

# Distracted Driver Detection

K Mani Kumar Reddy, K Sarath Chandra Reddy,

## Problem Statement

- Road Accidents are increasing day by day. Driver Distraction is one of the main cause of road accidents. So, the detection of driver distraction is very important in today's scenario.
- The aim of our project is to build a model that detects the distraction of drivers in vehicles using various machine learning techniques with the help of dashboard cameras.
- Input to our model is an image of driver taken in a car while driving and model outputs a predicted type of distraction activity of the driver.

## Dataset Description

- The dataset we will be using for this project is from Kaggle's challenge <https://www.kaggle.com/c/state-farm-distracted-driver-detection/overview>
- The Dataset contains 22,424 images categorized into 10 classes (9 classes of distraction and 1 class without distraction or safe driving). Each image size is 640 x 480 pixels.
  - Different classes:
    - c0 - Safe driving
    - c1 - Texting (right hand)
    - c2 - Talking on the phone (right hand)
    - c3 - Texting (left hand)
    - c4 - Talking on the phone (left hand)
    - c5 - Operating the radio
    - c6 - Drinking
    - c7 - Reaching behind
    - c8 - Hair and makeup
    - c9 - Talking to passenger(s)



Figure 1: Example Image Of Distracted Driver

## Preprocessing Techniques

- Grey scale to RGB conversion (if any image is in Greyscale)
- Resizing
- Elimination of Noise (if any)
- Normalization or Standardization

## Learning Techniques

- Neural Networks (Multi-Layered Perceptron's)

## Evaluation Metrics

- Accuracy
- Multi Class Log Loss
- F1 score

## References

- [1] B. Baheti, S. Gajre, and S. Talbar. Detection of distracted driver using convolutional neural network. In *2018 IEEE/CVF Conference on Computer Vision and Pattern Recognition Workshops (CVPRW)*, pages 1145–11456, June 2018.
- [2] Y. Liang, M. L. Reyes, and J. D. Lee. Real-time detection of driver cognitive distraction using support vector machines. *IEEE Transactions on Intelligent Transportation Systems*, 8(2):340–350, June 2007.