1	/Users/ryanwu/Project2/bin/python /Users/ryanwu/
	Documents/CMU/24-677 Modern Control Theory/Project/
	Project2/Q1.py
2	At 2 m/s:
3	Rank of controllability matrix P: 4, Controllable:
	Yes
4	Rank of observability matrix Q: 4, Observable: Yes
5	=======================================
	====
6	At 5 m/s:
7	Rank of controllability matrix P: 4, Controllable:
	Yes
	Rank of observability matrix Q: 4, Observable: Yes
9	
4.0	==== A+ 0 /
	At 8 m/s:
11	Rank of controllability matrix P: 4, Controllable:
1 2	Yes Pank of observability matrix 0: / Observable: Vos
	Rank of observability matrix Q: 4, Observable: Yes
13	====
14	
	Process finished with exit code 0
16	Troccos Timismed With CAIL Code C
10	