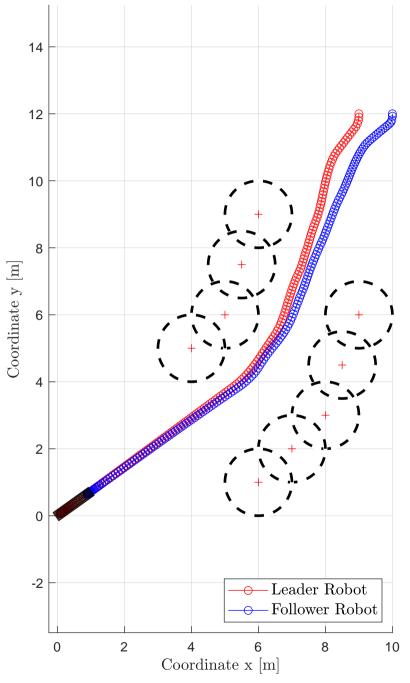
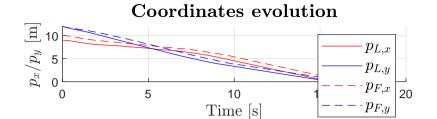
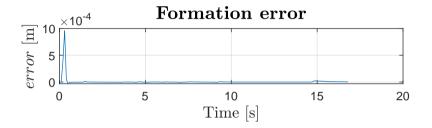
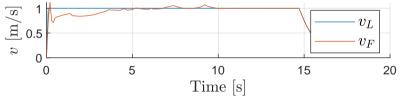
Leader-Follower Trajectory











Angular velocities evolution

