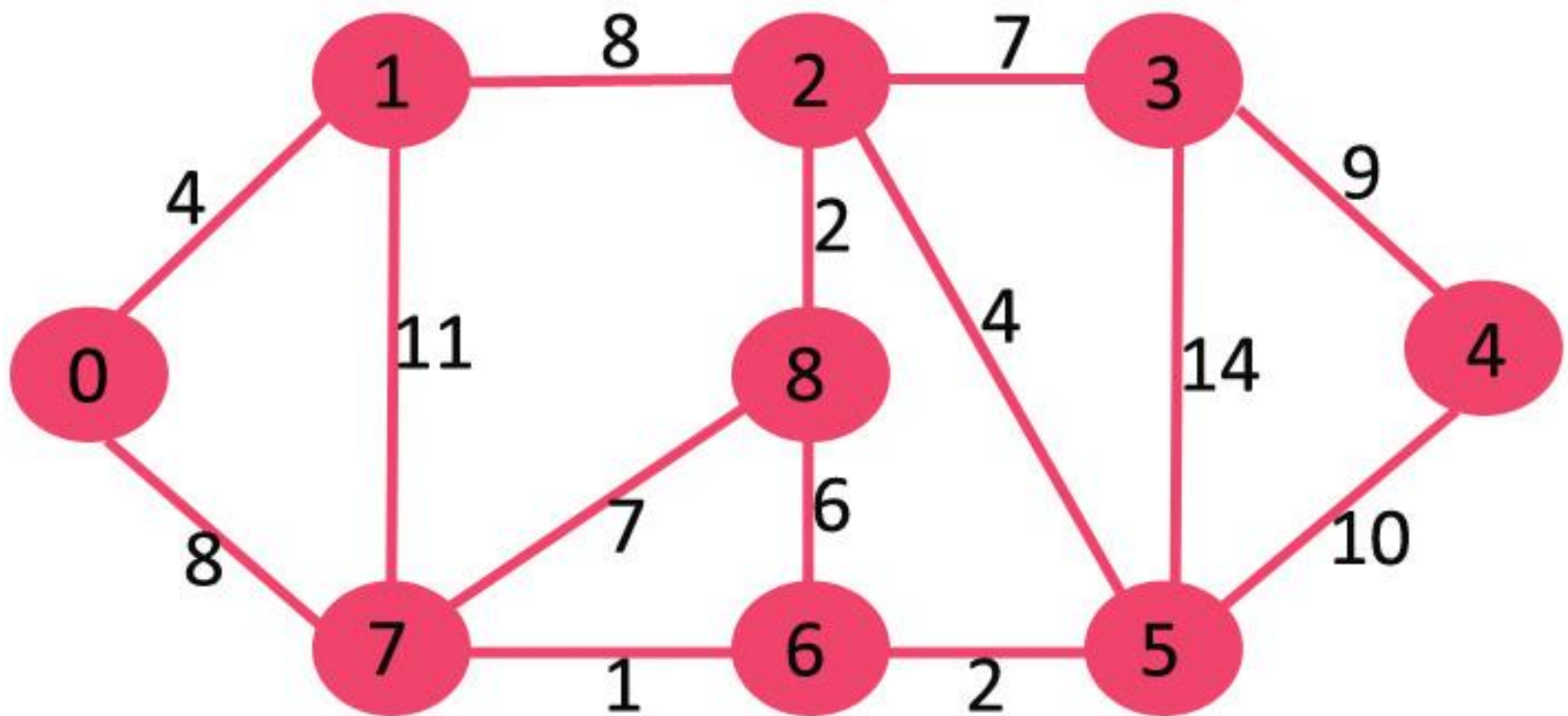
Types of Design Paradigms

- Incremental Approach
- Greedy approach
- Dynamic Programming
- Divide and Conquer

Greedy approach

- *builds up a solution piece by piece*
- *always choosing the next piece that offers the most obvious and immediate benefit*
- *choosing locally optimal also leads to a global solution in general*
- Example: Dijkstra's shortest path algorithm

Dijkstra's shortest path algorithm



Motivation for Divide and Conquer

Our life is frittered away by detail. Simplify, simplify.

— Henry David Thoreau

*The control of a large force is the same principle as the control of a few men:
it is merely a question of dividing up their numbers.*

— Sun Zi, *The Art of War* (c. 400 C.E.), translated by Lionel Giles (1910)

Nothing is particularly hard if you divide it into small jobs.

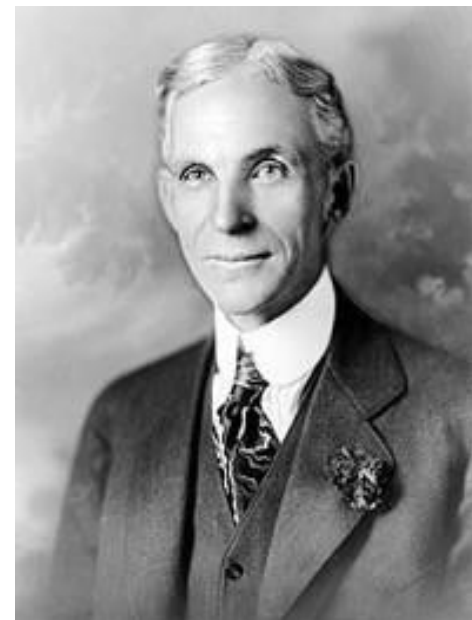
— Henry Ford

Henry Ford (July 30, 1863 - April 7, 1947) was an American captain of industry and a business magnate.

Founder of the Ford Motor company

Sponsor of the development of the *assembly line technique of mass production*.

Breaks the manufacture of a good into steps that are completed in a pre-defined sequence



Henry Ford's Assembly line



Divide and Conquer

- **Three crucial steps**
 - **Divide** the problem into smaller sub problems
 - **Conquer** the smaller subproblems recursively
 - **Combine** solutions of the subproblems to get the solution of the original problem

Divide and conquer - First step

- Divide/Break the problem into smaller sub problems
 - For example, Problem P is divided into subproblems P1 and P2
 - Also, P1 and P2 resemble the original problem and their input size is small

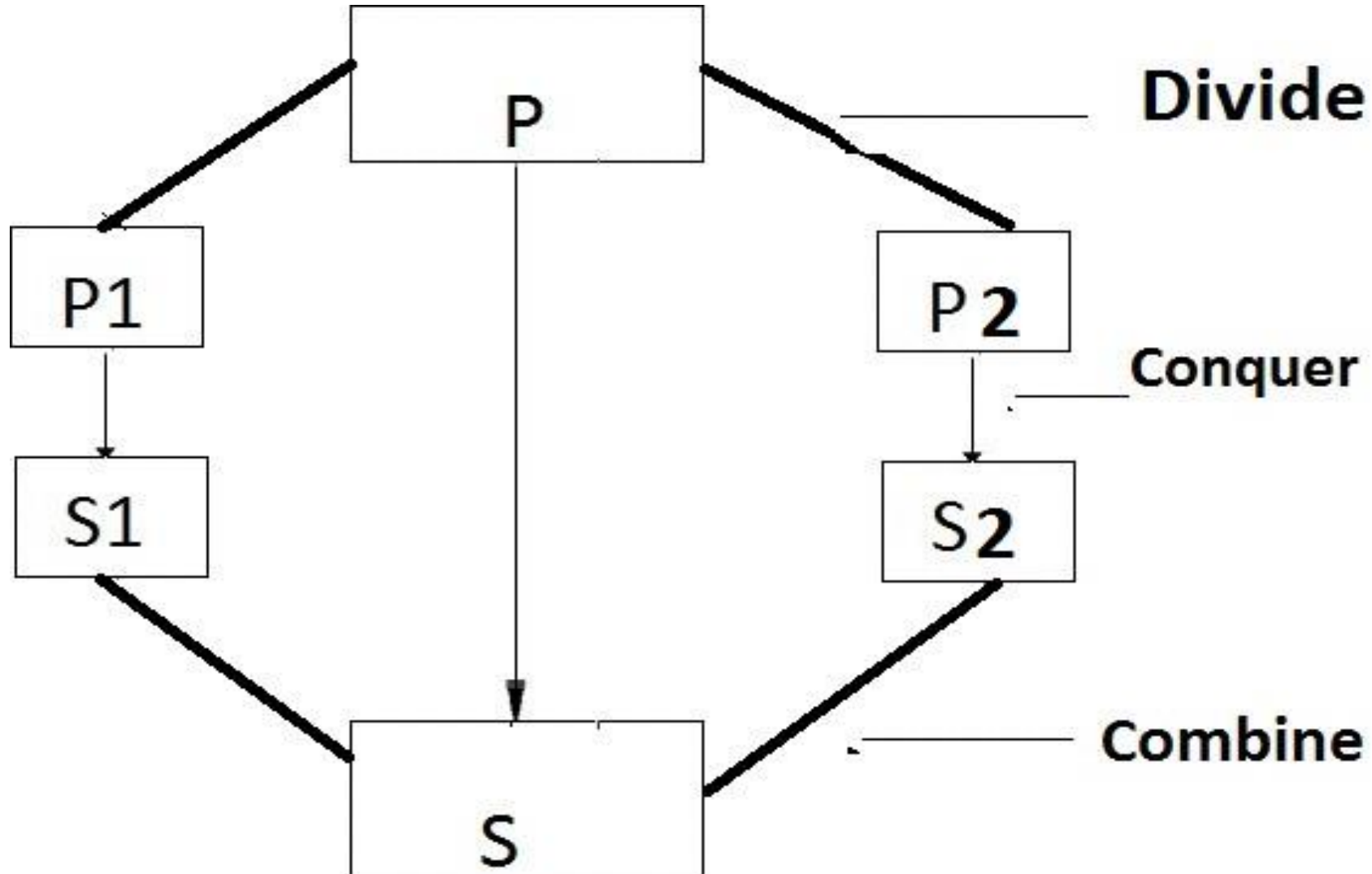
Divide and conquer - Second step

- Conquer/Solve the smaller subproblems recursively. If the input size of the sub problem is very small, solve them directly
 - P1 is solved to give solution S1, P2 is solved to give solution S2

Divide and conquer - Third step

- Merge/Combine these solutions to create a solution to the original problem
 - S_1 and S_2 are combined to give the solution S for the original problem P

Pictorial Representation: Divide and Conquer



Divide and Conquer (D & C)

- Most of the algorithms designed using D & C are **recursive** in nature
- **Recursive algorithms:** Call themselves recursively to solve the closely related subproblems
- **Examples**
 - Towers of Hanoi
 - Binary search
 - Merge Sort
 - Quick sort

Towers of Hanoi



Merge Sort

- Follows D & C paradigm
- Divide: Divide the n -element array into two subarrays of size $n/2$
- Conquer: Sort the two subarrays recursively
- Combine: Merge the two sorted subarrays to produce the sorted array

Merge Sort - Example

The operation of merge sort on the array

$A = \{5, 2, 4, 7, 1, 3, 2, 6\}$

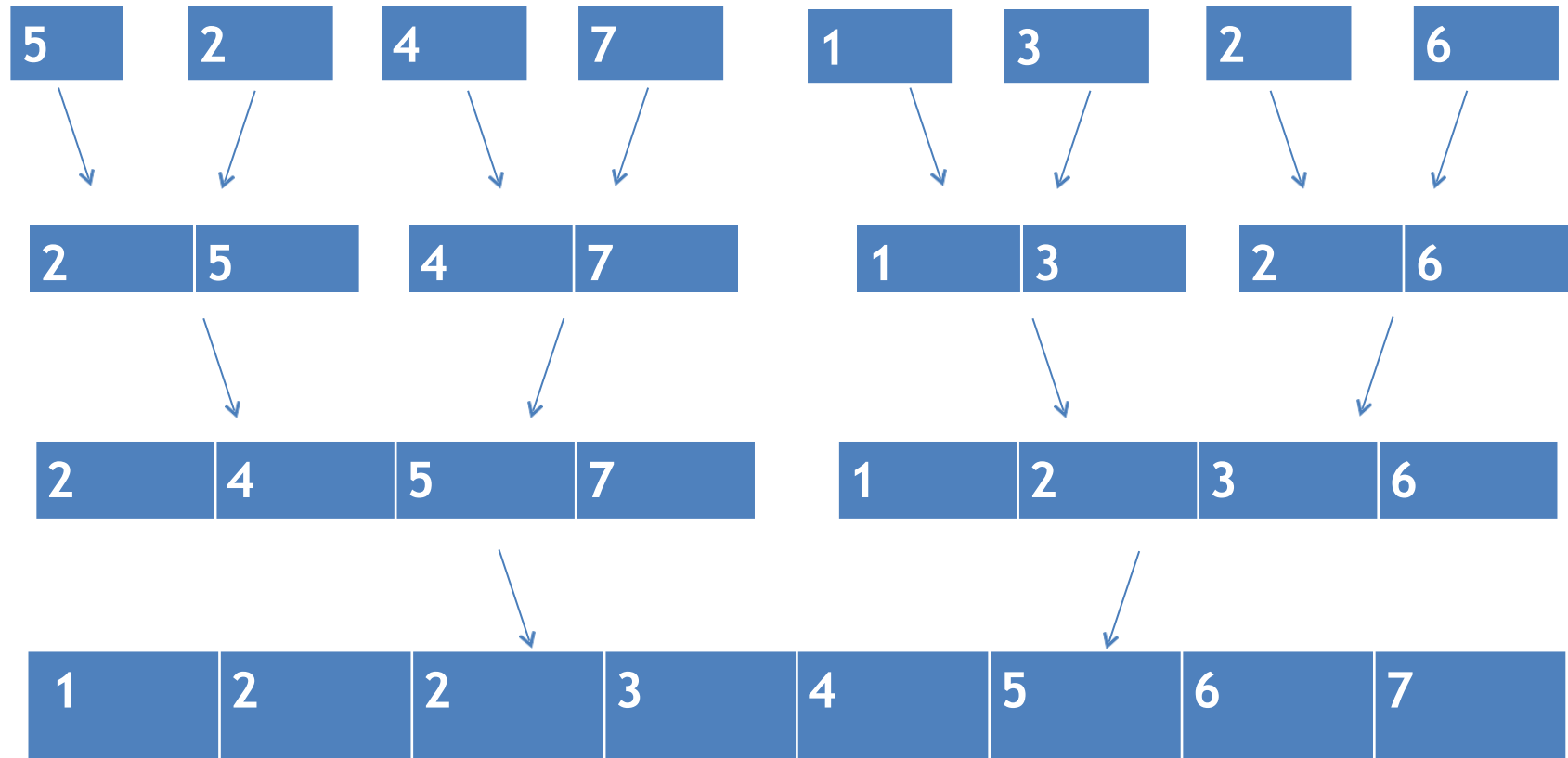
5	2	4	7	1	3	2	6
---	---	---	---	---	---	---	---

5	2	4	7	1	3	2	6
---	---	---	---	---	---	---	---

5	2	4	7	1	3	2	6
---	---	---	---	---	---	---	---

5	2	4	7	1	3	2	6
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Merging of sorted subarrays



Merge Sort - Recursive Algorithm

MERGE-SORT(A, p, r)

1 **if** $p < r$

2 $q = \lfloor (p + r) / 2 \rfloor$

3 MERGE-SORT(A, p, q)

4 MERGE-SORT($A, q + 1, r$)

5 MERGE(A, p, q, r)

Ref: CLRS Book

MERGE-SORT

- If $p \geq r$, the subarray has at most one element and is therefore already sorted.
- Otherwise, the divide step, computes an index q that partitions $A[p \dots r]$ into two subarrays $A[p \dots q]$ and $A[q+1 \dots r]$ containing $(n/2)$ elements

MERGE-SORT(A, p, r)

```
1  if  $p < r$ 
2       $q = \lfloor (p + r) / 2 \rfloor$ 
3      MERGE-SORT( $A, p, q$ )
4      MERGE-SORT( $A, q + 1, r$ )
5      MERGE( $A, p, q, r$ )
```

Function call:

MERGE-SORT($A, 1, A.length$)

Merge sort – Recursive algorithm

- **Base case:**
 - When the size of the subproblem is 1, we don't need to do any further
 - Its already sorted
- **Key operation:** Merging of two sorted arrays in the combine step
- Merge is done by calling another function **Merge (A,p,q,r)**

How to Merge?

Merge function

Merge is done by calling another function **Merge**
(A,p,q,r)

A- Array, p,q,r are indices such that $p \leq q < r$

Assumption: $A[p \dots q]$ and $A[q+1 \dots r]$ are in sorted order

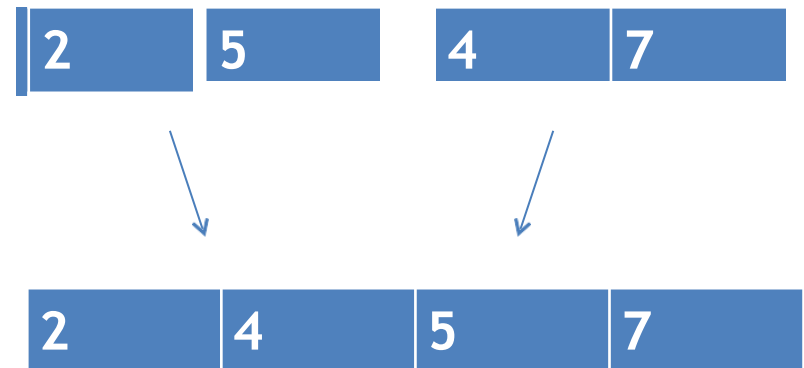
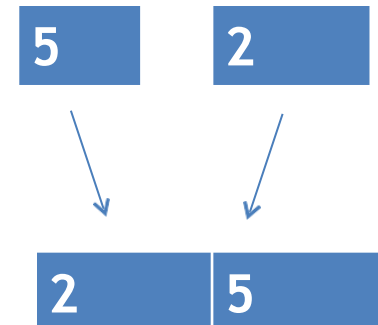
Input: Array A, indices p, q, and r

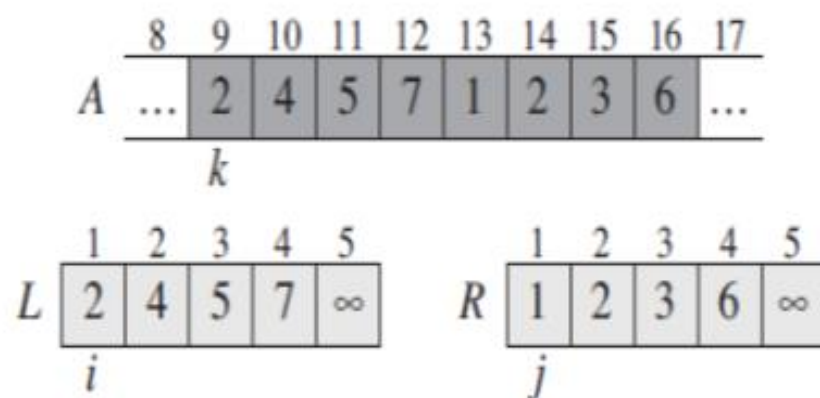
Output: Merges $A[p \dots q]$ and $A[q+1 \dots r]$ and produce a single sorted subarray $A[p \dots r]$

Merge function

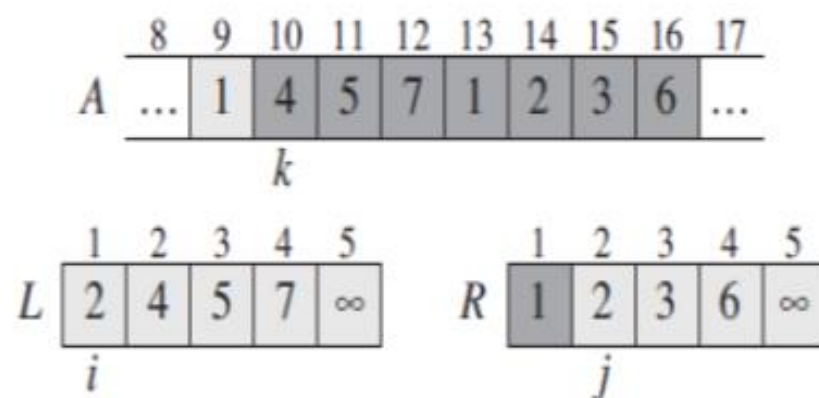
MERGE(A, p, q, r)

```
1   $n_1 = q - p + 1$ 
2   $n_2 = r - q$ 
3  let  $L[1..n_1 + 1]$  and  $R[1..n_2 + 1]$  be new arrays
4  for  $i = 1$  to  $n_1$ 
5       $L[i] = A[p + i - 1]$ 
6  for  $j = 1$  to  $n_2$ 
7       $R[j] = A[q + j]$ 
8   $L[n_1 + 1] = \infty$       Sentinel - a special value
9   $R[n_2 + 1] = \infty$ 
10  $i = 1$ 
11  $j = 1$ 
12 for  $k = p$  to  $r$ 
13     if  $L[i] \leq R[j]$ 
14          $A[k] = L[i]$ 
15          $i = i + 1$ 
16     else  $A[k] = R[j]$ 
17          $j = j + 1$ 
```





(a)

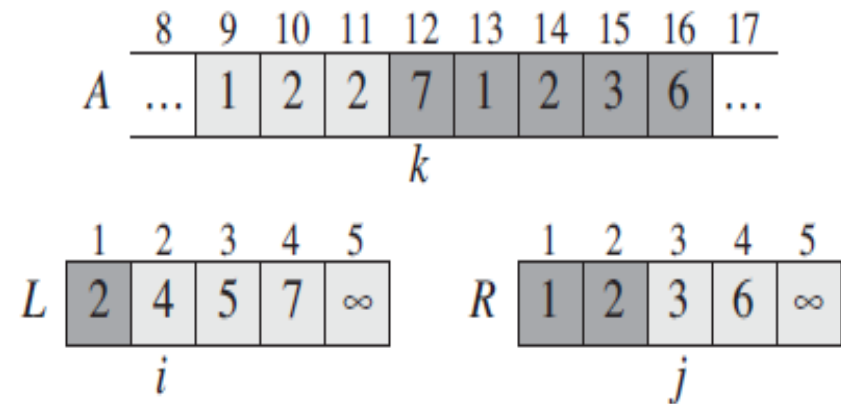
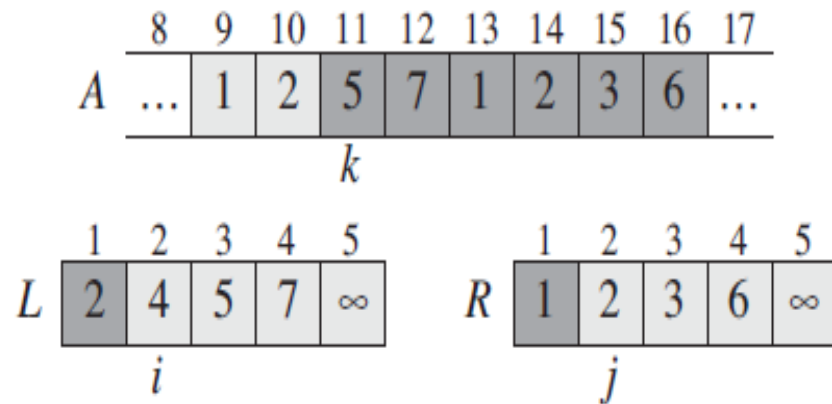
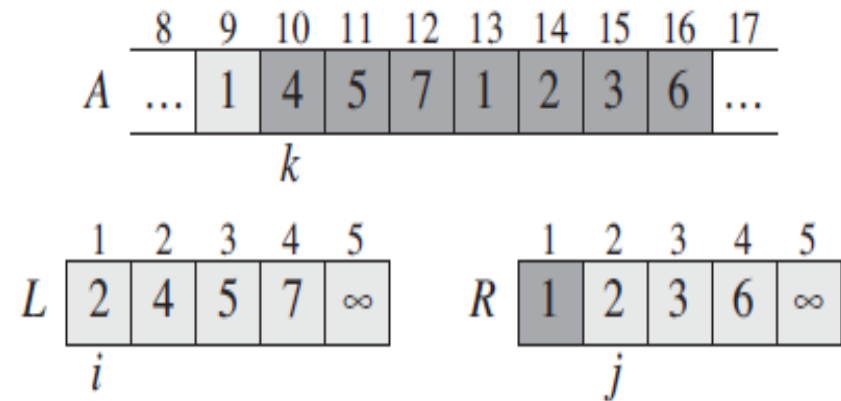
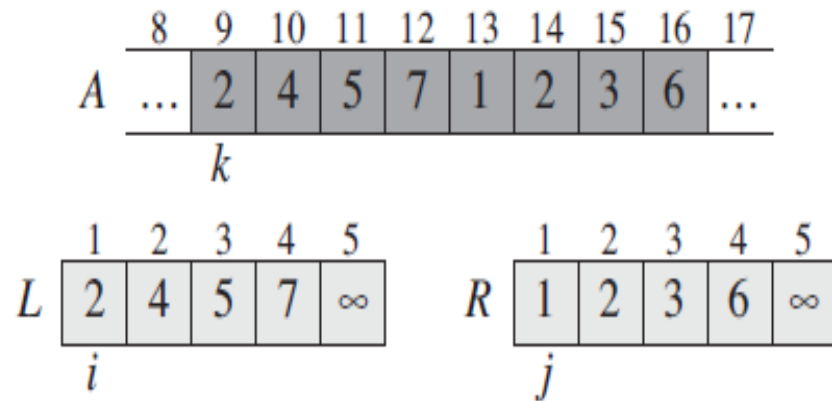


(b)

MERGE(A, p, q, r)

- 1 $n_1 = q - p + 1$
- 2 $n_2 = r - q$
- 3 let $L[1..n_1 + 1]$ and $R[1..n_2 + 1]$ be new arrays
- 4 **for** $i = 1$ **to** n_1
- 5 $L[i] = A[p + i - 1]$
- 6 **for** $j = 1$ **to** n_2
- 7 $R[j] = A[q + j]$
- 8 $L[n_1 + 1] = \infty$
- 9 $R[n_2 + 1] = \infty$

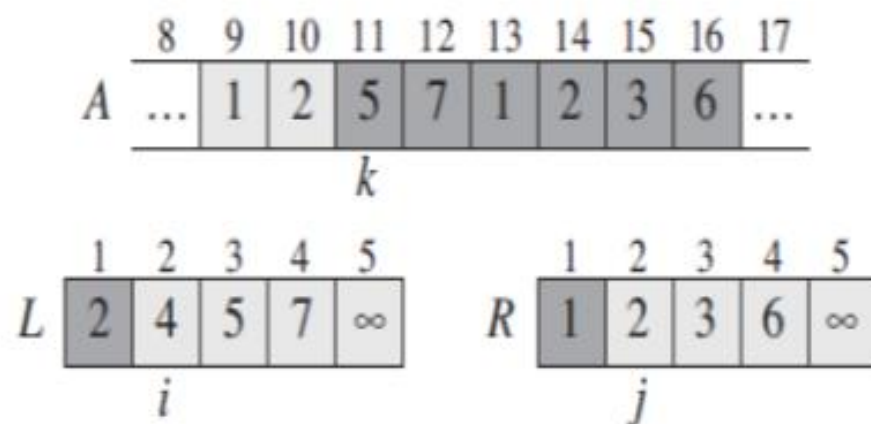
Working of Merge function



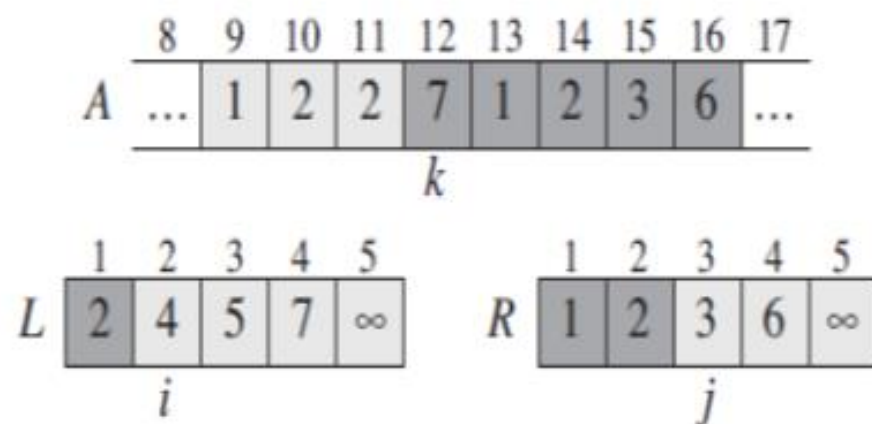
```

10   $i = 1$ 
11   $j = 1$ 
12  for  $k = p$  to  $r$ 
13      if  $L[i] \leq R[j]$ 
14           $A[k] = L[i]$ 
15           $i = i + 1$ 
16      else  $A[k] = R[j]$ 
17           $j = j + 1$ 

```



(c)



(d)

Merge :Running time

- MERGE procedure runs in $\Theta(n)$ -time, $n=r-p+1$
- Line 1-3 and 8-11 takes constant time
- Line 4-7 take $\Theta(n_1 + n_2)$ -time
- Line 12-17 : n iterations of the for loop
 - Each statement within for loop takes constant time

MERGE(A, p, q, r)

```
1   $n_1 = q - p + 1$ 
2   $n_2 = r - q$ 
3  let  $L[1..n_1 + 1]$  and  $R[1..n_2 + 1]$  be new arrays
4  for  $i = 1$  to  $n_1$ 
5       $L[i] = A[p + i - 1]$ 
6  for  $j = 1$  to  $n_2$ 
7       $R[j] = A[q + j]$ 
8   $L[n_1 + 1] = \infty$ 
9   $R[n_2 + 1] = \infty$ 
10  $i = 1$ 
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12 for  $k = p$  to  $r$ 
13     if  $L[i] \leq R[j]$ 
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15          $i = i + 1$ 
16     else  $A[k] = R[j]$ 
17          $j = j + 1$ 
```

Analysis of D & C algorithms

- Running time using recurrence equation or recurrence
- Recurrence describes the overall running time on a problem of size n in terms of the running time on smaller inputs
- Use mathematical tools to solve recurrence

Merge Sort – Recursive Algorithm

MERGE-SORT(A, p, r)

1 **if** $p < r$

2 $q = \lfloor (p + r) / 2 \rfloor$

3 **MERGE-SORT**(A, p, q)

4 **MERGE-SORT**($A, q + 1, r$)

5 **MERGE**(A, p, q, r)

Recurrence for D & C algorithms

- Suppose the division of the problem yields **a** sub problems, each of which is **1/b the size** of the original.
- **$T(n/b)$ -time** to solve one sub problem of **size n/b**
- **$aT(n/b)$ - time** to solve **a** of them
- **$D(n)$ -time** to divide the problem into sub problems and **$C(n)$ -time** to combine the solutions to the sub problems into the solution to the original problem

Recurrence:

$$T(n) = \begin{cases} \Theta(1) & \text{if } n \leq c, \\ aT(n/b) + D(n) + C(n) & \text{otherwise.} \end{cases}$$

Merge Sort – Recursive Algorithm

MERGE-SORT(A, p, r)

1 **if** $p < r$

2 $q = \lfloor (p + r) / 2 \rfloor$

3 **MERGE-SORT**(A, p, q)

4 **MERGE-SORT**($A, q + 1, r$)

5 **MERGE**(A, p, q, r)

Analysis of Merge sort

- Recurrence-based analysis is simplified if we assume that original problem size is a power of 2.
- Each divide step then yields two subsequences of size exactly $n/2$.
- Let $T(n)$ be the worst-case running time of merge sort on n numbers

Analysis of Merge sort

- Merge sort on just one element takes constant time.
- When $n > 1$ elements, break down the running time as follows.
- **Divide:** The divide step just computes the middle of the subarray, which takes constant time. Thus, $D(n) = \Theta(1)$
- **Conquer:** Solve two sub problems, each of size $n/2$, which contributes $2T(n/2)$ to the running time.
- **Combine:** MERGE procedure on an n -element subarray takes time $\Theta(n)$, and so $C(n) = \Theta(n)$

Analysis of Merge sort

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1, \\ 2T(n/2) + \Theta(n) & \text{if } n > 1. \end{cases}$$

We can solve the above recurrence using **Master's theorem**.

Now, we rewrite the recurrence as follows to solve it using **recursion tree** technique.

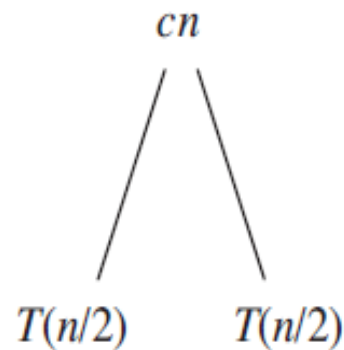
$$T(n) = \begin{cases} c & \text{if } n = 1, \\ 2T(n/2) + cn & \text{if } n > 1, \end{cases}$$

Constant c represents the time required to solve problems of size 1 as well as the time per array element of the divide and combine steps

Recursion tree

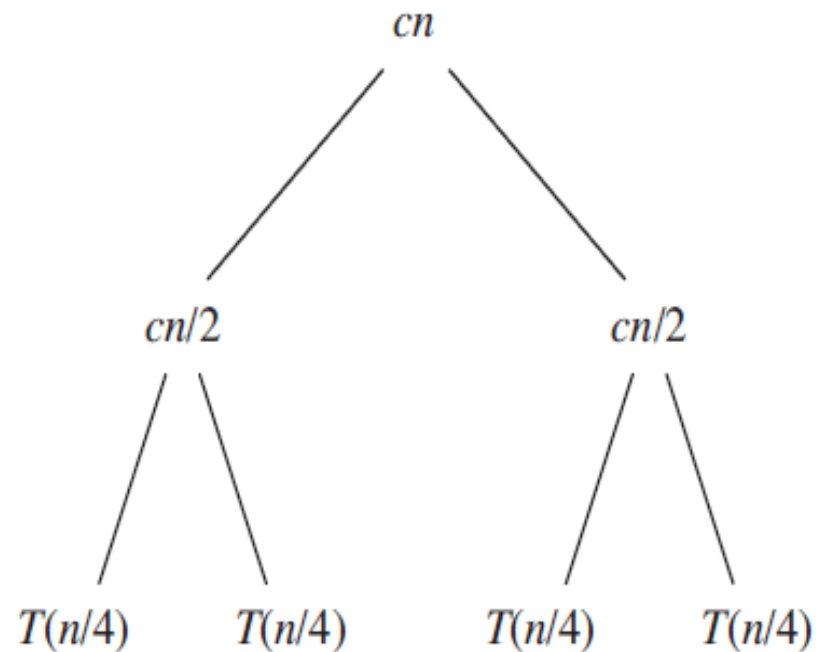
- Assume that **n is an exact power of 2.**
- The **cn** term is the root (the cost incurred at the top level of recursion)
- Two subtrees of the root are the **two smaller recurrences $T(n/2)$**

$T(n)$



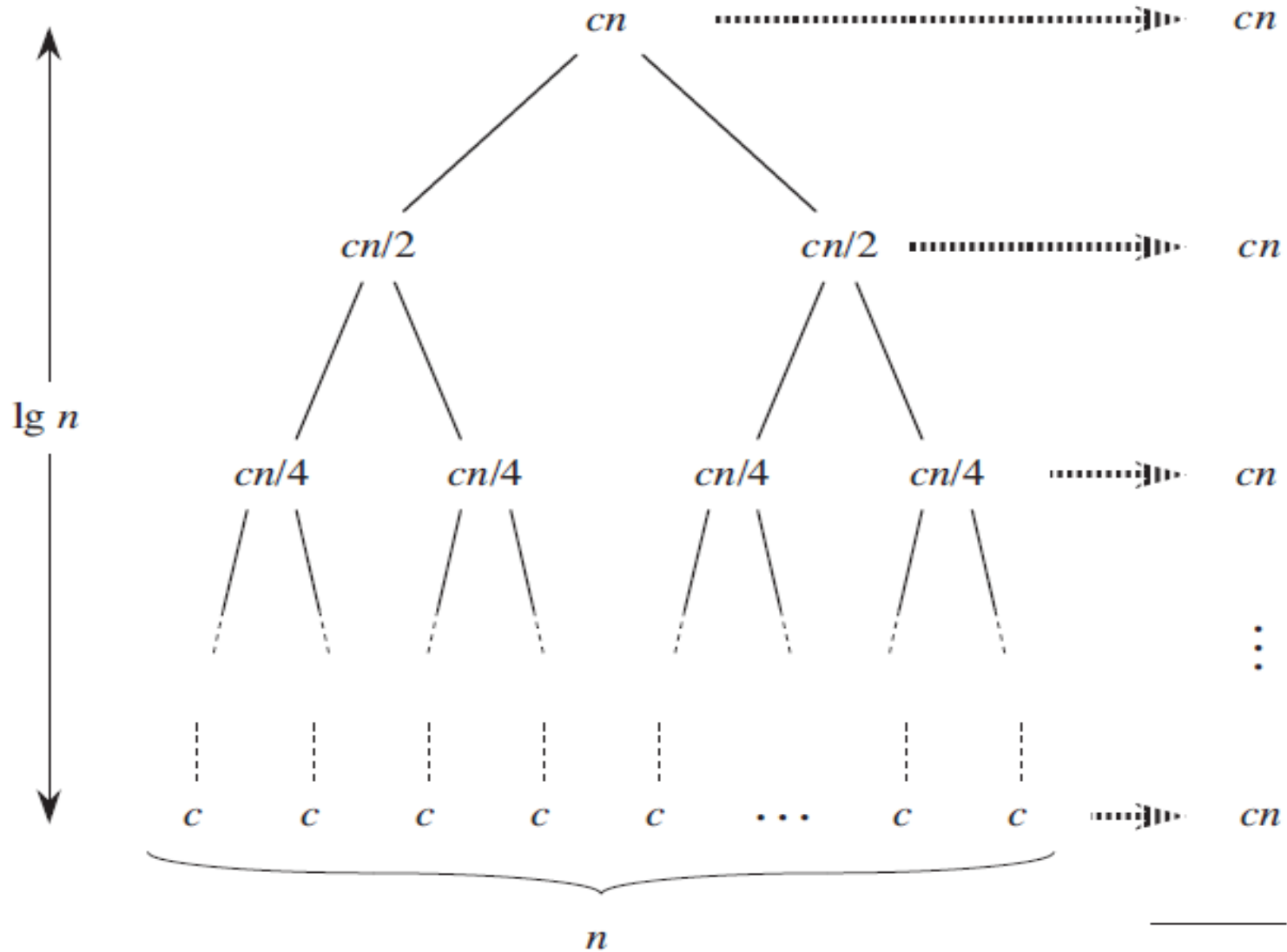
(a)

(b)



(c)

Continue expanding each node in the tree as determined by the recurrence, until the **problem sizes get down to 1, each with a cost of c .**



(d)

Total: $cn \lg n + cn$

- **Total cost of the recursion tree = Cost of each level * total number of levels**

Costs across each level of the tree:

- The top level (root) has total cost **cn**
- Next level down has total cost
$$c(n/2) + c(n/2) = cn$$
- Level after that has total cost
$$c(n/4) + c(n/4) + c(n/4) + c(n/4) = cn, \text{ and so on}$$
- **Level i has 2^i nodes**, each contributing a cost of **$c(n/2^i)$** , total cost **$2^i * c(n/2^i) = cn$**
- **Bottom level has n nodes**, each contributing a cost of **c**, for a **total cost of cn**

Compute the total cost

- Cost of each level * height of the tree
= $cn * (\lg n)$
= $cn \lg n$
= $\Theta(n \lg n)$

Hence, Merge sort running time is $\Theta(n \lg n)$.

Correctness of Merge

Correctness of Merge

```
12  for  $k = p$  to  $r$   
13      if  $L[i] \leq R[j]$   
14           $A[k] = L[i]$   
15           $i = i + 1$   
16      else  $A[k] = R[j]$   
17           $j = j + 1$ 
```

- **Loop invariant:** At the start of each iteration of the **for** loop of lines 12–17, the subarray $A[p \dots k-1]$ contains the $k - p$ smallest elements of $L[1.. n_1 + 1]$ and $R[1.. n_2 + 1]$, in sorted order.
- Moreover, $L[i]$ and $R[j]$ are the smallest elements of their arrays that have not been copied back into A .

Maintaining the loop invariant

- Show that loop invariant holds **prior to the first iteration** of the for loop of lines 12–17
- **Each iteration of the loop** maintains the invariant
- Show correctness when **the loop terminates.**

```
12  for  $k = p$  to  $r$ 
13      if  $L[i] \leq R[j]$ 
14           $A[k] = L[i]$ 
15           $i = i + 1$ 
16      else  $A[k] = R[j]$ 
17           $j = j + 1$ 
```

Initialization

```
12  for  $k = p$  to  $r$ 
13      if  $L[i] \leq R[j]$ 
14           $A[k] = L[i]$ 
15           $i = i + 1$ 
16      else  $A[k] = R[j]$ 
17           $j = j + 1$ 
```

- Prior to the first iteration of the loop, we have $k = p$
- Subarray $A[p \dots k-1]$ is empty.
- This empty subarray contains the $k - p = 0$ smallest elements of L and R , and since $i = j = 1$
- Both $L[i]$ and $R[j]$ are the smallest elements of their arrays that have not been copied back into A .

Maintenance: Each iteration maintains the loop invariant

```
12  for  $k = p$  to  $r$ 
13      if  $L[i] \leq R[j]$ 
14           $A[k] = L[i]$ 
15           $i = i + 1$ 
16      else  $A[k] = R[j]$ 
17           $j = j + 1$ 
```

- First, **suppose that $L[i] \leq R[j]$**
- $L[i]$ is the smallest element not yet copied back into A .
- Because $A[p \dots k-1]$ contains $k - p$ smallest elements, after line 14 copies $L[i]$ into $A[k]$
- Subarray $A[p \dots k]$ will contain $k-p+1$ smallest elements
- Incrementing k (in the **for** loop) and i (in line 15) reestablishes the loop invariant for the next iteration
- **Suppose if $L[i] > R[j]$** , lines 16 – 17 perform appropriate action to maintain loop invariant

Termination

- At termination, $k = r + 1$. By the loop invariant, the subarray $A[p \dots k-1]$, which is $A[p \dots r]$, contains k
- $p = r - p + 1$ smallest elements of $L[1.. n_1 + 1]$ and $R[1.. n_2 + 1]$, in sorted order.
- The arrays L and R together contain
$$n_1 + n_2 + 2 = r - p + 3 \text{ elements.}$$
- All but the two largest have been copied back into A , and these two largest elements are the sentinels.

Conclusion

- What is the best case, worst case and average case input of Merge sort algorithm?
- What about Bubble sort algorithm?
- Merge sort's worst case running time is much less than that of insertion sort
- Divide-and-conquer algorithms running times are easily determined by solving recurrence relations

Thank You