NNRF

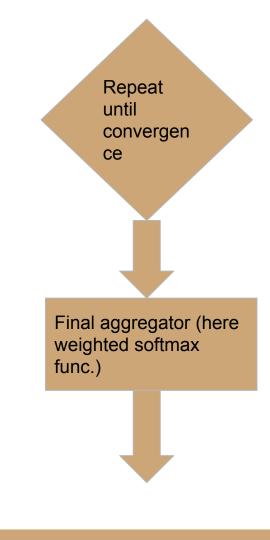
Flowchart:

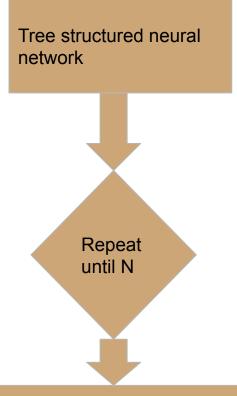
Image data from google maps(both tanks and non-tanks)

Draw a bootstrapped sample from whole procured imagery data.

Construct the bootstrapped data with features selected at random(r): $r = \sqrt{no}$. of features for each node

Perform forward propagation for calculating cost, also use a function to activate one path at a time and update the weights and biases using backward propagation.





Predicted output that has occured most of the time