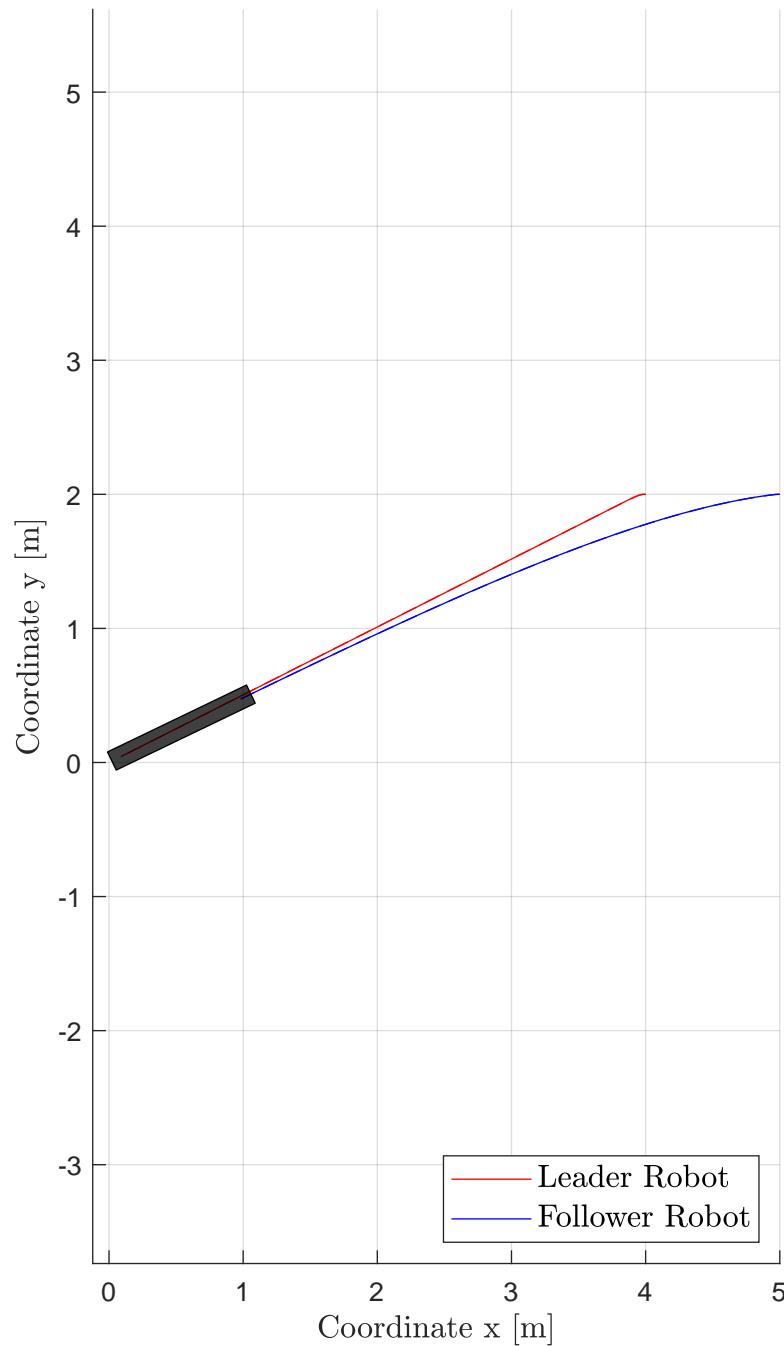
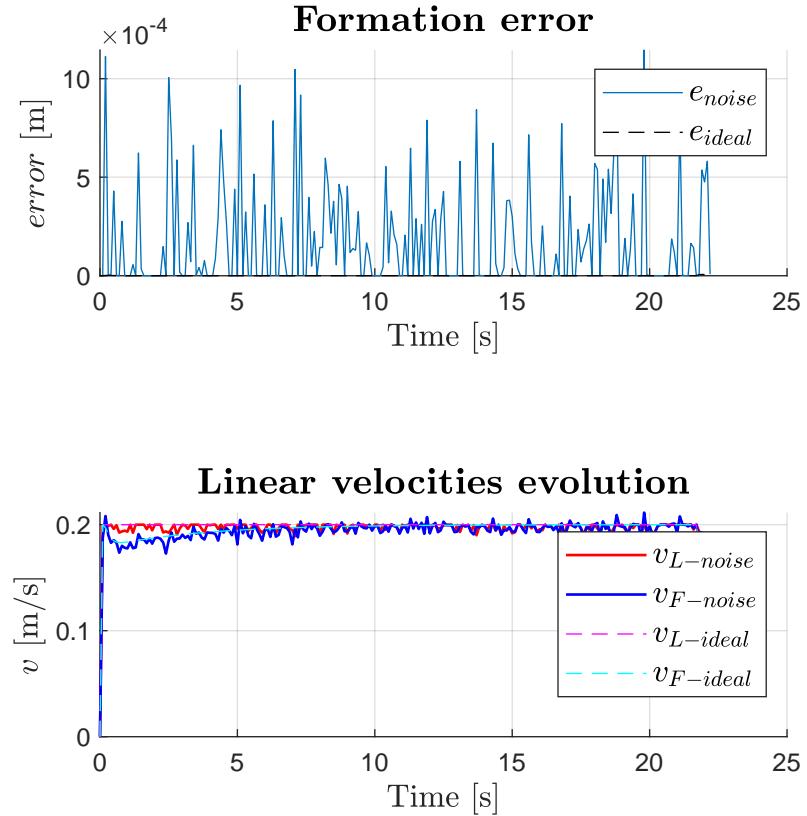


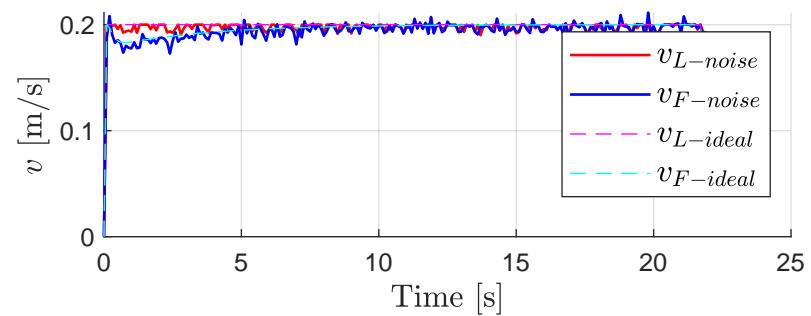
Leader-Follower Trajectory



Formation error



Linear velocities evolution



Angular velocities evolution

