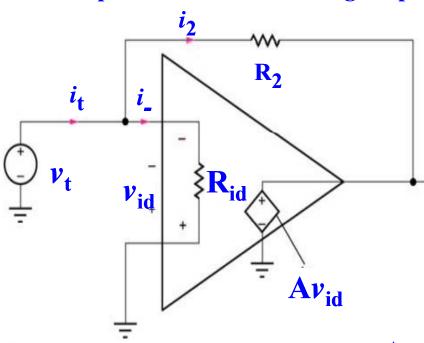


### ESc201, Lecture 24: Operational Amplifier

#### Input resistances for non-ideal OpAmp:

Difficult to derive with non-ideality in both. Hence do it one at a time (Let  $R_0=0$ )

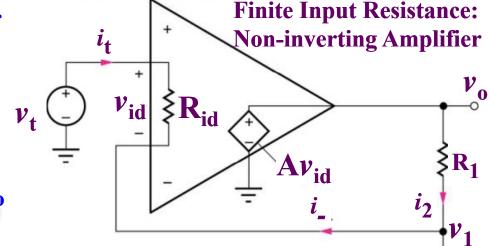
Finite Input Resistance: Inverting Amplifier



$$\vec{i}_1 = i - + i_2 = \frac{v_1}{R_{id}} + \frac{v_1 - v_0}{R_2} = \frac{v_1}{R_{id}} + \frac{v_1 - Av_1}{R_2}$$

$$\therefore G_1 = \frac{i_1}{v_1} = \frac{1}{R_{id}} + \frac{1+A}{R_2} \text{ Hence with } R_1$$

$$R_{in} = R_1 + R_{id} \left| \frac{R_2}{1+A} \cong R_1 + \left( \frac{R_2}{1+A} \right) \right|$$



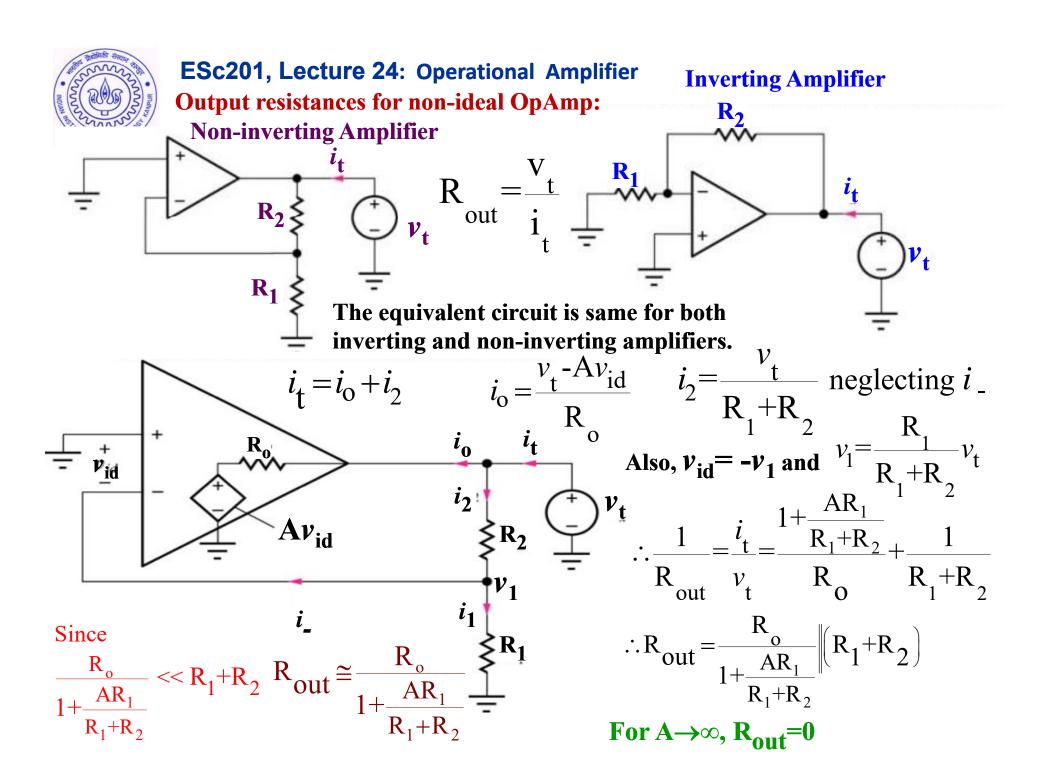
Test voltage source  $v_t$  is applied to input and current  $i_t$  is calculated.

$$\mathbf{s} \ \mathbf{i}_{1} = \mathbf{i}_{2}, v_{1} = \mathbf{i}_{1} \mathbf{R}_{1} \stackrel{\mathbf{R}_{2}}{=} \overline{\mathbf{i}}_{2} \mathbf{R}_{1}$$

 $\vec{i}_{1} = i - + i_{2} = \frac{v_{1}}{R_{id}} + \frac{v_{1} - v_{0}}{R_{2}} = \frac{v_{1}}{R_{id}} + \frac{v_{1} - Av_{1}}{R_{2}} \quad \text{Assuming } i_{-} << i_{2} \text{ implies } i_{1} = i_{2}, v_{1} = i_{1}R_{1} \cong \overline{i_{2}}R_{1} \\
v_{1} \cong \frac{R_{1}}{R_{1} + R_{2}} v_{0} = \beta v_{0} = \beta (A v_{id}) = A \beta (v_{t} - v_{1})$ 

$$\therefore G_1 = \frac{i_1}{v_1} = \frac{1}{R_{id}} + \frac{1+A}{R_2} \text{ Hence with } R_1 \quad v_1 = \frac{A\beta}{1+A\beta} v_t, \text{ or } = \frac{v_t - \frac{A\beta}{1+A\beta} v_t}{R_{id}}$$

$$R_{in} = R_1 + R_{id} \left| \frac{R_2}{1 + A} \cong R_1 + \left( \frac{R_2}{1 + A} \right) \right| \qquad \therefore i_t = \frac{v_t}{(1 + A\beta)R_{id}}, R_{in} = R_{id}(1 + \frac{AR_1}{R_1 + R_2})$$



## ESc201, Lecture 24: Operational Amplifier Summary of Non-ideal OpAmp

**Inverting Amplifier** Non-inverting Amplifier

Non-Inverting 
$$v_{id} = v_i - v_l = v_i - \frac{R_1 v_o}{R_1 + R_2}$$

$$=v_{1} - \frac{1}{1 + \frac{R_{1} + R_{2}}{AR_{1}}} v_{1} = \frac{v_{1}}{1 + \frac{AR_{1}}{R_{1} + R_{2}}} \Big|_{A \to \infty} = 0$$

Input Resistance (R<sub>in</sub>)

Open Loop Voltage Gain (A)
Finite A:
Non-Inverting 
$$v_{id} = v_i - v_1 = v_i - \frac{R_1 v_0}{R_1 + R_2}$$

Finite A:
Same for both

No longer zero,  $v_{id}$  is small for large  $AR_1/(R_1 + R_2)$ .

Voltage Gain (A<sub>v</sub>) (negative feedback)

$$= v_1 - \frac{1}{1 + \frac{R_1 + R_2}{AR_1}} v_1 = \frac{v_1}{1 + \frac{AR_1}{R_1 + R_2}} \Big|_{A \to \infty} = 0$$

Voltage Gain (A<sub>v</sub>) (negative feedback)

$$= v_1 - \frac{1}{1 + \frac{R_1 + R_2}{AR_1}} v_2 = \frac{v_1}{1 + \frac{AR_1}{R_1 + R_2}} \Big|_{A \to \infty} = 0$$

Voltage Gain (A<sub>v</sub>) (negative feedback)

$$= v_1 - \frac{1}{1 + \frac{R_1 + R_2}{AR_1}} v_2 = \frac{v_1}{1 + \frac{AR_1}{R_1 + R_2}} \Big|_{A \to \infty} = 0$$

$$R_1 + R_{id} \left| \frac{R_2}{1+A} \cong R_1 + \left( \frac{R_2}{1+A} \right) \right|$$

Input Resistance (R<sub>in</sub>)
$$R_1 + R_{id} \begin{vmatrix} R_2 \\ 1+A \end{vmatrix} \cong R_1 + \left(\frac{R_2}{1+A}\right) \qquad R_{id} \left(1 + \frac{AR_1}{R_1 + R_2}\right)$$
Output Resistance (R<sub>out</sub>)
$$\frac{R_0}{1 + AR_1/(R_1 + R_2)} || (R_1 + R_2) \cong \frac{R_0}{1 + AR_1/(R_1 + R_2)}$$
Same for both

Instrumentation Amplifier: The signal may get thoroughly corrupted by noise during transmission from a sensor to the signal measuring unit, and it becomes extremely difficult to distinguish the original signal using conventional circuits.

Solution: Have a Differential Amplifier stage with High A<sub>d</sub> and High CMRR, preceded by a buffer stage to provide a high  $R_{\mbox{\scriptsize in}}$  and impedance matching.

Combines 2 non-inverting OpAmps with a difference OpAmp for high gain and low input resistance.

### ESc201, Lecture 23: Operational Amplifier

### Requirements of an Instrumentation Amplifier:

Finite, Accurate and Stable Gain: Since the instrumentation amplifiers are required to amplify very low-level signals from the transducer device, extremely high but finite differential gain  $A_{dm}$  is the basic requirement. The gain also needs to be accurate and the closed-loop gain must be stable.

Easier Gain Adjustment: Apart from a finite and stable gain, variation in the gain factor over a prescribed range of values is also necessary. The gain adjustment must be easier and precise.

High Input Impedance: To avoid the loading of input sources, the input impedance of the instrumentation amplifier must be very high (ideally infinite).

Low Output Impedance: The output impedance of a good instrumentation amplifier must be very low (ideally zero), to avoid loading effect on the immediate next stage.

Perfect impedance matching is required for maximum power transfer from the sensor.

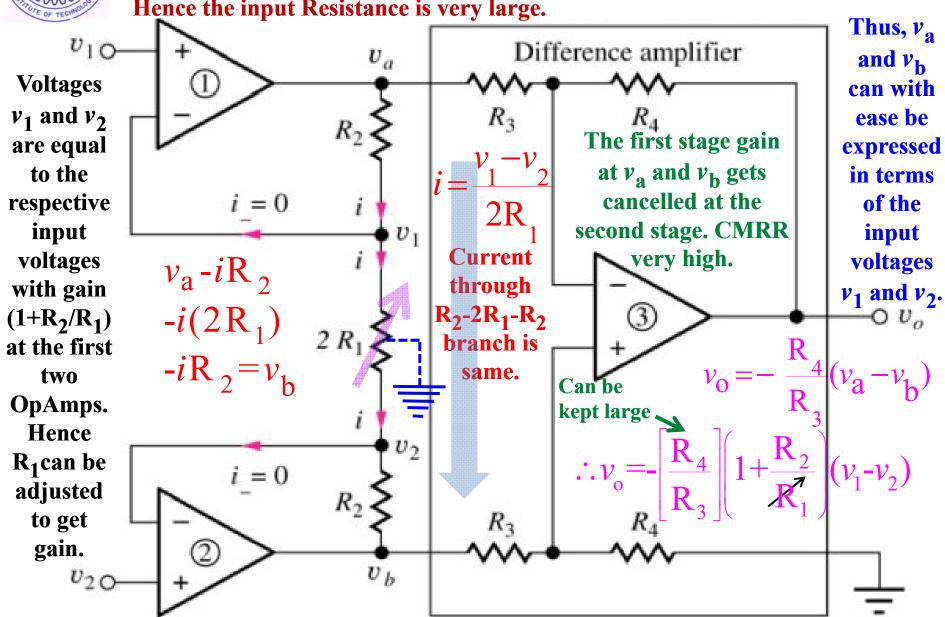
High CMRR: The output from the transducer usually contains common mode signals, when transmitted over long wires. A good instrumentation amplifier must amplify only the differential input, completely rejecting common mode inputs. Ideally zero common mode gain  $A_{cm}$  to suppress noise. Thus, CMRR must  $\rightarrow \infty$ .

High Slew Rate: The slew rate of the instrumentation amplifier must be as high as possible to provide maximum undistorted output voltage swing.

**ESc201**, Lecture 23: Operational Amplifier **Instrumentation Amplifier:** 

Buffer stage: OpAmps (1) and (2) draw little or no input current.

Hence the input Resistance is very large.



# ESc201, Lecture 24: Operational Amplifier (LIMITATIONS) Input OffsetVoltage. (MOS input OpAmps have high R; but also higher VOS than BJT input)

With inputs being zero, the amplifier output rests at some dc voltage level instead of zero. The equivalent dc input offset voltage is:  $V_{OS}=V_{o}/A$  (1-10 mV).

The amplifier is connected as voltage-follower to give output voltage equal to offset voltage.

To include effect of offset voltage, 
$$v_o = A \left[ v_{id} + \frac{v_{ic}}{CMRR} + V_{OS} \right]$$

If  $v_{id} = 0$ ,
$$v_o = A \left[ \frac{v_{ic}}{CMRR} + V_{OS} \right] = A(v_{OS}) \quad \therefore CMRR = \frac{v_{ic}}{v_{OS}} \mu V/V$$

Limitations: Bandwidth (Unity Gain Cut-off)  $f_T$ : OpAmps are compensated for stability to suppress unwanted oscillations, which introduces a pole in the frequency response characteristic, typically  $\sim 5-10$ Hz.

After that, the gain rolls off at  $-20 \, \text{dB/decade}$ . The frequency at which the magnitude of this gain becomes unity (i.e., 0 dB) is known as the unity gain cut-off frequency ( $f_T$ ). Where :

 $A_{vop.\ loop}$   $xf_{op.\ loop} = Af_{op.\ loop} = f_T = A_{vfeedback}$   $xf_{3dB}$  For a closed-loop feedback amplifier:

$$A_{v}(s) = \frac{A_{o}/\{1 + A_{o}R_{1}/(R_{1} + R_{1})\}}{1 + s/\{[1 + A_{o}R_{1}/(R_{1} + R_{1})]\omega_{3dB}\}} = \frac{A_{v}(0)}{1 + s/\omega_{H}}$$

$$\omega_{H} = [1 + A_{o}R_{1}/(R_{1} + R_{1})]\omega_{3dB} = \frac{\omega_{T}}{A_{v}(0)}$$

