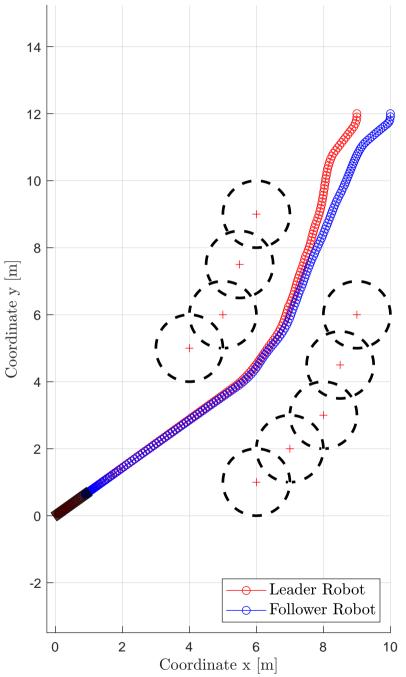
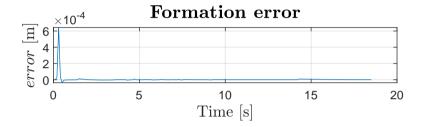
## Leader-Follower Trajectory

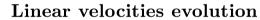


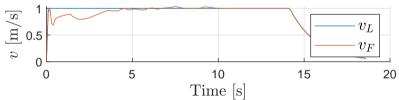
## Coordinates evolution $\begin{bmatrix} \text{m} \end{bmatrix} \begin{array}{c} 10 \\ 5 \\ 0 \\ 0 \\ \end{array} \begin{array}{c} 0 \\ 0 \\ \end{array}$ $p_{L,x}$ $p_{L,y}$ $p_{F,x}$ 10

Time [s]

 $p_{F,y}$ 







## Angular velocities evolution

