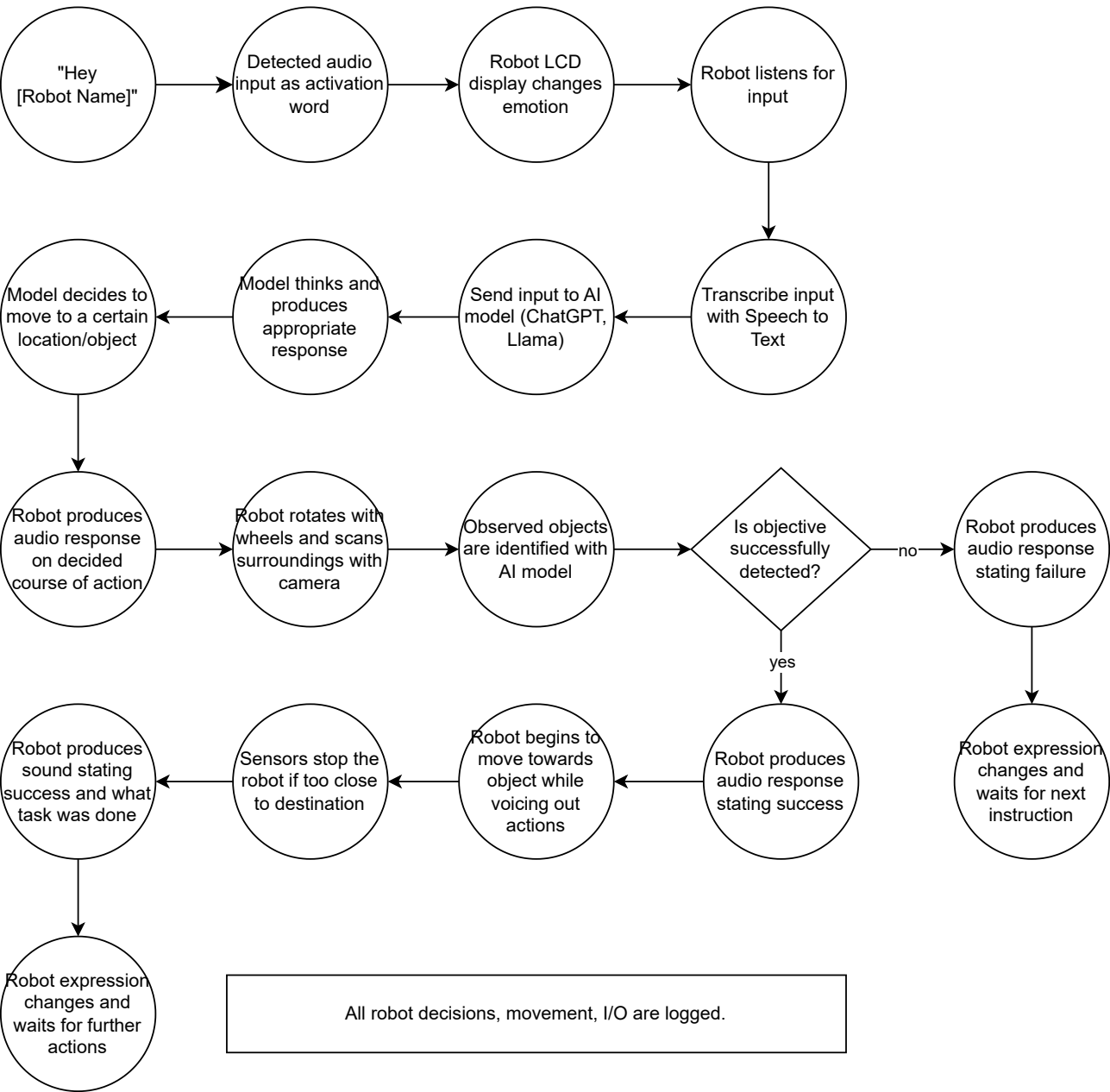


Action: Requesting robot to move to a certain object in a room



Action: Requesting robot to enter exploration mode

