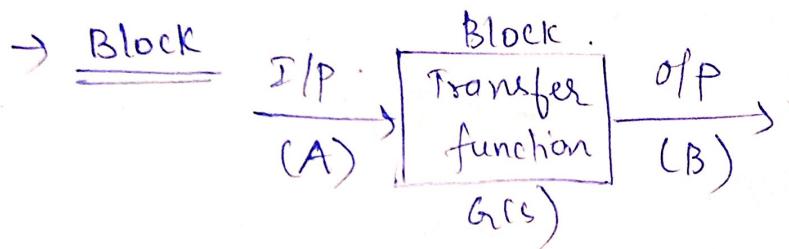


~~6/9/20~~

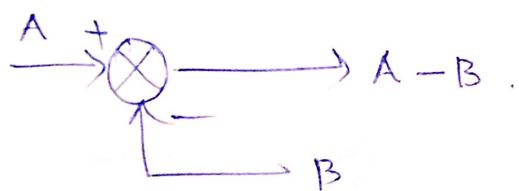
Block Diagrams

- A block diagram of a system is a pictorial representation of the functions performed by each component and the flow of signals.
- The elements of a block diagram are block, branch point and summing point.

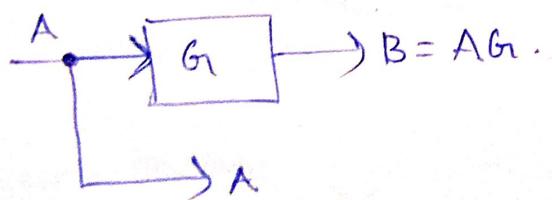


$$B = A(G(s))$$

- Summing point → used to add two or more



- Branch point → the signal from a block goes concurrently to other blocks.



Eg 1) construct the block diagram for the following differential equation.

$$(1) \rightarrow V_a = I_a R_a + L_a \frac{dI_a}{dt} + E_b$$

$$(2) \rightarrow T = K_t I_a$$

$$(3) \rightarrow T = J \frac{d\omega}{dt} + B\omega$$

$$(4) \rightarrow E_b = K_b \omega$$

$$(5) \rightarrow \omega = \frac{d\theta}{dt}$$

Solution: Take LT for all equations.

$$\underline{V_a(s)} = \underline{I_a(s) R_a} + \underline{L_a s I_a(s)} + \underline{E_b(s)} \quad (1)$$

$$T(s) = K_t I_a(s) \quad (2)$$

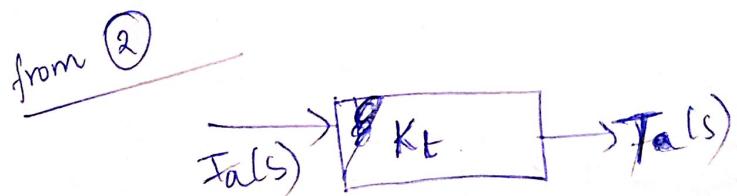
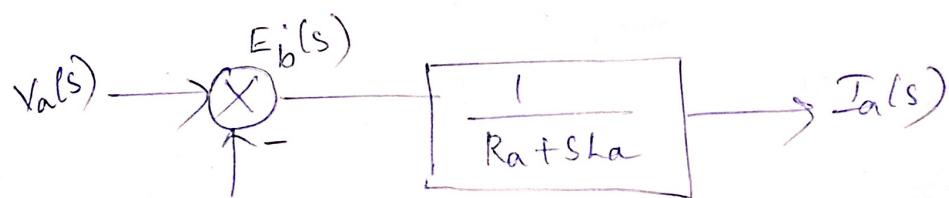
$$T(s) = J s \omega(s) + B \omega(s) \quad (3)$$

$$E_b(s) = K_b \omega(s) \quad (4)$$

$$\omega(s) = s \theta(s) \quad (5)$$

from (1)

$$V_a(s) - E_b(s) = I_a(s) (R_a + s L_a) \Rightarrow I_a(s) = \frac{V_a(s) - E_b(s)}{R_a + s L_a}$$



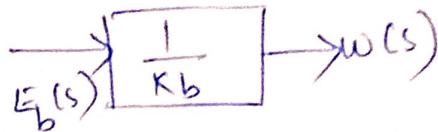
from (3)

$$\omega(s) = \frac{1}{J s + B} T(s)$$

$$T(s) \rightarrow \left[\frac{1}{J s + B} \right] \rightarrow \omega(s)$$

$$④ E_b(s) = k_b \omega(s)$$

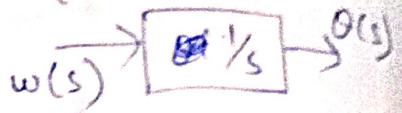
$$\omega(s) = \frac{1}{k_b} [E_b(s)]$$



⑤

$$\omega(s) = s(\theta(s))$$

$$\theta(s) = \frac{1}{s} \omega(s)$$

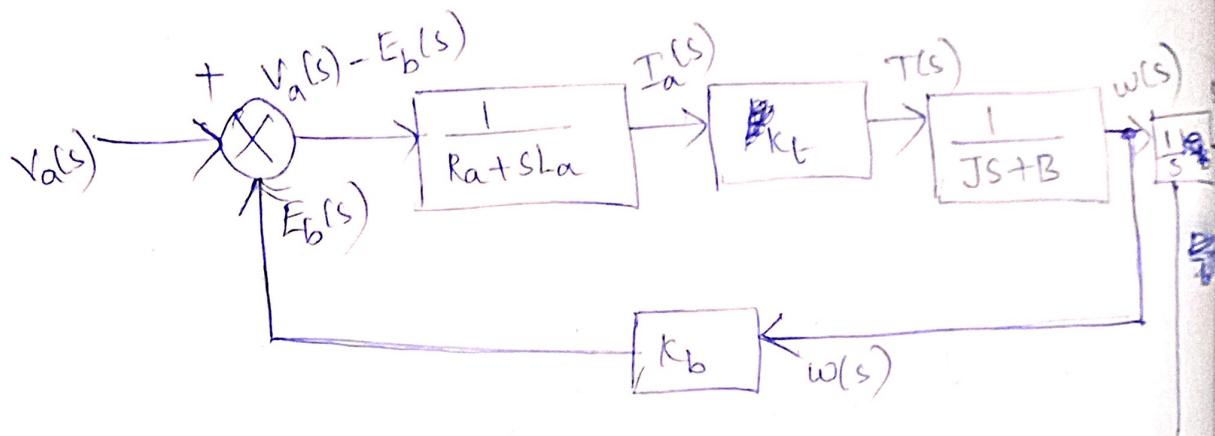


By combining
all the blocks,

$$V_a(s) \rightarrow \text{o/p}$$

$$\text{o/p} \rightarrow \theta(s)$$

all other blocks are
intermediate blocks.



2) construct the block diagram for the following diff. eqns.

$$V_f = R_f i_f + L_f \frac{di_f}{dt}$$

$$T = K_H i_f$$

$$T = J \frac{d^2 \theta}{dt^2} + B \frac{d\theta}{dt}$$

~~Topper~~ → take L.T. for all equations.

$$① \rightarrow V_f(s) = R_f I_f(s) + L_f s I_f(s)$$

$$② \rightarrow T(s) = K_{tf} I_f(s)$$

$$③ \rightarrow T(s) = JS^2 \theta(s) + BS \theta(s)$$

$$T(s) = \theta(s) \left[JS^2 + BS \right]$$

$$\theta(s) = \frac{1}{JS^2 + BS}$$

①

$$V_f(s) \xrightarrow{\frac{1}{R_f + SL_f}} I_f(s)$$

②

$$I_f(s) \xrightarrow{K_{tf}} T(s)$$

③

$$T(s) \xrightarrow{\frac{1}{S(JS+B)}} \theta(s)$$

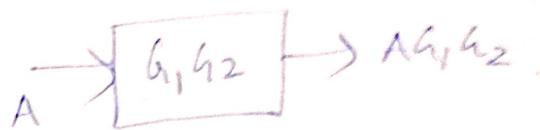
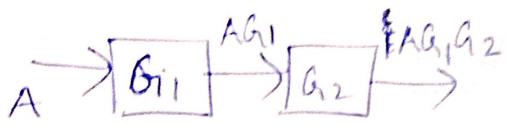
$$V_f(s) \xrightarrow{\frac{1}{R_f + SL_f}} I_f(s) \xrightarrow{K_{tf}} T(s) \xrightarrow{\frac{1}{S(JS+B)}} \theta(s)$$

Rules of Block diagram algebra :-

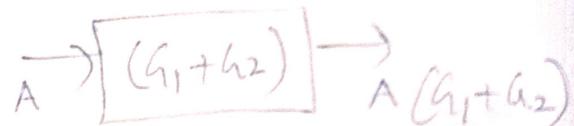
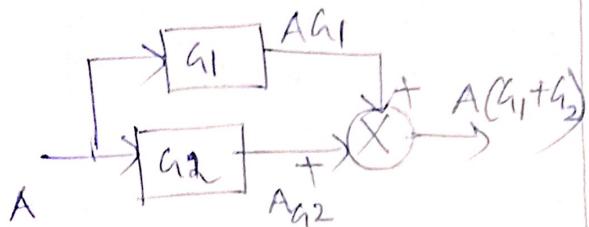
Rules - Blocks

Reduced / modified Blocks

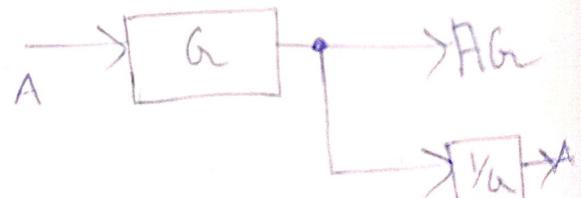
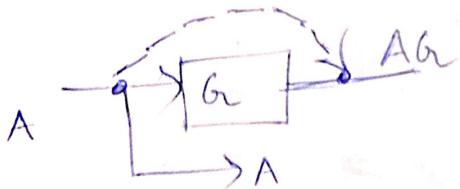
1) cascade blocks



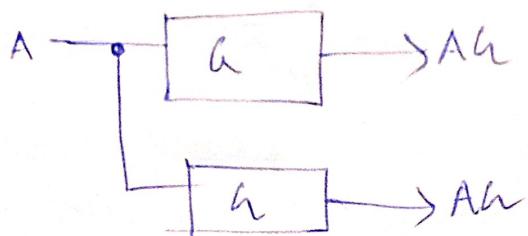
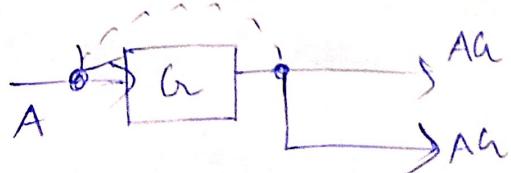
2) parallel blocks



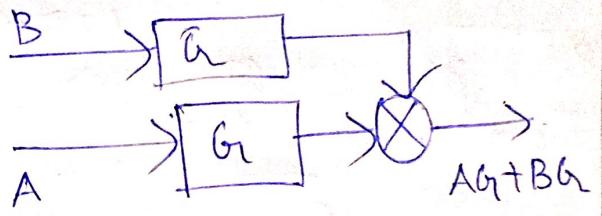
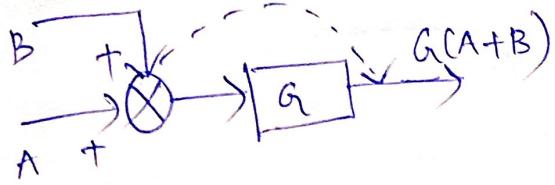
3) Moving branch point ahead of the block



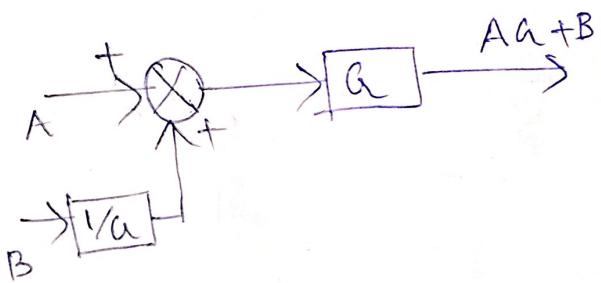
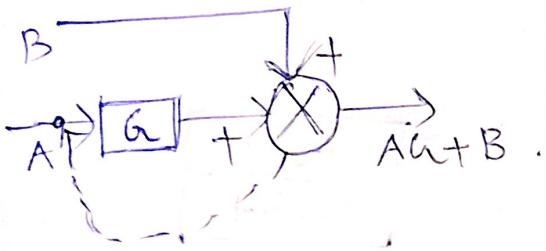
4) Moving the branch point before the block



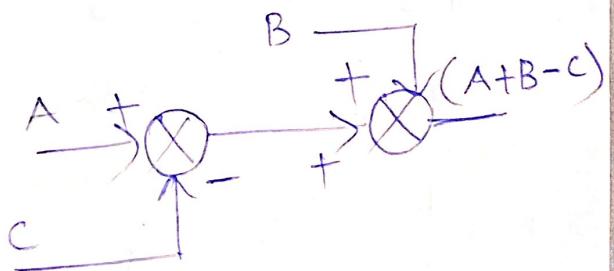
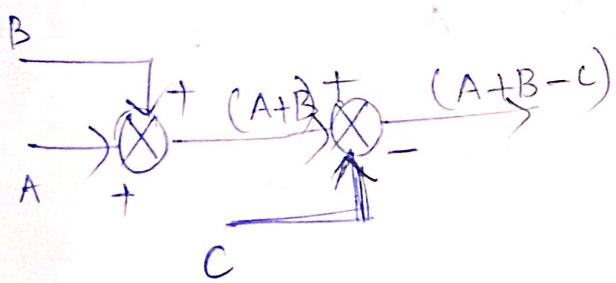
5) Moving the summing point ahead of the block



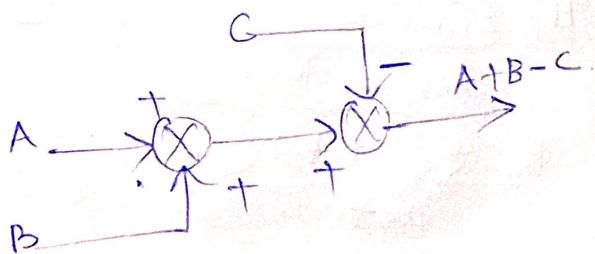
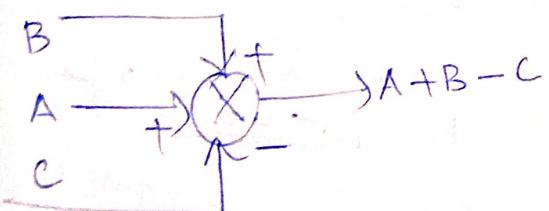
6) Moving the summing point before the block



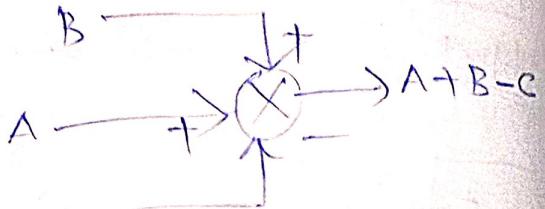
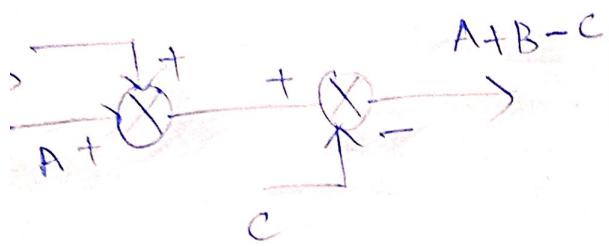
7) Interchanging summing point



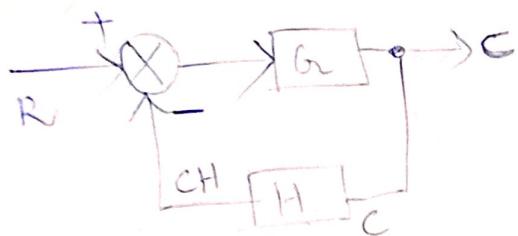
8) splitting summing point



9) combining summing points



10) eliminating - negative feedback loop



$$R \rightarrow \frac{G}{1+GH} \rightarrow C$$

$$(R - CH) G = C$$

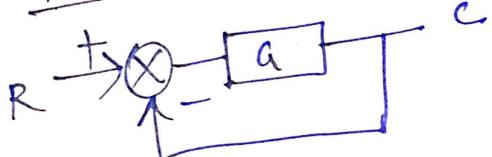
$$RG - CHG = C$$

$$RG = C + CHG$$

$$RG = C(1 + HG)$$

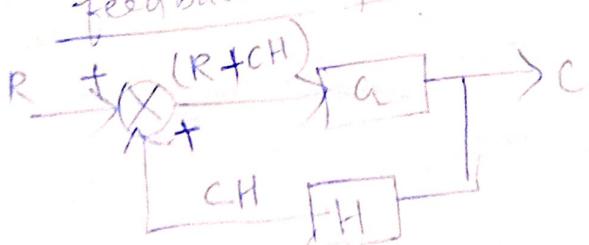
$$C = R \left(\frac{G}{1+GH} \right)$$

for unity fb (-ve)



$$\frac{C}{R} = \frac{a}{1+a}$$

11) eliminating - positive feedback loop

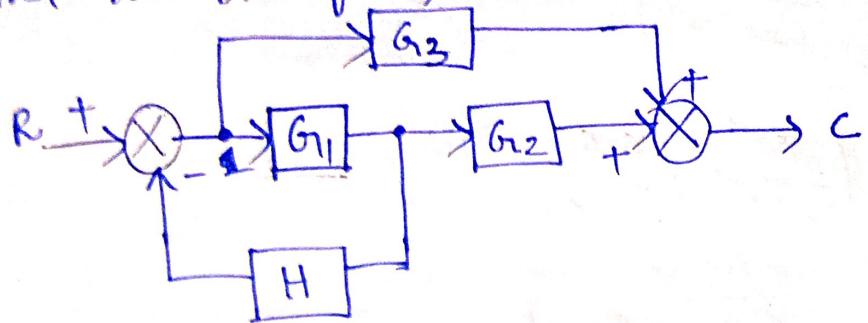


$$R \rightarrow \frac{a}{1-GH} \rightarrow C$$

for unity fb (+ve)

$$R \rightarrow \frac{a}{1-a} \rightarrow C \Rightarrow \frac{C}{R} = \frac{a}{1-a}$$

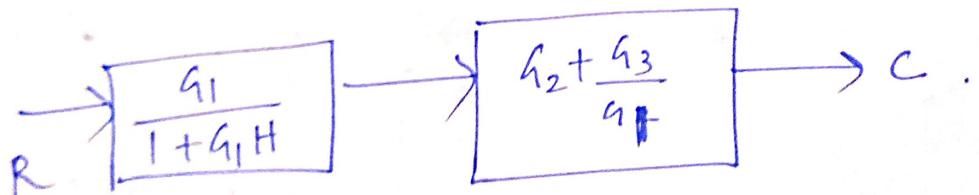
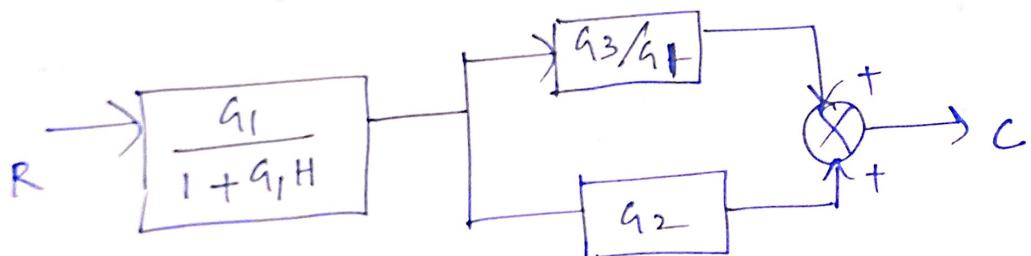
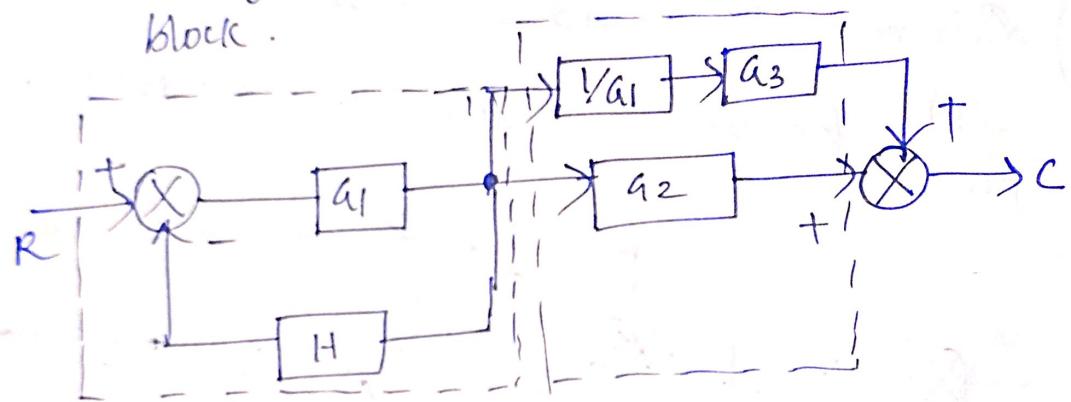
(q1) Reduce the block diagram shown in figure 4 find the transfer function.



solve:

step 1

moving the branch point ahead of the block.



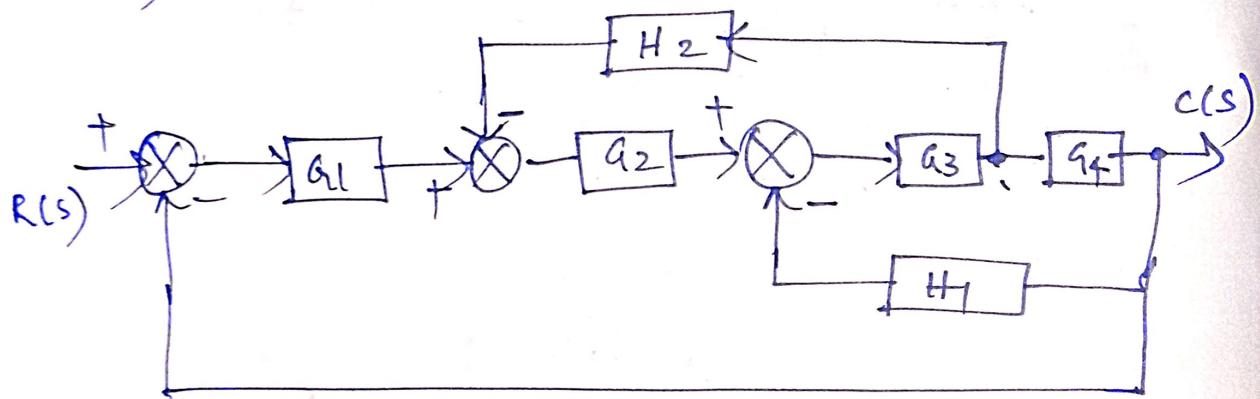
$$R \rightarrow \left[\frac{G_1}{1+G_1H} \right] \left(G_2 + \frac{G_3}{G_1} \right) \rightarrow C .$$

$$\frac{C}{R} = \left(\frac{G_1}{1+G_1H} \right) \left(G_2 + \frac{G_3}{G_1} \right)$$

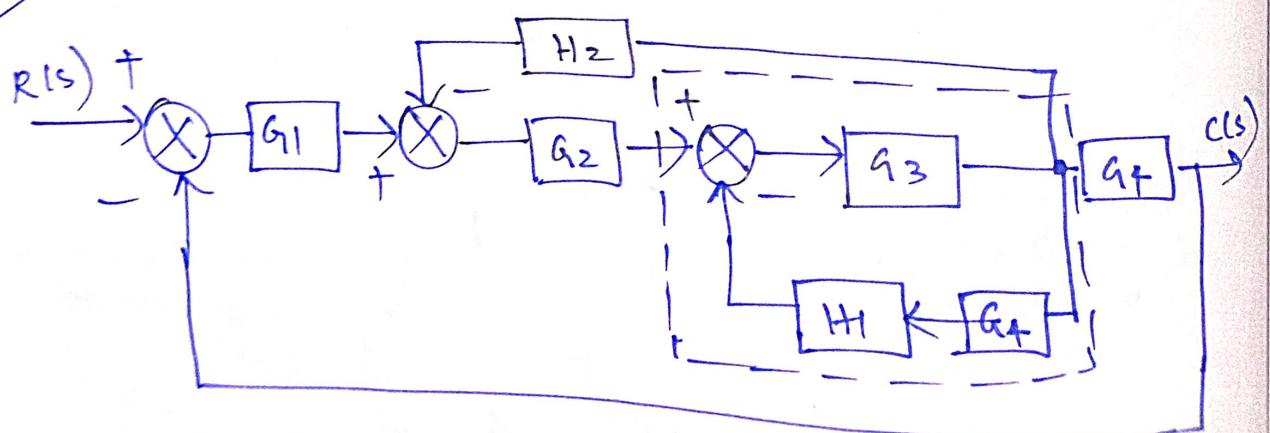
$$= \left(\frac{G_1}{1+G_1H} \right) \left(\frac{G_1G_2 + G_3}{G_1} \right)$$

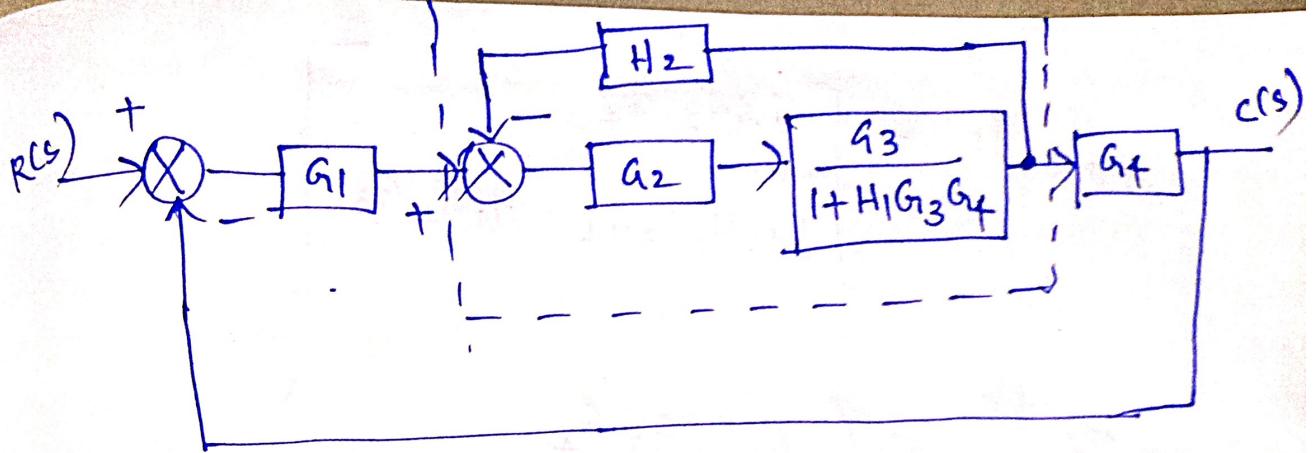
$$\frac{C}{R} = \frac{G_1G_2 + G_3}{1 + G_1H}$$

2) Determine the overall transfer function $\frac{C(s)}{R(s)}$ for the SIm shown in the figure



SIM:





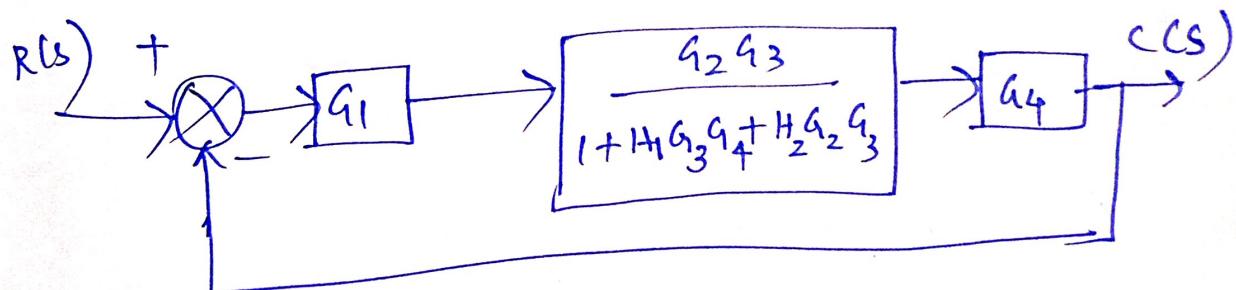
$$\text{cascade} \Rightarrow h_2 \left(\frac{g_3}{1+H_1 g_3 g_4} \right)$$

$$\text{n/o fb} \Rightarrow \frac{g_2 g_3}{1+H_1 g_3 g_4}$$

$$1 + H_2 \left(\frac{g_2 g_3}{1+H_1 g_3 g_4} \right)$$

$$\Rightarrow \frac{g_2 g_3}{\cancel{(1+H_1 g_3 g_4)}} \\ \frac{\cancel{(1+H_1 g_3 g_4)} + H_2 g_2 g_3}{\cancel{(1+H_1 g_3 g_4)}}$$

$$\Rightarrow \frac{g_2 g_3}{1+H_1 g_3 g_4 + H_2 g_2 g_3}$$



$$\text{cascade} \Rightarrow \left[\frac{G_1 G_2 G_3 G_4}{1 + H_1 G_3 G_4 + H_2 G_2 G_3} \right]$$

$$\text{unity fb} \Rightarrow \left(\frac{G_1 G_2 G_3 G_4}{1 + H_1 G_3 G_4 + H_2 G_2 G_3} \right) \overline{1 + \left(\frac{G_1 G_2 G_3 G_4}{1 + H_1 G_3 G_4 + H_2 G_2 G_3} \right)}$$

$$\therefore \frac{C(s)}{R(s)} = \frac{G_1 G_2 G_3 G_4}{1 + H_1 G_3 G_4 + H_2 G_2 G_3 + G_1 G_2 G_3 G_4}$$

$$R(s) \xrightarrow{\quad} \boxed{\frac{G_1 G_2 G_3 G_4}{1 + H_1 G_3 G_4 + H_2 G_2 G_3 + G_1 G_2 G_3 G_4}} \xrightarrow{\quad} C(s)$$