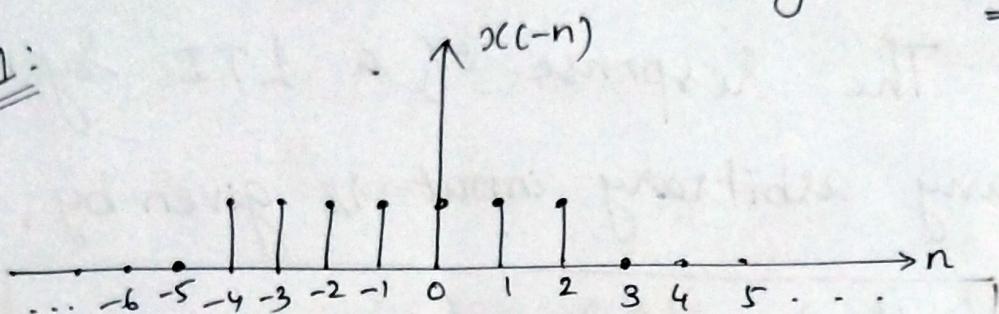


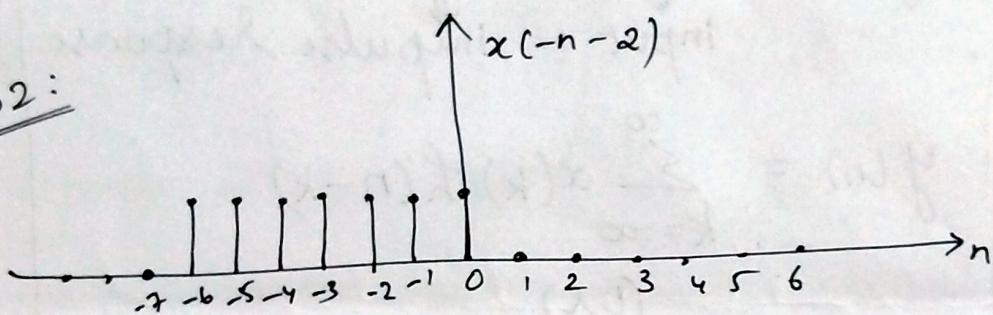
Step 1: fold $x(n)$ to get $x(-n)$

Step 2: Shift $x(-n)$ by 2 units
towards left to get $x(-n-2)$ \Rightarrow

Step 1:



Step 2:



Linear - Time Invariant System (LTI):

If a system satisfies both
Linearity and Time-Invariance
property, then it is said to be LTI.

26.

Analysis of DT - LTI System:

Linear Convolution (or) Convolution sum:

The response of a LTI system for any arbitrary input is given by,

$$y(n) = \underset{\text{input}}{\downarrow} x(n) * \underset{\text{impulse response}}{\downarrow} h(n)$$

$$y(n) = \sum_{k=-\infty}^{\infty} x(k) h(n-k) \quad (\text{or})$$

$$y(n) = \sum_{k=-\infty}^{\infty} h(k) x(n-k)$$

If $N_1 \rightarrow$ no. of samples in $x(n)$

$N_2 \rightarrow$ " " " in $h(n)$

then, no. of samples in $y(n)$ } = $N_1 + N_2 - 1$
 (or)
 length of $y(n)$ }

The output $y(n)$ is a non-periodic sequence

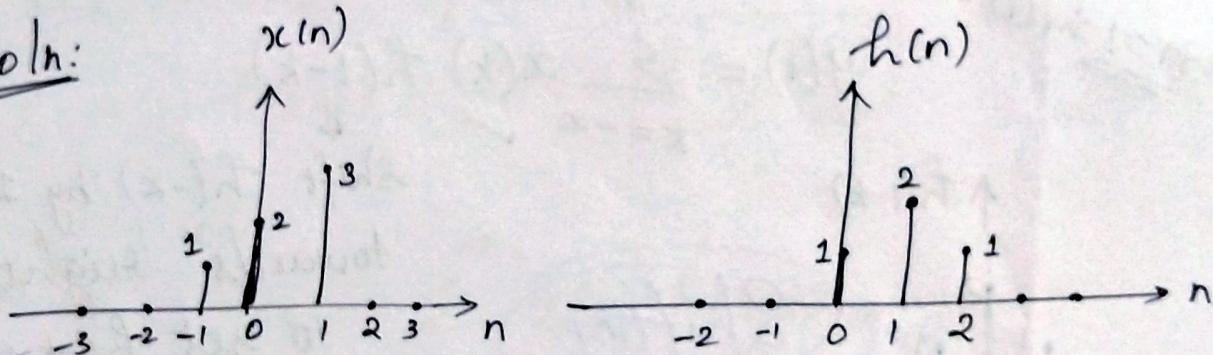
\therefore this convolution is called as Aperiodic Convolution

Steps to perform Convolution Sum:

1. Folding
2. Shifting
3. Multiplication
4. Summation.

pblm: The impulse response of a LTI system is $h(n) = \{ \uparrow 1, 2, 1 \}$, Determine the response of the system to i/p $x(n) = \{ 1, 2, 3 \}$

Soln:



$$y(n) = \sum_{k=-\infty}^{\infty} x(k) h(n-k) \quad \textcircled{1}$$

$$N_1 = 3$$

$$N_2 = 3$$

put $n=0$,
in $\textcircled{1}$

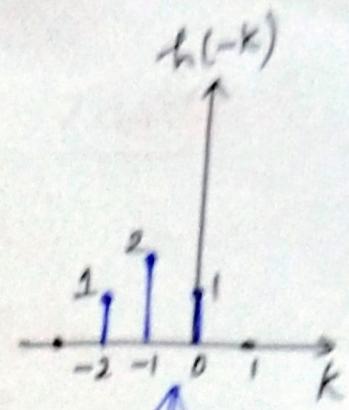
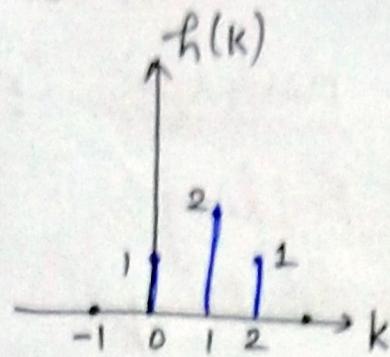
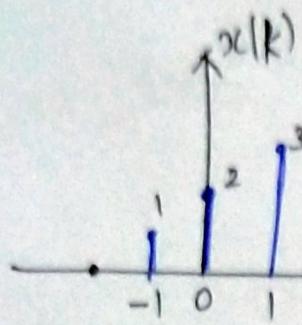
$$y(0) = \sum_{k=-\infty}^{\infty} x(k) h(0-k)$$

put $n=k$
in $x(n)$

fold $h(k)$

put $n=k$
in $h(n)$

$L = N_1 + N_2 - 1$
 $= 3 + 3 - 1$
 $L = 5$



$$x(k) = \{ 1, 2, 3 \}$$

$$h(-k) = \{ 1, 2, 1 \}$$

$$x(k) \cdot h(-k) = \{ 0, 2, 2, 0 \}$$

$$\sum_{k=-\infty}^{\infty} x(k) h(-k) = 2 + 2 = 4 = y(0)$$

addition

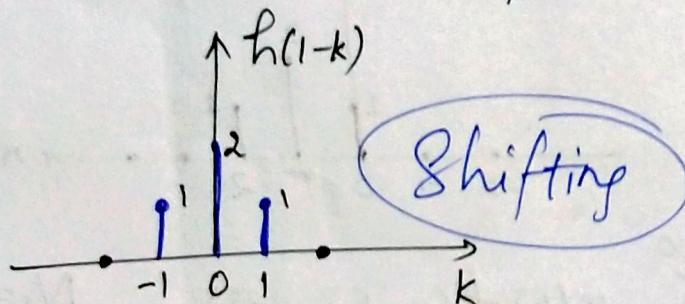
put n=1 in ①

$$y(1) = \sum_{k=-\infty}^{\infty} x(k) h(1-k)$$

shift $h(-k)$ by 1 unit
towards right

to get $h(-k+1)$

\downarrow
 $h(1-k)$



$$x(k) = \{ 1, 2, 3 \}$$

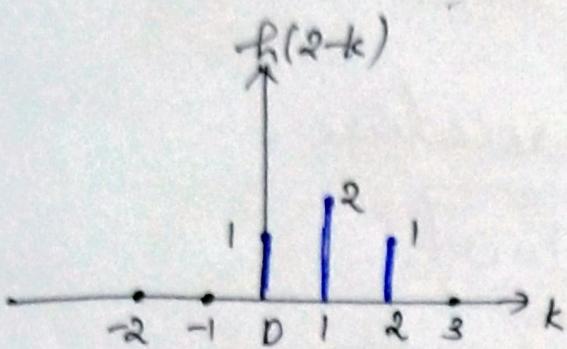
$$h(1-k) = \{ 2, 1, 1 \}$$

$$x(k) \cdot h(1-k) = \{ 1, 4, 3 \}$$

$$\sum_{k=-\infty}^{\infty} x(k) h(1-k) = 1 + 4 + 3 = 8 = y(1)$$

put $n=2$ in ①,
 $y(2) = \sum_{k=-\infty}^{\infty} x(k) h(2-k)$

Shift $h(1-k)$ by 1 unit
towards right.



(a) Shift $h(-k)$ by 2 units
towards right.

$$x(k) = \{ \cancel{1}, \cancel{2}, \cancel{3} \}$$

$$h(2-k) = \{ \cancel{1}, \cancel{2}, \cancel{3} \}$$

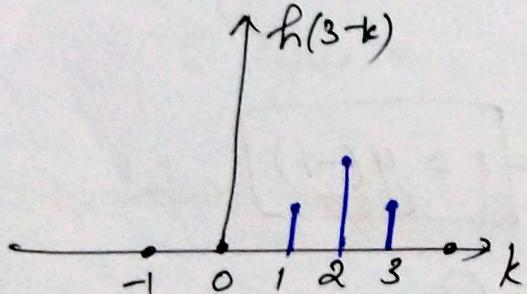
$$x(k) \cdot h(2-k) = \{ 2, 6 \}$$

$$\sum x(k) \cdot h(2-k) = 2+6 = \boxed{8 = y(2)}$$

put $n=3$ in ①

$$y(3) = \sum_{k=-\infty}^{\infty} x(k) h(3-k)$$

Shift $h(2-k)$ by 1 unit
towards right.



(a) Shift $h(1-k)$ by 2 units
towards right

$$x(k) = \{ \cancel{1}, \cancel{2}, \cancel{3} \}$$

$$h(3-k) = \{ \cancel{0}, \cancel{1}, \cancel{2}, \cancel{3} \}$$

(a) Shift $h(-k)$ by 3 units
towards right

$$x(k) \cdot h(3-k) = \{ 0, 3 \}$$

$$\sum x(k) \cdot h(3-k) = 0+3 = \boxed{3 = y(3)}$$

by put $n=4$ in ①

do the same procedure.

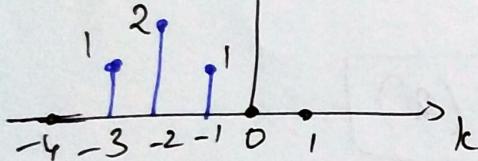
$$\boxed{y(4)=0} \cdot \boxed{y(5)=0} \dots \dots$$

put $n=-1$ in ①

$$y(-1) = \sum_{k=-\infty}^{\infty} x(k) h(-1-k)$$

$h(-1-k)$

shift $h(-k)$ by 1 unit towards left



$$x(k) = \{ 1, 2, 3 \}$$

$$h(-1-k) = \{ 0, 1, 2, 1, 0 \}$$

$$x(k) \cdot h(-1-k) = \{ 1, 0, 0 \}$$

$$\sum x(k) \cdot h(-1-k) = 1+0 = \boxed{1 = y(-1)}$$

put $n=-2, -3$

$$y(-2)=y(-3)=\dots=0$$

$$\therefore \boxed{y(n)=\{ 0, 1, 4, 8, 8, 30, \dots \}}$$

31.

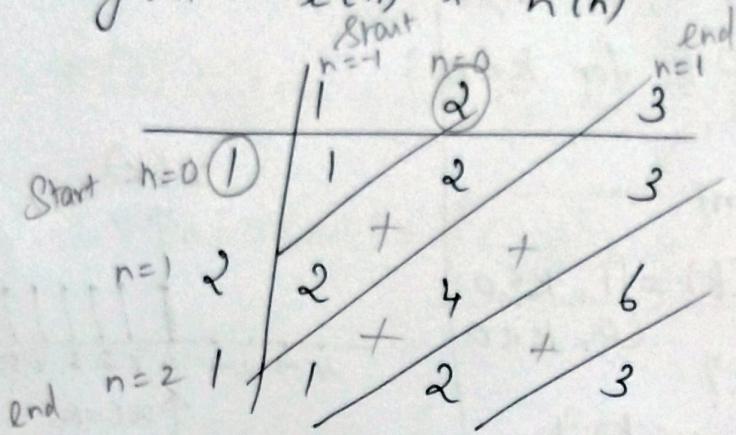
(08)

Alternate method

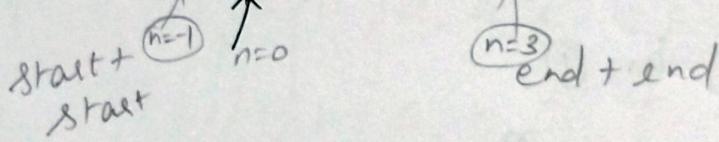
$$x(n) = \{ 1, 2, 3 \}$$

$$h(n) = \{ \underset{\uparrow}{1}, \underset{\uparrow}{2}, \underset{\uparrow}{1} \}$$

$$y(n) = x(n) * h(n)$$



$$y(n) = \{ 1, 4, 8, 8, 3 \}$$



pbm Determine the output $y(n)$ of a relaxed LTI system with $h(n) = a^n u(n)$, where $|a| < 1$

when input is a step sequence.

$$g_n: \quad x(n) = u(n)$$

$$h(n) = a^n u(n)$$

$$\left| \begin{array}{l} \therefore u(n) = 1, n \geq 0 \\ 0, n < 0 \end{array} \right)$$

Soln:

$$y(n) = x(n) * h(n)$$

$$y(n) = \sum_{k=-\infty}^{\infty} h(k) x(n-k)$$

$$h(k) = a^k u(k)$$

$$\text{ie. } h(k) = \begin{cases} a^k \cdot 1, & \text{for } k \geq 0 \\ 0, & \text{for } k < 0 \end{cases}$$

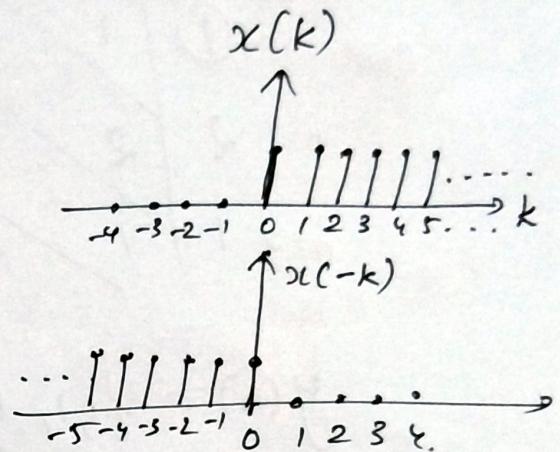
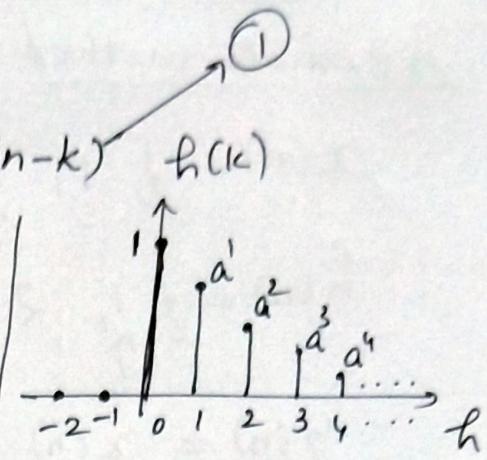
$$\underline{x(n-k) = ?}$$

$$x(n) = u(n)$$

$$x(k) = u(k) = \begin{cases} 1, & k \geq 0 \\ 0, & k < 0 \end{cases}$$

$$x(-k+n) = ?$$

Shift $x(-k)$ by
'n' units towards right.



put $n=0$ in ①,

$$y(0) = \sum_{k=-\infty}^{\infty} h(k) x(-k)$$

$$h(k) = \{ 0, 0, 1, a^1, a^2, a^3, a^4, a^5, \dots \}$$

$$x(-k) = \{ \dots, 1, 1, 1, 1, 0, 0, 0, \dots \}$$

$$h(k) \cdot x(-k) = \{ 0, 0, 0, 1, 0, 0, 0, \dots \}$$

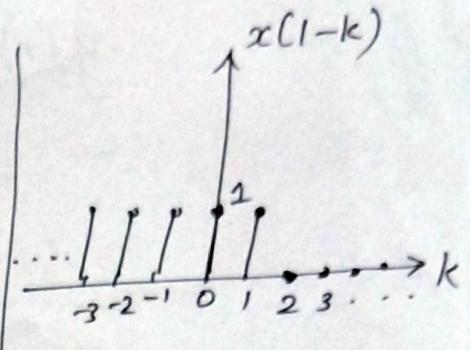
$$\sum h(k) x(-k) = 0 + 1 + 0 = \boxed{1 = y(0)}$$

put $n=1$ in ①,

$$y(1) = \sum_{k=-\infty}^{\infty} h(k) x(1-k)$$

$$h(k) = \{ \dots, 0, 0, 1, a^1, a^2, a^3, a^4, \dots \}$$

$$x(1-k) = \{ \dots; 1, 1, 1, 0, 0, 0, \dots \}$$



$$h(k) x(1-k) = \{ \dots, 0, 0, 1, a^1, 0, 0, \dots \}$$

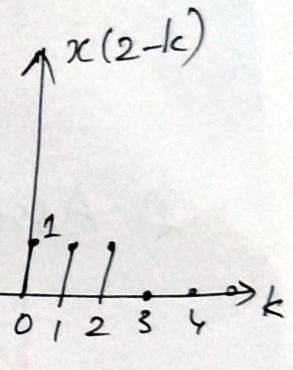
$$\sum h(k) x(1-k) = [1 + a^1 = y(1)]$$

put $n=2$ in ②

$$y(2) = \sum_{k=-\infty}^{\infty} h(k) x(2-k)$$

$$h(k) = \{ \dots, 0, 0, 1, a^1, a^2, a^3, a^4, a^5, \dots \}$$

$$x(2-k) = \{ \dots, 1, 1, 1, 1, 0, 0, 0, \dots \}$$



$$h(k) x(2-k) = \{ \dots, 0, 0, 1, a^1, a^2, 0, 0, \dots \}$$

$$\sum h(k) x(2-k) = [1 + a + a^2 = y(2)]$$

Similarly $y(3) = 1 + a + a^2 + a^3$

$$y(4) = 1 + a + a^2 + a^3 + a^4$$

:

$$y(n) = 1 + a + a^2 + a^3 + \dots + a^n$$

$$= \sum_{m=0}^n a^m \quad \text{for } n \geq 0$$

$$y(n) = \frac{1 - a^{n+1}}{1 - a}, \quad n \geq 0.$$

Properties of Linear Convolution:

1) Commutative:

$$y(n) = x(n) * h(n) = h(n) * x(n)$$

$$= \sum_{k=-\infty}^{\infty} x(k)h(n-k) = \sum_{k=-\infty}^{\infty} h(k)x(n-k)$$

2) Associative:

$$[x(n) * h_1(n)] * h_2(n) = x(n) * [h_1(n) * h_2(n)]$$

3) Distributive:

$$x(n) * [h_1(n) + h_2(n)] = [x(n) * h_1(n)] + [x(n) * h_2(n)]$$

Causal LTI system:

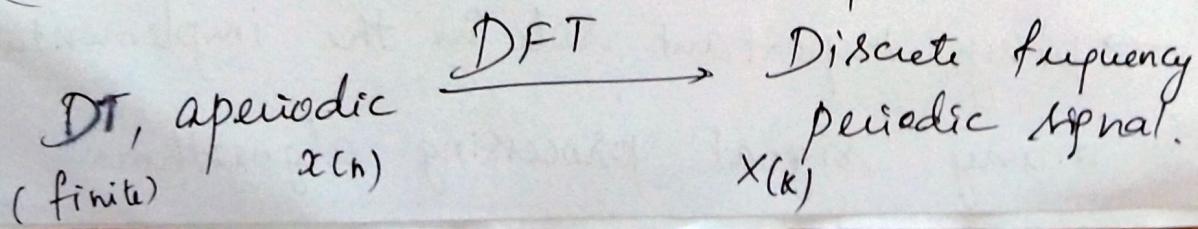
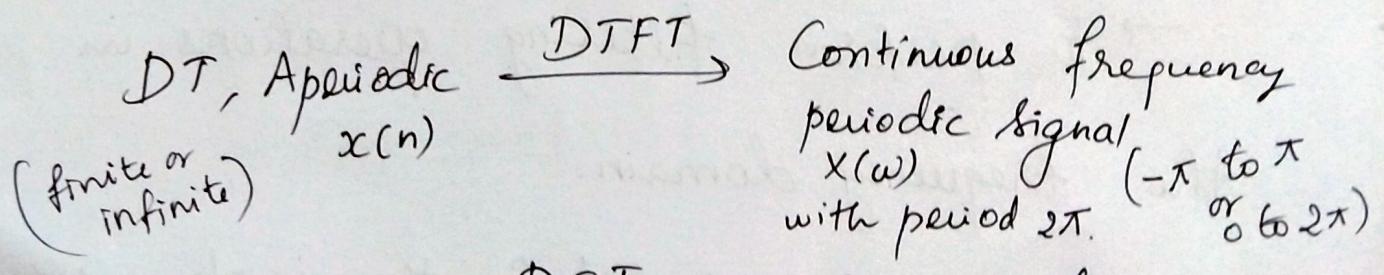
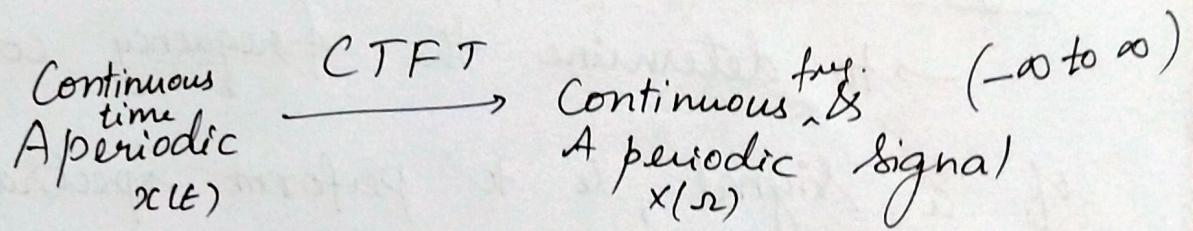
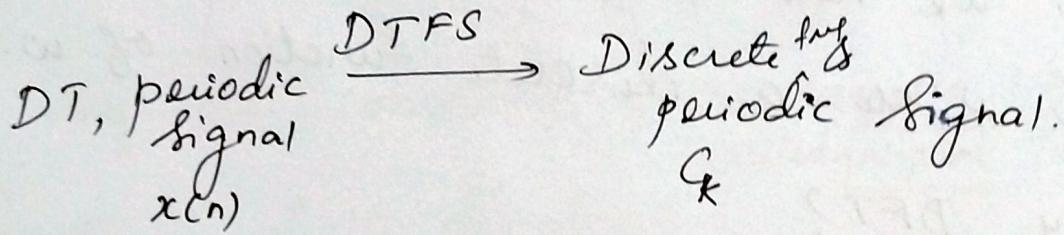
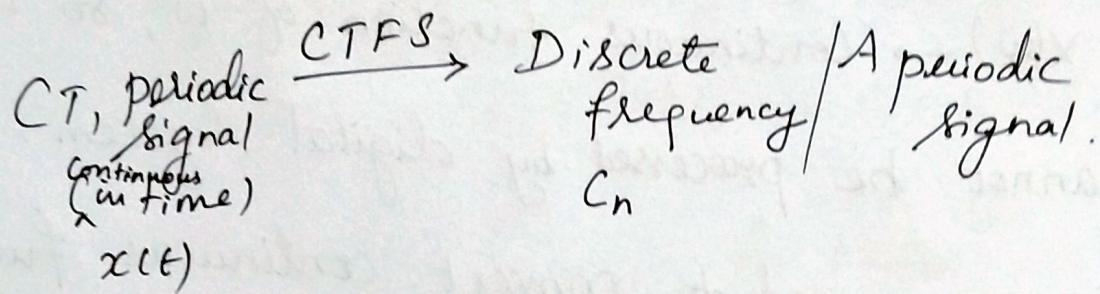
If $\underset{n < 0}{\not\exists} h(n)$ LTI system is $h(n) = 0, n < 0$

then it is causal.

Discrete Fourier Transform (DFT) :

Intro:

In order to perform spectral analysis (i.e. to find the frequency content) of the signals and systems, either Fourier Series (or) Fourier Transform is performed.



Fourier Transform (or) DTFT: $x(\omega)$

$$x(\omega) = \sum_{n=-\infty}^{\infty} x(n) \cdot e^{-j\omega n}$$

$$x(n) \xleftarrow{\text{FT}} x(\omega)$$

$$x(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} x(\omega) \cdot e^{j\omega n} d\omega.$$

$x(\omega)$ → continuous function of ω , so it cannot be processed by digital system.
so, we need to convert continuous function of ω into a discrete function of ω .

why DFT?

→ to determine the frequency content of a signal, i.e. to perform spectral analysis.

→ to perform filtering operations in the frequency domain.

→ plays important role in the implementation of many signal processing algorithms

Conversion of DTFT to DFT: (frequency-domain sampling) ^{by}

The DFT is obtained by sampling one period of the FT $X(\omega)$ of the signal $x(n)$ at a finite number of frequency points.

This sampling is conventionally performed at N equally spaced points in the period

$$0 \leq \omega \leq 2\pi \text{ (or) at } \omega_k = \frac{2\pi k}{N}, 0 \leq k \leq N-1.$$

$$x(k) = X(\omega) \Big|_{\omega = \frac{2\pi k}{N}}, \text{ for } k=0,1,2 \dots (N-1)$$

↓
Sequence consisting of N samples of $x(\omega)$.
called N -point DFT

Let
 Length of finite duration }
 sequence $x(n)$ } $\Rightarrow L$

No. of samples in $x(k) \Rightarrow N$

condition: $N \geq L$

definition of DFT:

$$X(k) = \text{DFT} \{ x(n) \} = \sum_{n=0}^{N-1} x(n) \cdot e^{-j \frac{2\pi kn}{N}}, \quad k=0,1,2 \dots N-1$$

$$\text{IDFT, } x(n) = \text{IDFT} \{ X(k) \} = \frac{1}{N} \sum_{k=0}^{N-1} X(k) e^{+j \frac{2\pi kn}{N}}, \quad n=0,1,2 \dots N-1$$

This DFT of a signal $x(n)$ is said to exist if the signals are absolutely summable.

$$\text{i.e. } \sum_{n=-\infty}^{\infty} |x(n)| < \infty$$

DFT pair:

$$\begin{array}{ccc} x(n) & \xleftarrow{\text{DFT}} & x(k) \\ (\text{of length } L) & & (\text{of Length } N) \end{array}$$

$\boxed{N \geq L}$