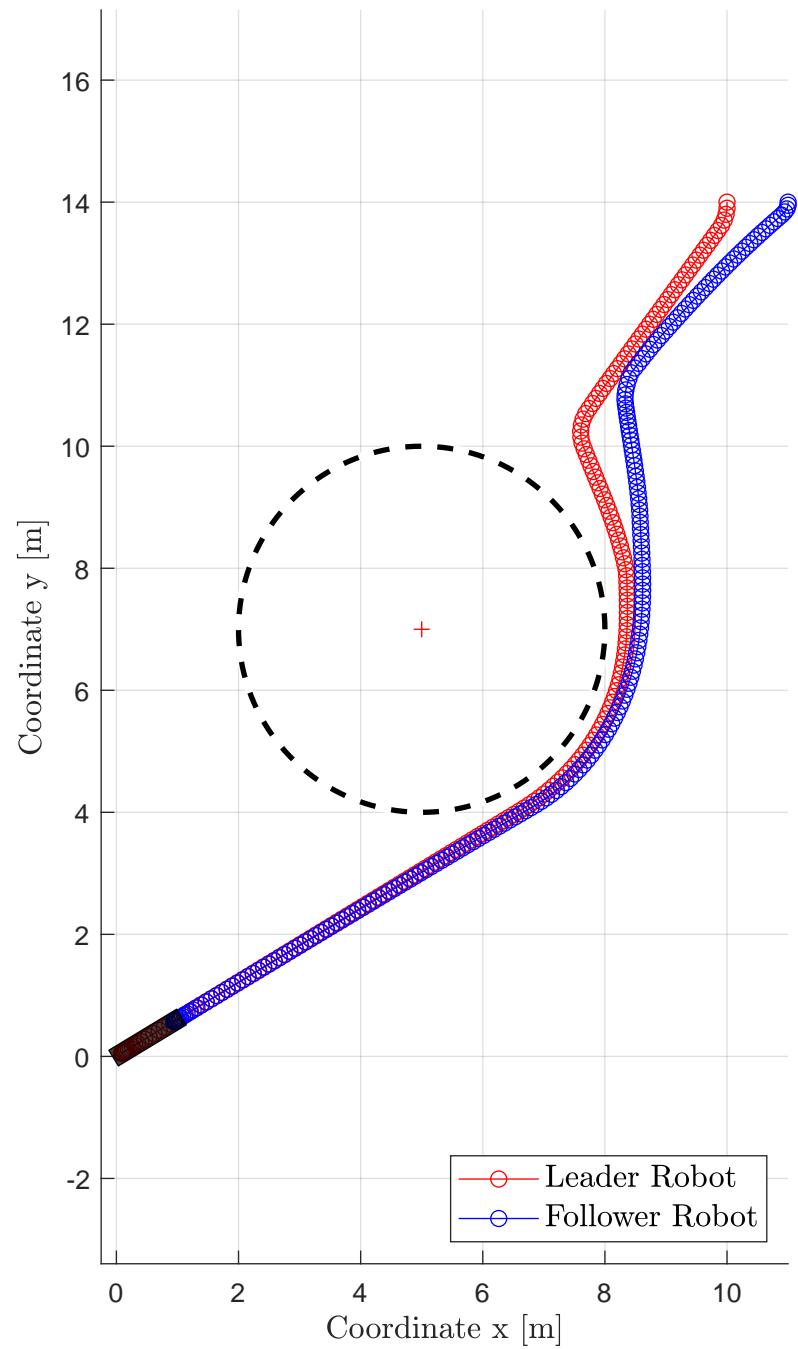
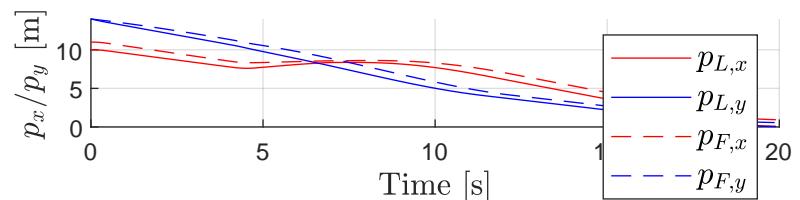


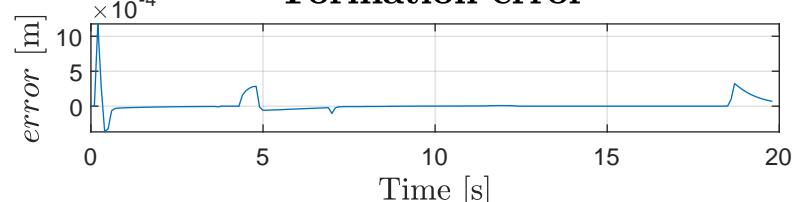
Leader-Follower Trajectory



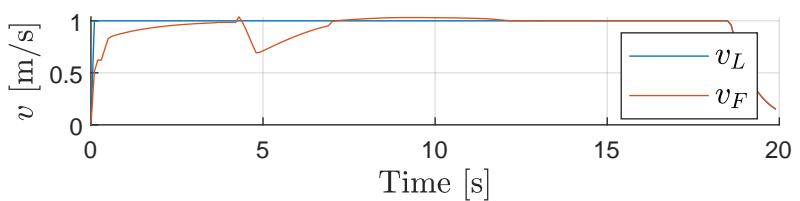
Coordinates evolution



Formation error



Linear velocities evolution



Angular velocities evolution

