



Elektrobit



UDACITY

Functional Safety Concept Lane Assistance

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Document history

[Instructions: Fill in the date, version and description fields. You can fill out the Editor field with your name if you want to do so. Keep track of your editing as if this were a real world project.]

For example, if this were your first draft or first submission, you might say version 1.0. If this is a second submission attempt, then you'd add a second line with a new date and version 2.0]

Date	Version	Editor	Description
25/12/2018	1.0	Manjunath Gasthi	Initial version

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Purpose of the Functional Safety Concept

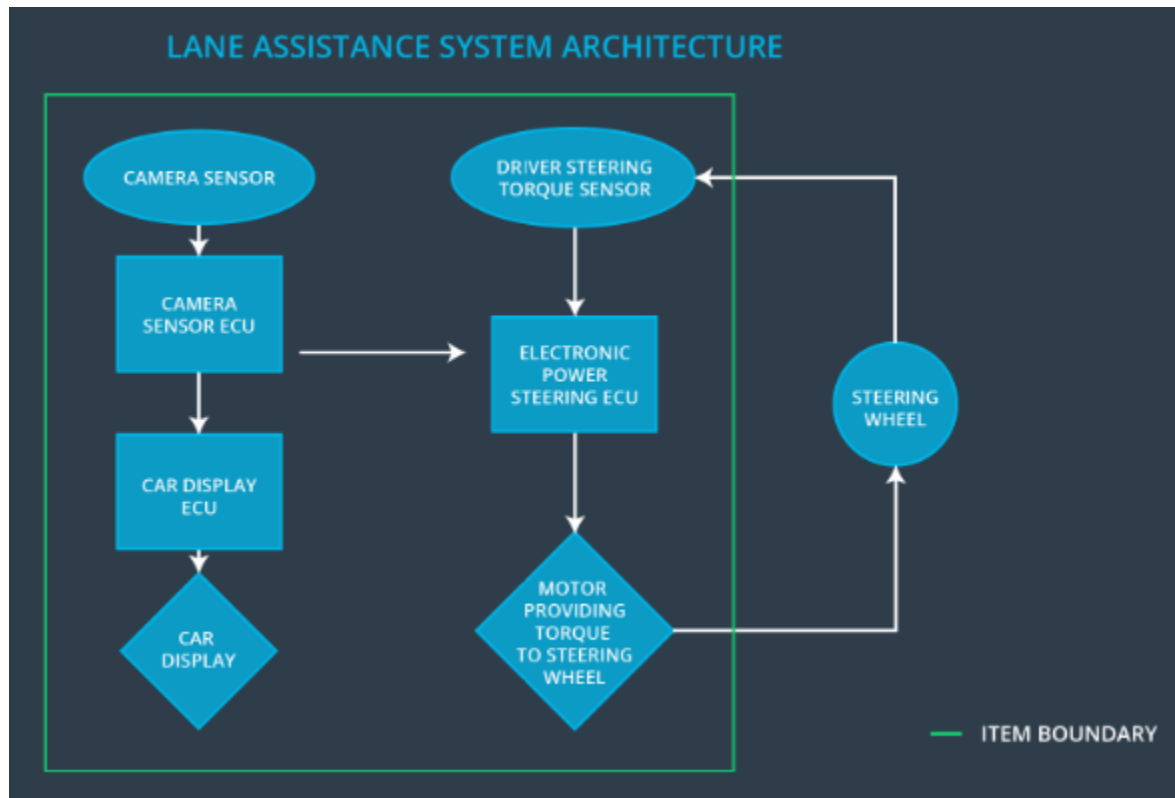
The Functional Safety Concept documents the identified system high level requirements. These requirements are allocated to different parts of the item architecture. Technical safety requirements will be derived from the safety concept. The validation and verification concept for these requirements are presented as well.

Inputs to the Functional Safety Concept

Safety goals from the Hazard Analysis and Risk Assessment

ID	Safety Goal
Safety_Goal_01	The oscillating steering torque from the Lane Departure Warning function shall be limited.
Safety_Goal_02	The Lane Keeping Assistance function shall be time limited, and additional steering torque shall end after a given time interval so the driver cannot misuse the system for autonomous driving.
Safety_Goal_03	The Lane Departure Warning function shall be deactivated when the camera sensor stop working.
Safety_Goal_04	The LKA function shall always react on time or inform the driver that it has a malfunction and turns itself off.

Preliminary Architecture



Description of architecture elements

Element	Description
Camera Sensor	Capture road images and provide them to the Camera Sensor ECU.
Camera Sensor ECU	Analyze provided images to calculate the car position on the road respect to the road lanes.
Car Display	Provide feedback to the driver displaying warnings and the Lane Departure Assistance status.
Car Display ECU	Controls the Car Display component to show the Lane Keeping Assistance warning and Lane Departure Assistance status.
Driver Steering Torque Sensor	Measure the torque applied to the steering wheel by the driver.
Electronic Power Steering ECU	Use the information received from the Driver Steering Torque Sensor and the torque requested by the Lane

	Keeping Assistance and Lane Warning and request the necessary torque to be applied by the Motor actuator.
Motor	Applies the torque indicated by the Electronic Power Steering ECU to the steering wheel.

Functional Safety Concept

The functional safety concept consists of:

- Functional safety analysis
- Functional safety requirements
- Functional safety architecture
- Warning and degradation concept

Functional Safety Analysis

Malfunction ID	Main Function of the Item Related to Safety Goal Violations	Guidewords (NO, WRONG, EARLY, LATE, MORE, LESS)	Resulting Malfunction
Malfunction_01	Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver a haptic feedback	MORE	The lane departure warning function applies an oscillating torque with very high torque amplitude (above limit).
Malfunction_02	Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver a haptic feedback	MORE	The lane departure warning function applies an oscillating torque with very high torque amplitude (above limit).
Malfunction_03	Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane	NO	The LKA function is not limited in time duration which leads to misuse as an autonomous driving function.

Functional Safety Requirements

Lane Departure Warning (LDW) Requirements:

ID	Functional Safety Requirement	ASIL	Fault Tolerant Time Interval	Safe State
Functional Safety Requirement 01-01	The Lane Departure Warning item shall ensure that the lane departure oscillating torque amplitude is below Max_Torque_Amplitude.	C	50 mS	Turn system off.
Functional Safety Requirement 01-02	The Lane Departure Warning item shall ensure that the lane departure oscillating torque frequency is below Max_Torque_Frequency.	C	50 mS	Turn system off.
Functional Safety Requirement 01-03	The Lane Departure Warning function shall be deactivated when the camera sensor stop working.	C	50 mS	Function is deactivated.

Lane Departure Warning (LDW) Verification and Validation Acceptance Criteria:

ID	Validation Acceptance Criteria and Method	Verification Acceptance Criteria and Method
Functional Safety Requirement 01-01	Validate Max_Torque_Amplitude chosen is high enough to be detected by a driver while low enough not to cause loss of steering	Verify the system does turn off if the Lane Departure Warning exceeded Max_Torque_Amplitude.
Functional Safety Requirement 01-02	Validate Max_Torque_Frequency chosen is adequate to be detected by the driver and not cause the loss of steering.	Verify the system does turn off if the Lane Departure Warning exceeded Max_Torque_Frequency.
Functional Safety Requirement 01-03	Validate Lane Departure Warning is off when the camera sensor is not working.	Verify the Lane Departure Warning is never on when the camera sensor is not working.

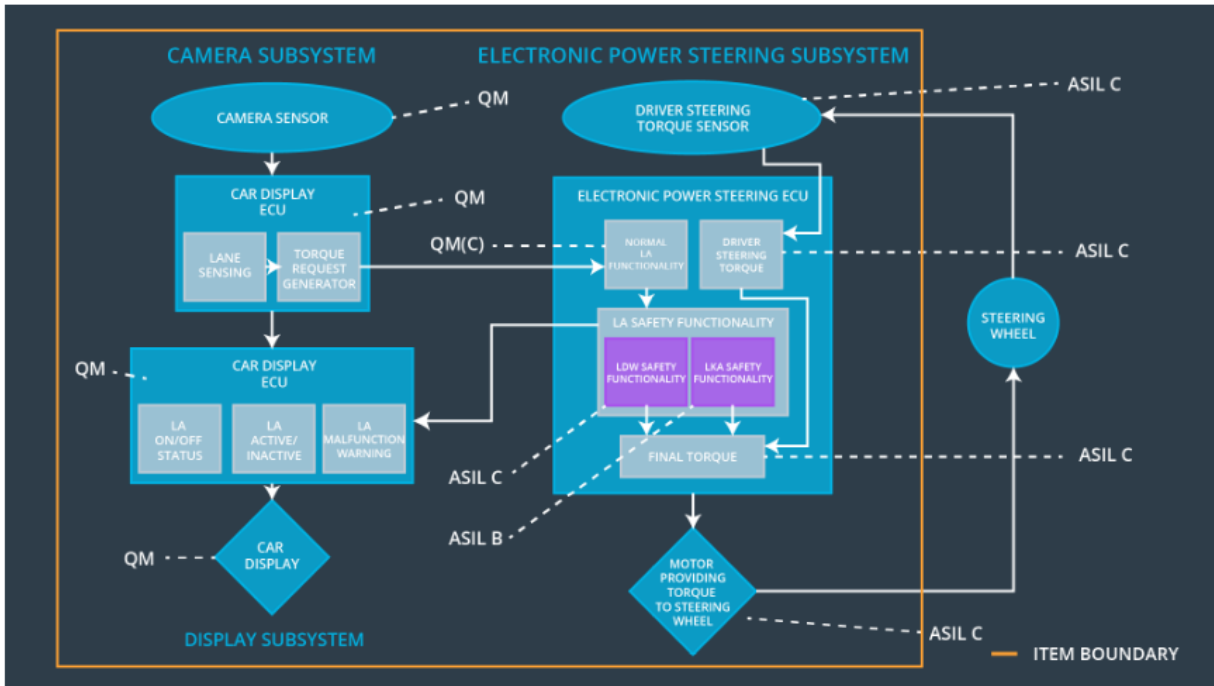
[Instructions: Fill in the functional safety requirements for the lane keeping assistance]

Lane Keeping Assistance (LKA) Requirements:

ID	Functional Safety Requirement	ASIL	Fault Tolerant Time Interval	Safe State
Functional Safety Requirement 02-01	The electronic power steering ECU shall ensure that the Lane Keeping Assistance torque is applied only Max_Duration.	B	500mS	Lane Keeping Assistance torque is zero.

Lane Keeping Assistance (LKA) Verification and Validation Acceptance Criteria:

ID	Validation Acceptance Criteria and Method	Verification Acceptance Criteria and Method
Functional Safety Requirement 02-01	Test and validate that the max_duration chosen really did dissuade drivers from taking their hands off the wheel.	Verify that the system does turn off if the lane keeping assistance every exceeded max_duration.



Allocation of Functional Safety Requirements to Architecture Elements

ID	Functional Safety Requirement	Electronic Power Steering ECU	Camera ECU	Car Display ECU
Functional Safety Requirement 01-01	The electronic power steering ECU shall ensure that the lane departure oscillating torque amplitude is below Max_Torque_Amplitude.	X		
Functional Safety Requirement 01-02	The electronic power steering ECU shall ensure that the lane departure oscillating torque frequency is below Max_Torque_Frequency.	X		
Functional Safety Requirement 02-01	The electronic power steering ECU shall ensure that the lane keeping assistance torque is applied for only Max_Duration.	X		

Warning and Degradation Concept

ID	Degradation Mode	Trigger for Degradation Mode	Safe State invoked?	Driver Warning
WDC-01	Turn system off.	Malfunction_01 Malfunction_02	Yes	Warning light on the dashboard
WDC-02	Turn system off.	Malfunction_03	Yes	Warning light on the dashboard