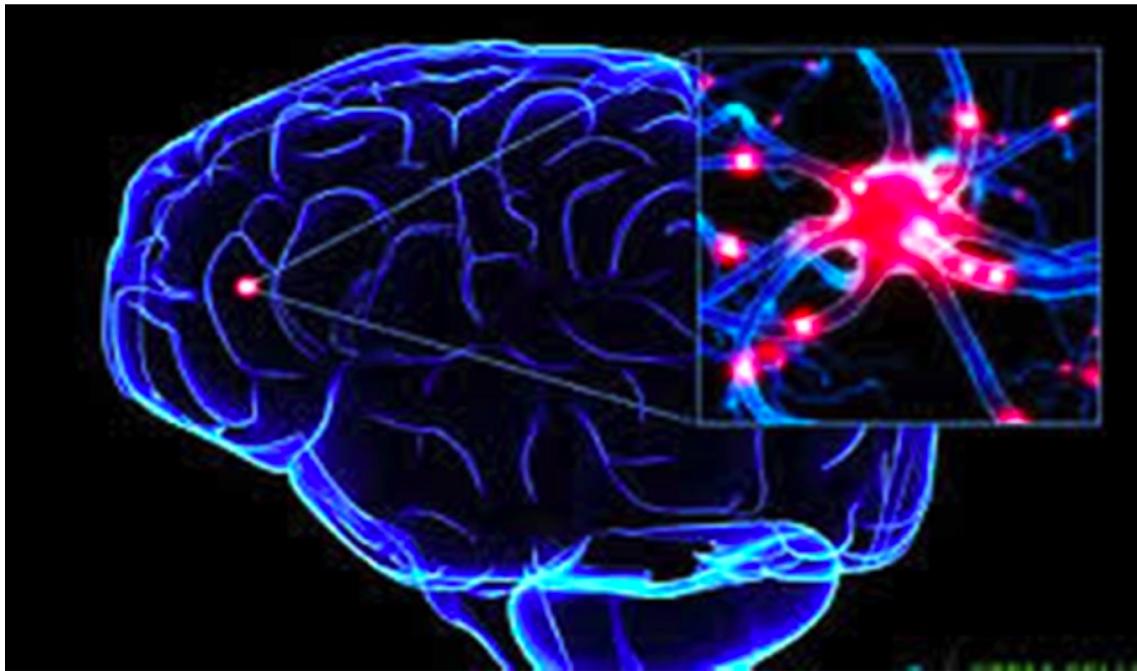


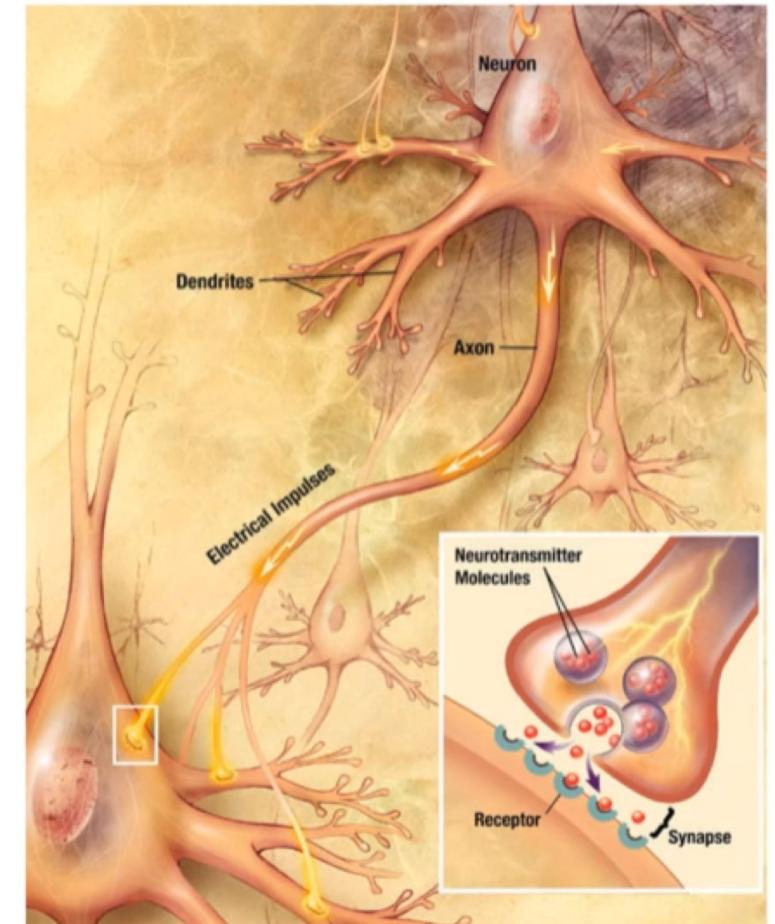
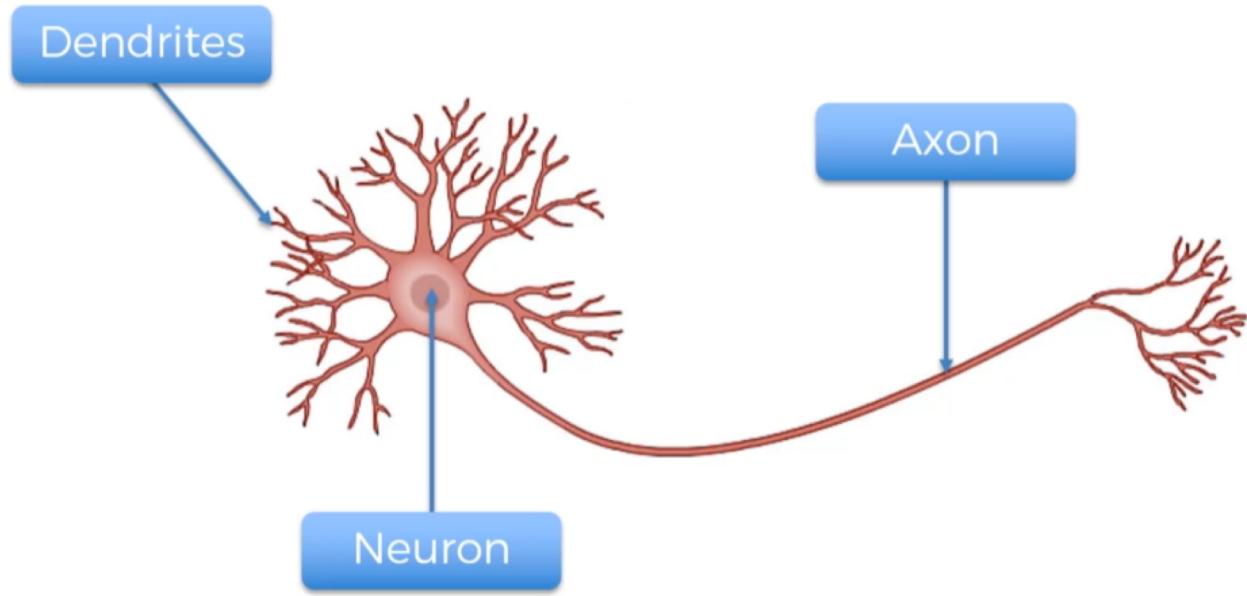
AI

Artificial Intelligent

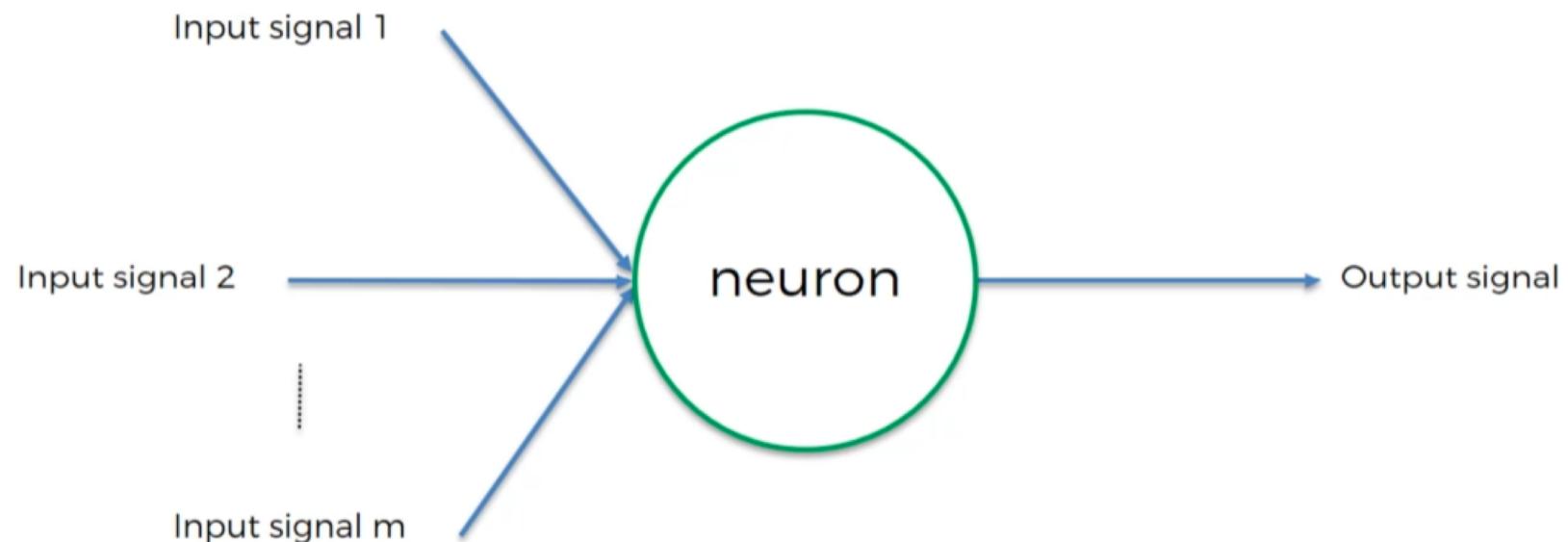
Neural Network



Neuron



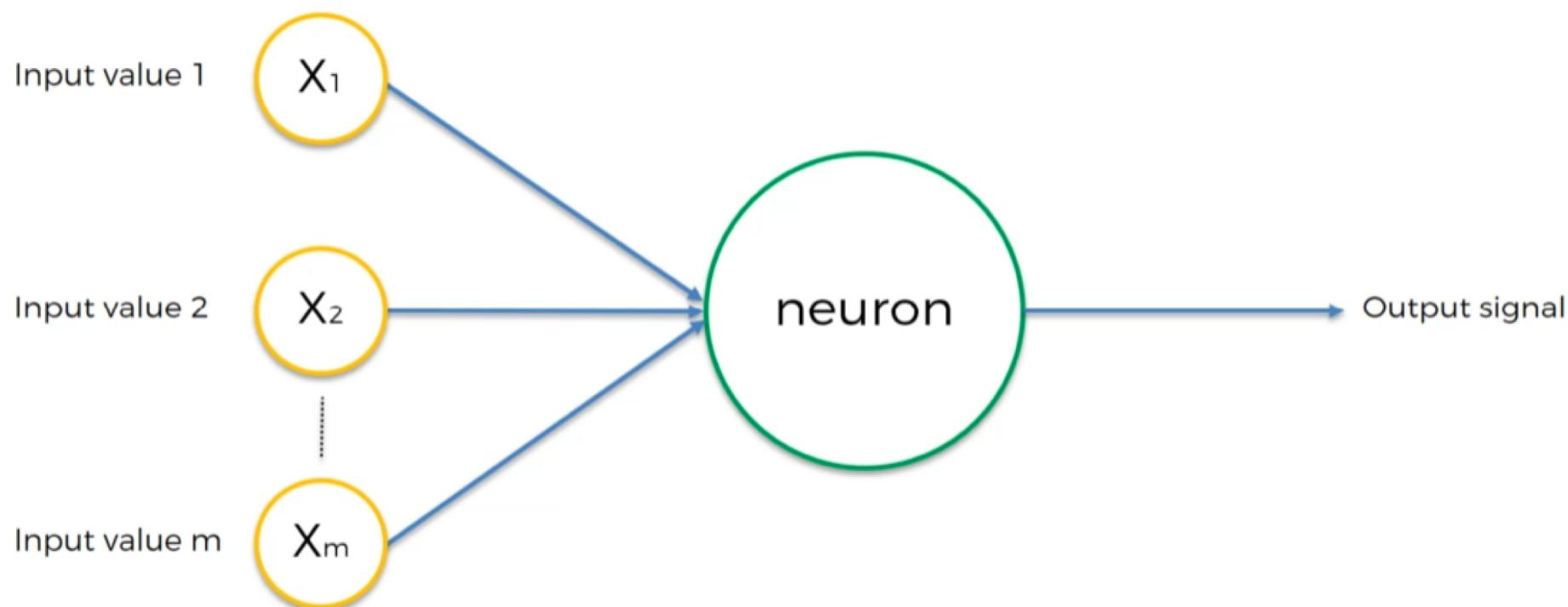
Neuron



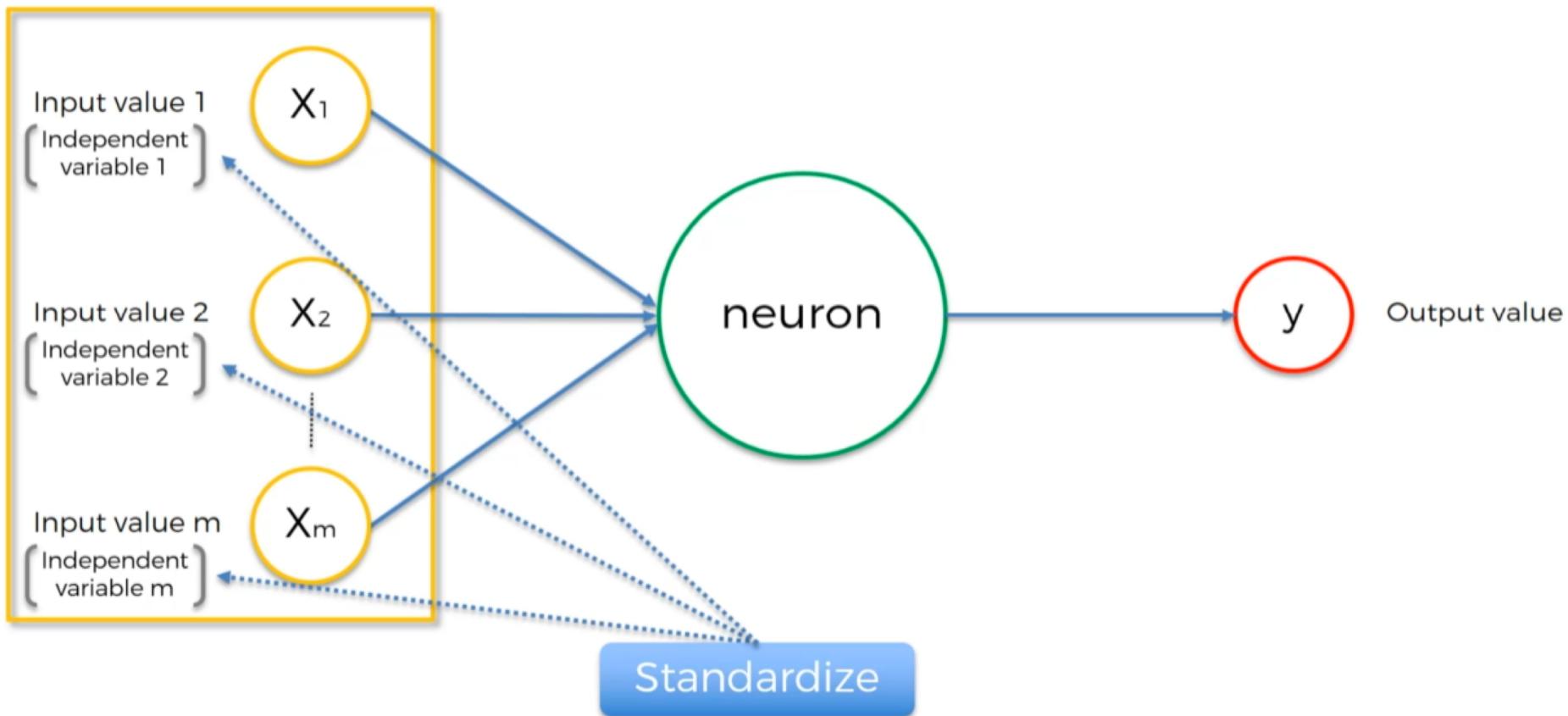
Neuron – Data Set

Row ID	Study Hrs	Sleep Hrs	Quiz	Exam
1	12	6	78%	93%
2	22	6.5	24%	68%
3	115	4	100%	95%
4	31	9	67%	75%
5	0	10	58%	51%
6	5	8	78%	60%
7	92	6	82%	89%
8	57	8	91%	97%

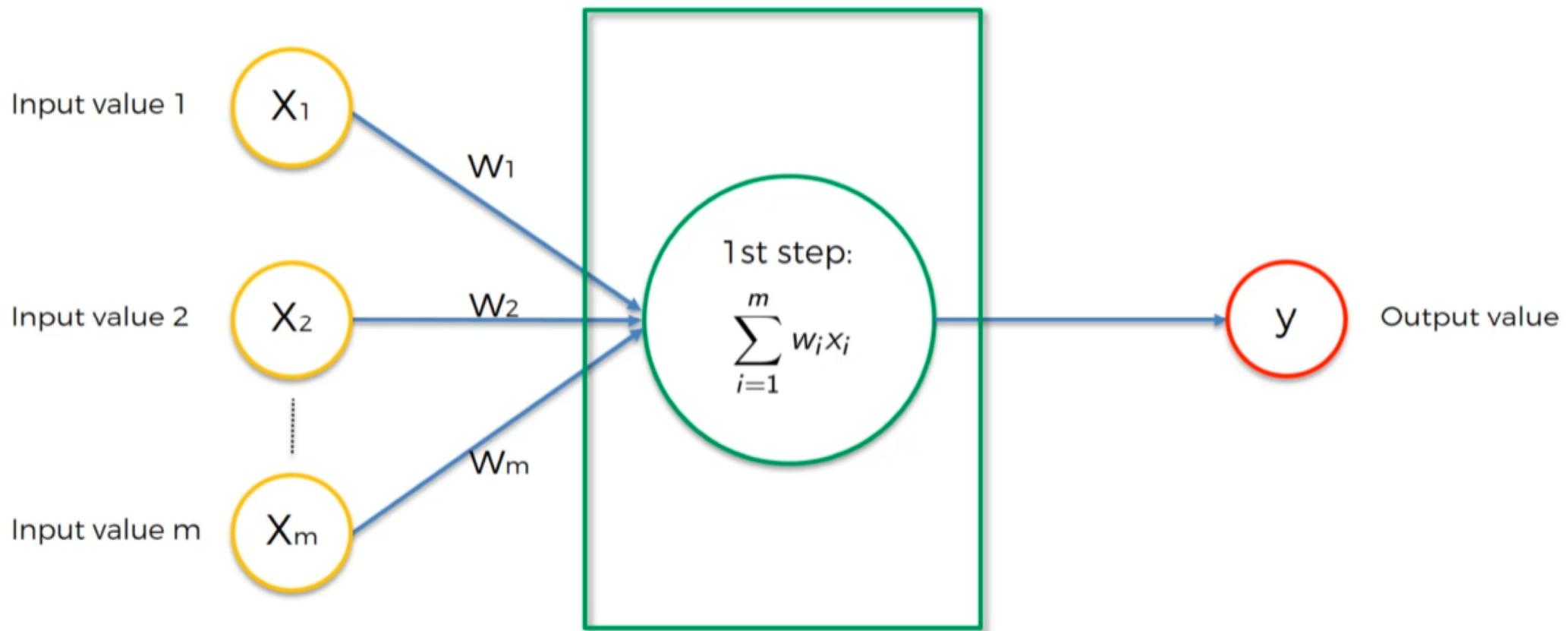
Neuron



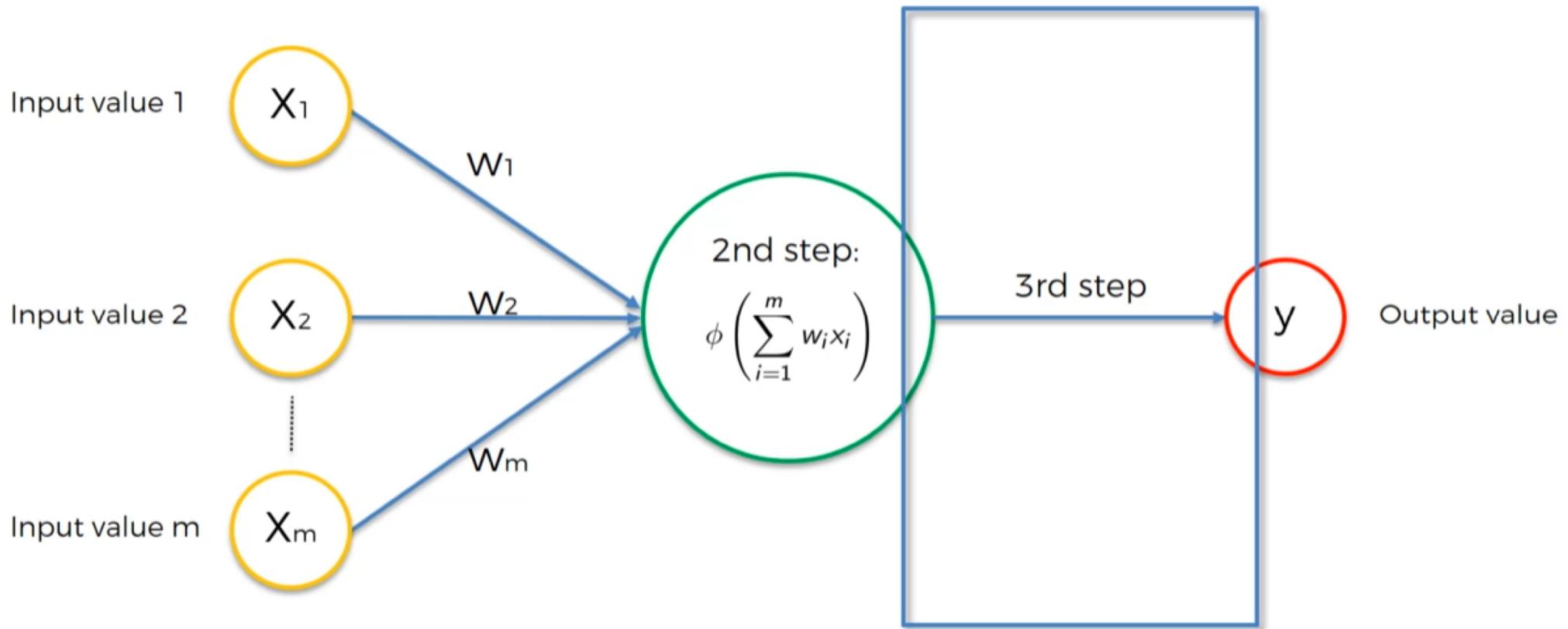
Neuron



Neuron



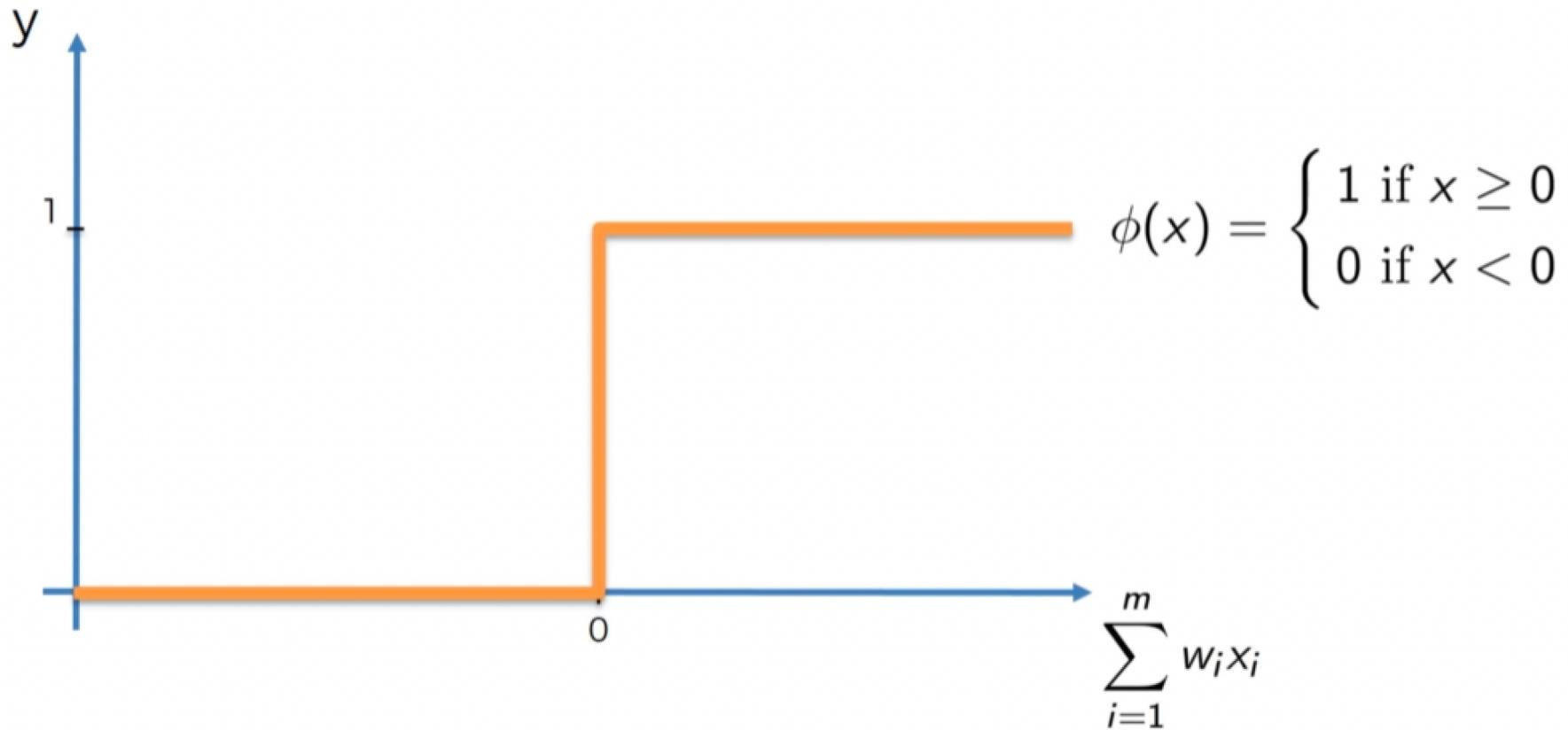
Activation Function



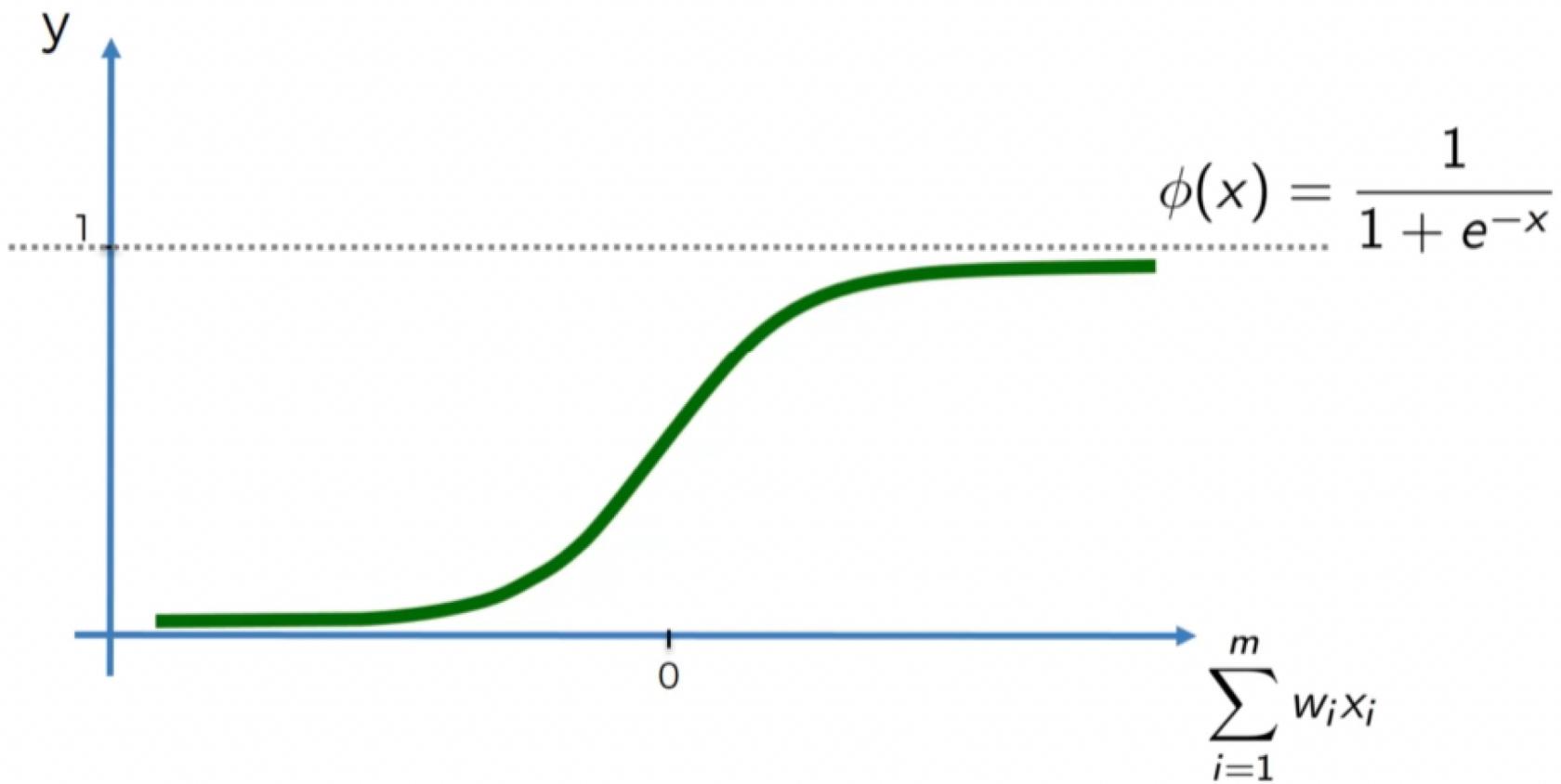
Activation Function

- Their main purpose is to convert a input signal of a node in a A-NN to an output signal
- That output signal can be used as a input in the next layer in the stack
- Specifically in A-NN
 - we do the sum of products of inputs(**X**) and their corresponding Weights(**W**)
 - apply a Activation function **f(x)** to it to get the output of that layer
 - feed it as an input to the next layer

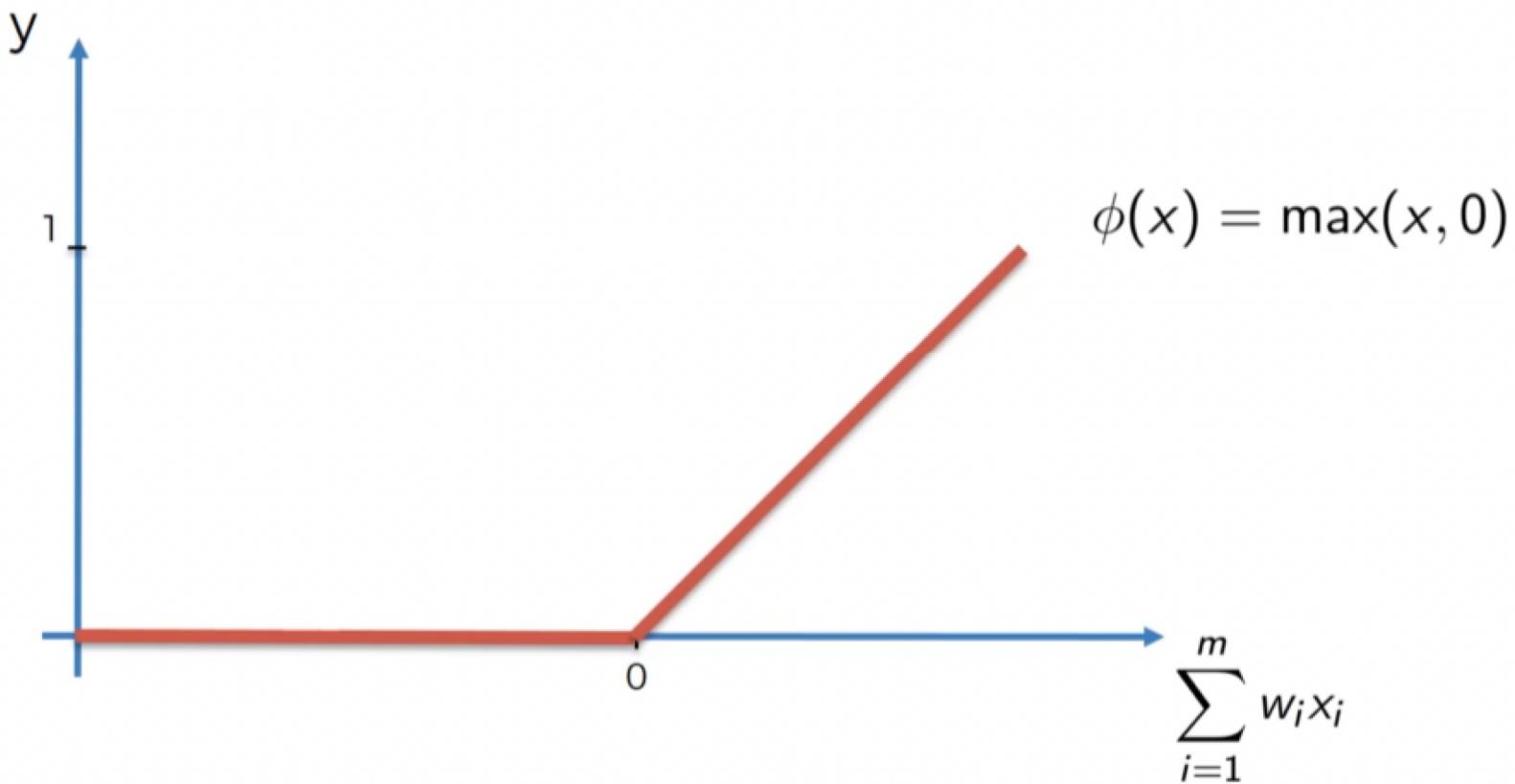
Threshold Function



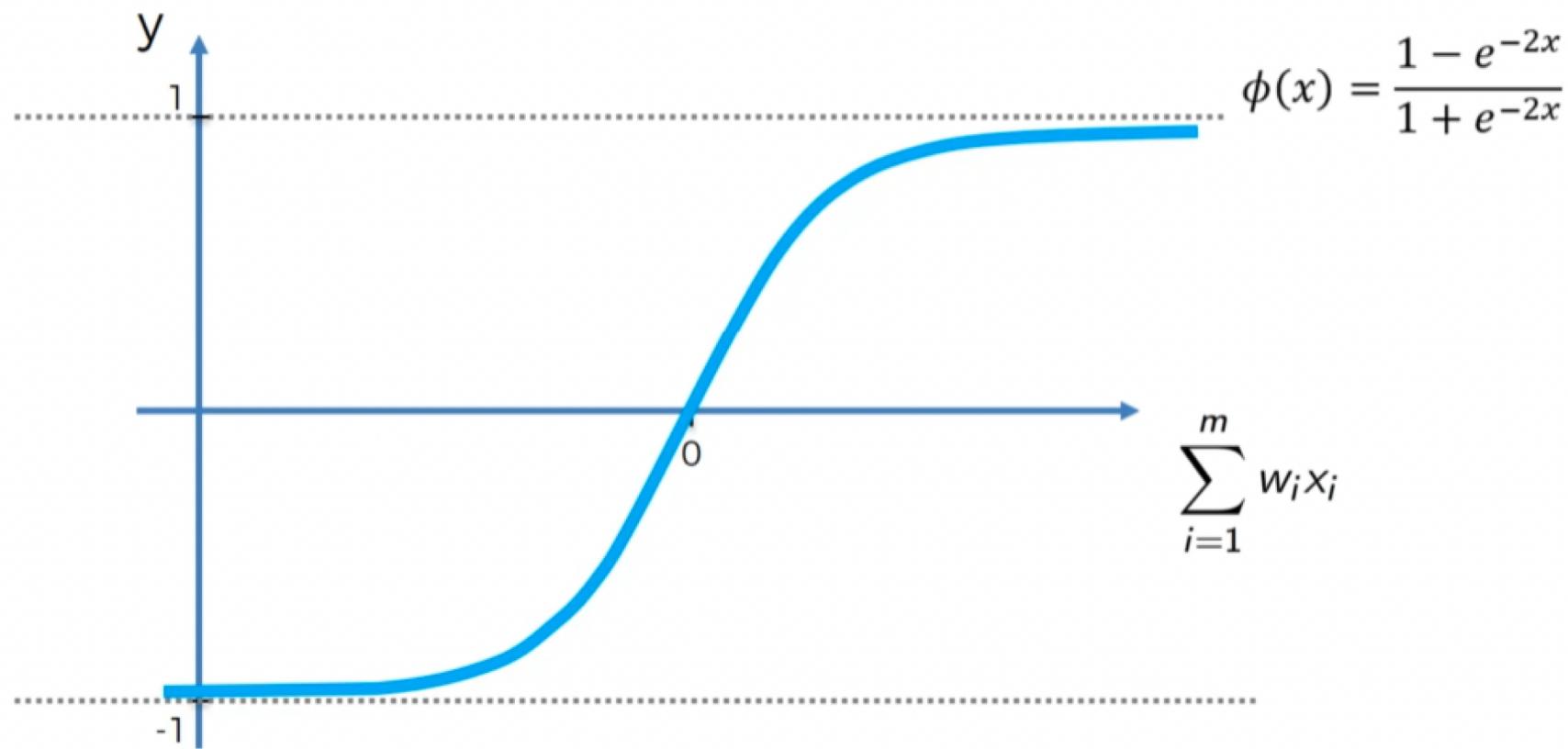
Sigmoid Function



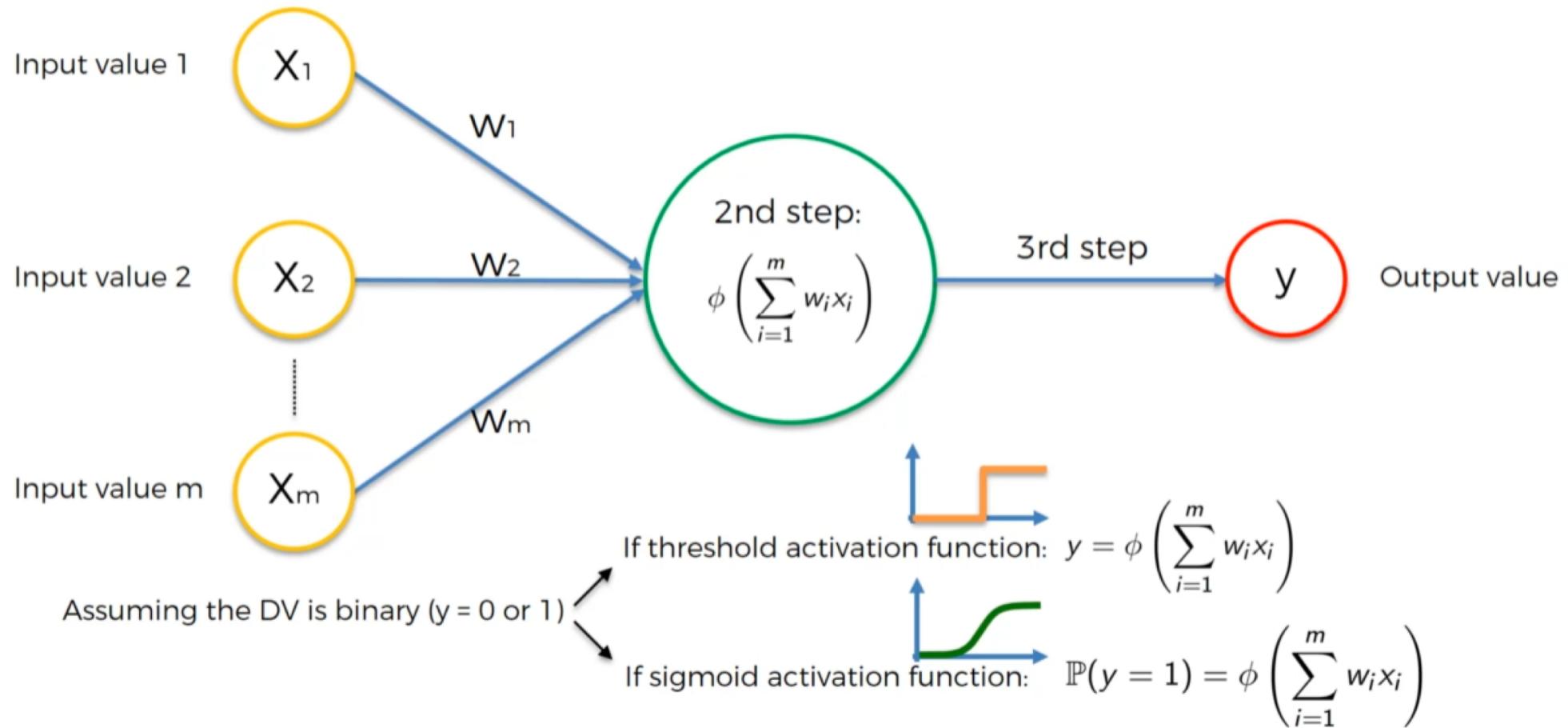
Rectifier Function



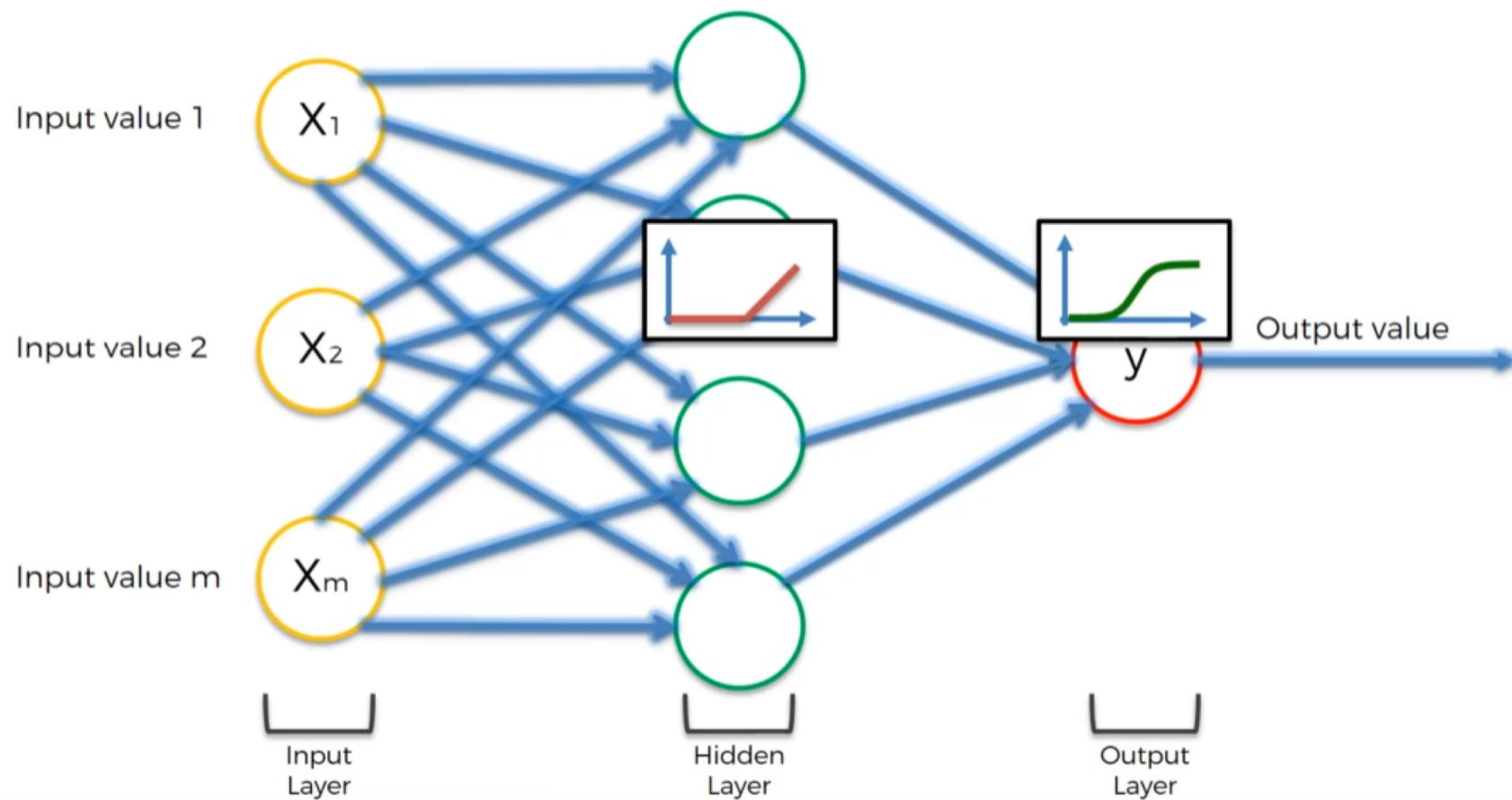
Hyperbolic Tangent Function



Activation Function

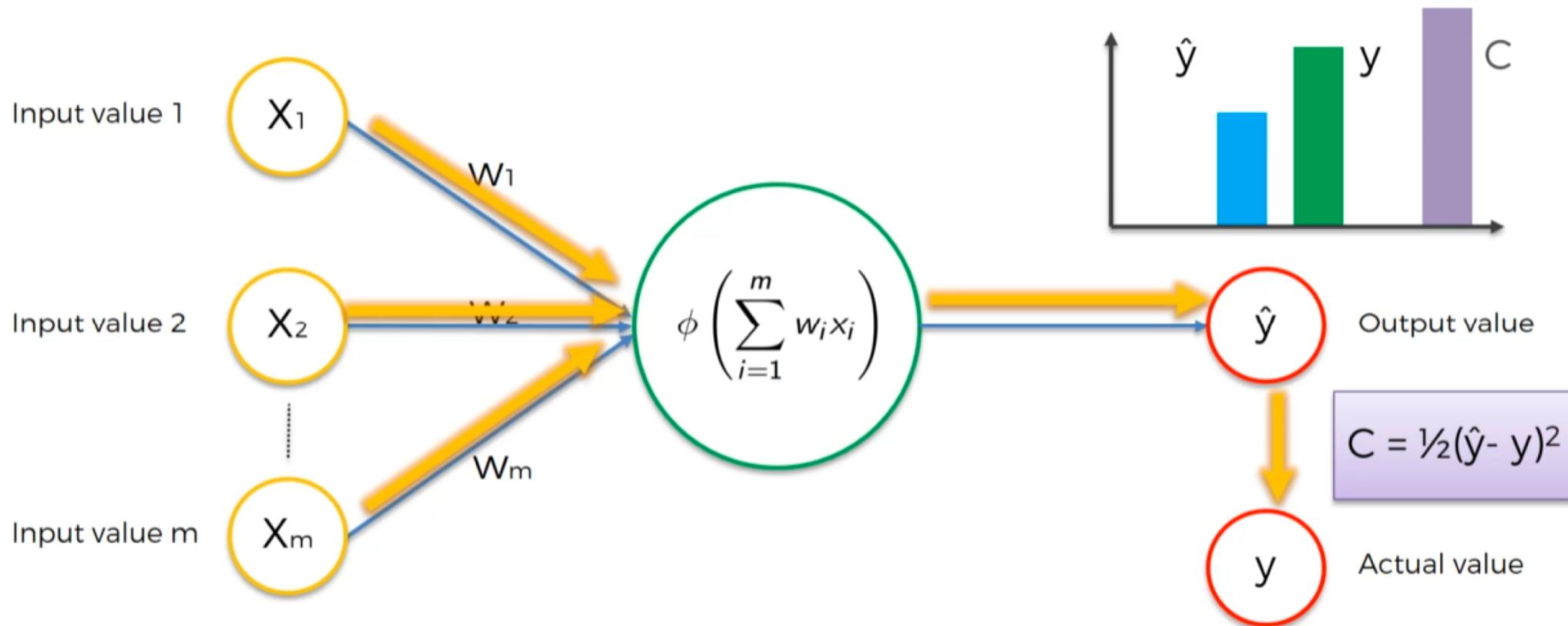


Activation Function

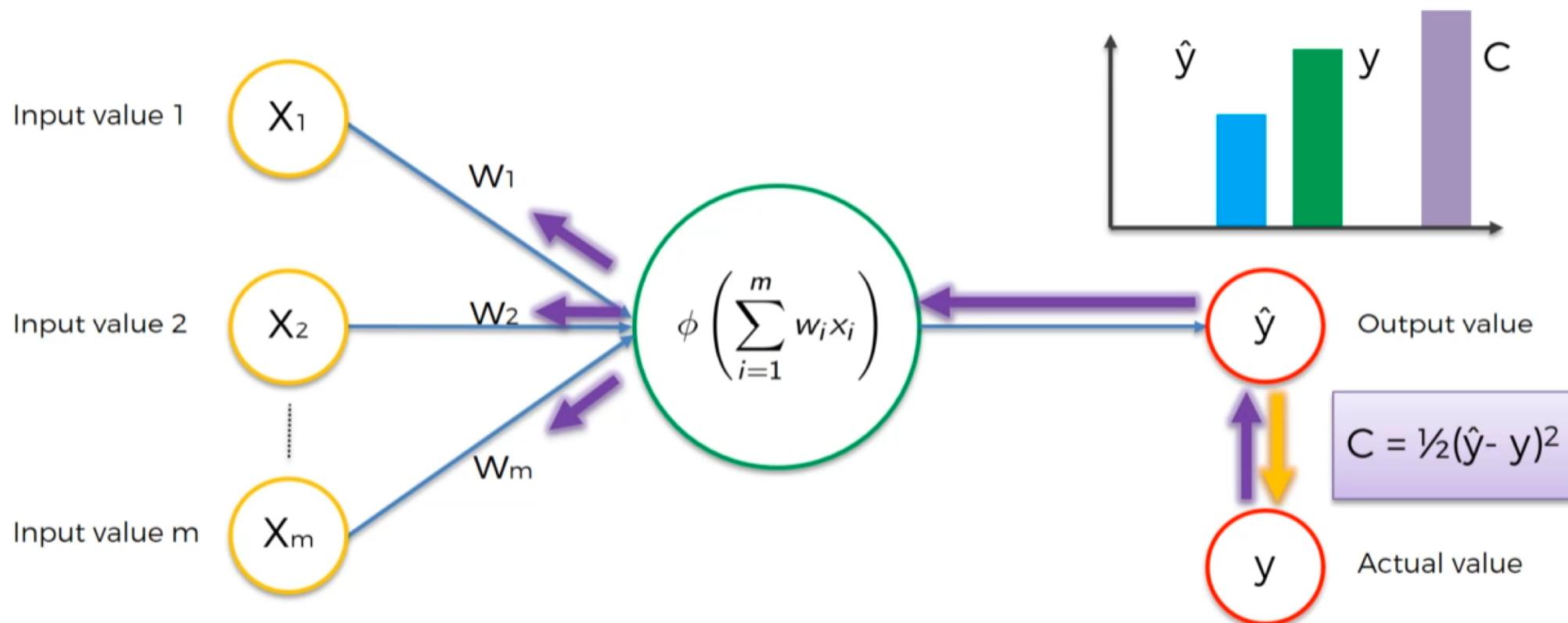


How NN learn ?

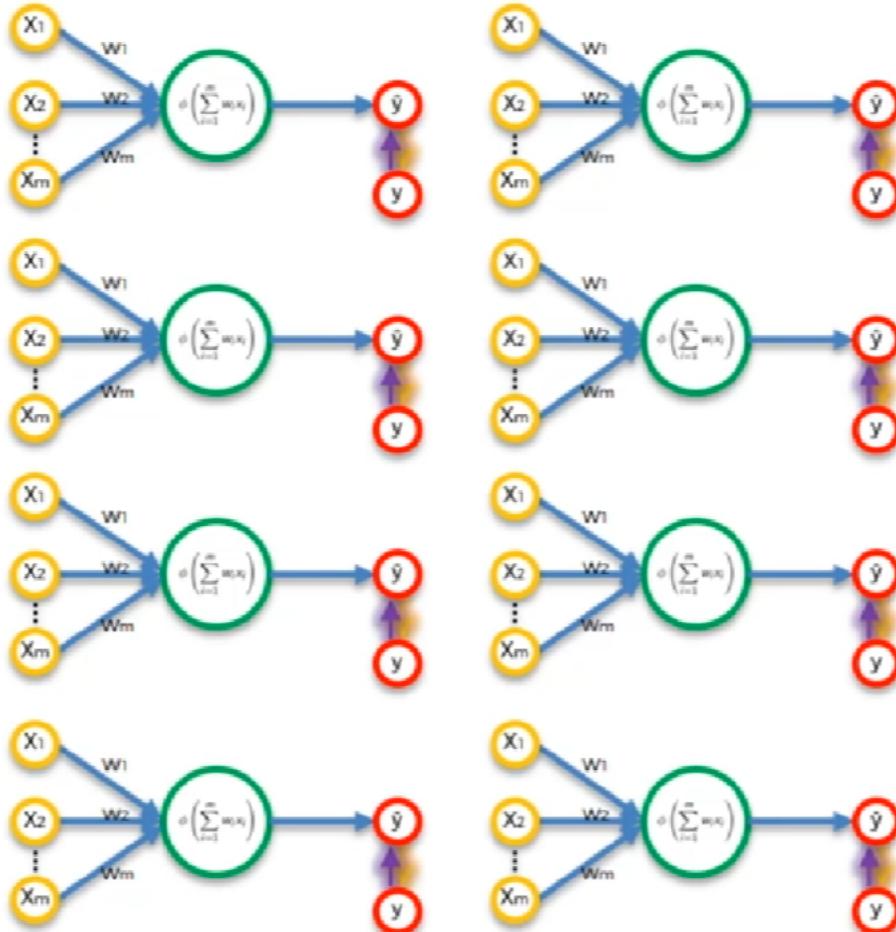
Neural Network - learn



Neural Network - learn



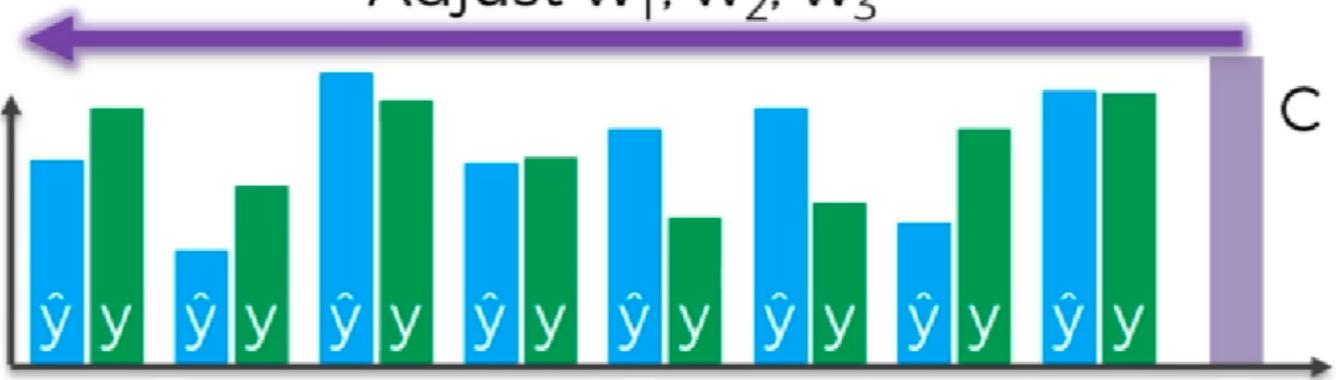
Neural Network - learn



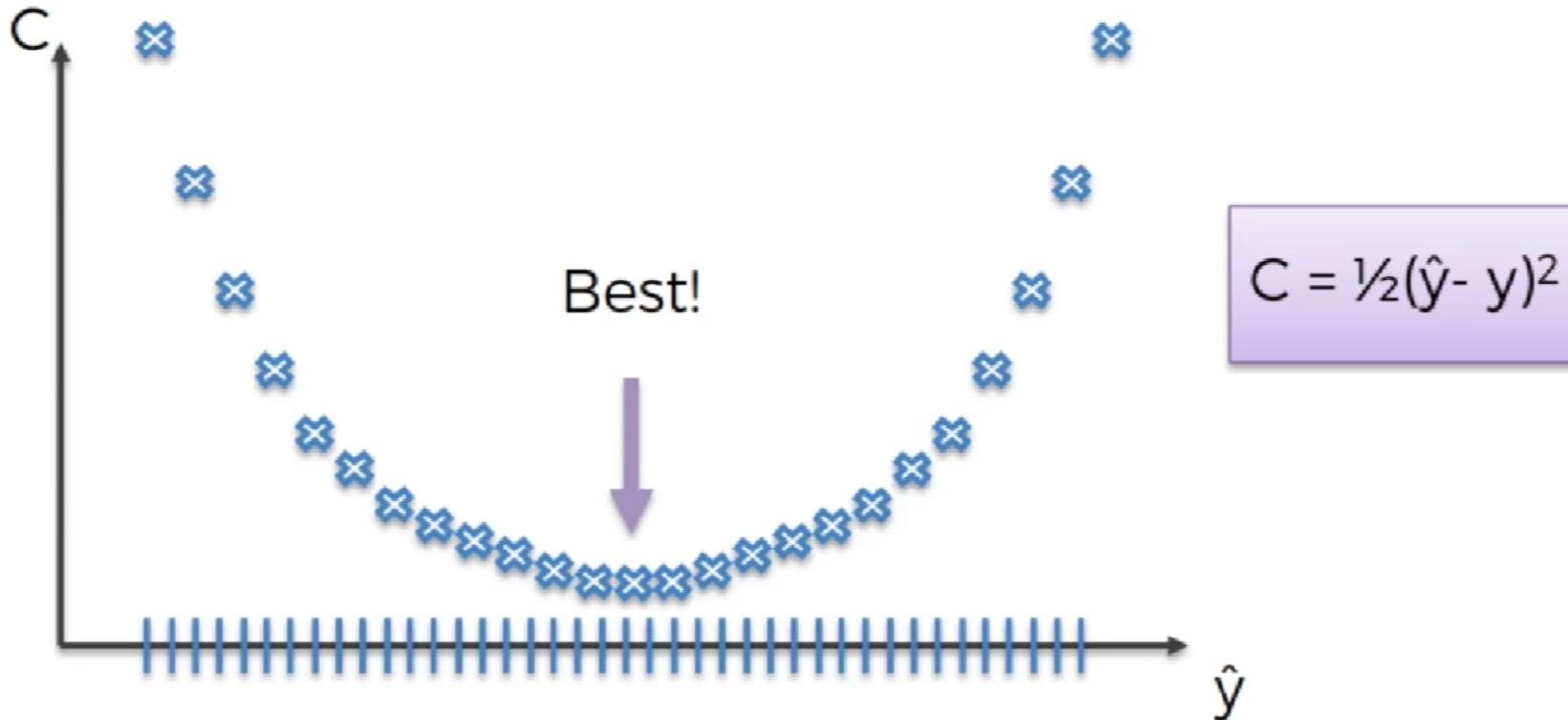
Row ID	Study Hrs	Sleep Hrs	Quiz	Exam
1	12	6	78%	93%
2	22	6.5	24%	68%
3	115	4	100%	95%
4	31	9	67%	75%
5	0	10	58%	51%
6	5	8	78%	60%
7	92	6	82%	89%
8	57	8	91%	97%

$$C = \sum \frac{1}{2}(\hat{y} - y)^2$$

Adjust w_1, w_2, w_3



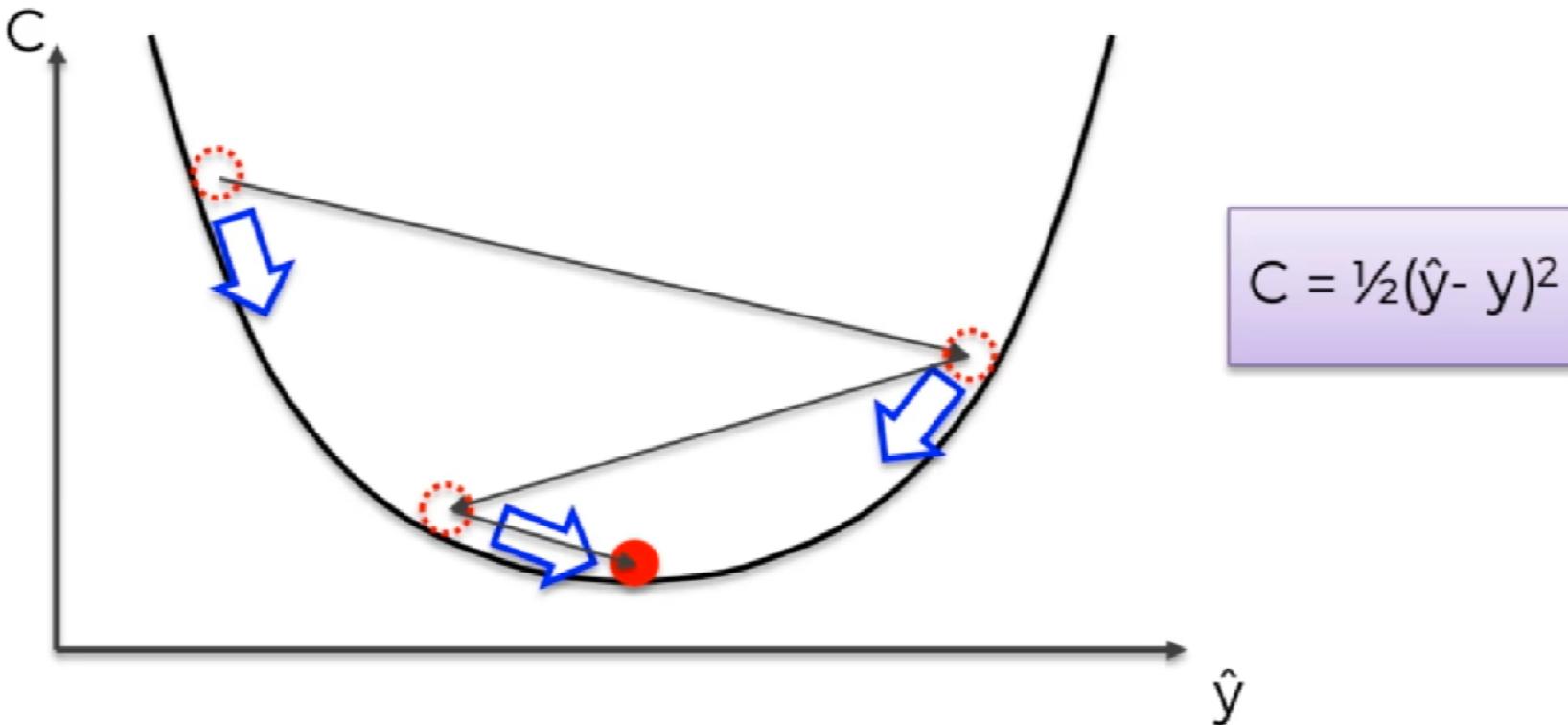
Gradient Descent



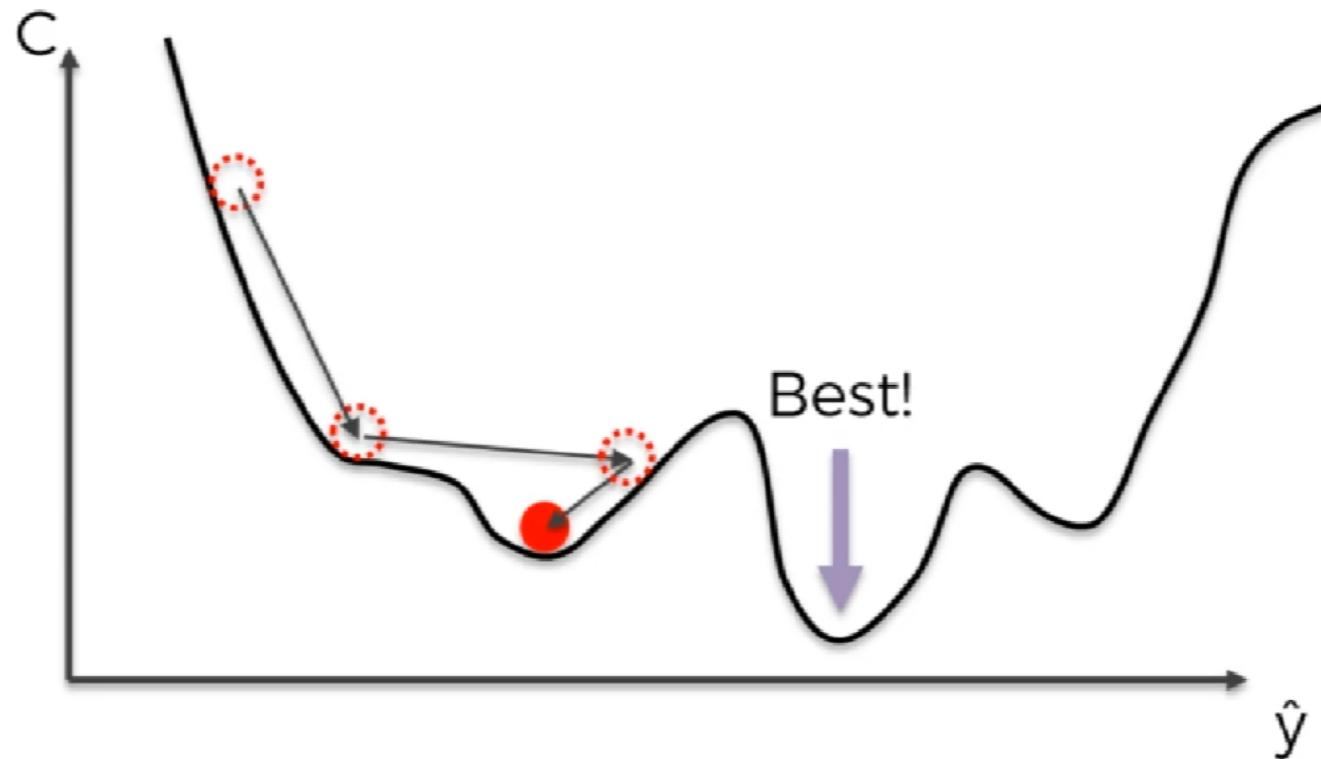
Curse of Dimensionality

- As the dimensionality of features increases, the number of configurations grow exponentially and thus the number of configurations covered by observations decreases

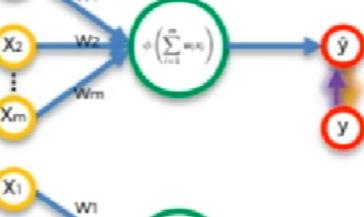
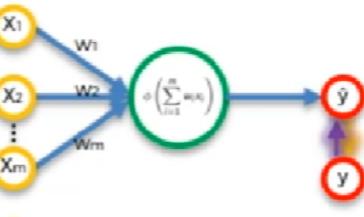
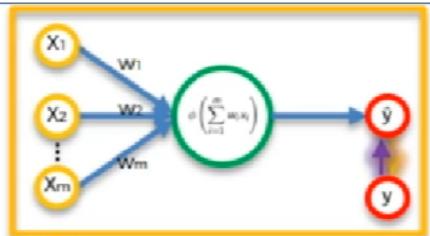
Gradient Descent



Stochastic Gradient Descent



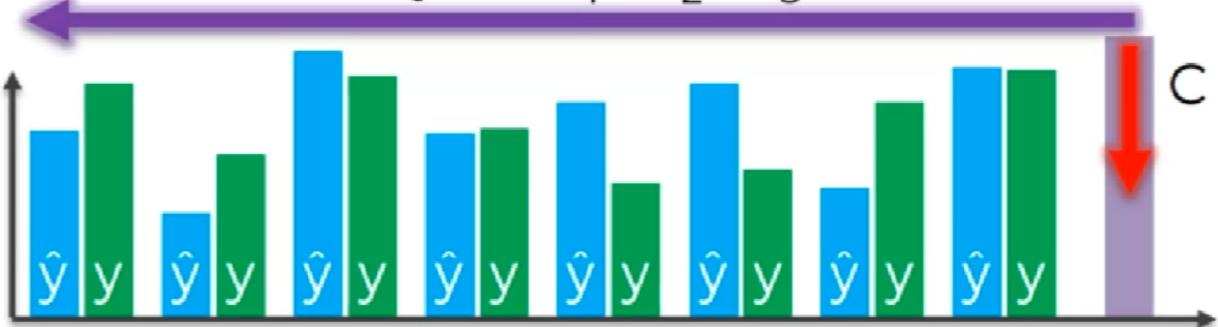
Stochastic Gradient Descent



Row ID	Study Hrs	Sleep Hrs	Quiz	Exam
1	12	6	78%	93%
2	22	6.5	24%	68%
3	115	4	100%	95%
4	31	9	67%	75%
5	0	10	58%	51%
6	5	8	78%	60%
7	92	6	82%	89%
8	57	8	91%	97%

$$C = \sum \frac{1}{2}(\hat{y} - y)^2$$

Adjust w_1, w_2, w_3



Stochastic Gradient Descent

Row ID	Study Hrs	Sleep Hrs	Quiz	Exam
1	12	6	78%	93%
2	22	6.5	24%	68%
3	115	4	100%	95%
4	31	9	67%	75%
5	0	10	58%	51%
6	5	8	78%	60%
7	92	6	82%	89%
8	57	8	91%	97%

Upd w's 

Row ID	Study Hrs	Sleep Hrs	Quiz	Exam
1	12	6	78%	93%
2	22	6.5	24%	68%
3	115	4	100%	95%
4	31	9	67%	75%
5	0	10	58%	51%
6	5	8	78%	60%
7	92	6	82%	89%
8	57	8	91%	97%

Upd w's 

Batch
Gradient
Descent

Stochastic
Gradient
Descent

Stochastic Gradient Descent - Steps

- Randomly initialize the weights to small numbers close to 0 ($\neq 0$)
- Input the first observation in the input layer, each feature in one input node
- Forward Propagation:
 - From left to right
 - The neurons are activated in a way that the impact of each neuron's activation is limited by the weights
 - Propagate until getting the predicted result
- Compare the predicted result to the actual result
- Measure the generated error

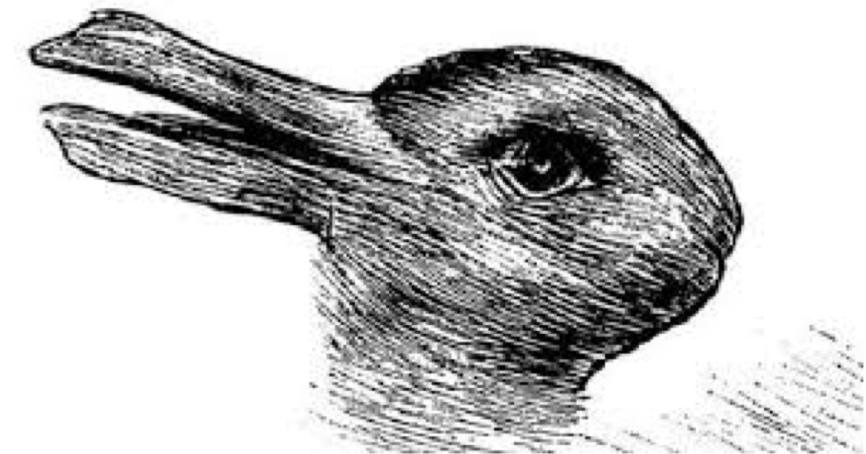
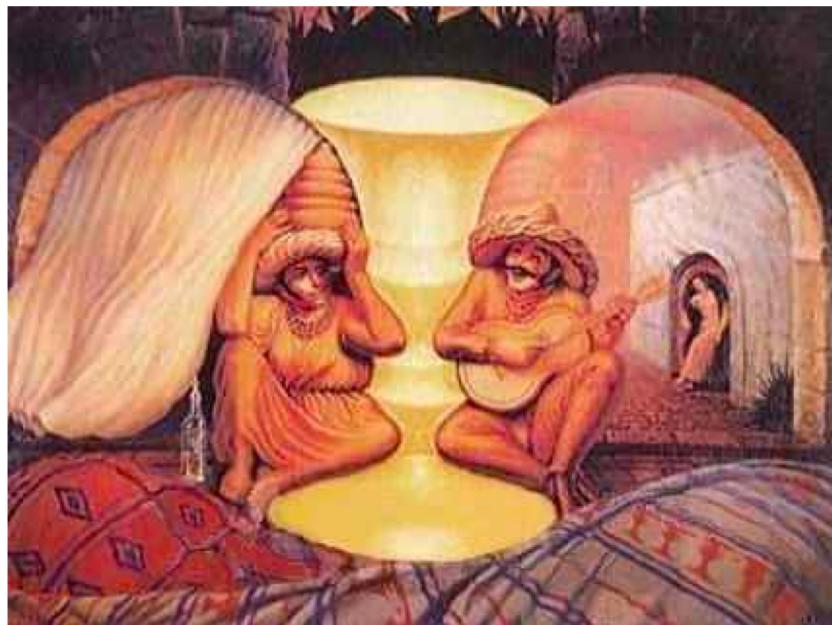
Stochastic Gradient Descent - Steps

- Back Propagation
 - From right to left
 - The error is back propagated
 - Update the weights according to how much they are responsible for the error
 - The learning rate decides by how much we update the weights
- Repeat the steps and update the weights
 - after each observation
 - After a batch of observations
- When the whole training set passes through the ANN, that makes an epoch. Redo more epochs.

CNN

Convolutional Neural Network

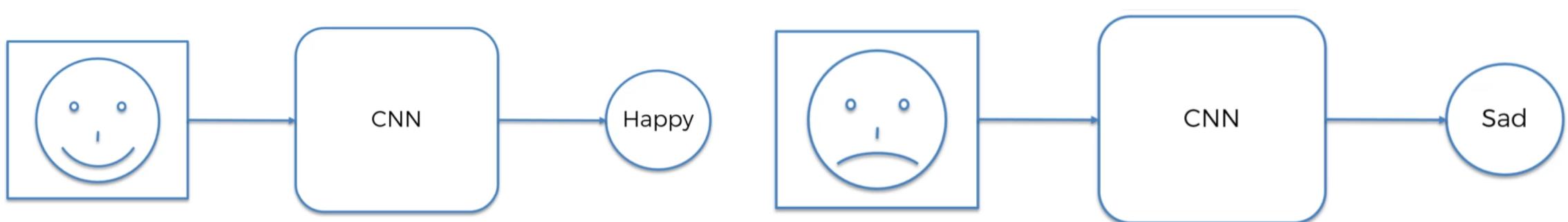
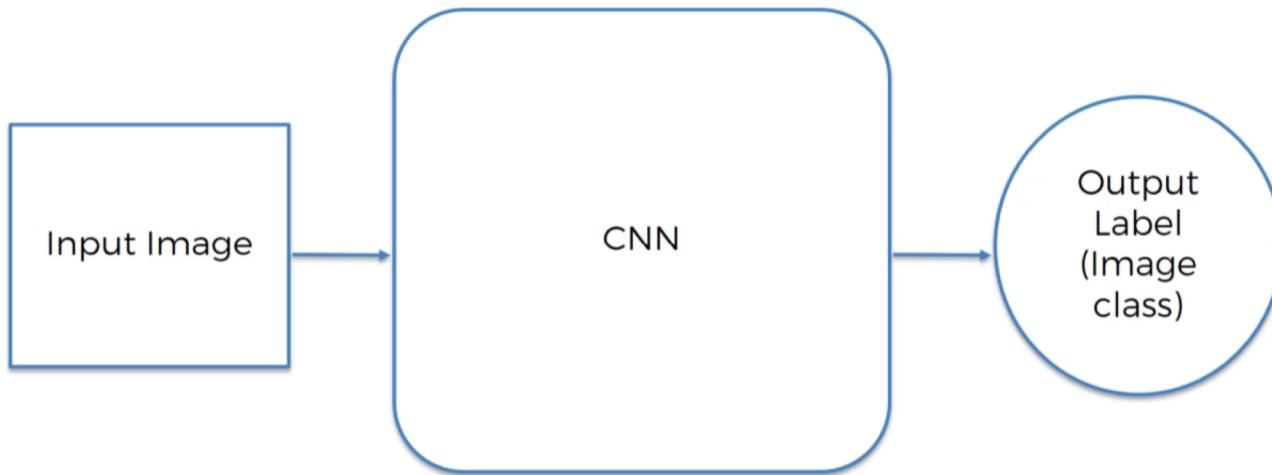
CNN



CNN



CNN



CNN

B / W Image 2x2px

Pixel 1	Pixel 2
Pixel 3	Pixel 4

2d array

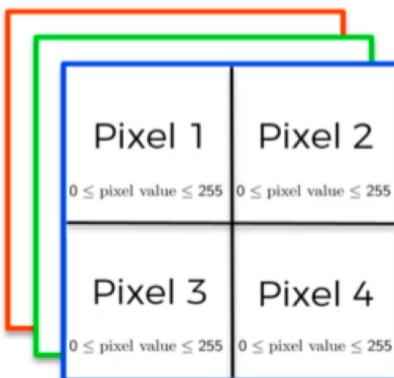
Pixel 1 0 ≤ pixel value ≤ 255	Pixel 2 0 ≤ pixel value ≤ 255
Pixel 3 0 ≤ pixel value ≤ 255	Pixel 4 0 ≤ pixel value ≤ 255

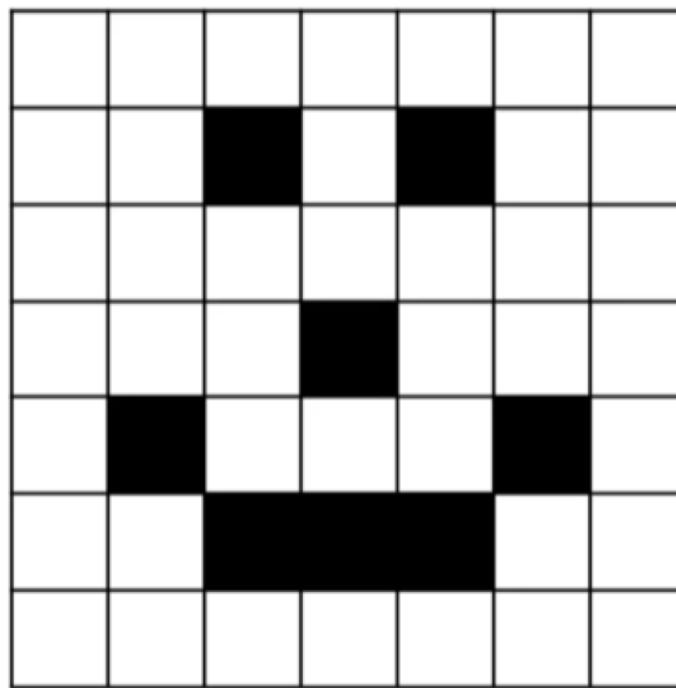
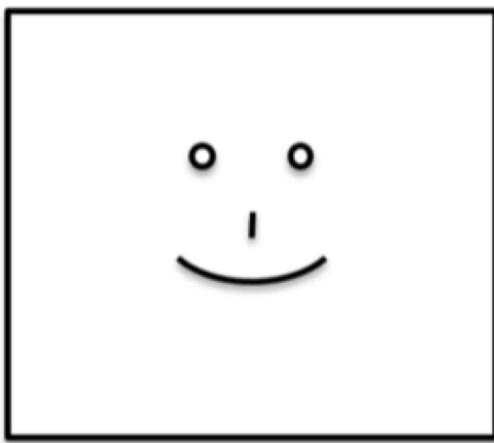
Colored Image 2x2px

Pixel 1	Pixel 2
Pixel 3	Pixel 4

3d array

Pixel 1 0 ≤ pixel value ≤ 255	Pixel 2 0 ≤ pixel value ≤ 255
Pixel 3 0 ≤ pixel value ≤ 255	Pixel 4 0 ≤ pixel value ≤ 255





0	0	0	0	0	0	0	0
0	1	0	0	0	0	1	0
0	0	0	0	0	0	0	0
0	0	0	1	0	0	0	0
0	1	0	0	0	0	1	0
0	0	1	1	1	0	0	0
0	0	0	0	0	0	0	0

CNN - Steps

- Step 1: Convolutions
- Step 2: Max Pooling
- Step 3: Fattening
- Step 4: Full Connection

Step 1 – Convolution

$$(f * g)(t) \stackrel{\text{def}}{=} \int_{-\infty}^{\infty} f(\tau) g(t - \tau) d\tau$$

- Convolution is a mathematical operation on two functions (f and g) to produce a third function that expresses how the shape of one is modified by the other
- convolution refers to both the result function and to the process of computing it

Step 1 – Convolution

0	0	0	0	0	0	0	0
0	1	0	0	0	1	0	0
0	0	0	0	0	0	0	0
0	0	0	1	0	0	0	0
0	1	0	0	0	1	0	0
0	0	1	1	1	0	0	0
0	0	0	0	0	0	0	0



0	0	1
1	0	0
0	1	1

=

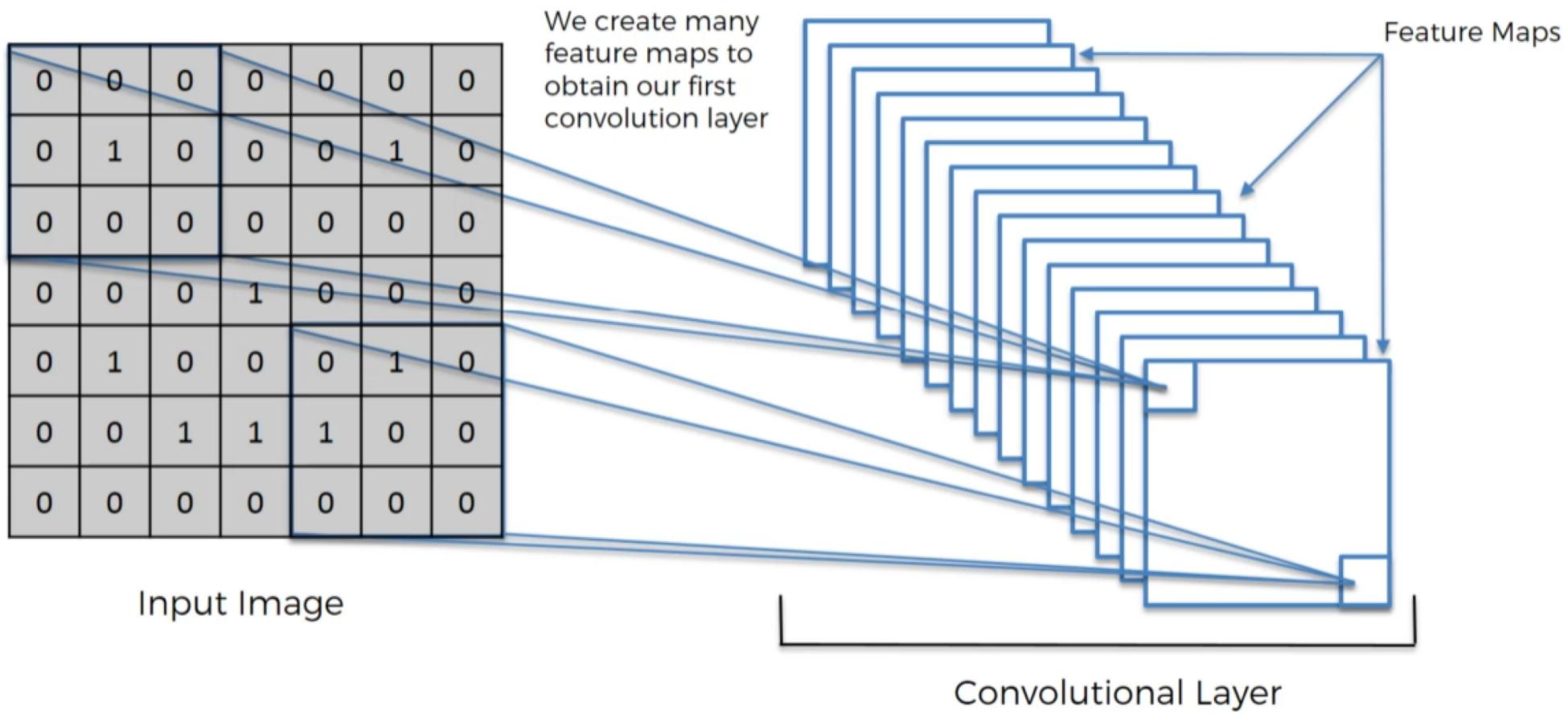
0	1	0	0	0
0	1	1	1	0
1	0	1	2	1
1	4	2	1	0
0	0	1	2	1

Input Image

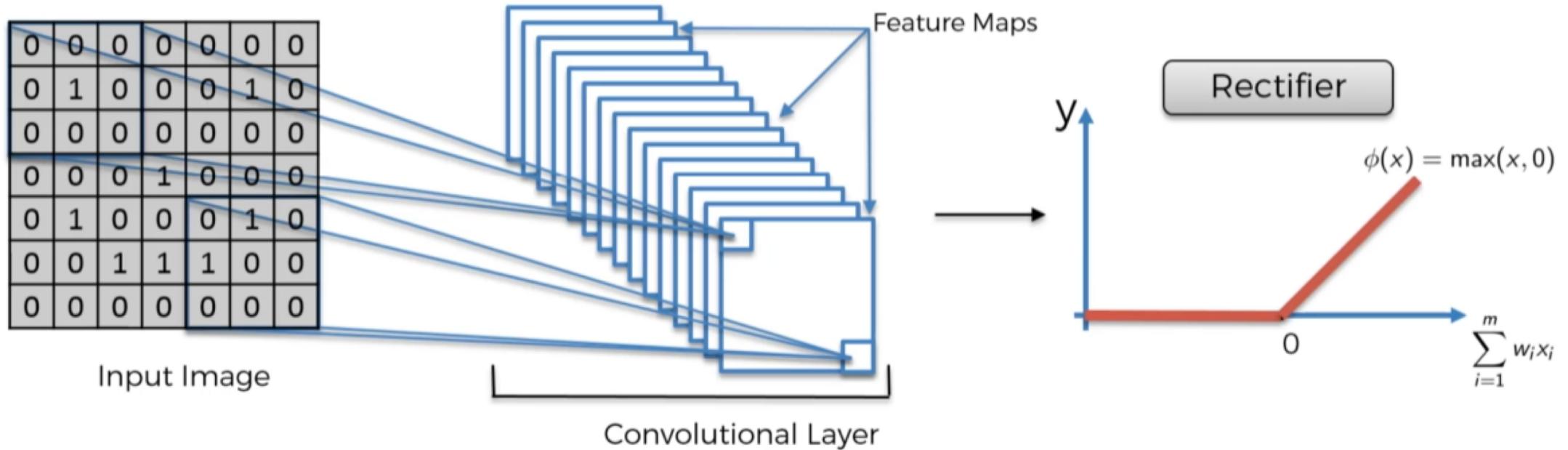
Feature
Detector

Feature Map

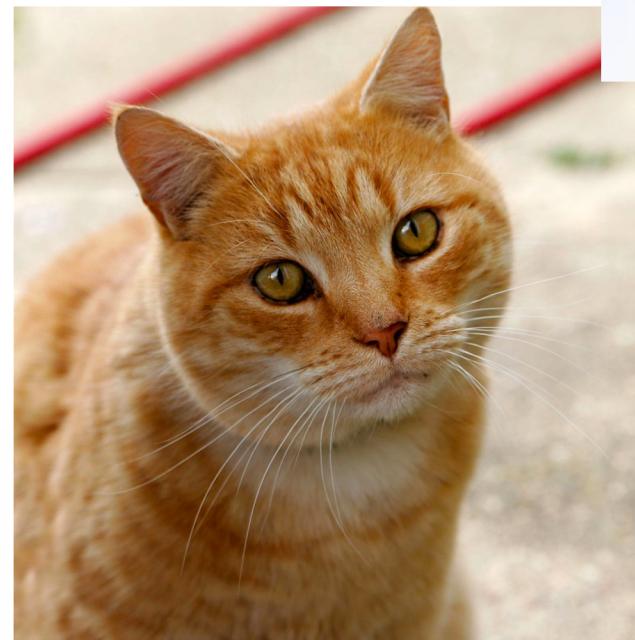
Step 1 – Convolution



Step 1 (B) – ReLu Layer



Step 2 – Max Pooling



Step 2 – Max Pooling

0	1	0	0	0
0	1	1	1	0
1	0	1	2	1
1	4	2	1	0
0	0	1	2	1

Feature Map

Max Pooling



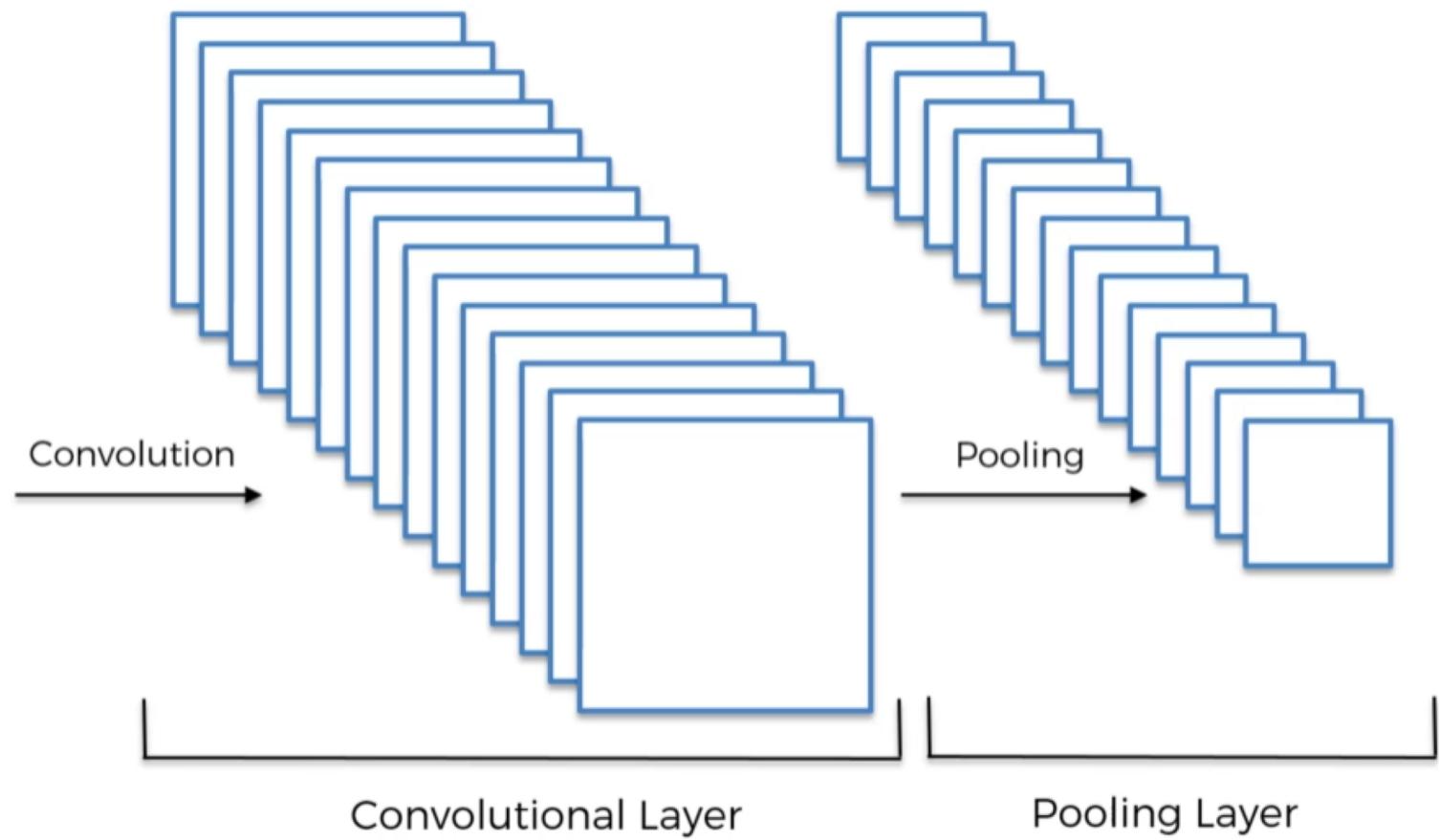
1	1	0
4	2	1
0	2	1

Pooled Feature Map

Step 2 – Max Pooling

0	0	0	0	0	0	0
0	1	0	0	0	1	0
0	0	0	0	0	0	0
0	0	0	1	0	0	0
0	1	0	0	0	1	0
0	0	1	1	1	0	0
0	0	0	0	0	0	0

Input Image



Step 3 – Flattening

1	1	0
4	2	1
0	2	1

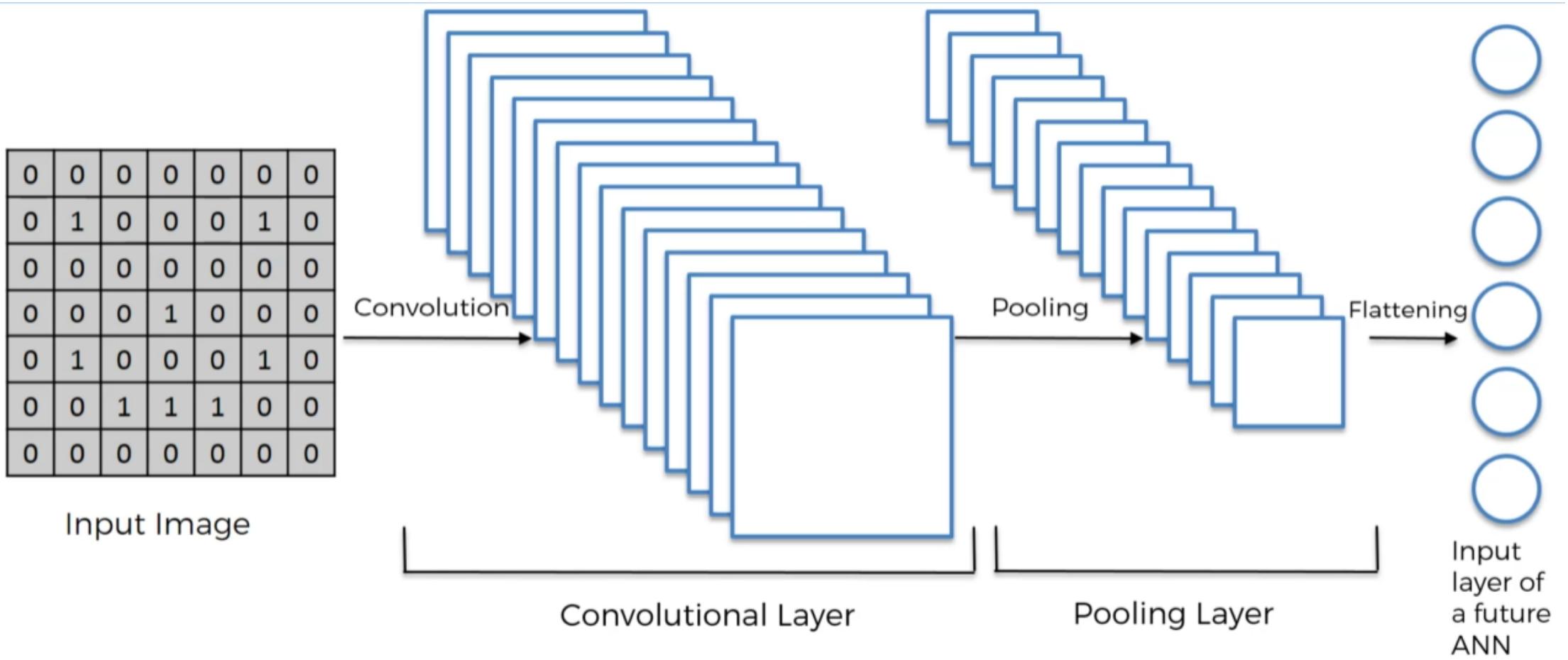
Pooled Feature Map

Flattening

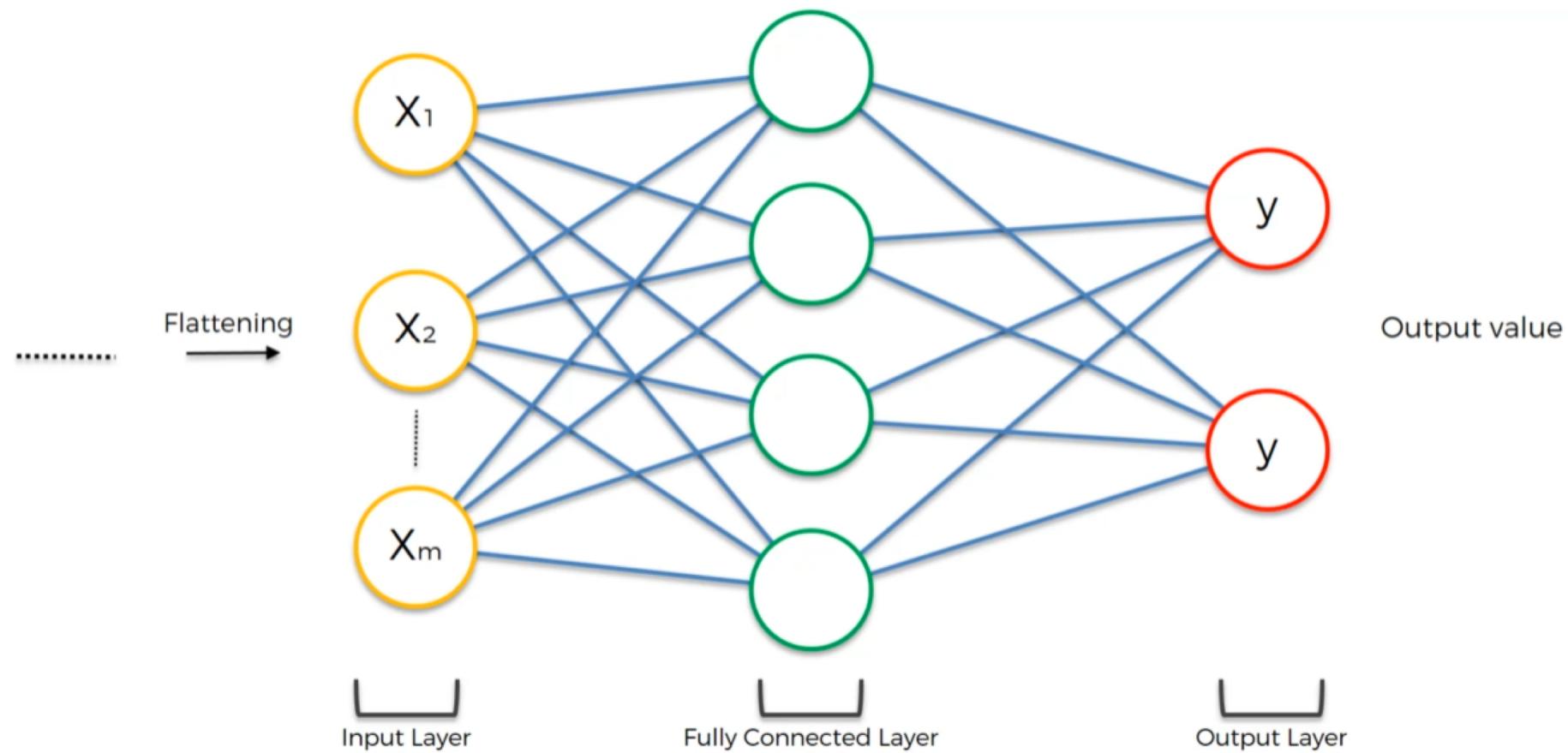


1
1
0
4
2
1
0
2
1

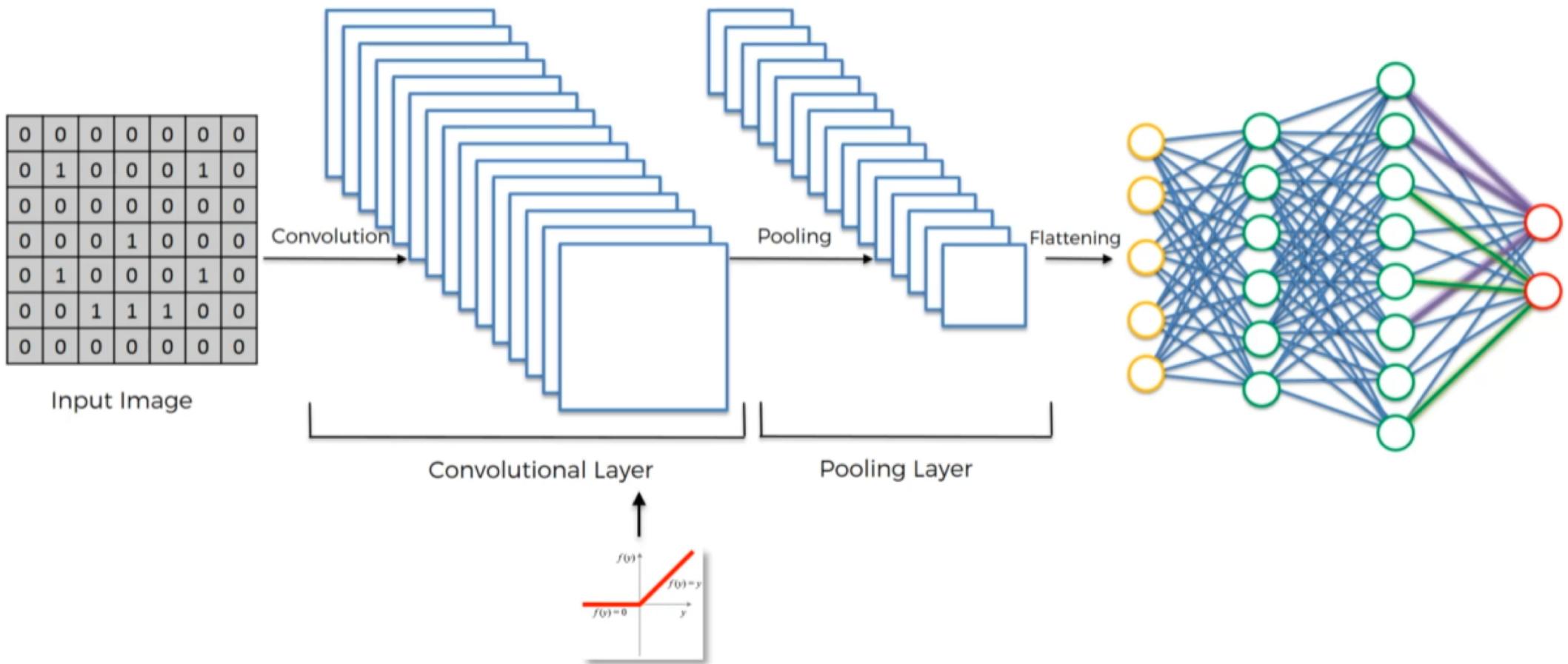
Step 3 – Flattening



Step 4 – Full Connection



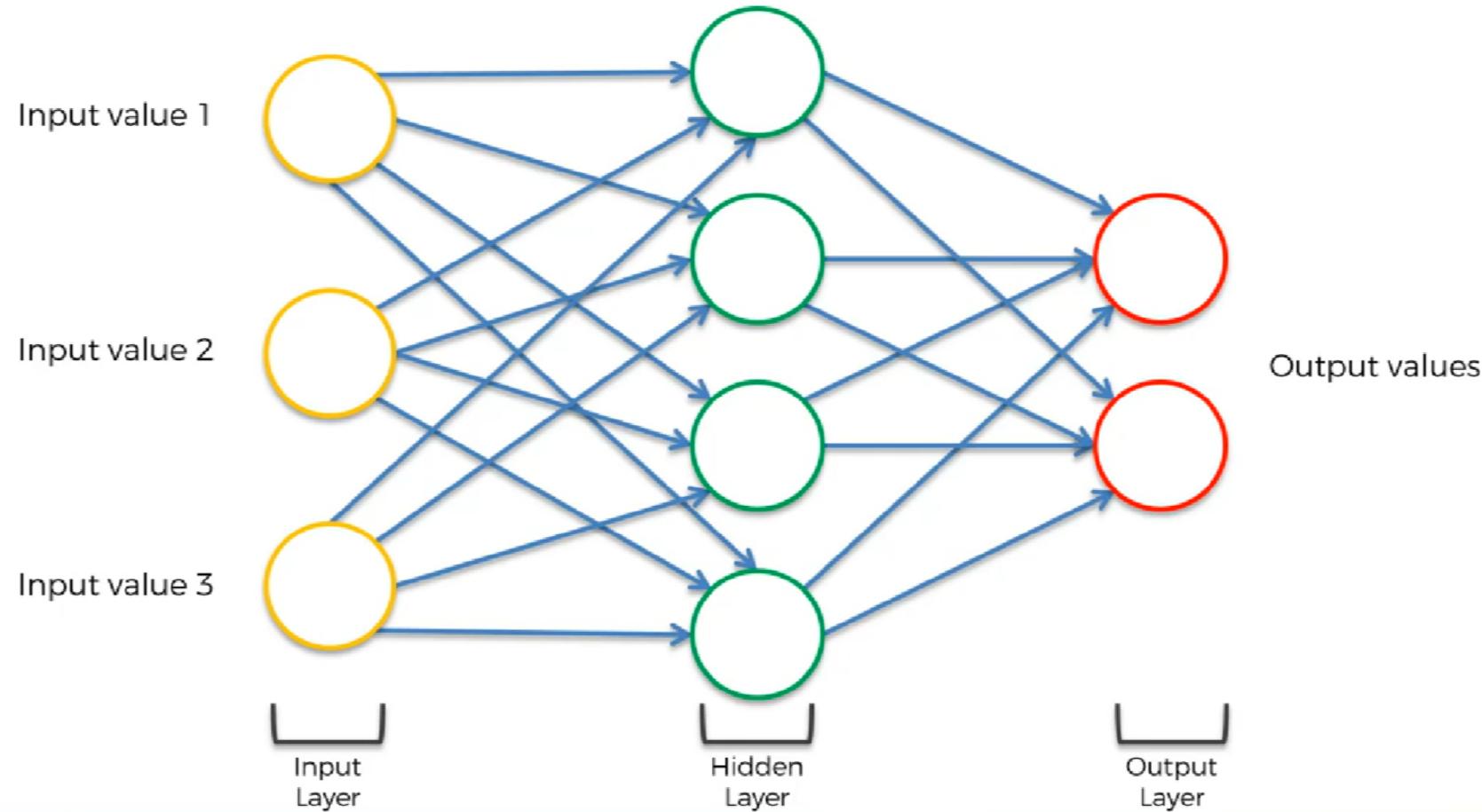
Step 4 – Full Connection



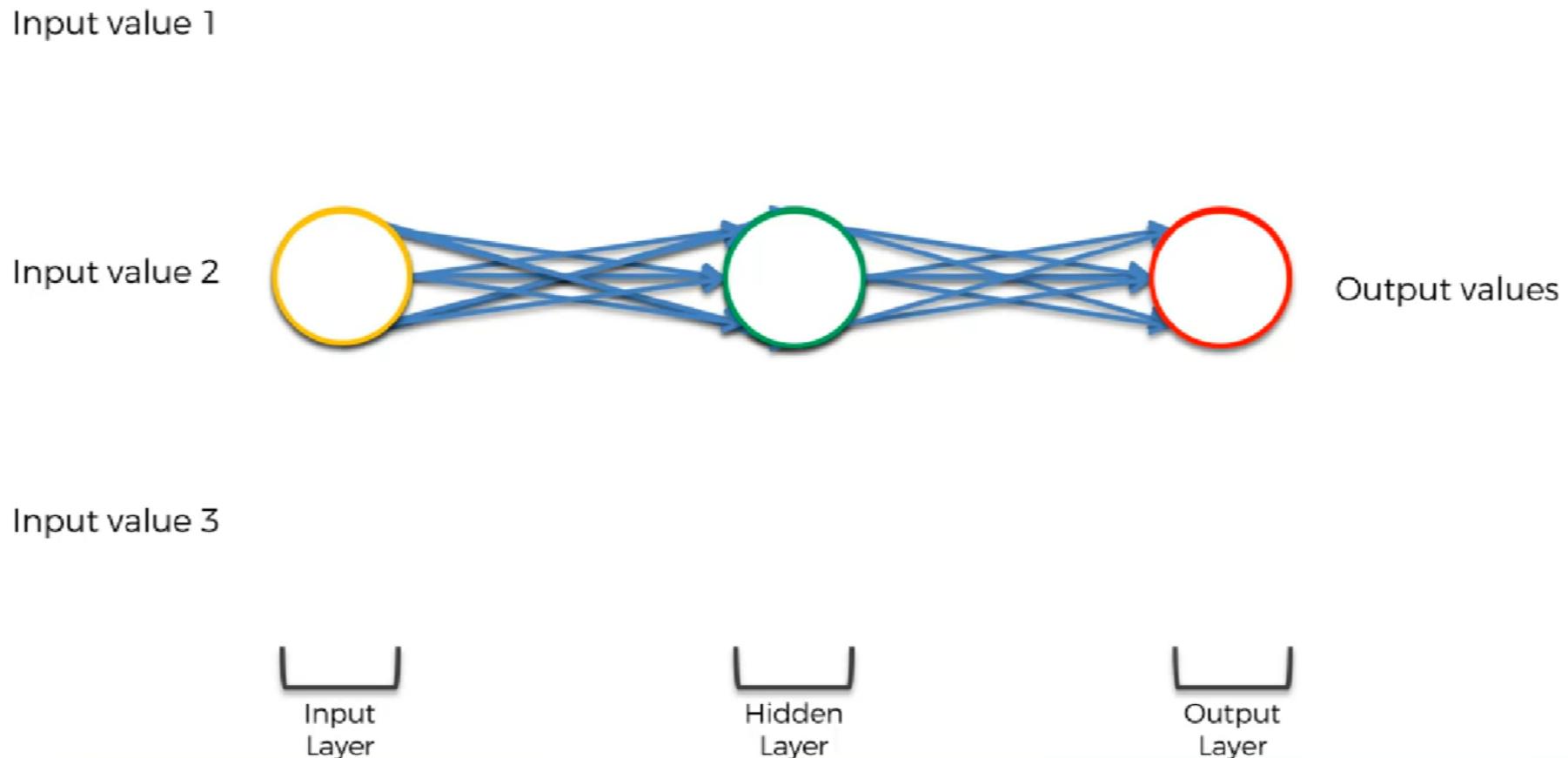
RNN

Recurrent Neural Network

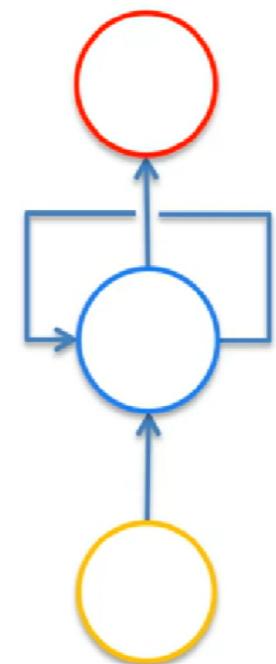
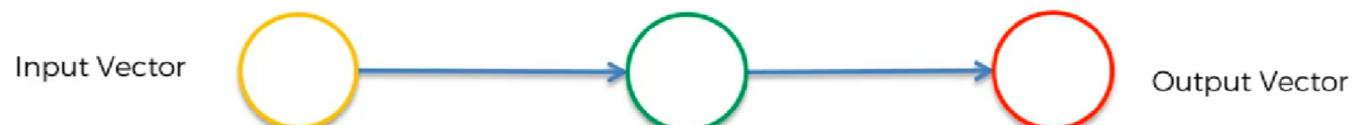
NN



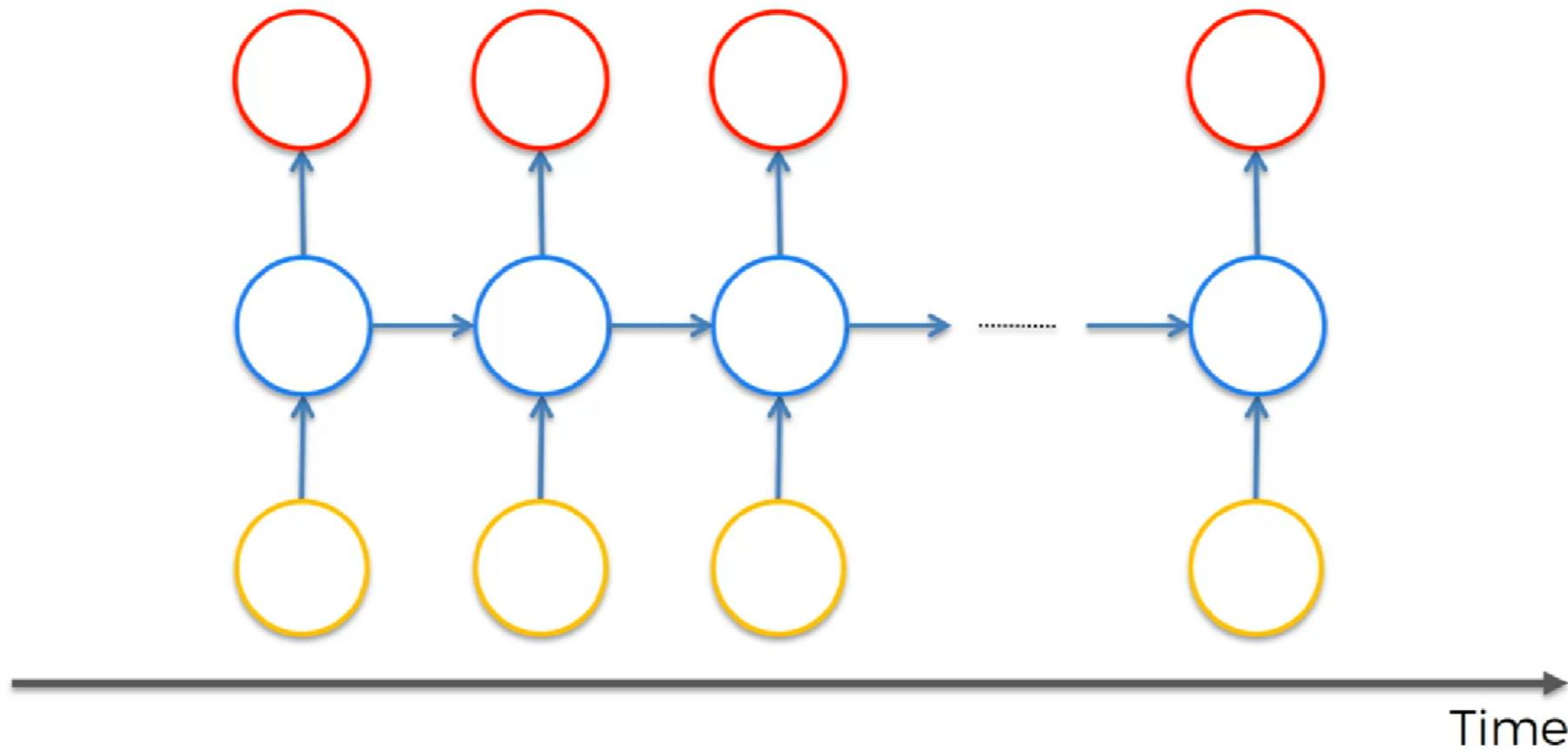
RNN



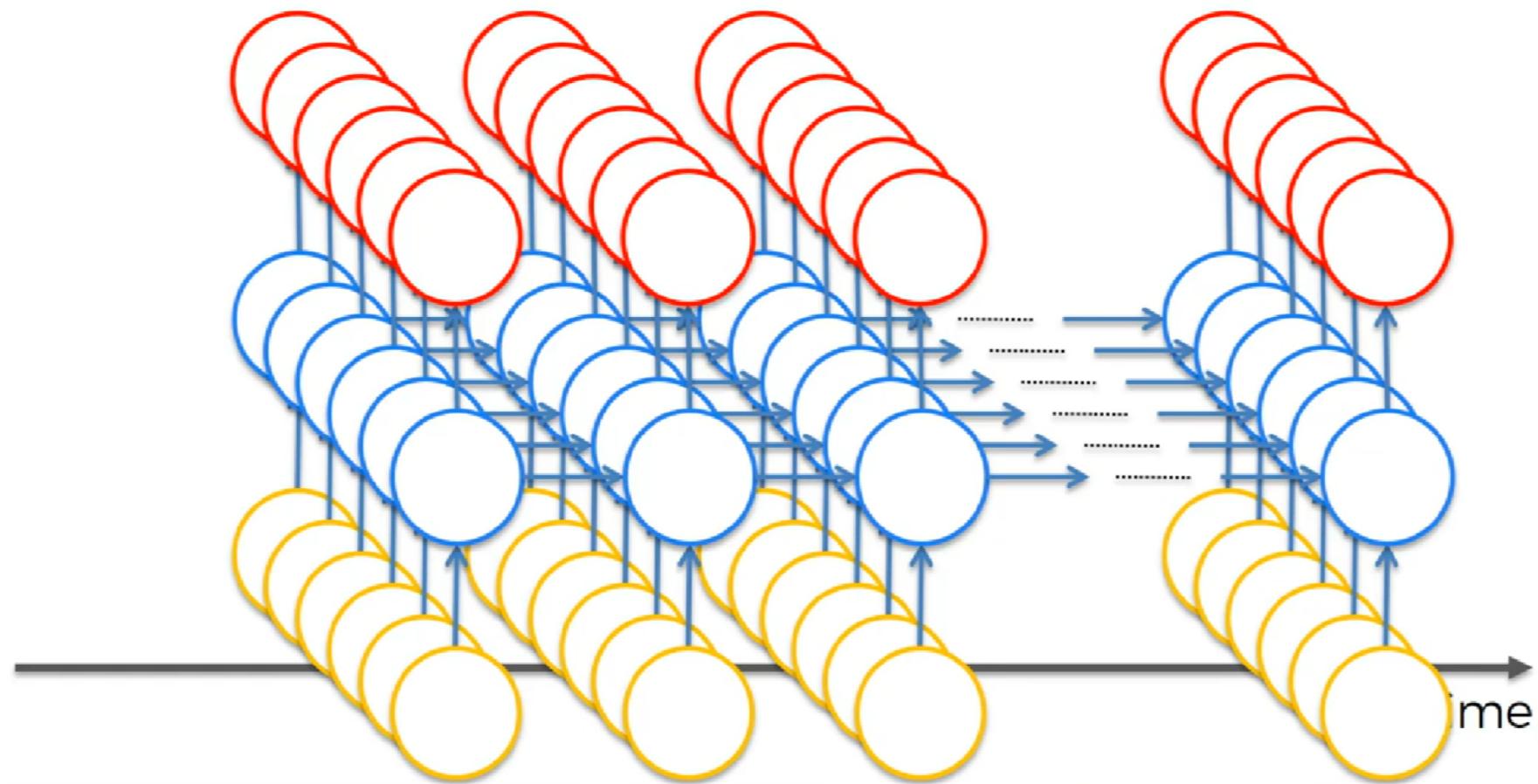
RNN



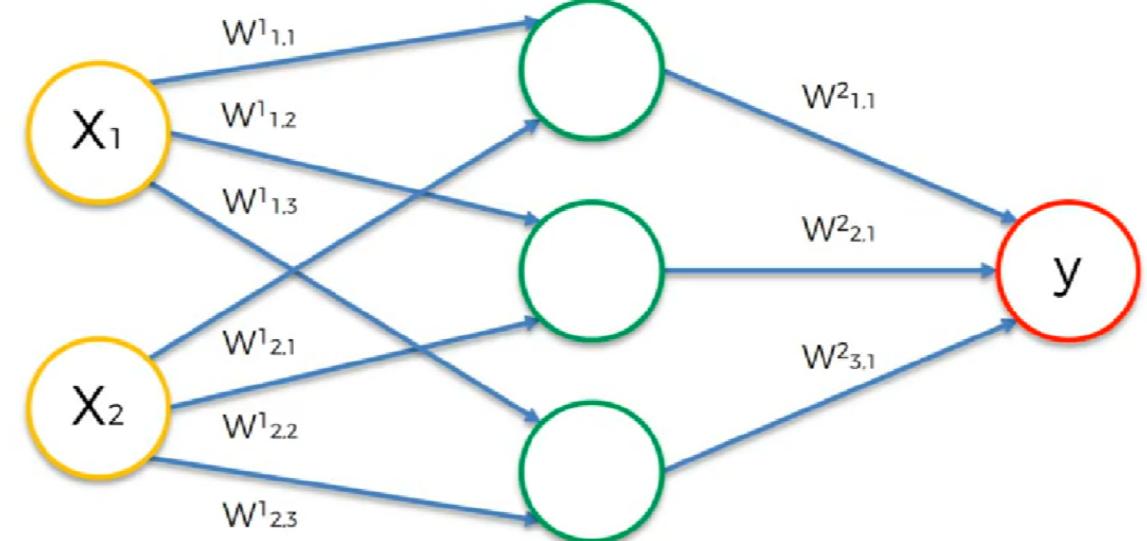
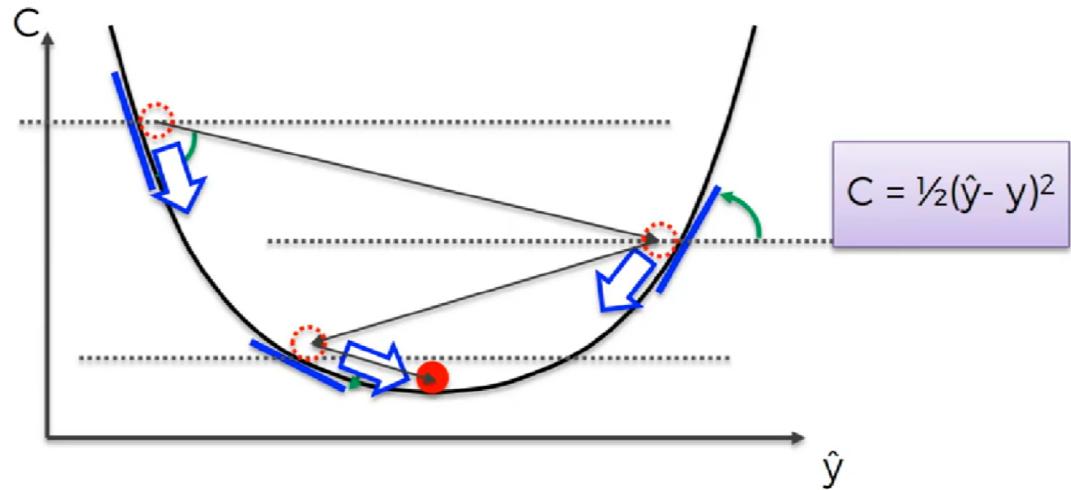
RNN



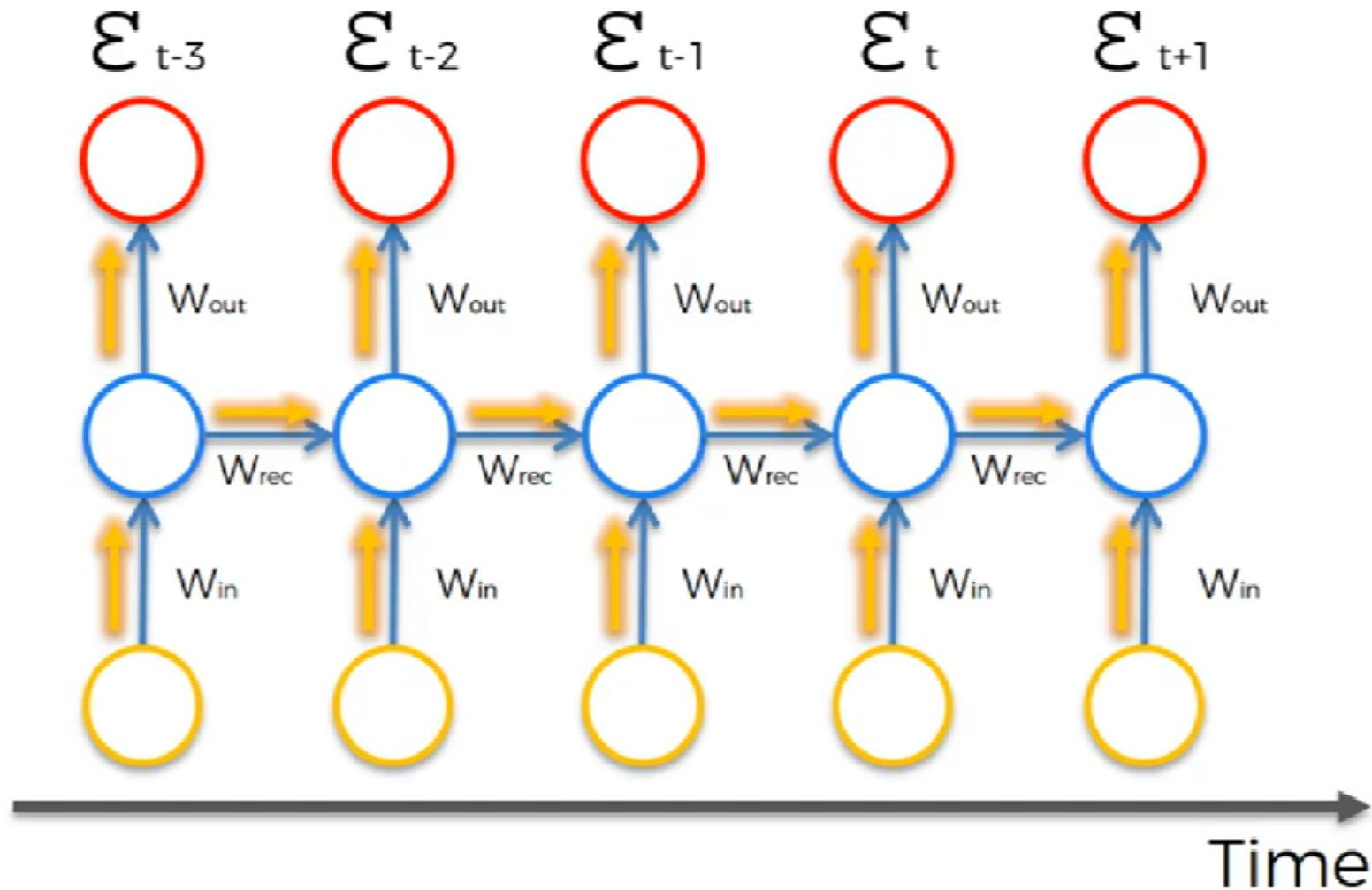
RNN



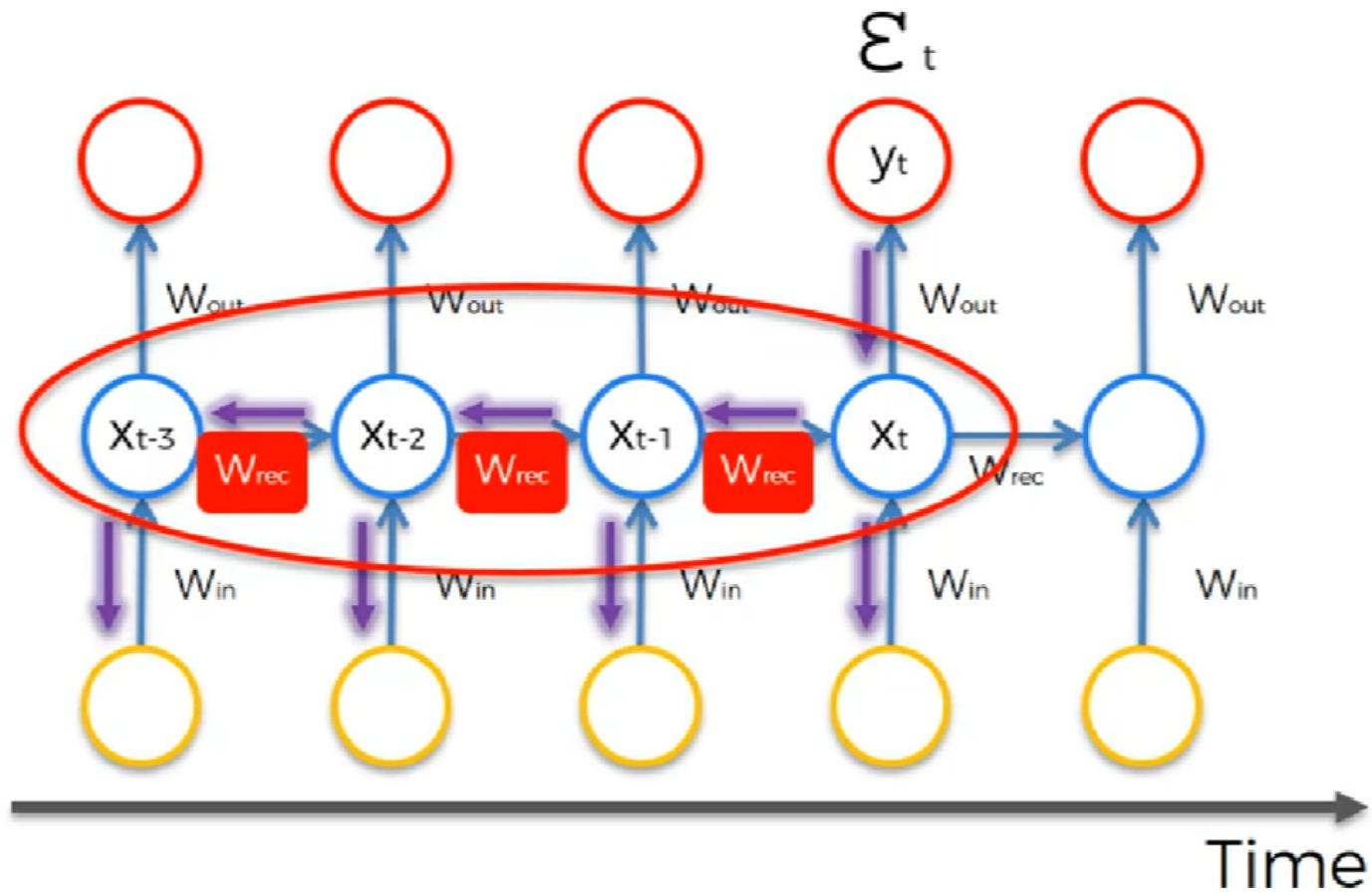
Vanishing Gradient Problem



Vanishing Gradient Problem



Vanishing Gradient Problem



$w_{rec} \sim \text{small}$ \rightarrow Vanishing
 $w_{rec} \sim \text{large}$ \rightarrow Exploding

Vanishing Gradient Problem - Solutions

- Exploding Gradient
 - Truncated Backpropagation
 - Penalties
 - Gradient Clipping
- Vanishing Gradient
 - Weight initialization
 - Echo State Network
 - Long Short-Term Memory Networks (LSTMs)

