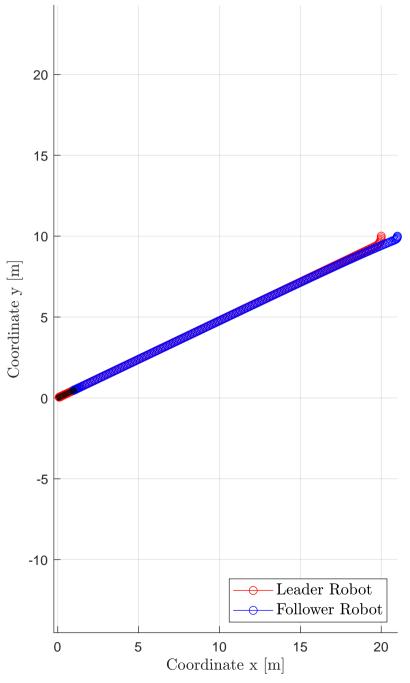
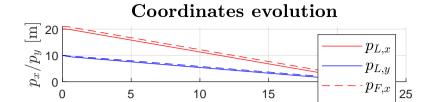
## Leader-Follower Trajectory





Time [s]

 $p_{F,y}$ 

