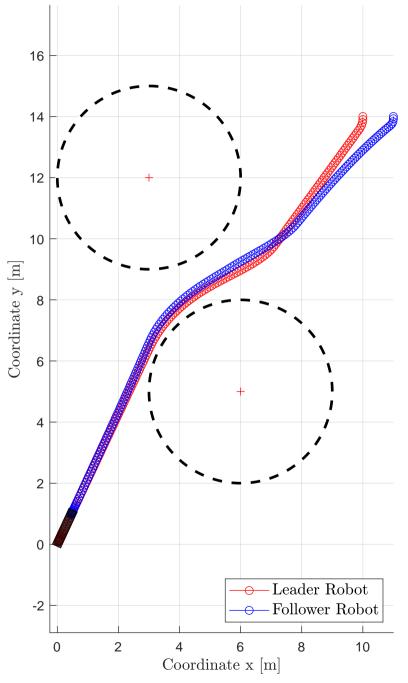
## Leader-Follower Trajectory



## Coordinates evolution $p_{L,x}$ $p_{L,y}$ $p_{L,y}$

